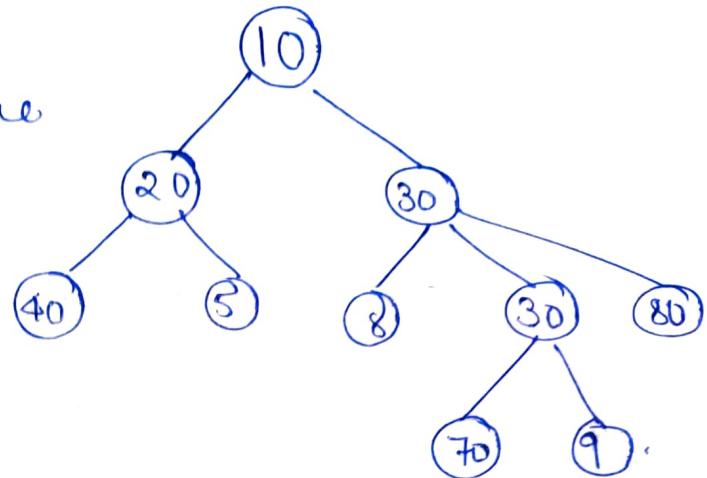


Tree Data Structure

- Hierarchical fashion
- Non linear data structure

Root

- First node of the tree - 10



Edge

- Link connecting any two nodes of the tree.

Siblings

- Children nodes of the same parent are called siblings

Descendants :- all the nodes that lies in the subtree having the node as root

Ex:- descendants of 10 - everything

descendants of 30 - 8, 30, 70, 9.

descendants of 20 - 40, 5

Ancestors :- A node that is connected to all lower levels of nodes is called ancestor

→ 30, 30, 10 are ancestors of 70.

Degree - No of children a node has

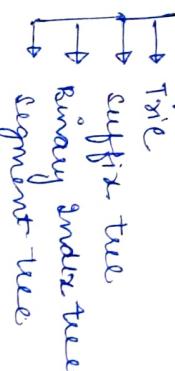
- leaf node has 0 degree.
- here only direct children are considered

degree of 10 → 2.

Applications

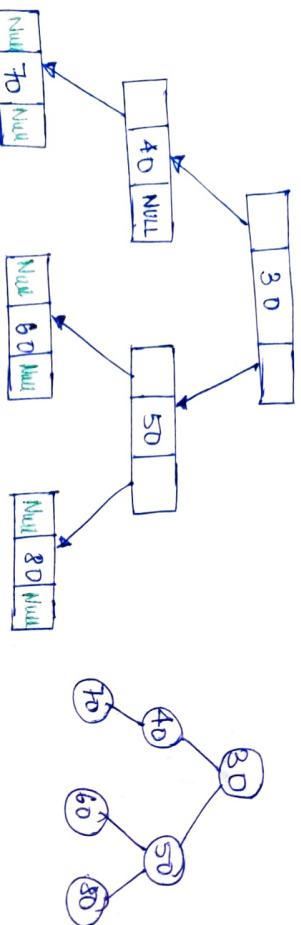
- organisation str. / folder str. / → hierarchical structures
- Nesting is involved → Tree is used
- Inheritance
- HTML DOM elements.

Variations of Trees



Binary Tree

- degree of a node can be almost 2
i.e. each node can have 10, 11, 12, ... nodes.



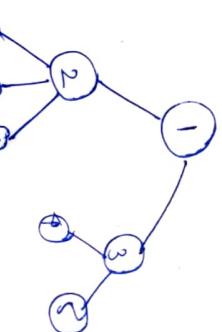
Implementation of Trees

- we have to store many children (address) for every node.

- we can't use array → size is not fixed
we can't use \ll → access time is $O(n)$.

Best option in vector

- stores the address of all the child nodes in the vector of nodes.



j.

making root —

root → 1
children of → 2, 3
root

children of 2 → 6, 7, 8
children of 3 → 4, 5

treeNode * &root =

new treeNode(2)

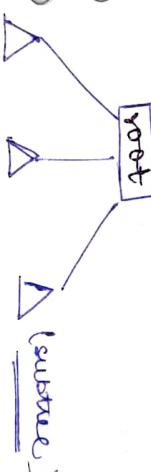
treeNode * &child =

new treeNode(2)

root → child, pushback

(child)

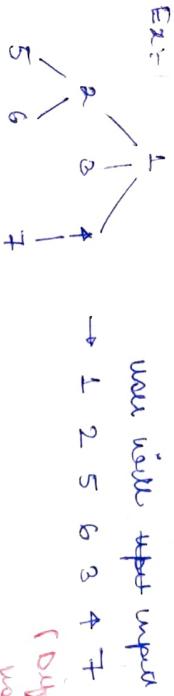
we have to imagine
tree as



Tree Input

- ① recursive (depth first input)

