

Geometrie S5

Ex 1:

$$q(x) = 2x_1x_2 + x_2^2 - x_1x_3 + \frac{3}{4}x_3^2$$

$$A = \begin{pmatrix} 0 & 1 & -\frac{1}{2} \\ 1 & 1 & 0 \\ -\frac{1}{2} & 0 & \frac{3}{4} \end{pmatrix} \begin{matrix} \leftarrow x_1 \\ \leftarrow x_2 \\ \leftarrow x_3 \end{matrix}$$

$\begin{matrix} \uparrow & \uparrow & \uparrow \\ x_1 & x_2 & x_3 \end{matrix}$

$$(i, j) \rightarrow \text{coef lui } \frac{x_i x_j}{2}, i \neq j$$

$$x_i^2 \quad i=j$$

Méthode Jacobi

$$\Delta_1 = 0$$

$$\Delta_2 = \begin{vmatrix} 0 & 1 \\ 1 & 1 \end{vmatrix} = -1$$

$$\Delta_3 = \begin{vmatrix} 0 & 1 & -\frac{1}{2} \\ 1 & 1 & 0 \\ -\frac{1}{2} & 0 & \frac{3}{4} \end{vmatrix} = -\frac{1}{4} - \frac{3}{4} = -1 = \det A$$

Dacă tot Δ sunt ~~negativi~~ (~~sa~~ ^{sunt} > 0)

$$q(x') = \frac{1}{\Delta_1} (x'_1)^2 + \frac{\Delta_1}{\Delta_2} (x'_2)^2 + \frac{\Delta_2}{\Delta_3} (x'_3)^2$$

$$q(x) = x_1^2 + x_3^2 + 4x_1x_2 - 4x_1x_3$$

$$A = \begin{pmatrix} 1 & 2 & -2 \\ 2 & 0 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

$$\Delta_1 = 1$$

$$\Delta_2 = -4$$

$$\Delta_3 = \begin{vmatrix} 1 & 2 & -2 \\ 2 & 0 & 0 \\ -2 & 0 & 1 \end{vmatrix} = -4$$

$$q(x) = x_1^2 - x_3^2 - 4x_1x_2 - 4x_1x_3$$

$$A = \begin{pmatrix} 1 & -2 & -2 \\ -2 & 0 & 0 \\ -2 & 0 & -1 \end{pmatrix}$$

$$\Delta_1 = 1$$

$$\Delta_2 = 4$$

$$\Delta_3 = 4$$

$$q(x') = \frac{1}{\Delta_1} (x'_1)^2 + \frac{\Delta_1}{\Delta_2} (x'_2)^2 + \frac{\Delta_2}{\Delta_3} (x'_3)^2$$

$$= (x'_1)^2 + \frac{1}{4} (x'_2)^2 + \frac{1}{4} (x'_3)^2 \leftarrow \text{forma canonică}$$

$$\exists \{f_1, \dots, f_n\} \text{ bază a.î. } x = \sum_{i=1}^n x'_i f_i$$

$$f_i = c_{1i} e_1 + \cancel{c_{1i} e_1} + c_{2i} e_2 + c_{3i} e_3 + \dots + c_{bi} e_i$$

$$\text{unde } \begin{pmatrix} a_{11} & \dots & a_{1i} \\ \vdots & & \vdots \\ a_{i1} & \dots & a_{ii} \end{pmatrix} \begin{pmatrix} c_{1i} \\ \vdots \\ c_{ii} \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}$$

$$\exists \{f_1, f_2, f_3\} \text{ bază în } \mathbb{R}^3$$

$$f_1 = c_{11} \cdot e_1$$

$$a_{11} \cdot c_{11} = 1 \Rightarrow c_{11} = 1$$

$$a_{11} = 1$$

$$f_1 = e_1 = (1, 0, 0)$$

$$f_2 = c_{21} \cdot e_1 + c_{22} e_2 = -\frac{1}{2} (1, 0, 0) - \frac{1}{4} (0, 1, 0) = \left(-\frac{1}{2}, -\frac{1}{4}, 0\right)$$

$$\begin{pmatrix} 1 & -2 \\ -2 & 0 \end{pmatrix} \begin{pmatrix} c_{21} \\ c_{22} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$c_{21} - 2c_{22} = 0$$

$$-2c_{21} = 1$$

$$\Rightarrow c_{21} = -\frac{1}{2}$$

$$c_{22} = -\frac{1}{4}$$

$$f_3 = c_{31} e_1 + c_{32} e_2 + c_{33} e_3$$

$$\begin{pmatrix} 1 & -2 & -2 \\ -2 & 0 & 0 \\ -2 & 0 & 1 \end{pmatrix} \begin{pmatrix} c_{31} \\ c_{32} \\ c_{33} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$c_{31} - 2c_{32} - 2c_{33} = 0$$

