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MÔN HỌC: VI XỬ LÝ - VI ĐIỀU KHIỂN (TN) (CO3010)

LAB 3 - BUTTONS AND SWITCHES

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Contents

1	Exercise 1: Sketch an FSM	2
2	Exercise 2: Proteus Schematic	2
3	Exercise 3: Create STM32 Project	3
4	Exercise 4: Modify Timer Parameters	6
5	Exercise 5: Adding code for button debouncing	6
6	Exercise 6: Adding code for displaying modes	10
7	Exercise 7: Adding code for increasing time duration value for the red LEDs, amber, greenLEDs	16
8	Link	22



1 Exercise 1: Sketch an FSM

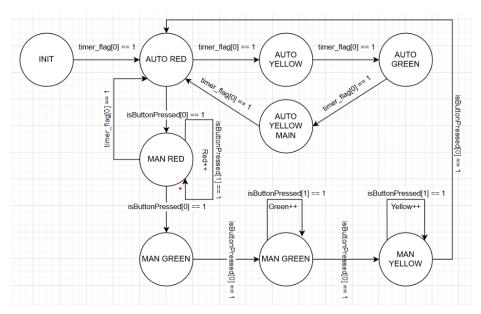


Figure 1: Exercise 1

2 Exercise 2: Proteus Schematic



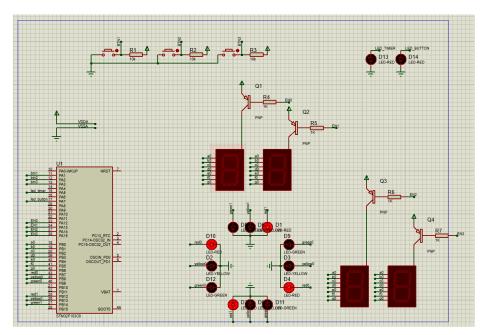


Figure 2: Exercise 2

3 Exercise 3: Create STM32 Project



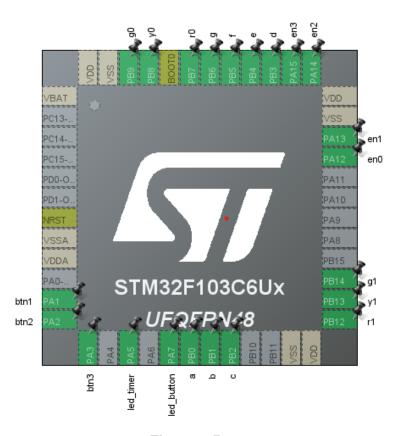


Figure 3: Exercise 3



```
#include "software_timer.h"
int timer_flag[100];
3 int timer_counter[100];
5 void set_timer(int index, int counter)
6 {
    timer_flag[index] = 0;
    timer_counter[index] = counter/tick;
9 }
void led_timer()
12 {
    HAL_GPIO_TogglePin(GPIOA, GPIO_Pin_11);
15
void timer_run()
    for(int i = 0; i < 10; i++)</pre>
      if(timer_counter[i] >= 0)
21
        timer_counter[i]--;
        if(timer_counter[i] <= 0)</pre>
23
          timer_flag[i] = 1;
        }
    }
28
29 }
int is_timer_expired(int index)
    if(index < 0 || index >= MAX_TIMERS)
      return -1;
36
    return timer_flag[index];
37
38 }
```

Listing 1: Source code in the software_timer.c



4 Exercise 4: Modify Timer Parameters

I use the variable *tick* to represent the timer interrupt period.

When setting the duration for the software timer, I divide duration_ms by tick to calculate the number of required interrupts.

Each time the timer interrupt occurs, the function $timer_run()$ decreases the counters. When a counter reaches zero, the variable $timer_flag$ is set.

With this method, even if the timer interrupt period (tick = 1 ms, 10 ms, or 100 ms) changes, the total real-time duration of each timer remains accurate, and the LED continues to blink at exactly 2 Hz.

