```
import json
import random
import sys

import numpy as np

sys.path.insert(1, '../../src')

from ce.algorithms.greedy_heuristics import random_solution
from ce.algorithms.local_search import two_edges_neighborhood
from ce.algorithms.local_search.local_search_cache import steepest_local_search_cache
from ce.tsp import create_tsp, TSP
from ce.utils.experiments import quality_plots
from ce.algorithms.evolutionary import evolution
```

Hybrid evolutionary algorithm

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```
In [2]: problem_instance_A_path = '../../data/TSPA.csv'
    problem_instance_B_path = '../../data/TSPB.csv'
    problem_instance_C_path = '../../data/TSPC.csv'
    problem_instance_D_path = '../../data/TSPD.csv'

In [3]: tspa = create_tsp(problem_instance_A_path)
    tspb = create_tsp(problem_instance_B_path)
    tspc = create_tsp(problem_instance_C_path)
    tspd = create_tsp(problem_instance_D_path)
```

Algorithms

Selection

Parents are selected randomly with uniform distribution.

```
def select_parents(population):
    return random.sample(population, 2)
```

Crossover

The half of the first parent is copied into the offspring, then all nodes from this half are removed from second parent. From the second parent (with removed nodes) first 50 nodes are used as second half of the offspring.

```
def crossover(parent1, parent2):
    return parent1[:50] + [p for p in parent2 if p not in set(parent1[:50])][:50]
```

Evolutionary algorithm

Steady state algorithm is used, only elite (best so far) solutions are kept. Offspring is improved with the usage of steepest local search (this can be treated as offspring growing up).

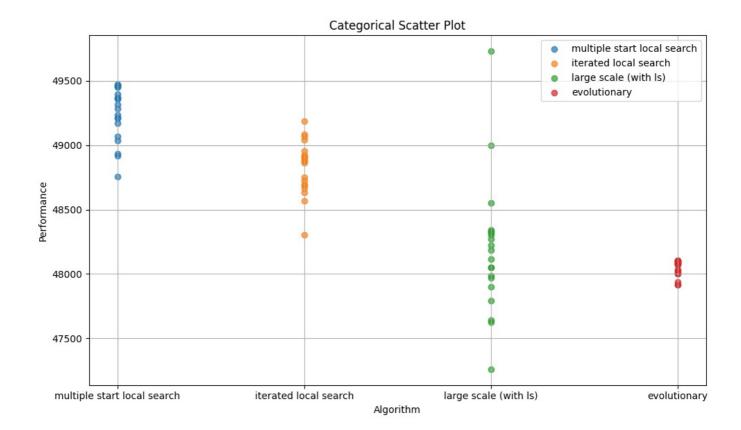
```
def evolution(tsp, initial_population, local_search_fn, time_limit):
    population = [local_search_fn(tsp, x)[0] for x in initial_population]
    population = SortedDict({tsp.get_solution_cost(x): x for x in population})