$$-2c_{31} = 0 \Rightarrow c_{31} = 0$$

$$-2c_{31} - c_{33} = 1 \Rightarrow c_{33} = -1$$

$$-2c_{32} = -2 \Rightarrow c_{32} = 1$$

$$f_3 = (0, 1, -1)$$

$$(x_1, x_2, x_3) = x_1' \cdot p_1 + x_2' \cdot p_2 + x_3' \cdot p_3 = x_1' (1, 0, 0) + x_2' \left(-\frac{1}{2}, -\frac{1}{4}, 0\right) + x_3' (0, 1, -1) =$$

$$= \left(x_1' - \frac{1}{2}x_2', -\frac{1}{4}x_2' + x_3', -x_3'\right)$$

$$x_1 = x_1' - \frac{1}{2}x_2'$$

$$x_2 = -\frac{1}{4}x_2' + x_3' \Rightarrow x_2' = -4x_2 - 4x_3$$

$$x_3 = -x_3' \Rightarrow x_3' = -x_3$$

$$\Rightarrow x_1' = x_1 + \frac{1}{2}(-4x_2 - 4x_3) = x_1 - 2x_2 - 2x_3$$

• V sp. vect / \mathbb{R}

$\langle, \rangle : V \times V \rightarrow \mathbb{R}$ biliniară

$$\langle x, y \rangle = \langle y, x \rangle \text{ (simetrică)}$$

$$\langle x, x \rangle \geq 0$$

$$\langle x, x \rangle = 0 \Rightarrow x = 0_V$$

• \mathbb{R}^n , $x = (x_1, \dots, x_n)$

$$y = (y_1, \dots, y_n)$$

$$\langle x, y \rangle = x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

• $\mathcal{C}([a, b]) = \{f: [a, b] \rightarrow \mathbb{R} \mid f \text{-cont}\}$ $\leftarrow f.c. \text{ continue pe intervalul } [a, b]$

$$\langle f, g \rangle = \int_a^b f(x) g(x) dx$$

$$\langle f + f', g \rangle = \langle f, g \rangle + \langle f', g \rangle$$

$$\begin{aligned} \langle f + f', g \rangle &= \int_a^b [f(x) + f'(x)] \cdot g(x) dx = \int_a^b [f(x) g(x) + f'(x) g(x)] dx = \\ &= \int_a^b f(x) g(x) dx + \int_a^b f'(x) g(x) dx = \langle f, g \rangle + \langle f', g \rangle \end{aligned}$$

$$\langle f, g + g' \rangle = \langle f, g \rangle + \langle f, g' \rangle$$

$$\langle \alpha \cdot f, g \rangle = \alpha \cdot \langle f, g \rangle$$

$$\alpha \in \mathbb{R}$$

$$\langle f, f \rangle = \int_a^b f(x) f(x) dx = \int_a^b f^2(x) dx \quad \left| \begin{array}{l} f^2(x) \geq 0 \\ \Rightarrow \int_a^b f^2(x) dx \geq 0 \end{array} \right.$$

$$\langle f, f \rangle = 0 \Leftrightarrow \int_a^b f^2(x) dx = 0$$

$$\int_a^b f^2(x) dx = 0$$

$$\left\{ \begin{array}{l} f: [a, b] \rightarrow [0, \infty) \text{ cont} \\ \exists x_0 \in [a, b], f(x_0) > 0 \\ \Rightarrow \int_a^b f(x) dx > 0 \end{array} \right.$$

$$f^2(x) \geq 0 \quad \forall x \in [a, b]$$

$$P_p \quad f \neq 0 \Rightarrow \exists x_0 \in [a, b] \text{ a.t. } f(x_0) \neq 0 \Rightarrow f^2(x_0) > 0$$

$$\Rightarrow \int_a^b f^2(x) dx > 0 \quad \text{No} \quad \Rightarrow f \equiv 0$$

• Norma

$$\| \cdot \| : V \rightarrow \mathbb{R}$$

$$\|x\| \geq 0 \quad \forall x \in V$$

$$\|x\| = 0 \Leftrightarrow x = 0_V$$

$$\|\alpha x\| = |\alpha| \cdot \|x\|, \quad \forall \alpha \in \mathbb{R}, \forall x \in V$$

$$\|x + y\| \leq \|x\| + \|y\| \quad \forall x, y \in V$$

$$\|x\|^2 = \langle x, x \rangle$$

$$\|x\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

$$x \perp y \Leftrightarrow \langle x, y \rangle = 0$$

(ortogonali)

$$\|x\| = 1 \quad x \text{ s.n. vector normat}$$

$$x \in \mathbb{R}^2, \quad x = (2, 1)$$

$$\|x\| = \sqrt{2^2 + 1^2} = \sqrt{5}$$

$$x' = \frac{1}{\|x\|} \cdot x = \left(\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}} \right) \quad \|x'\| = 1$$

Teorema:

$\{e_1, \dots, e_n\}$ bază a lui $V \Rightarrow \exists \{f_1', \dots, f_n'\}$ bază ortonormală

(i.e. : $\langle f_i', f_j' \rangle = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$ unde să găsim la bază asta