5 Exercise 5: Adding code for button debouncing

```
#include "button.h"
int KeyReg00 = NORMAL_STATE;
int KeyReg10 = NORMAL_STATE;
int KeyReg20 = NORMAL_STATE;
5 int KeyReg30 = NORMAL_STATE;
6 int KeyReg01 = NORMAL_STATE;
7 int KeyReg11 = NORMAL_STATE;
s int KeyReg21 = NORMAL_STATE;
9 int KeyReg31 = NORMAL_STATE;
int KeyReg02 = NORMAL_STATE;
int KeyReg12 = NORMAL_STATE;
int KeyReg22 = NORMAL_STATE;
int KeyReg32 = NORMAL_STATE;
int TimeOutForKeyPress =
int button0_pressed = 0;
int button1_long_pressed = 0;
int button0_flag = 0;
int button1_pressed = 0;
int button1_flag = 0;
int button2_pressed = 0;
int button2_flag = 0;
int isButtonOPressed(){
```



```
if(button0_flag == 1){
      button0_flag = 0;
26
      return 1;
    return 0;
30 }
int isButton1Pressed(){
    if(button1_flag == 1){
      button1_flag = 0;
      return 1;
    }
35
    return 0;
36
37 }
int isButton2Pressed(){
    if(button2_flag == 1){
      button2_flag = 0;
      return 1;
41
    }
42
    return 0;
43
44 }
45
int isButton1LongPressed(){
    if(button1_long_pressed == 1){
      button1_long_pressed = 0;
     return 1;
    }
    return 0;
51
<sub>52</sub> }
54
  void getKeyInput()
57 {
    KeyReg20 = KeyReg10;
    KeyReg10 = KeyReg00;
    // Add your key
    KeyReg00 = HAL_GPIO_ReadPin(btn1_GPIO_Port, btn1_Pin);
61
    if ((KeyReg10 == KeyReg00) && (KeyReg10 == KeyReg20))
```



```
if (KeyReg20 != KeyReg30)
      {
66
         KeyReg30 = KeyReg20;
         if (KeyReg30 == PRESSED_STATE)
68
         {
             TimeOutForKeyPress = 500;
             //HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
71
             button0_flag = 1;
         }
74
      }
75
       else
76
       {
         TimeOutForKeyPress --;
         if (TimeOutForKeyPress == 0)
80
           TimeOutForKeyPress = 500;
           if (KeyReg30 == PRESSED_STATE)
83
             //HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
             button0_flag = 1;
           }
         }
      }
    }
89
    KeyReg21 = KeyReg11;
90
      KeyReg11 = KeyReg01;
91
       // Add your key
      KeyReg01 = HAL_GPIO_ReadPin(btn2_GPIO_Port, btn2_Pin);
93
      if ((KeyReg11 == KeyReg01) && (KeyReg11 == KeyReg21))
      {
96
         if (KeyReg21 != KeyReg31)
           KeyReg31 = KeyReg21;
           if (KeyReg31 == PRESSED_STATE)
100
             TimeOutForKeyPress = 500;
```



```
//HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
             button1_flag = 1;
104
           }
         }
         else
         {
108
           TimeOutForKeyPress --;
           if (TimeOutForKeyPress == 0)
           {
             TimeOutForKeyPress = 500;
             if (KeyReg31 == PRESSED_STATE)
             {
114
               //HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
               button1_flag = 1;
117
           }
         }
120
       KeyReg22 = KeyReg12;
121
       KeyReg12 = KeyReg02;
         // Add your key
       KeyReg02 = HAL_GPIO_ReadPin(btn3_GPIO_Port, btn3_Pin);
124
       if ((KeyReg12 == KeyReg02) && (KeyReg12 == KeyReg22))
126
       {
         if (KeyReg22 != KeyReg32)
         {
           KeyReg32 = KeyReg22;
           if (KeyReg32 == PRESSED_STATE)
           {
             TimeOutForKeyPress = 500;
             //HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
             button2_flag = 1;
135
           }
136
           }
         else
138
139
           TimeOutForKeyPress --;
               if (TimeOutForKeyPress == 0)
141
```