Ex:



use new input

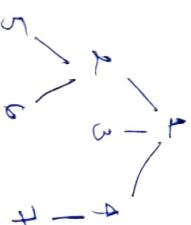
→ 1 2 5 6 3 4 7

(different from
new to provide
input)

- ② level wise (Breadth)

1 2 3 4 5 6 7

(Empty)



Taking input recursive

Basic approach is to call recursion when we have intutive no of child

~~function takeInput() {
 cout << "Enter data";
 cin >> data;
 cout << "Enter no of children for " << n;
 cin >> child;~~

```
TreeNode * takeInput() {
    cout << "Enter data";
    cin >> n;
    cout << "Enter no of children for " << n;
    cin >> child;
    for (int i = 0; i < child; i++) {
        TreeNode * c = takeInput();
        root->children.push_back(c);
    }
}
```

takeInput iterative

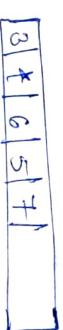
Approach is to use deque, use well instead the next first and while popping an element node will ask - no of children it have and push the menu inside the deque.



poping 1 & inserting 2,3,4



poping 2 & inserting 5,6,7



poping 3 & inserting nothing

TreeNode * takeInput()

```
cout << "Enter data";
cin >> data;
TreeNode * root = new TreeNode(data);
```

```
queue < TreeNode * > q;
q.push(root);
```

```
while (!q.empty()) {
    cout << "number of children of " << q.front() >> data;
    cin >> child;
    while (child--) {
        Enter cout << "Enter the data";
        cin >> data;
        TreeNode * child = new TreeNode(data);
        q.front()->children.push_back(child);
        q.pop();
    }
}
```

Traversal

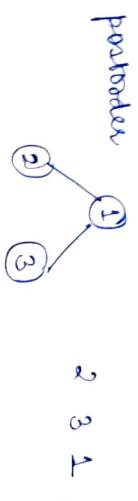
- (a) depth first traversal
- (b) Breadth first traversal (level order)

Depth First Traversal

→ inorder 2 1 3

→ preorder 1 2 3

→ postorder 2 3 1



Inorder {

 return;

 inorder (root->left);

 cout << root->data;

 inorder (root->right);

}

Preorder

{

 if (root == NULL)

 return;

 preorder (root->left);

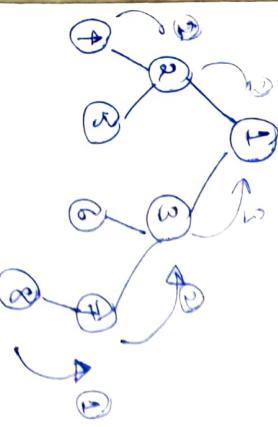
 cout << root->data;

 preorder (root->right);

 preorder (root->right);

Height of Binary Tree

height = max (left-tree, right-tree) + 1.

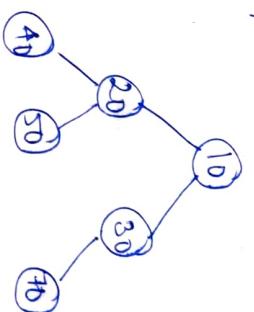


```

int height (TreeNode *root) {
    if (root == NULL)
        return 0;
    else
        return max (height (root->left),
                    height (root->right)) + 1;
}
  
```

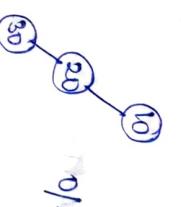
I/P k = 2

O/P → 40, 50, 70



I/P → k = 1

O/P → 20



I/P → k = 3

O/P → 11, 12



Print Nodes at Distance 'k'

I/P → k = 0

O/P → 10



I/P → k = 1

O/P → 20

I/P → k = 2

O/P → 40, 50, 70

printKm (TreeNode *root, int k, int count=0)

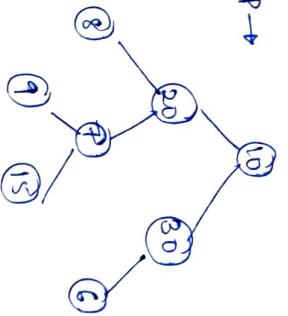
```

int printKm (TreeNode *root, int k, int count=0) {
    if (root == NULL)
        return 0;
    else {
        cout << root->data;
        printKm (root->left, k, count);
        printKm (root->right, k, count);
    }
    count++;
    if (count == k)
        cout << endl;
}
  
```

Level Order Traversal

I/P →

O/P → 10 20 30 8 7 6
9 15



Naive Approach

- calculate height of binary tree (n)
- print nodes on all levels from 0 to n

print(0)
print(1)
print(2)
print(3)

Efficient Approach

void levelTraversal (TreeNode* root) {

queue < TreeNode* > q;

q.push (root);

while (!q.empty()) {

if (q.front() == NULL) {

q.push (q.front() -> left);

q.push (q.front() -> right);

if (q.front() == right) {

q.push (q.front() -> right);

if (q.front() == left) {

q.push (q.front() -> left);

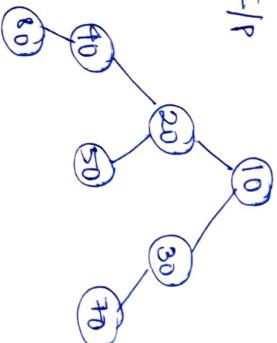
cout << q.front() -> data << " ";

q.pop();

y.

