The `physics` package

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https://github.com/leedehai/typst-physics

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NOTE (2023-04-02): Typst is in beta and evolving, and this package evolves with it. Also, the package itself is under development and fine-tuning. While the major version stays 0, no backward compatibility is guaranteed.

Contents

1. Introduction

Typst is typesetting framework aiming to become the next generation alternative to LATEX. It excels in its friendly user experience and performance.

The `physics` package provides handy Typst typesetting functions that make academic writing for physics simpler and faster, by simplifying otherwise very complex and repetitive expressions in the domain of physics.

This manual itself was generated using the Typst CLI and the `physics` package, so hopefully this document is able to provide you with a sufficiently self evident demonstration of how this package shall be used.

2. Using `physics`

- To use the `physics` package, you may import names specifically:

```
#import "physics.typ": curl, grad

The expression $op("curl")(op("grad") f) ident curl (grad f) = 0$ is not
foreign to any trained eye in physical mathematics.
```

- or you may simply import all names:

```
#import "physics.typ": *

The expression $op("curl")(op("grad") f) ident curl (grad f)$ is not foreign
to any trained eye in physical mathematics.
```

- sometimes you may want to import the names under a name space:

```
#import "physics.typ"

The expression $op("curl")(op("grad") f) ident physics.curl (physics.grad f)$
is not foreign to any trained eye in physical mathematics.
```

3. The symbols

Some symbols are already provided as a Typst built-in. They are listed here just for completeness with annotation like Typst `this`, as users coming from LATEX might not know they are already available in Typst out of box.

All symbols need to be used in **math mode** `$...$`.

3.1. Braces

Symbol	Abbr.	Example	Notes
Typst `abs(`*content*`)`		`abs(phi(x))` $\longrightarrow \lvert\varphi(x)\rvert$	absolute
Typst `norm(`*content*`)`		`norm(phi(x))` $\longrightarrow \lVert\varphi(x)\rVert$	norm
`order(`*content*`)`		`order(x^2)` $\longrightarrow \mathcal{O}(x^2)$	order of magnitude
`Set`		`Set(a_n)` $\longrightarrow \{a_n\}$ `Set(integral u, forall u)` $\longrightarrow \{\int u \mid \forall u\}$	math set, use `Set` not `set` since the latter is a Typst keyword

`evaluated`	`eval`	`eval(f(x))_0^infinity` $\longrightarrow f(x)\vert_0^\infty$ `eval(f(x)/g(x))_0^1` $\longrightarrow \left.\frac{f(x)}{g(x)}\right\vert_0^1$	attach a vertical bar on the right to denote evaluation boundaries
`expectationvalue`	`expval`	`expval(u)` $\longrightarrow \langle u \rangle$	expectation value

3.2. Vector notations

Symbol	**Abbr.**	**Example**	**Notes**
Typst `vec`		`vec(1,2)` $\longrightarrow \begin{pmatrix} 1 \\ 2 \end{pmatrix}$	column vector
`vecrow`		`vecrow(1,2)` $\longrightarrow (1, 2)$ `vecrow(sum_0^n a_i, b)` $\longrightarrow \left(\sum_0^n a_i, b\right)$	row vector
`TT`		`v^TT, A^TT` $\longrightarrow v^\mathsf{T}, A^\mathsf{T}$	transpose
`vectorbold(`*content*`)`	`vb`	`vb(a),va(mu_1)` $\longrightarrow \boldsymbol{a}, \boldsymbol{\mu}_1$	vector, bold
`vectorarrow(`*content*`)`	`va`	`va(a),va(mu_1)` $\longrightarrow \vec{\boldsymbol{a}}, \vec{\boldsymbol{\mu}}_1$	vector, arrow
`vectorunit(`*content*`)`	`vu`	`vu(a),vu(mu_1)` $\longrightarrow \hat{\boldsymbol{a}}, \hat{\boldsymbol{\mu}}_1$	unit vector
`gradient`	`grad`	`grad f` $\longrightarrow \boldsymbol{\nabla} f$	gradient
`divergence`	`div`	`div vb(E)` $\longrightarrow \boldsymbol{\nabla} \cdot \boldsymbol{E}$	divergence
`curl`		`curl vb(B)` $\longrightarrow \boldsymbol{\nabla} \times \boldsymbol{B}$	curl
`laplacian`		`diaer(u) = c^2 laplacian u` $\longrightarrow \ddot{u} = c^2 \nabla^2 u$	Laplacian
`dotproduct`	`dprod`	`a dprod b` $\longrightarrow a \cdot b$	dot product
`crossproduct`	`cprod`	`a cprod b` $\longrightarrow a \times b$	cross product

