

# COMP90051 Statistical Machine Learning

Semester 2, 2016

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## 21. Independence in PGMs; Example PGMs



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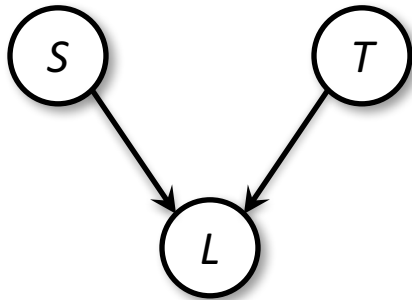
# Independence

*PGMs encode assumption of statistical independence between variables.*

*Critical to understanding the capabilities of a model, and for efficient inference.*

# Recall: Directed PGM

- Nodes
- Edges (acyclic)
- Random variables
- Conditional dependence
  - \* **Node table:**  $\Pr(\text{child}|\text{parents})$
  - \* Child directly depends on parents
- Joint factorisation



$$\Pr(X_1, X_2, \dots, X_k) = \prod_{i=1}^k \Pr(X_i | X_j \in \text{parents}(X_i))$$

Graph encodes:

- independence assumptions
- parameterisation of CPTs

# Independence relations (D-separation)

- Important *independence* relations between RV's
  - \* *Marginal independence*  $P(X, Y) = P(X) P(Y)$
  - \* *Conditional independence*  $P(X, Y | Z) = P(X | Z) P(Y | Z)$
- Notation  $A \perp B | C$ :
  - \* *RVs in set A are independent of RVs in set B, when given the values of RVs in C.*
  - \* *Symmetric: can swap roles of A and B*
  - \*  $A \perp B$  denotes marginal independence,  $C = \emptyset$
- Independence captured in graph structure
  - \* *Caveat: dependence does not follow **in general** when X and Y are not independent*

# Marginal Independence

- Consider graph fragment

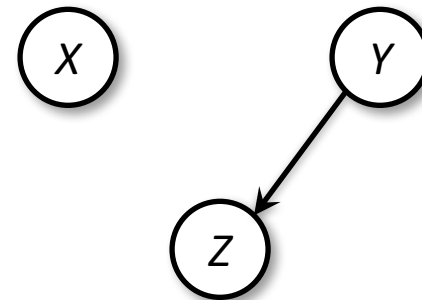


- What [marginal] independence relations hold?

\*  $X \perp Y$ ?

Yes –  $P(X, Y) = P(X) P(Y)$

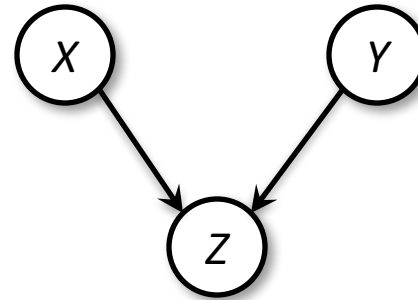
- What about  $X \perp Z$ , where Z connected to Y?



# Marginal Independence

- Consider graph fragment

*Marginal independence  
denoted  $X \perp Y$*



- What [marginal] independence relations hold?

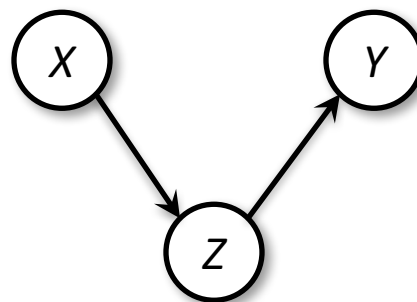
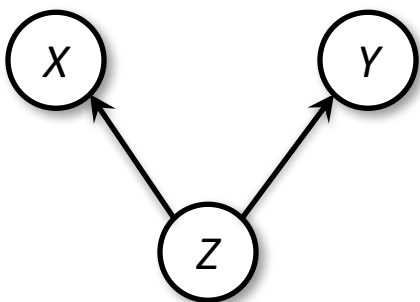
\*  $X \perp Z$ ?

**No** –  $P(X, Z) = \sum_Y P(X)P(Y)P(Z|X, Y)$

\*  $X \perp Y$ ?