I/P

O/P → 10 20 30
40 50 70
80



- idea is to insert a marker in the end of every level

As the queue is of `TreeNode*` type, the best marker is used by `NULL`.

After pushing root, we push a `NULL` marker and while traversing the queue whenever we see a null marker, we are sure that a particular level is processed and the elements in the queue are the part of next level only. Hence, we push `NULL`

at end of queue. To denote the end of upcoming level.

Time Complexity: $\Theta(n)$
Aux. space: $\Theta(n)$

void printLevelOrder (TreeNode* root) {

if (root == NULL) return;

queue < TreeNode* > q;

q.push (root); q.push (NULL);

while (q.size() > 1) {

TreeNode* curr = q.front();

q.pop();

if (curr == NULL) {

cout << "\n";

q.push (NULL);

continue;

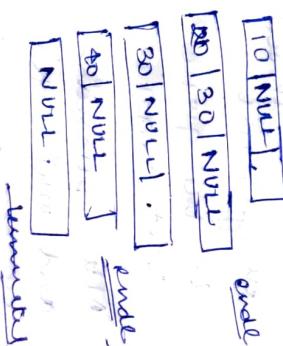
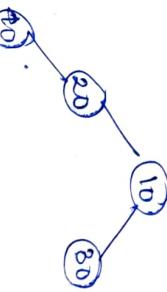
y.

5.

i (curr \rightarrow left) $\&$ push (curr \rightarrow left);
 i (curr \rightarrow right) $\&$ push (curr \rightarrow right);

y .

- we will terminate loop when $q.size == 1$ because at that point tree will be only null pointer left.



- Second Approach
- we basically have two loops, inner loop prints the level and outer loop puts "\n" after every level.

void levelTraversal (TreeNode *root) {

i (root == NULL) return;
 queue <TreeNode* > q;

q.push (root);

while (!q.empty()) {

int count = q.size();

for (int i=0; i<count; i++) {

TreeNode* c = q.front();

q.pop();

cout << c->data << " ";

i (c \rightarrow left) $\&$ push (c \rightarrow left);

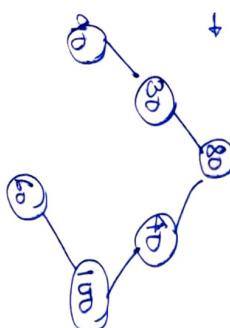
i (c \rightarrow right) $\&$ push (c \rightarrow right);

y .

Size of Binary Tree

I/P \rightarrow

O/P \rightarrow 6



int getSize (TreeNode *root) {

i (root == NULL)
 return 0;

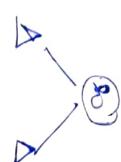
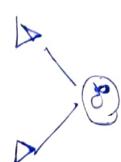
return 1 + getSize (root->left) + getSize (root->right);

Time complexity $\rightarrow O(n)$.

Aux space $\rightarrow O(n)$

\rightarrow height of binary tree

Maximum in Binary Tree



int getMax (TreeNode *root) {

i (root == NULL) return INT_MIN;
 else

return max (root->data, max (getMax (root->left), getmax (root->right)));

out \ll "m"

time complexity $\rightarrow O(n)$

aux space $\rightarrow O(n)$

Print left view of Binary Tree

```
void leftview (TreeNode<int> *root) {
```

 queue < TreeNode<int> *q> q;

 if (root == NULL) q.push (NULL);

 cout << q.front () >> data << "\n";

 while (q.size () > 1) {

 TreeNode *cur = q.front ();

 if (cur == NULL) {

 q.pop ();

 push back to

 cout << q.front () >> data;

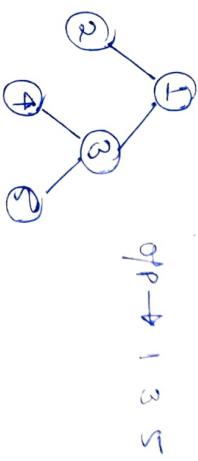
 continiue;

 if (cur->left) q.push (cur->left);

 if (cur->right) q.push (cur->right);

 }

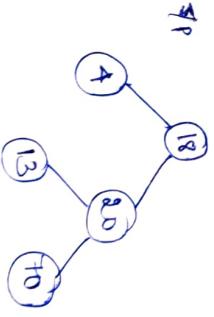
Right view of Tree



O/P → 1 3 5

Height Balanced Binary tree

difference between the heights of left and right subtree is almost one.