3.3. Matrix notations

Symbol	**Abbr.**	**Example**	**Notes**
`TT`		`v^TT, A^TT` $\longrightarrow v^\mathsf{T}, A^\mathsf{T}$	transpose
Typst `mat`		`mat(1,2;3,4)` $\longrightarrow \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$	matrix
`matrixdet(...)`	`mdet`	`mdet(1,x;1,y)` $\longrightarrow \begin{vmatrix} 1 & x \\ 1 & y \end{vmatrix}$	matrix determinant
`diagonalmatrix(...)`	`dmat`	`dmat(1,2)` $\longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$ `dmat(1,a,xi,delim:"[")` $\longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & \xi \end{bmatrix}$	diagonal matrix
`antidiagonalmatrix(...)`	`admat`	`admat(1,2)` $\longrightarrow \begin{pmatrix} 0 & 1 \\ 2 & 0 \end{pmatrix}$ `admat(1,a,xi,delim:"[")` $\longrightarrow \begin{bmatrix} 0 & 0 & 1 \\ 0 & a & 0 \\ \xi & 0 & 0 \end{bmatrix}$	anti-diagonal matrix
`identitymatrix(...)`	`imat`	`imat(2)` $\longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ `imat(3,delim:"[")` $\longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$	identity matrix

`zeromatrix(...)`	`zmat`	`zmat(2)` $\longrightarrow \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ `zmat(3,delim:"[")` $\longrightarrow \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	zero matrix
`jacobianmatrix(...)`	`jmat`	`jmat(f_1,f_2;x,y)` $\longrightarrow \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix}$ `jmat(f_1,f_2;x,y;delim:"[")` $\longrightarrow \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix}$	Jacobian matrix
`hessianmatrix(...)`	`hmat`	`hmat(f;x,y)` $\longrightarrow \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$ `hmat(f;x,y;delim:"[")` $\longrightarrow \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix}$	Hessian matrix

3.4. Dirac braket notations

Symbol	**Abbr.**	**Example**	**Notes**
`bra(`*content*`)`		`bra(u)` $\longrightarrow \langle u \vert$ `bra(limits(sum)_(i=0)^n i)` $\longrightarrow \left\langle \sum_{i=0}^{n} i \right\vert$	bra
`ket(`*content*`)`		`ket(u)` $\longrightarrow \vert u \rangle$ `ket(limits(sum)_(i=0)^n i)` $\longrightarrow \left\vert \sum_{i=0}^{n} i \right\rangle$	ket

`braket(`*a*, *b*`)`		`braket(u), braket(u, v)`
		$\longrightarrow \langle u \vert u \rangle, \langle u \vert v \rangle$
		`braket(limits(sum)_(i=0)^n i, b)`
		$\longrightarrow \left\langle \sum_{i=0}^{n} i \middle\vert b \right\rangle$
			braket

`ketbra(`*a*, *b*`)`		`ketbra(u), ketbra(u, v)`
		$\longrightarrow \vert u \rangle \langle u \vert, \vert u \rangle \langle v \vert$
		`ketbra(limits(sum)_(i=0)^n i, b)`
		$\longrightarrow \left\vert \sum_{i=0}^{n} i \right\rangle \langle b \vert$
			ketbra

