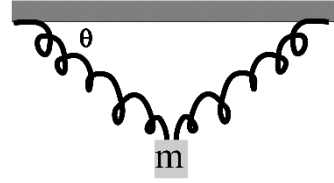


Problem: Find the value of θ at which this system will be equilibrium.



Since we know that the mass of the object is m , the gravity of the object equals to mg . And L_0 is half the distance between the two supports as well as the original length of the spring. So, the change of the spring's length $\Delta L = L - L_0 = \frac{L_0}{\cos(\theta)} - L_0$, and the tension of the spring $T = k\Delta L = k(\frac{L_0}{\cos(\theta)} - L_0)$. Hence, the tension on the vertical direction can be expressed as $T_{\perp} = 2T\sin(\theta) = 2kL_0(\tan(\theta) - \sin(\theta))$ which equals to the gravity of the object. So, the equation which we need to solve is $f(\theta) = \tan(\theta) - \sin(\theta) - \frac{mg}{2kL_0} = 0$.

For this system, the value of θ is limited to $[0, \frac{\pi}{2}]$. Since we've already had an interval, we can firstly use bisection method to get a rough solution, and then "polish it up" by using Newton-Raphson method to get a more accurate solution. In this way, we don't need to search for an appropriate original value for Newton method.

We firstly define the function of bisection method. The function takes 2 parameters as input, the first x_1 refers to the lower bound and the second x_2 refers to the upper bound. In this question, we take 0 as the lower bound, and 1.57 as the upper bound. The reason why we use 1.57 to replace the $\frac{\pi}{2}$ is that if we choose $\theta = \frac{\pi}{2}$, the value of the function $\tan(\theta)$ will tend to infinity which turns out to be a large negative number in program. Inside the function, we define $x_3 = \frac{x_1 + x_2}{2}$. And then, we use a while-loop, the while-loop continues when $f(x_3) > 1 \times 10^{-4}$. Inside the while-loop, we use an if-else structure: if $f(x_1) * f(x_3) < 0$ (which means the root is in $[x_1, x_3]$), then $x_2 \leftarrow x_3, x_3 \leftarrow \frac{x_1 + x_2}{2}$; else (which means the root is in $[x_3, x_2]$) $x_1 \leftarrow x_3, x_3 \leftarrow \frac{x_1 + x_2}{2}$. This function will finally return a rough solution x of the equation, which satisfies $f(x) < 1 \times 10^{-4}$.

Then we define the function of Newton method. The method takes 1 parameter x as input, which is the original value of the iteration. In this question, we can use the rough

solution returned from the bisection method as the input. Inside the function, we use a while-loop. We define $a = f(x), b = f'(x)$. If $|a| > 1 \times 10^{-14}$, $x \leftarrow x - \frac{a}{b}$; else ($|a| \leq 1 \times 10^{-14}$) return x and break the while-loop. In this way, we get an accurate solution of the equation.

Input: $f(\theta) = \tan(\theta) - \sin(\theta) - \frac{mg}{2kL_0}$, lower bound x_1 , upper bound x_2

Output: The solution x of the equation $f(\theta) = \tan(\theta) - \sin(\theta) - \frac{mg}{2kL_0} = 0$

1. $x_3 \leftarrow \frac{x_1 + x_2}{2}$
2. **While** $f(x_3) > 1 \times 10^{-4}$ **Do**
3. **If** $f(x_1) * f(x_3) < 0$ **Then**
4. $x_2 \leftarrow x_3, x_3 \leftarrow \frac{x_1 + x_2}{2}$
5. **Else**
6. $x_1 \leftarrow x_3, x_3 \leftarrow \frac{x_1 + x_2}{2}$
7. **Return** x_3
8. $x \leftarrow x_3$
9. **While True Do**
10. $a \leftarrow f(x)$
11. $b \leftarrow f'(x)$
12. **If** $|a| > 1 \times 10^{-14}$ **Then**
13. $x \leftarrow x - \frac{a}{b}$
14. **Else**
15. **Return** x
16. **Break**

```
2_3_17307110134.py X
C: > Users > 11765 > Desktop > 学习 > 物理 > 计算物理 > 作业 > homework2 > 2_3_17307110134.py > Bisection
1  import sympy as sp
2  import math as ma
3
4  def main():
5      root1 = Bisection(0,1.57)
6      # First, we use Bisection Method to search for a rough solution.
7      # The value of theta satisfies  $0^\circ < \theta < 90^\circ$ , so the interval is  $[0, \pi/2]$ .
8
9      root2 = Newton(root1)
10     # Then we use Newton Method to polish it up.
11
12     theta = (root2/ma.pi) * 180
13     print('The system is in equilibrium at %s°.' % theta)
14
15
16 def Bisection(x1,x2):
17     # Bisection Method
18     root = 0
19
20     if f(x1)*f(x2) < 0:
21         # The root is between [x1,x2].
22         x3 = (x1+x2) / 2
23
24         while abs(f(x3)) > 1e-4:
25             if f(x1)*f(x3) < 0:
26                 # The root is between [x1,x3]
27                 x1 = x3
28             else:
29                 # The root is between [x3,x2]
30                 x2 = x3
31         root = x3
32     return root
33
34 def Newton(x):
35     # Newton Method
36     root = x
37     for i in range(10):
38         root = root - f(root)/f'(root)
39     return root
40
41 def f(x):
42     # f(x) = 0.00006476269707 - 0.48631455376744 * x
43     return 0.00006476269707 - 0.48631455376744 * x
44
45 def f'(x):
46     # f'(x) = -0.48631455376744
47     return -0.48631455376744
48
49 if __name__ == '__main__':
50     main()
```

终端 问题 输出 调试控制台

Windows PowerShell
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尝试新的跨平台 PowerShell <https://aka.ms/pscore6>

PS C:\Users\11765\Desktop\学习\物理\计算物理\作业\homework2> & 'python' 'c:\Users\11765\.vscode\launcher' '56267' '--' 'c:\Users\11765\Desktop\学习\物理\计算物理\作业\homework2\2_3_17307110134.py' &&
Roughly, 0.5328 is a root of the equation.
f(x)=0.00006476269707, f'(x)=0.48631455376744, the times of iteration is 0.
f(x)=0.00000001859504, f'(x)=0.48603530600667, the times of iteration is 1.
f(x)=0.00000000000000, f'(x)=0.48603522777557, the times of iteration is 2.
0.53265487729242 is a root of the equation.
The system is in equilibrium at 30.5188764059145°.
PS C:\Users\11765\Desktop\学习\物理\计算物理\作业\homework2> □

The picture shows the result after running the program.

By using the bisection method, the program shows that “Roughly, 0.5328 is a root of the equation.”

Then by using the Newton method, after 2 times of iteration, the program gives out a more accurate root. After changing the rad into degree, it finally shows that “The system is in equilibrium at 30.5188764059145°.”