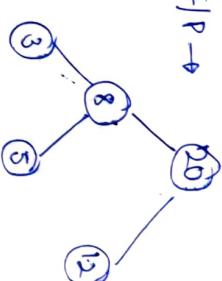


O/P → Yes.

- * similar approach like the left view just have to maintain a **prev pointer** pointing to the node before the current node

O/P → No.

Width sum property



I/P → 20

O/P → Yes

(sum of children of particular node is equal to root)

base childrensum (TreeNode<int> *root) {

 if (root == NULL) return true;

 if (!root->left || !root->right)

 int sum = (root->left ? root->left->data : 0)

 + (root->right ? root->right->data : 0);

 return (root->data == sum) ||

 childrensum (root->left);

 childrensum (root->right);

time complexity → O(n)
aux space → O(n)

Name Solution

bool "unbalanced (Node * root) {

 if (root == NULL) return true;

 int lh = height (root → left);

 int rh = height (root → right);

 return (abs (lh - rh) ≤ 1) &&

 isBalanced (root → left) &&

 isBalanced (root → right));

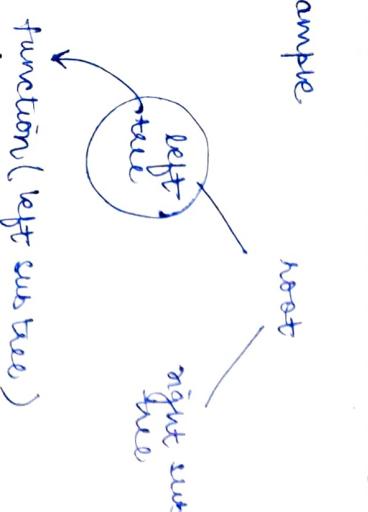
time complexity → O(n)

Effective approach

- we need at least two purposes by one function to reduce the complexity to O(n)

- ① difference in heights.
- ② whether balanced or not.

example



- ↓
returns
 ① height of left subtree
 ② whether left subtree is balanced or not.

- Returns -1 when tree is not balanced
- otherwise return height of tree

int "isBalanced (Node * root) {

 if (root == NULL) return 0;

 int lh = "unbalanced (root → left);

 int rh = "isBalanced (root → right);

 if (lh == -1) return -1;

 if (rh == -1) return -1;

 if (abs (lh - rh) > 1) return -1;

 else return max (lh, rh) + 1;

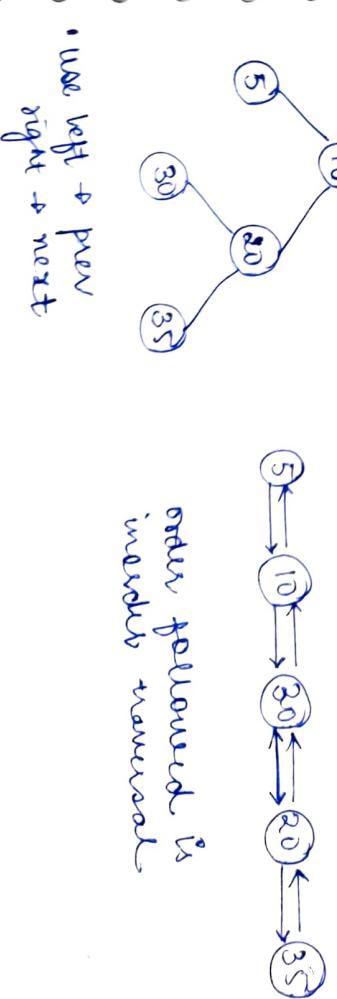
}

Maximum width of Binary Tree

- using the concept of level order traversal line by line.
- maintain a count variable which gives the width of current level i.e. between two NULL markers.

Convert a Binary tree to DLL

- inorder traversal

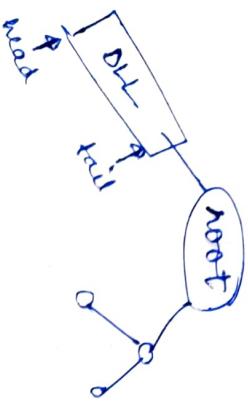


order followed is
inorder traversal

Windows → function (root → left)

```
print (root → data)
function (root → right)
```

- g will assume at a particular node we have made DLL till left of it no more scenario will be



case at a particular node we have

root

? head = NULL
↓
head = root;

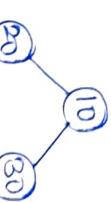
connections of

root to tail

root → right = tail

tail → left = root

tail = root



- in this we have to pass pointers by reference because we're changing the node using ~~copy~~ now