`innerproduct(`*a*, *b*`)`	`iprod`	`iprod(u, v)`
		$\longrightarrow \langle u \vert v \rangle$
		`iprod(limits(sum)_(i=0)^n i, b)`
		$\longrightarrow \left\langle \sum_{i=0}^{n} i \middle\vert b \right\rangle$
			innerproduct

`outerproduct(`*a*, *b*`)`	`oprod`	`oprod(u, v)`
		$\longrightarrow \vert u \rangle \langle v \vert$
		`oprod(limits(sum)_(i=0)^n i,b)`
		$\longrightarrow \left\vert \sum_{i=0}^{n} i \right\rangle \langle b \vert$
			outerproduct

`matrixelement(`n, M, m`)`	`mel`	`mel(n, diff_nu H, m)` $\longrightarrow \langle n \vert \partial_\nu H \vert m \rangle$ `mel(n, limits(sum)_(i=0)^n i, m)` $\longrightarrow \left\langle n \middle\vert \sum_{i=0}^{n} i \middle\vert m \right\rangle$	matrix element (quantum theory)

3.5. Math functions

Typst built-in math operators: source code.

Expressions	Results
`sin(x), sinh(x), arcsin(x), asin(x)`	$\sin(x), \sinh(x), \arcsin(x), \operatorname{asin}(x)$
`cos(x), cosh(x), arccos(x), acos(x)`	$\cos(x), \cosh(x), \arccos(x), \operatorname{acos}(x)$
`tan(x), tanh(x), arctan(x), atan(x)`	$\tan(x), \tanh(x), \arctan(x), \operatorname{atan}(x)$
`sec(x), sech(x), arcsec(x), asec(x)`	$\sec(x), \operatorname{sech}(x), \operatorname{arcsec}(x), \operatorname{asec}(x)$
`csc(x), csch(x), arccsc(x), acsc(x)`	$\csc(x), \operatorname{csch}(x), \operatorname{arccsc}(x), \operatorname{acsc}(x)$
`cot(x), coth(x), arccot(x), acot(x)`	$\cot(x), \coth(x), \operatorname{arccot}(x), \operatorname{acot}(x)$

Expressions	Results	Notes
Typst `Pr(x)`	$\Pr(x)$	probability
Typst `exp x`	$\exp x$	exponential
Typst `log x, lg x, ln x`	$\log x, \lg x, \ln x$	logarithmic
Typst `det A`	$\det A$	matrix determinant
`diag(-1,1,1,1)`	$\operatorname{diag}(-1, 1, 1, 1)$	diagonal matrix, compact form (use `dmat` for the "real" matrix form)
`trace A, tr A`	$\operatorname{trace} A, \operatorname{tr} A$	matrix trace
`Trace A, Tr A`	$\operatorname{Trace} A, \operatorname{Tr} A$	matrix trace, alt.
`rank A`	$\operatorname{rank} A$	matrix rank
`erf(x)`	$\operatorname{erf}(x)$	Gauss error function
`Res A`	$\operatorname{Res} A$	residue
`Re z, Im z`	$\operatorname{Re} z, \operatorname{Im} z$	real, imaginary parts of a complex number
`sgn x`	$\operatorname{sgn} x$	sign function

3.6. Differentials and derivatives

Symbol	Abbr.	Example	Notes
`differential(...)`	`dd`	e.g. $\mathrm{d}f, \mathrm{d}x\mathrm{d}y, \mathrm{d}^3x, \mathrm{d}x \wedge \mathrm{d}y$ See Section 3.6.1	differential
`variation(...)`	`var`	`var(f)` $\longrightarrow \delta f$ `var(x,y)` $\longrightarrow \delta x \delta y$	variation, shorthand of `dd(..., d: delta)`
`difference(...)`		`difference(f)` $\longrightarrow \Delta f$ `difference(x,y)` $\longrightarrow \Delta x \Delta y$	difference, shorthand of `dd(..., d: Delta)`