Listing 2: Source code button.c

6 Exercise 6: Adding code for displaying modes

To add code for display mode on seven-segment LEDs

```
#include "fsm_auto.h"
3 int i = 0;
int led_buffer[4] = {0, 0, 0, 0};
5 int num_to_display_1 = 0;
6 int num_to_display_2 = 0;
8 void fsm_auto()
 {
    if(is_timer_expired(3) && (status == AUTO_GREEN_RED ||
                   status == AUTO_RED_GREEN ||
                    status == AUTO_YELLOW_RED ||
                    status == AUTO_RED_YELLOW ||
                    status == AUTO_INIT))
14
15
      getKeyInput();
      if (isButtonOPressed())
        HAL_GPIO_TogglePin(GPIOA, GPIO_PIN_7);
        clear();
20
        led_buffer[0] = 0;
        led_buffer[1] = 0;
```



```
led_buffer[2] = 0;
        led_buffer[3] = 0;
24
        status = MANUAL_INIT;
      }
      else set_timer(3, 20);
    }
28
    if(is_timer_expired(5)
                              && (status == AUTO_GREEN_RED ||
30
                             status == AUTO_RED_GREEN ||
31
                    status == AUTO_YELLOW_RED ||
                    status == AUTO_RED_YELLOW ||
33
                    status == AUTO_INIT))
34
35
      num_to_display_1--;
36
      num_to_display_2--;
      led_buffer[0] = num_to_display_1/10;
      led_buffer[1] = num_to_display_1%10;
39
      led_buffer[2] = num_to_display_2/10;
40
      led_buffer[3] = num_to_display_2%10;
41
      set_timer(5, 1000);
    }
43
    if (is_timer_expired(4))
44
      if(i == 4) i = 0;
46
      update7SEG(i);
      display7SEG(led_buffer[i]);
49
      set_timer(4, 150);
50
    }
    if(is_timer_expired(2))
53
      switch (status)
55
      {
56
        case AUTO_INIT:
          status = AUTO_RED_GREEN;
          break:
59
        case AUTO_RED_GREEN:
          led_red_and_green();
```



```
num_to_display_1 = 5;
          num_to_display_2 = 3;
63
          status = AUTO_RED_YELLOW;
          set_timer(2, 3000);
          break;
66
        case AUTO_RED_YELLOW:
          led_red_and_yellow();
          num_to_display_1 = 2;
69
          num_to_display_2 = 2;
          status = AUTO_GREEN_RED;
          set_timer(2, 2000);
          break;
        case AUTO_GREEN_RED:
          led_green_and_red();
          num_to_display_1 = 3;
          num_to_display_2 = 5;
          status = AUTO_YELLOW_RED;
          set_timer(2, 3000);
          break;
        case AUTO_YELLOW_RED:
81
          led_yellow_and_red();
          num_to_display_1 = 2;
          num_to_display_2 = 2;
          status = AUTO_GREEN_RED;
          set_timer(2, 2000);
          break;
        default:
          break;
      }
    }
91
92 }
```