- the pointers are pointing

- To reflect those changes discuss the function we can either use Node * & root

Nodes are root

05

```
void BTtoDLL( Node *root, Node *&head = NULL,
Node *&tail = NULL);
```

```
if (root == NULL) return NULL;
BTtoDLL (root → left, head, tail);
if (!, head) {
    head = root;
```

```
tail → left
root → left = tail
tail → right = root;
```

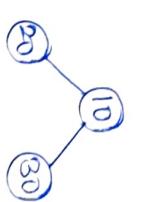
tail = root;

BTtoDLL (root → right, head, tail);

construct a binary tree when inorder and Preorder Traversal are given -

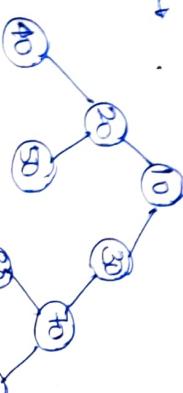
I/P : in[] = {20, 10, 30}
pr[] = {10, 20, 30}

O/P : root →

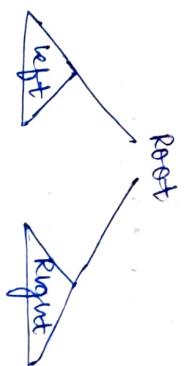


I/P : in[] = {40, 20, 50, 10, 30, 80, 70, 90}
pr[] = {10, 20, 40, 50, 30, 70, 40, 80, 90}.

- To reflect those changes discuss the function we can either use Node * & root



in-order \rightarrow left root right
 pre \rightarrow root left right



- we need inorder traversal to form a tree,
we can't form a tree if we are given only
preorder and postorder traversals

- Because inorder uniquely divides left
and right subtree.

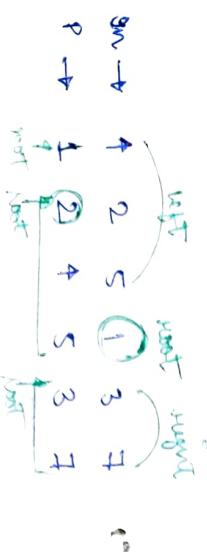
Ex:-

A \swarrow
B

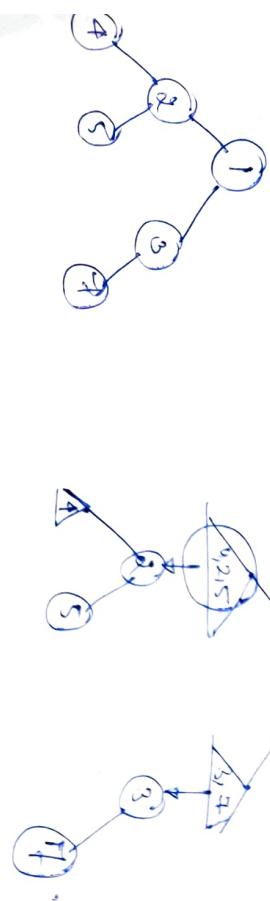
Pre	In	Post
AB	B A	

A B
B A

If we are given
this info we can't
construct a unique
tree.



root will be first element
of pre-order traversal.



we will move our pointer in preorder traversal
 maintain a window in inorder traversal and search
 for root.

Ex:-

in - 9 3 15 20 7
 Pre - 3 9 20 15 7

at $i=0$ search 3 in inorder

left 3 is 20 right
 (connect 3 with
fun root window)

at $i=1$ search 9 in inorder

① ③ 15 20 7
 only node
(i.e. root)

at $i=2$ search 20 in inorder

② ③ ⑤ 25 ⑦ 7

4 6 7 9 10 8 6
 9 7 4 10 6 8 1 6

4 \rightarrow left = fun(6, 7, 8)
 6 \rightarrow left = fun(7, 8, 10)

7 \rightarrow left = fun(8, 10, 9)
 9 \rightarrow left = fun(10, 9, 7)

10 \rightarrow left = fun(9, 7, 6)

```
int preIndex = 0;
```

```
Node * buildTree (int in[], int pre[], int is, int ie)
```

```
'if (is > ie) return NULL;
```

```
Node * root = new Node [pre[preIndex]];
```

```
preIndex++;
```

```
for (int i = is, i <= ie; i++) {
```

```
'if (in[i] == root->key) {
```

```
wIndex = i;
```

```
break;
```

```
}
```

```
root->left = buildTree (in, pre, wIndex - 1);
```

```
root->right = buildTree (in, pre, wIndex + 1);
```

```
return root;
```

```
g.
```

Build Tree from Post Order and Inorder

```
P → {6, 2, 4, 5, 3, 1}      PRE LNR
```

```
I → {6, 2, 1, 4, 3, 5} g
```

we'll follow same approach but

① start from last (because in post order

root in last
(left right root)

i.e. root post(i) = root of tree

② we'll call ~~tree~~ → ~~root~~ → right first

because as we are traversing from last

the order will be

NRL
node → right
node → left

Build Tree from Inorder and Level Order Traversal

Inorder - H D P L A Z C E

level order - A D Z H L C P E

Identifying root

① First element of LOT is root

(aggregate left & right part
of BT using Inorder)