`derivative(...)`	`dv`	e.g. $\frac{\mathrm{d}}{\mathrm{d}x}, \frac{\mathrm{d}f}{\mathrm{d}x}, \frac{\Delta^k f}{\Delta x^k}, \mathrm{d}f/\mathrm{d}x$ See Section 3.6.2	derivative
`partialderivative(...)`	`pdv`	e.g. $\frac{\partial}{\partial x}, \frac{\partial f}{\partial x}, \frac{\partial^4 f}{\partial x^2 \partial y^2}, \frac{\partial^5 f}{\partial x^2 \partial y^3}, \partial f/\partial x$ See Section 3.6.3	partial derivative, could be mixed order

3.6.1. Differentials

Functions: `differential(`**args*, ***kwargs*`)`, abbreviated as `dd(...)`.
- positional *args*: the variable names, then at the last **optionally** followed by an order number e.g. `2`, or an order array e.g. `[2,3]`, `[k]`, `[m n, lambda+1]`.
- named *kwargs*:
  - `d`: the differential symbol [default: `upright(d)`].
  - `p`: the product symbol connecting the components [default: `none`].

Order assignment algorithm:
- If there is no order number or order array, all variables has order 1.
- If there is an order number (not an array), then this order number is assigned to *every* variable, e.g. `dd(x,y,2)` assigns $x \leftarrow 2, y \leftarrow 2$.
- If there is an order array, then the orders therein are assigned to the variables in order, e.g. `dd(f,x,y,[2,3])` assigns $x \leftarrow 2, y \leftarrow 3$.
- If the order array holds fewer elements than the number of variables, then the orders of the remaining variables are 1, e.g. `dd(x,y,z,[2,3])` assigns $x \leftarrow 2, y \leftarrow 3, z \leftarrow 1$.
- If a variable x has order 1, it is rendered as $\mathrm{d}x$ not $\mathrm{d}^1 x$.

Examples

(1) `dd(f), dd(x,y)`

$$\mathrm{d}f, \mathrm{d}x\mathrm{d}y$$

(2) `dd(x,3), dd(f,[k]), dd(f,[k],d:delta)`

$$\mathrm{d}^3 x, \mathrm{d}^k f, \delta^k f$$

(3) `dd(f,2), dd(vb(x),t,[3,])`

$$\mathrm{d}^2 f, \mathrm{d}^3 \boldsymbol{x} \mathrm{d}t$$

(4) `dd(x,y,[2,3]), dd(x,y,z,[2,3])`

$$\mathrm{d}^2 x \mathrm{d}^3 y, \mathrm{d}^2 x \mathrm{d}^3 y \mathrm{d}z$$

(5) `dd(x, y, z, [[1,1],rho+1,n_1])`

$$\mathrm{d}^{[1,1]} x \mathrm{d}^{\rho+1} y \mathrm{d}^{n_1} z$$

(6) `dd(x,y,d:Delta), dd(x,y,2,d:Delta)`

$$\Delta x \Delta y, \Delta^2 x \Delta^2 y$$

(7) `dd(t,x_1,x_2,x_3,p:and)`

$$\mathrm{d}t \wedge \mathrm{d}x_1 \wedge \mathrm{d}x_2 \wedge \mathrm{d}x_3$$

(7) `dd(t,x_1,x_2,x_3,d:upright(D))`

$$\mathrm{D}t \mathrm{D}x_1 \mathrm{D}x_2 \mathrm{D}x_3$$

3.6.2. Ordinary derivatives

Function: `derivative(`*f*, **args*, ***kwargs*`)`, abbreviated as `dv(...)`.
- *f*: the function, which can be `#none` or omitted,
- positional *args*: the variable name, then at the last **optionally** followed by an order number e.g. `2`,
- named *kwargs*:
  - `d`: the differential symbol [default: `upright(d)`].
  - `s`: the “slash” separating the numerator and denominator [default: `none`], by default it produces the normal fraction form $\frac{\mathrm{d}f}{\mathrm{d}x}$. The most common non-default is `slash` or simply `\/`, so as to create a flat form $\mathrm{d}f/\mathrm{d}x$ that fits inline.