Alg Gram-Schmidt

Pas 1: Găsim o bază ortogonală

$$f_1 = e_1$$

$$f_2 = e_2 + \alpha_{21} \cdot f_1$$

$$\langle f_2, f_1 \rangle = 0 \Rightarrow \langle e_2 + \alpha_{21} \cdot f_1, f_1 \rangle = 0$$

$$\langle e_2, f_1 \rangle + \alpha_{21} \langle f_1, f_1 \rangle = 0$$

$$\alpha_{21} = \frac{-\langle e_2, f_1 \rangle}{\langle f_1, f_1 \rangle}$$

$$f_2 = e_2 - \frac{\langle e_2, f_1 \rangle}{\langle f_1, f_1 \rangle} \cdot f_1$$

$$f_i = e_i - \frac{\langle e_i, f_1 \rangle}{\langle f_1, f_1 \rangle} \cdot f_1 - \dots - \frac{\langle e_i, f_{i-1} \rangle}{\langle f_{i-1}, f_{i-1} \rangle} \cdot f_{i-1}$$

$$f_i \perp f_j \quad \forall i \neq j$$

$$f_i' = \frac{1}{\|f_i\|} \cdot f_i \Rightarrow \|f_i'\| = 1$$

Ex

$B = \{e_1 = (1, 1, 1), e_2 = (0, 1, 1), e_3 = (0, 0, 1)\}$ bază în \mathbb{R}^3

Găsim o bază ortogonală a lui \mathbb{R}^3

$$f_1 = e_1 = (1, 1, 1)$$

$$\|f_1\| = \sqrt{0^2 + 1^2 + 1^2 + 1^2} = \sqrt{3}$$

$$f_2 = e_2 - \frac{\langle e_2, f_1 \rangle}{\langle f_1, f_1 \rangle} \cdot f_1 = (0, 1, 1) - \frac{\langle (0, 1, 1), (1, 1, 1) \rangle}{\langle (1, 1, 1), (1, 1, 1) \rangle} \cdot (1, 1, 1) =$$

$$= (0, 1, 1) - \frac{\langle (0, 1, 1), (1, 1, 1) \rangle}{\langle (1, 1, 1), (1, 1, 1) \rangle} \cdot (1, 1, 1) = (0, 1, 1) - \left(\frac{2}{3}, \frac{2}{3}, \frac{2}{3}\right) = \left(-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}\right)$$

$$f_3 = e_3 - \frac{\langle e_3, f_1 \rangle}{\langle f_1, f_1 \rangle} \cdot f_1 - \frac{\langle e_3, f_2 \rangle}{\langle f_2, f_2 \rangle} \cdot f_2 =$$

$$= (0, 0, 1) - \frac{\langle (0, 0, 1), (1, 1, 1) \rangle}{\langle (1, 1, 1), (1, 1, 1) \rangle} \cdot (1, 1, 1) - \frac{\langle (0, 0, 1), (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) \rangle}{\langle (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}), (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) \rangle} \cdot (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) =$$

$$= (0, 0, 1) - \frac{1}{3} (1, 1, 1) - \frac{\frac{1}{3}}{\frac{4}{9} + \frac{1}{9} + \frac{1}{9}} \cdot (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) =$$

$$= (-\frac{1}{3}, -\frac{1}{3}, \frac{2}{3}) - \frac{1}{2} \cdot \frac{8}{8} \cdot (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) =$$

$$= (-\frac{1}{3}, -\frac{1}{3}, \frac{2}{3}) - (-\frac{1}{3}, \frac{1}{6}, \frac{1}{6}) = (0, -\frac{3}{6}, \frac{3}{6}) = (0, -\frac{1}{2}, \frac{1}{2})$$

$$\|f_1\| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$$

$$\|f_2\| = \sqrt{\frac{4}{9} + \frac{1}{9} + \frac{1}{9}} = \sqrt{\frac{6}{9}} = \sqrt{\frac{2}{3}}$$

$$\|f_3\| = \sqrt{\frac{1}{4} + \frac{1}{4}} = \sqrt{\frac{1}{2}}$$

$$f_1' = \frac{1}{\sqrt{3}} \cdot (1, 1, 1) = (\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})$$

$$f_2' = \frac{1}{\sqrt{\frac{2}{3}}} \cdot (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) = \frac{\sqrt{3}}{\sqrt{2}} \cdot (-\frac{2}{3}, \frac{1}{3}, \frac{1}{3}) = (-\frac{2\sqrt{3}}{3\sqrt{2}}, \frac{\sqrt{3}}{3\sqrt{2}}, \frac{\sqrt{3}}{3\sqrt{2}}) = (-\frac{\sqrt{2}}{\sqrt{3}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}})$$

$$f_3' = \sqrt{2} \cdot (0, -\frac{1}{2}, \frac{1}{2}) = (0, -\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$$

$$x = (x_1, x_2, x_3)$$

$$y = (y_1, y_2, y_3)$$

$$y_1 \cdot \vec{i} + y_2 \cdot \vec{j} + y_3 \cdot \vec{k}$$

$$x \cdot y = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix} = (\dots) \vec{i} + (\dots) \vec{j} + (\dots) \vec{k}$$

prod
vect