H D P L A H Z C E

Among them
the root is

whichever comes

first in LOT

1st

H D P L

H is
root

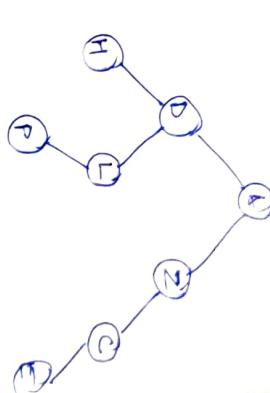
P is
left

L is
right

2nd

left of
2. v. will

C is root
E is right
of C



we will

we have to find the element in inorder traversal
that have minimum index in level order traversal

Algorithm

TreeNode * construct (start, end) {

'if (start > end) return NULL;

wIndex = Find wIndex index of node from
instart to inend which was minimum

level order index. node = new tree with
node->left = construct (start, end wIndex + 1);

node->right = construct (wIndex + 1, end);
return node;

The complexity of search ~~hence~~ seems to be $O(n^2)$.

which makes whole algorithm $O(n^3)$.

We can use map to store level order traversal elements and their indices.

→ Reduce the search complexity → $O(n^2)$.

TreeNode * constructTree (vector<int> &inorder,

unordered_map<int, int> &map, int start, int end) {

if (start > end)

return NULL;

int minder = start;

for (int j = start + 1; j <= end; j++) {

if (m[inorder[j]] < m[inorder[minder]])

inorder[minder] = j;

j.

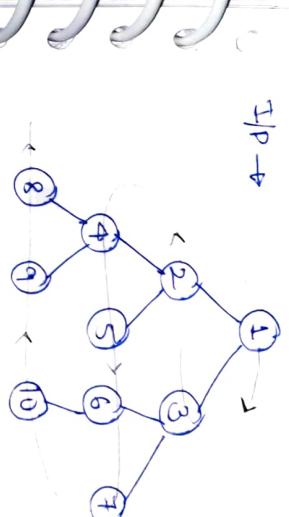
TreeNode * root = new TreeNode (inorder[0], minder);

root->left = construct (inorder, &inorder, start, minder - 1);

root->right = construct (inorder, &inorder, minder + 1, end);

return root;

j.

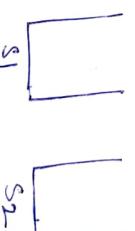


I/P → 1 3 2 4 5 6
7 10 9 8

Method-1
using level order traversal along with stacks.
(we'll store alternate levels inside stack and
then reverse them).

Method-2

We will use two stacks here to store alternate levels.



① Push root to S1
② while any of stack is not

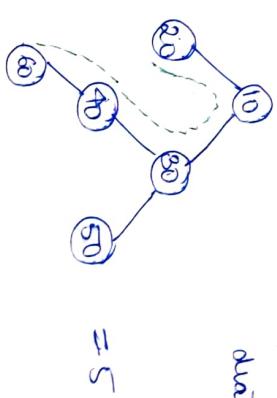
empty
If S1 is not empty
(a) Take out a node, print it
(b) push its children in S2

If S2 is not empty
(a) Take out the node & print
(b) push children of the taken out node in reverse
order.

Tree Traversal: spiral form

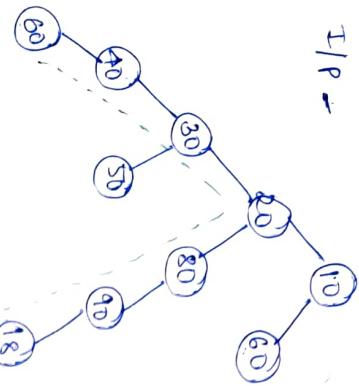
Diameter of Binary Tree

I/P



diameter = longest path b/w
two leaf nodes

I/P -



= 5

O/P → 7

For any node
we need to calc.
 $1 + \text{left} + \text{right}$
return max
of all
left height
right height

Naive Approach?

```
int diameter (Node * root) {
```

if (~~root == NULL~~) return 0;

```
int d1 = 1 + height (root->left) + height (root->right);
int d2 = diameter (root->left);
int d3 = diameter (root->right);
return max (d1, max (d2, d3));
```

5.

$O(n^2)$.

Efficient weight of every node approach

- Precompute weight of every node.
- and store all of them in map.

→ Reduced to $O(n)$
but overhead of map.