Order assignment algorithm: there is just one variable, so the assignment is trivial: simply assign the order number (default to 1) to the variable. If a variable x has order 1, it is rendered as x not x^1.

Examples

(1) `dv(,x), dv(,x,2), dv(f,x,k+1)`

$$\frac{\mathrm{d}}{\mathrm{d}x}, \frac{\mathrm{d}^2}{\mathrm{d}x^2}, \frac{\mathrm{d}^{k+1}}{\mathrm{d}x^{k+1}}$$

(2) `dv(, vb(r)), dv(f, vb(r)_e, 2)`

$$\frac{\mathrm{d}}{\mathrm{d}\boldsymbol{r}}, \frac{\mathrm{d}^2}{\mathrm{d}\boldsymbol{r}_e^2}$$

(3) `dv(f,x,2,s:\/), dv(f,xi,k+1,s:slash)`

$$\mathrm{d}^2 f/\mathrm{d}x^2, \mathrm{d}^{k+1} f/\mathrm{d}\xi^{k+1}$$

(4) `dv(, x, d:delta), dv(, x, 2, d:Delta)`

$$\frac{\delta}{\delta x}, \frac{\Delta^2}{\Delta x^2}$$

(5) `dv(vb(u), t, 2, d: upright(D))`

$$\frac{\mathrm{D}^2\boldsymbol{u}}{\mathrm{D}t^2}$$

(6) `dv(vb(u),t,2,d:upright(D),s:slash)`

$$\mathrm{D}^2\boldsymbol{u}/\mathrm{D}t^2$$

3.6.3. Partial derivatives

Function: `partialderivative(`*f*, **args*, ***kwargs*`)`, abbreviated as `pdv(...)`.

- *f*: the function, which can be `#none` or omitted,
- positional *args*: the variable names, then at last **optionally** followed by an order number e.g. `2`, or an order array e.g. `[2,3]`, `[k]`, `[m n, lambda+1]`.
- named *kwargs*:
  - `s`: the "slash" separating the numerator and denominator [default: `none`], by default it produces the normal fraction form $\frac{\partial f}{\partial x}$. The most common non-default is `slash` or simply `\/`, so as to create a flat form $\partial f/\partial x$ that fits inline.
  - `total`: the user-specified total order.
    - If it is absent, then (1) if the orders assigned to all variables are numeric, the total order number will be **automatically computed**; (2) if non-number symbols are present, computation will be attempted with minimum effort, and a user override with argument `total` may be necessary.

Order assignment algorithm:

- If there is no order number or order array, all variables has order 1.
- If there is an order number (not an array), then this order number is assigned to *every* variable, e.g. `pdv(f,x,y,2)` assigns $x \leftarrow 2, y \leftarrow 2$.
- If there is an order array, then the orders therein are assigned to the variables in order, e.g. `pdv(f,x,y,[2,3])` assigns $x \leftarrow 2, y \leftarrow 3$.
- If the order array holds fewer elements than the number of variables, then the orders of the remaining variables are 1, e.g. `pdv(f,x,y,z,[2,3])` assigns $x \leftarrow 2, y \leftarrow 3, z \leftarrow 1$.
- If a variable x has order 1, it is rendered as x, not x^1.