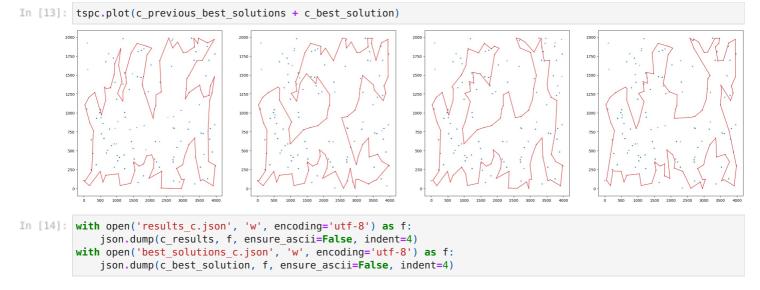
iterations, iterations_with_improvements, start_time = 0, 0, time.time()
    while time.time() - start_time < time_limit:
        parents = select_parents(population.values())
        offspring = crossover(*parents)
        offspring_cost = tsp.get_solution_cost(offspring)
        if offspring_cost < population.keys()[-1] and offspring_cost not in population:
            del population.keys()[-1]
            population[offspring_cost] = offspring
            iterations_with_improvements += 1
        iterations += 1</pre>
return population, iterations, iterations with improvements
```

Experiments

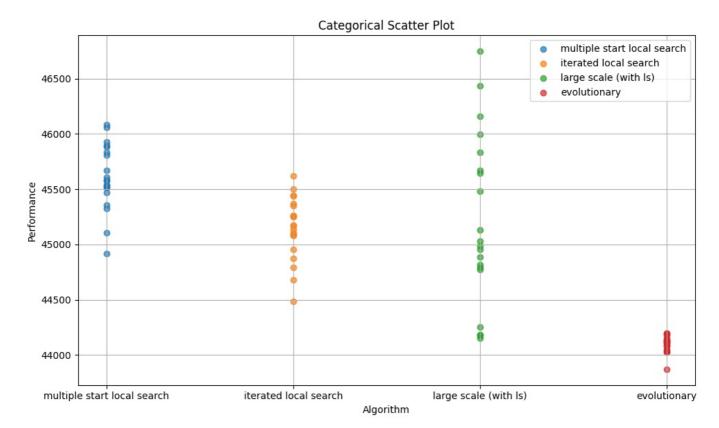
```
In [4]: time limit = 1800 # 30 minutes
        population size = 20
        experiments = ["multiple start local search", "iterated local search", "large scale (with ls)", "evolutionary"]
In [5]: def load previous results(instance):
            previous_results, previous_best_solutions = [], []
            with open(f'../report 6/results {instance}.json', 'r', encoding='utf-8') as f:
                previous_results += json.load(f)
            with open(f'../report 7/results {instance}.json', 'r', encoding='utf-8') as f:
                previous_results += [json.load(f)[1]]
            with open(f'../report 6/best solutions {instance}.json', 'r', encoding='utf-8') as f:
                previous_best_solutions += json.load(f)
            with open(f'../report 7/best solutions {instance}.json', 'r', encoding='utf-8') as f:
                previous_best_solutions += [json.load(f)[1]]
            return previous results, previous best solutions
In [6]: def get initial population(tsp: TSP, k: int):
            return [random_solution(tsp) for _ in range(k)]
In [7]: def local search fn(tsp: TSP, x):
            return steepest local search cache(tsp, x, two edges neighborhood)
In [8]: def experiment(tsp: TSP, k: int, time limit: float):
            initial_population = get_initial_population(tsp, k)
            population, iterations, iterations with improvement = evolution(tsp, initial population, local search fn, t
            results_cost = population.keys()
            print(f'cost: {sum(results cost) / len(results cost):0.1f}, ({min(results cost):0.0f} - {max(results cost):0.1f}
            print(f'iterations: {iterations}, iterations with improvement: {iterations with improvement}, ratio: {iterations
            return population
```

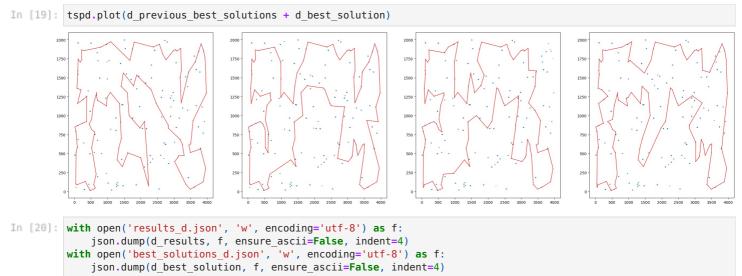
Instance C





Instance D





Conclusions

There is a difference in the performance of the evolutionary algorithm in comparison to other (most advanced) methods that were used between the instances.

In instance C, the evolutionary algorithm performed worse than large-scale search (taking into account the best obtained solution) but better than multiple-start local search and iterated local search. What is interesting is that the average result of the large-scale search and evolutionary algorithm is very similar; the worst result of 20 is much worse. The biggest difference between those two algorithms is the variability of the obtained solutions. The final population of the evolutionary algorithm is pretty dense.

In instance D, a similar conclusion can be drawn. However, for this instance, the evolutionary algorithm significantly outperformed other algorithms with respect to all metrics.

What is also visible from the scatter plots with results is that there is a little variability in the final population. We suspect that with greater variability, we could expect better results when it comes to the best-obtained solution as the evolution could cover a greater landscape of solutions. The simple solution for introducing more variability would be to include some kind of mutation in the algorithm.

Keeping in mind that the size of the population was rather small (only 20 solutions), we could consider the evolutionary algorithm to be a rather better meta-heuristic than other considered ones. However, it's also worth mentioning that there are a lot of parameters that could be tuned when it comes to the evolutionary algorithm (population size, way of choosing parents, enabling mutation, other corssover techniques).