Effective Approach

we can modify tree height function to compute diameter for every node.

```
int res = 0;
int height (Node * root) {
```

if (root == NULL) return 0;

```
int lh = height (root->left);
```

```
int rh = height (root->right);
```

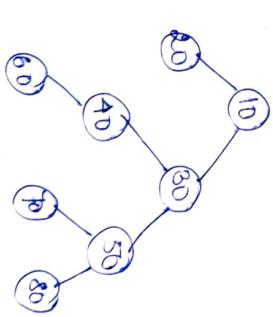
```
res = max (res, 1+lh+rh);
```

```
return 1+max (lh, rh);
```

5.

Lowest common ancestor (LCA)

I/P



known as 4D → 3D &
ancestor 03 → 10, 50, 30

↓
lowest common ancestor → 30

computation
diameter

discovered in 2nd subproblem
or 2nd dimension tree.

minimum distance
between two nodes.

→ use same kind of
LCA solution but
with added condition
distance of resulting
from LCA

LCA (10, 20) → 10
LCA (20, 30) → 30
LCA (30, 20) → 50

Name solution

Build two path arrays, i.e. from root to two node

```
path1 → {10, 50, 20, 90, 30}
path2 → {10, 50, 20, 80}
```

the common among
them are

10, 50, 20

0/1 → 20

lowest

complex part is to build the path arrays.

↳ we will add a particular node

if (node == targetnode) return true;

else value left
right

if both left and right return false
remove the node.

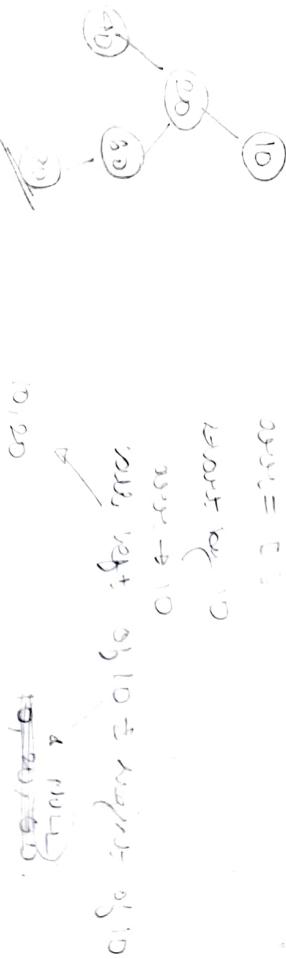
if (path1[i] != path2[i])

return path1[i];

return NULL;

3.

O(n) requires
both traversals



Efficient approach

- assumes that both nodes is present in tree.
- if either of both node is not present it gives the incorrect result.

parent left
parent right
10/20, 40/60
10, 20, 60
10, 20, 10, 80

```
bool funxpath (Node *root, vector<Node*>&p, int n) {
    if (root == NULL) return false;
    p.push_back (root);
    if (root->key == n) return true;
    if (funxpath (root->left, p, n)) return true;
    if (funxpath (root->right, p, n)) return true;
    p.pop_back ();
    return false;
}
```

A particular node in
root is included only if
it is target node

if (funxpath (root->left, p, n) && funxpath (root->right, p, n)) return true;

```
int main() {
    Node *p = pop_back ();
    cout << p->key;
}
```

```
Node * LCA (Node *root, int n1, int n2) {
    while (root < Node *) {
        if (funxpath (root, path1, n1) && funxpath (root, path2, n2))
            return root;
        root = root->right;
    }
    return NULL;
}
```

```
for (int i=0; i < path1.size()-1 && i < path2.size()-1; i++)
    if (path1[i] != path2[i])
        return path1[i];
    i++;
}
```

```
if (path1[i] != path2[i])
    return path1[i];
    i++;
}
```

if (path1[i] != path2[i])

return path1[i];

return NULL;

3.

Approach:
we will do normal tree traversal, possible cases

→ let curr is the node which is in process

- ① curr == n₁ or curr == n₂

(return curr)

In this case curr is going to be true

LCA as c₂ is in lower level.

Ex



$$\text{curr} = 20 == n_1$$

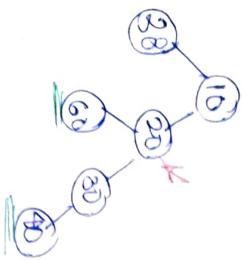
return 20

- ② if both subtree contain n₁ and other
contain n₂

→ curr becomes LCA

for 10 → both are on left
for 30 → none is present
for 20 → one is on left
other is in R
Other is in R

Hence 20 is LCA



O(n)
transversal
one of tree

case-3 {
if (curr != NULL)
return curr;
else

case-2 (curr != NULL & curr == n₁ || curr == n₂)
return root;

Node * LCA (Node * root, int n₁, int n₂) {
if (root == NULL) return NULL;
Node * lca1 = LCA (root → left, n₁, n₂);
Node * lca2 = LCA (root → right, n₁, n₂);
if (lca1 == NULL & lca2 == NULL) {
return root;
}

else if (lca1 == NULL & lca2 != NULL) {
return lca2;