Listing 3: Sourcecode of fsm auto.c

To add code for blinking LEDs depending on the mode that is selected.

```
#include "fsm_manual.h"

int red_time = 0;

int yellow_time = 0;
```



```
5 int green_time = 0;
6 int red;
7 int yellow;
8 int green;
9 int check = 0;
int num_to_display1 = 0;
int num_to_display2 = 0;
void fsm_manual()
    if (is_timer_expired(8))
16
      getKeyInput();
17
      set_timer(8, 20);
18
    }
19
20
    if(is_timer_expired(9))
21
22
      switch(status)
23
      case MANUAL_INIT:
25
        toggle();
26
        led_buffer[0] = 0;
        led_buffer[1] = 0;
28
        led_buffer[2] = 0;
        led_buffer[3] = 0;
30
        if (isButtonOPressed())
31
32
          clear();
           status = RED_SET;
34
35
        else if(isButton2Pressed())
          clear();
           status = AUTO_INIT;
        }
40
        else set_timer(3, 20);
41
        set_timer(9, 500);
42
        break;
```



```
case MAN_RED_GREEN:
        led_red_and_green();
45
        led_buffer[0] = red/10;
        led_buffer[1] = red%10;
        led_buffer[2] = green/10;
48
        led_buffer[3] = green%10;
        red --;
        green--;
51
        if(green == 0)
          green = green_time;
54
          status = MAN_RED_YELLOW;
        }
        if(isButton2Pressed())
          clear();
          red_time = 0; yellow_time = 0; green_time = 0;
60
          status = MANUAL_INIT;
          set_timer(3, 20);
        }
        set_timer(9, 1000);
64
        break;
65
      case MAN_RED_YELLOW:
66
        led_red_and_yellow();
        led_buffer[0] = red/10;
        led_buffer[1] = red%10;
        led_buffer[2] = yellow/10;
        led_buffer[3] = yellow%10;
        red--;
        yellow--;
        if(red == 0)red = red_time;
        if(yellow == 0)
76
          yellow = yellow_time;
          status = MAN_GREEN_RED;
        if(isButton2Pressed())
80
          clear();
```



```
red_time = 0; yellow_time = 0; green_time = 0;
           status = MANUAL_INIT;
           set_timer(3, 20);
         }
         set_timer(9, 1000);
         break;
       case MAN_GREEN_RED:
         led_green_and_red();
90
         led_buffer[0] = green/10;
         led_buffer[1] = green%10;
         led_buffer[2] = red/10;
93
         led_buffer[3] = red%10;
         red--;
         green --;
         if(green == 0)
           green = green_time;
           status = MAN_YELLOW_RED;
100
         }
101
         if(isButton2Pressed())
           clear();
           red_time = 0; yellow_time = 0; green_time = 0;
           status = MANUAL_INIT;
106
           set_timer(3, 20);
         }
         set_timer(9, 1000);
         break;
       case MAN_YELLOW_RED:
         led_yellow_and_red();
         led_buffer[0] = yellow/10;
         led_buffer[1] = yellow%10;
         led_buffer[2] = red/10;
         led_buffer[3] = red%10;
         yellow--;
         red --;
118
         if (yellow == 0)
119
           red = red_time;
```



```
yellow = yellow_time;
           status = MAN_RED_GREEN;
         if(isButton2Pressed())
           clear();
           red_time = 0; yellow_time = 0; green_time = 0;
           status = MANUAL_INIT;
           set_timer(3, 20);
         set_timer(9, 1000);
         break;
       default:
         break;
         }
136
    }
137
138 }
```