Examples

(1) `pdv(,x), pdv(,t,2), pdv(,lambda,[k])`

$$\frac{\partial}{\partial x}, \frac{\partial^2}{\partial t^2}, \frac{\partial^k}{\partial \lambda^k}$$

(2) `pdv(f,vb(r)), pdv(phi,vb(r)_e,2)`

$$\frac{\partial \varphi}{\partial \boldsymbol{r}}, \frac{\partial^2 \varphi}{\partial \boldsymbol{r}_e^2}$$

(3) `pdv(,x,y), pdv(,x,y,2)`

(4) `pdv(f,x,y,2), pdv(f,x,y,3)`

$$\frac{\partial^2}{\partial x \partial y}, \frac{\partial^4}{\partial x^2 \partial y^2}$$

(5) `pdv(,x,y,[2,]), pdv(,x,y,[1,2])`

$$\frac{\partial^3}{\partial x^2 \partial y}, \frac{\partial^3}{\partial x \partial y^2}$$

(6) `pdv(,t,2,s:\/), pdv(f,x,y,s:slash)`

$$\partial^2/\partial t^2, \partial^2 f/\partial x \partial y$$

(7) `pdv(, (x^1), (x^2), (x^3), [1,3])`

$$\frac{\partial^5}{\partial (x^1) \partial (x^2)^3 \partial (x^3)}$$

(8) `pdv(phi,x,y,z,tau, [2,2,2,1])`

$$\frac{\partial^7 \varphi}{\partial x^2 \partial y^2 \partial z^2 \partial \tau}$$

(9) `pdv(,x,y,z,t,[1,xi,2,eta+2])`

$$\frac{\partial^{\eta+\xi+5}}{\partial x \partial y^\xi \partial z^2 \partial t^{\eta+2}}$$

(10) `pdv(,x,y,z,[xi n,n-1],total:(xi+1)n)`

$$\frac{\partial^{(\xi+1)n}}{\partial x^{\xi n} \partial y^{n-1} \partial z}$$

Also shown above, paired with (5) and (6): $\frac{\partial^4 \varphi}{\partial x^2 \partial y^2}, \frac{\partial^6 \varphi}{\partial x^3 \partial y^3}$

(11) `integral_V dd(V) (pdv(cal(L), phi) - diff_mu (pdv(cal(L), (diff_mu phi)))) = 0`

$$\int_V \mathrm{d}V \left(\frac{\partial \mathcal{L}}{\partial \varphi} - \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial \left(\partial_\mu \varphi \right)} \right) \right) = 0$$

3.7. Miscellaneous

3.7.1. Reduced Planck constant (hbar)

In the default font, the Typst built-in symbol `planck.reduce` $\hslash$ looks a bit off: on letter "h" there is a slash instead of a horizontal bar, contrary to the symbol's colloquial name "h-bar". This package offers `hbar` to render the symbol in the familiar form: $\hbar$. Contrast:

Typst's `planck.reduce`	$E = \hslash \omega$	$\frac{\pi G^2}{\hslash c^4}$	$A e^{\frac{i(p x - E t)}{\hslash}}$	$i \hslash \frac{\partial}{\partial t} \psi = -\frac{\hslash^2}{2m} \nabla^2 \psi$
this package's `hbar`	$E = \hbar \omega$	$\frac{\pi G^2}{\hbar c^4}$	$A e^{\frac{i(p x - E t)}{\hbar}}$	$i \hbar \frac{\partial}{\partial t} \psi = -\frac{\hbar^2}{2m} \nabla^2 \psi$

3.7.2. Tensors

Tensors are often expressed using the abstract index notation, which makes the contravariant and covariant "slots" explicit. The intuitive solution of using superscripts and subscripts do not suffice if both upper (contravariant) and lower (covariant) indices exist, because the notation rules require the indices be vertically separated: e.g. ${T^a}_b$ and ${T_a}^b$, which are of different shapes. "T_b^a" is flatly wrong, and `T^(space w)_(i space j)` produces a weird-looking "$T_{i\ j}^{\ w}$" (note w, j vertically overlap).

Function: `tensor(`*symbol*, **args*`)`.

- *symbol*: the tensor symbol,
- positional *args*: each argument takes the form of $+\ldots$ or $-\ldots$, where a `+` prefix denotes an upper index and a `-` prefix denotes a lower index.