3

20

10

25
20
30

15
20
30

10
20

20

True sole elements
the node present
in the tree is
curr. if not present

15
20
30

15
20
30

15
20
30

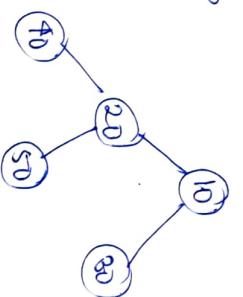
15
20
30

- ③ one of subtrees contain both n₁ and n₂
(one of return whatever that subtree
returns)

- ④ if none of subtree contain n₁ or n₂
return NULL

Count Nodes in complete Binary Tree

I/P
D/P → 5



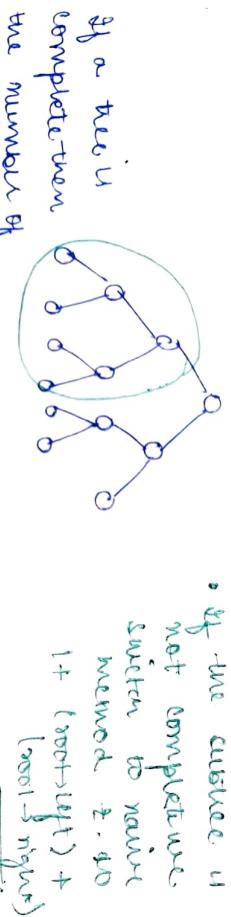
Naive Solution

using simple dfs traversal , we can compute the number of nodes

return $\text{1} + \text{fun}(\text{root} \rightarrow \text{left}) + \text{fun}(\text{root} \rightarrow \text{right})$

Efficient Approach

we can take advantage of the fact that the given tree is complete



where $d \geq \text{depth}$

* To check whether a tree is complete or not we can

use $\text{root} \rightarrow \text{left} \rightarrow \dots \rightarrow \text{longest of left most branches}$ --- length of right most branch

$\text{root} \rightarrow \text{right} \rightarrow \dots \rightarrow \text{longest of right most branch}$

if both are equal we can directly use the formula

Applications

- To send a tree across a network
- to save space in programs

```

int countNode (Node *root) {
    int m = 0, mh = 0;
    Node *curr = root;
    while (curr != NULL) {
        mh++;
        curr = curr->left;
    }
    return pow(2, mh) - 1;
}
  
```

```

}
while (curr != NULL) {
    mh++;
    curr = curr->right;
}
if (mh == mh) {
    return pow(2, mh) - 1;
}
  
```

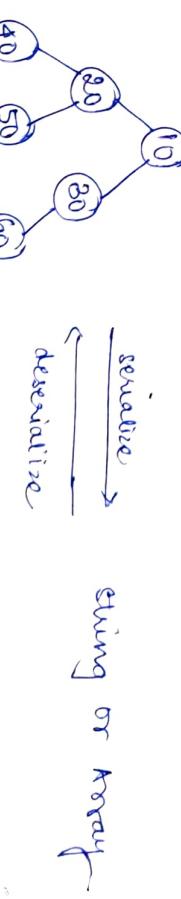
~~O(log₂ n)~~

```

}
return 1 + countNode (root->left) + countNode (root->right);
}
  
```

\rightarrow directly return height

Serialization and Deserialization of Binary Tree



We Solution

we can store inorder and (pre/post/inorder level order traversal (either of them)).

→ It requires two traversals of binary tree.

Effective approach:

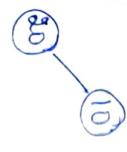


→ 10 20 -1 -1 30 -1 -1



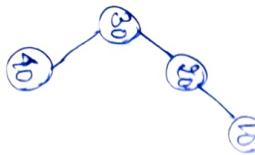
10 20 -1 -1 -1 -1

(2)



10 20 -1 -1 -1 -1 -1

(3)



10 20 -1 -1 -1 -1 -1 -1

Deserialize

we use -1 for
NULL
assuming -1 is
not present

g.

Deserialization

Node * deserialize (vector<int> &arr, int &index);

if (index == arr.size()) return NULL;

if (arr[index] == -1) return NULL;

Node * root = new Node (arr[index++]);

root->left = deserialize (arr, index);

root->right = deserialize (arr, index);

return root;

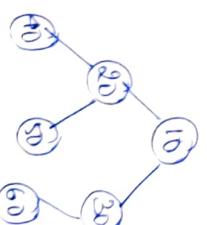
j.

Iterative inorder traversal

SI/P



10 20 -1 -1 30 -1 -1



10 20 50 60 30

Serialization

void serialize (Node * root, vector<int> &arr);
if (root == NULL) {
 arr.push_back (-1);
 return;
}

arr.push_back (root->key);
serialize (root->left, arr);
serialize (root->right, arr);