Listing 4: Source code of fsm manual.c

7 Exercise 7: Adding code for increasing time duration value for the red LEDs, amber, greenLEDs

In this exercise, this source code I show is also used for Exercise 8, 9

```
#include "fsm_manual.h"

int red_time = 0;
int yellow_time = 0;
int green_time = 0;
int red;
int yellow;
int green;
int dheck = 0;

int num_to_display1 = 0;
int num_to_display2 = 0;

void fsm_manual()
{
```



```
if(is_timer_expired(8))
      getKeyInput();
18
      set_timer(8, 20);
19
    }
20
21
    if (is_timer_expired(9))
22
23
      switch(status)
24
      case MANUAL_INIT:
26
        toggle();
27
         led_buffer[0] = 0;
         led_buffer[1] = 0;
29
         led_buffer[2] = 0;
30
         led_buffer[3] = 0;
         if(isButtonOPressed())
32
33
           clear();
           status = RED_SET;
         }
36
         else if(isButton2Pressed())
           clear();
           status = AUTO_INIT;
41
         else set_timer(3, 20);
42
         set_timer(9, 500);
43
         break;
      case RED_SET:
45
         togglered();
46
         if(isButtonOPressed())
           clear();
49
           if (red_time <= 1) red_time = 2;</pre>
           else red = red_time;
51
           status = YELLOW_SET;
           led_buffer[0] = yellow_time/10;
           led_buffer[1] = yellow_time%10;
```



```
led_buffer[2] = 0;
          led_buffer[3] = 0;
56
          set_timer(3, 20);
        }
        else if(isButton1Pressed())
60
          clear();
          red_time++;
62
          led_buffer[0] = red_time/10;
          led_buffer[1] = red_time%10;
          led_buffer[2] = 0;
65
          led_buffer[3] = 0;
66
          set_timer(3, 20);
        else if(isButton2Pressed())
69
          clear();
71
          if (red_time <= 1)</pre>
             red_time = 2;
            yellow_time = 1;
             green_time = red_time - yellow_time;
            red = red_time;
            yellow = yellow_time;
             green = green_time;
80
            status = MAN_RED_GREEN;
          }
          else
            yellow_time = 1;
             green_time = red_time - yellow_time;
            red = red_time;
             yellow = yellow_time;
             green = green_time;
90
             led_buffer[0] = red_time/10;
91
             led_buffer[1] = red_time%10;
             led_buffer[2] = 0;
```



```
led_buffer[3] = 0;
             status = MAN_RED_GREEN;
           }
           set_timer(3, 20);
         }
         else set_timer(3, 20);
         set_timer(9, 500);
         break;
       case YELLOW_SET:
         toggleyellow();
         if(isButtonOPressed())
105
           clear();
           if (yellow_time <= 1) yellow_time = 1;</pre>
           status = GREEN_SET;
108
           led_buffer[0] = green_time/10;
           led_buffer[1] = green_time%10;
           led_buffer[2] = 0;
111
           led_buffer[3] = 0;
           set_timer(3, 20);
         }
114
         else if(isButton1Pressed())
115
           yellow_time++;
           led_buffer[0] = yellow_time/10;
           led_buffer[1] = yellow_time%10;
           led_buffer[2] = 0;
120
           led_buffer[3] = 0;
121
           set_timer(3, 20);
         else if(isButton2Pressed())
           clear();
126
           if(yellow_time < 1)</pre>
127
             yellow_time = 1;
             green_time = red_time - yellow_time;
130
             red = red_time;
             yellow = yellow_time;
```



```
green = green_time;
             led_buffer[0] = yellow_time/10;
134
             led_buffer[1] = yellow_time%10;
135
             led_buffer[2] = 0;
             led_buffer[3] = 0;
137
             status = MAN_RED_GREEN;
138
           }
           else if (yellow_time >= red_time)
140
           {
             red_time = 0;
             yellow_time = 0;
143
             green_time = 0;
144
             led_buffer[0] = 0;
145
             led_buffer[1] = 0;
             led_buffer[2] = 0;
147
             led_buffer[3] = 0;
             status = RED_SET;
150
           else{
             yellow = yellow_time;
             green = green_time = red_time - yellow_time;
             status = MAN_RED_GREEN;
           }
           set_timer(3, 20);
156
         }
         else set_timer(3, 20);
         set_timer(9, 500);
         break;
160
       case GREEN_SET:
         togglegreen();
162
         if (isButtonOPressed())
163
           clear();
165
           status = RED_SET;
166
           set_timer(3, 20);
         }
168
         else if(isButton1Pressed())
169
           green_time++;
```



```
led_buffer[0] = green_time/10;
           led_buffer[1] = green_time%10;
           led_buffer[2] = 0;
174
           led_buffer[3] = 0;
           set_timer(3, 20);
         }
         else if(isButton2Pressed())
           if(green_time == (red_time - yellow_time) && (yellow_time
180
      != 0))
181
             clear();
182
             status = MAN_RED_GREEN;
           }
           else {
185
             status = RED_SET;
             red_time = 0;
             yellow_time = 0;
             green_time = 0;
             led_buffer[0] = 0;
             led_buffer[1] = 0;
191
             led_buffer[2] = 0;
             led_buffer[3] = 0;
           }
194
           set_timer(3, 20);
         }
         else set_timer(3, 20);
         set_timer(9, 500);
198
         break;
       default:
200
         break;
201
         }
    }
203
204
205 }
```

Listing 5: Source code of fsm manual.c



8 Link

For more details. please refer to this source code Link Github