Examples

(1) `tensor(u,+a), tensor(v,-a)`

(2) `tensor(h,+mu,+nu), tensor(g,-mu,-nu)`

$$u^a, v_a$$

$$h^{\mu\nu}, g_{\mu\nu}$$

(3) `tensor(T,+a,-b), tensor(T,-a,+b)`

$$T^a{}_b, T_a{}^b$$

(4) `tensor(T, -i, +w, -j)`

$$T_i{}^w{}_j$$

(5) `tensor((dd(x^lambda)),-a)`

$$\left(\mathrm{d}x^\lambda\right)_a$$

(6) `tensor(AA,+a,+b,-c,-d,+e,-f,+g,-h)`

$$\mathbb{A}^{ab}{}_{cd}{}^e{}_f{}^g{}_h$$

(7) `tensor(R, -a, -b, -c, +d)`

$$R_{abc}{}^d$$

(8) `tensor(T,+1,-I(1,-1),+a_bot,-+,+-)`

$$T^1{}_{I(1,-1)}{}^{a_\perp}{}_+{}^-$$

(9) `grad_mu A^nu = diff_mu A^nu + tensor(Gamma,+nu,-mu,-lambda) A^lambda`

$$\boldsymbol{\nabla}_\mu A^\nu = \partial_\mu A^\nu + \Gamma^\nu{}_{\mu\lambda} A^\lambda$$

3.7.3. Isotopes

Function: `isotope(`*element*, *a*: …, *z*: …`)`.

- *element*: the chemical element (use `".."` for multi-letter symbols)
- *a*: the mass number A [default: `none`].
- *z*: the atomic number Z [default: `none`].

Examples

(1) `isotope(I, a:127)`

$${}^{127}\mathrm{I}$$

(2) `isotope("Fe", z:26)`

$${}_{26}\mathrm{Fe}$$

(3) `isotope("Bi",a:211,z:83) --> isotope("Tl",a:207,z:81) + isotope("He",a:4,z:2)`

$${}^{211}_{83}\mathrm{Bi} \longrightarrow {}^{207}_{81}\mathrm{Tl} + {}^{4}_{2}\mathrm{He}$$

(4) `isotope("Tl",a:207,z:81) --> isotope("Pb",a:207,z:82) + isotope(e,a:0,z:-1)`

$${}^{207}_{81}\mathrm{Tl} \longrightarrow {}^{207}_{82}\mathrm{Pb} + {}^{0}_{-1}\mathrm{e}$$

3.8. Symbolic addition

This package implements a very rudimentary, **bare-minimum-effort** symbolic addition function to aid the automatic computation of a partial derivative's total order in the absence of user override (see Section 3.6.3). Though rudimentary and unsophisticated, this should suffice for most use cases in partial derivatives.

Function: `BMEsymadd([…])`.

- `...`: symbols that need to be added up e.g. `[1,2]`, `[a+1,b^2+1,2]`.

Examples

(1) `BMEsymadd([1]), BMEsymadd([2, 3])` $\longrightarrow$ $1, 5$

(2) `BMEsymadd([a, b^2, 1])` $\longrightarrow$ $a + b^2 + 1$

(3) `BMEsymadd([a+1,2c,b,2,b])` $\longrightarrow$ $a + 2b + 2c + 3$

(4) `BMEsymadd([a+1,2(b+1),1,b+1,15])` $\longrightarrow$ $a + b + 2(b + 1) + 18$

(5) `BMEsymadd([a+1,2(b+1),1,(b+1),15])` $\longrightarrow$ $a + 3(b + 1) + 17$

(6) `BMEsymadd([a+1,2(b+1),1,3(b+1),15])` $\longrightarrow$ $a + 5(b + 1) + 17$

(7) `BMEsymadd([2a+1,xi,b+1,a xi + 2b+a,2b+1])` $\longrightarrow$ $3a + 5b + \xi + a\xi + 3$

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