

Traffic Lights System using z64 processor

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1 Project

1.1 Requirements

A z64 processor controls the traffic light system of a pedestrian intersection. When the **BUTTON** is pressed, the processor programs the traffic lights of the cars to go from green to yellow and then from yellow to red. At the same time the pedestrian **TRAFFIC LIGHT** changes from red to green and then to yellow and then to red. To manage the transitions, the processor uses a programmable **TIMER** peripheral: it receives the number of seconds after which it will have to send an interrupt to the processor.

The transition times are defined as follows:

- After pressing the button, 10 seconds pass before switching to yellow for cars and a further 3 seconds to switch to red
- Green for pedestrians remains for 30 seconds, followed by 45 seconds of yellow

Even without pressing the button, the **TRAFFIC LIGHT** carries out a pedestrian crossing cycle every 5 minutes.

To design:

- The interfaces of the **TRAFFIC LIGHT**, **BUTTON**, **TIMER** peripherals.
- Device drivers and management software.

1.2 Implementation

The **BUTTON** device is represented as a classic *asynchronous daisy chain* device:

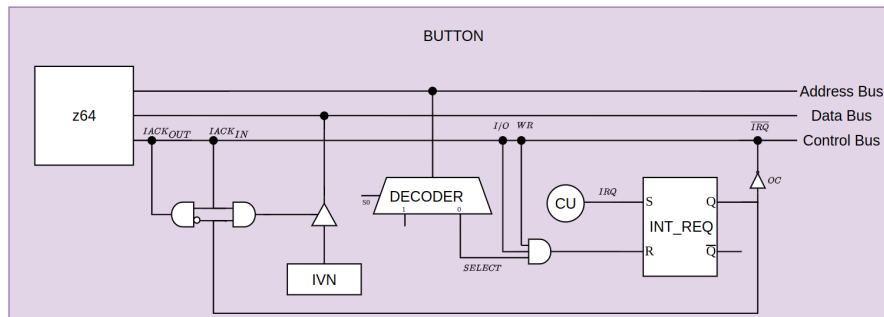


Figure 1. The **BUTTON** peripheral

The **TRAFFIC LIGHT** peripheral is represented as an output device that is used at the firmware level by implementing *busy waiting*:

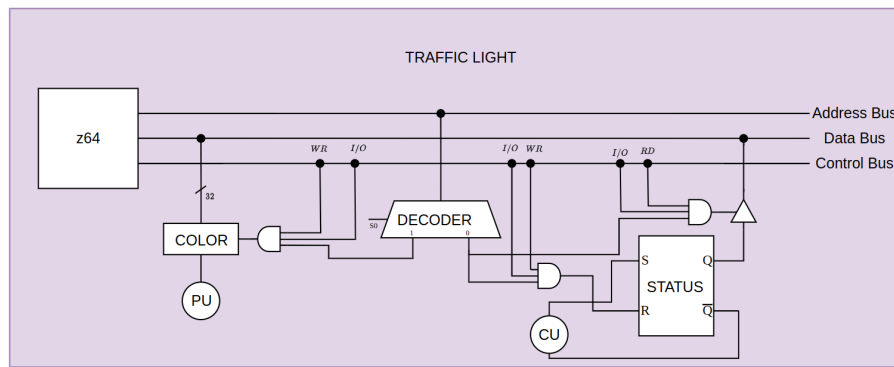


Figure 2. The TRAFFIC LIGHT peripheral

Finally, the **TIMER** peripheral is represented as a device that operates in mixed mode, i.e. both synchronously and asynchronously:

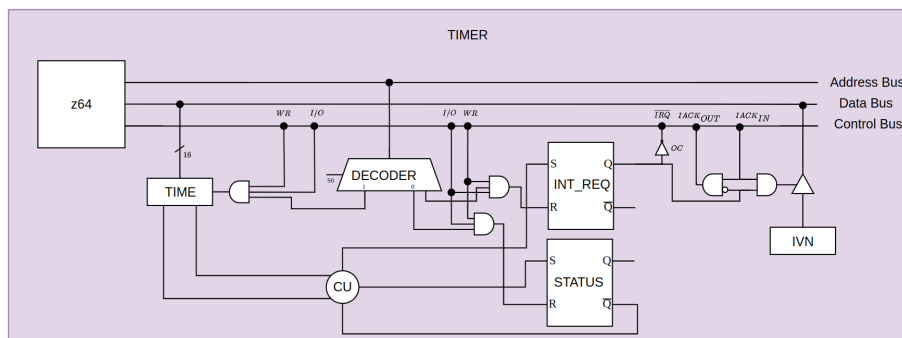


Figure 3. The TIMER peripheral

So, a possible *firmware implementation* can be found [here](#).