**Yes** –  $P(X, Y) = \sum_Z P(X)P(Y)P(Z|X, Y)$   
 $= P(X)P(Y)$

# Marginal Independence



Are X and Y marginally dependent? ( $X \perp Y$ ?)

$$P(X, Y) = \sum_Z P(Z)P(X|Z)P(Y|Z) \dots \text{No}$$

$$P(X, Y) = \sum_Z P(X)P(Z|X)P(Y|Z) \dots \text{No}$$

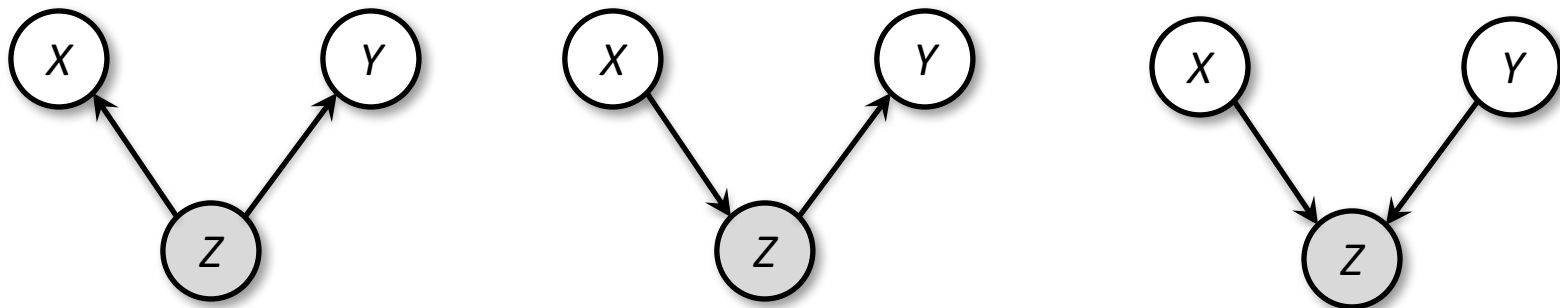
# Marginal Independence

- Marginal independence **can** be read off graph
  - \* however, must account for edge directions
  - \* relates (loosely) to *causality*:  
if edges encode causal links, can X affect (cause) Y?
- General rules, X and Y are linked by:
  - \* no edges, in any direction → independent
  - \* intervening node with incoming edges from X and Y  
(aka *head-to-head*) → independent
  - \* *head-to-tail*, *tail-to-tail* → not (necessarily) independent
- ... generalises to longer chains of intermediate nodes (coming)



# Conditional independence

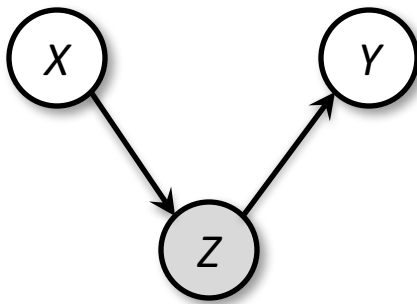
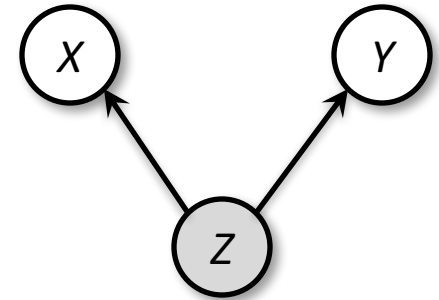
- What if we know the value of some RVs? How does this affect the in/dependence relations?
- Consider whether  $X \perp Y | Z$  in the canonical graphs



\* Test by trying to show  $P(X, Y | Z) = P(X | Z) P(Y | Z)$ .

# Conditional independence

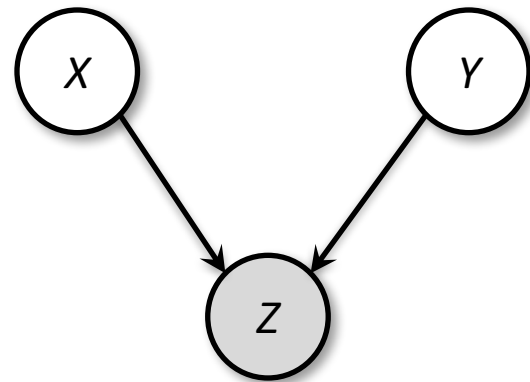
$$P(X, Y|Z) = \frac{P(Z)P(X|Z)P(Y|Z)}{P(Z)} \\ = P(X|Z)P(Y|Z)$$



$$P(X, Y|Z) = \frac{P(X)P(Z|X)P(Y|Z)}{P(Z)} \\ = \frac{P(X|Z)P(Z)P(Y|Z)}{P(Z)} \\ = P(X|Z)P(Y|Z)$$

# Conditional independence

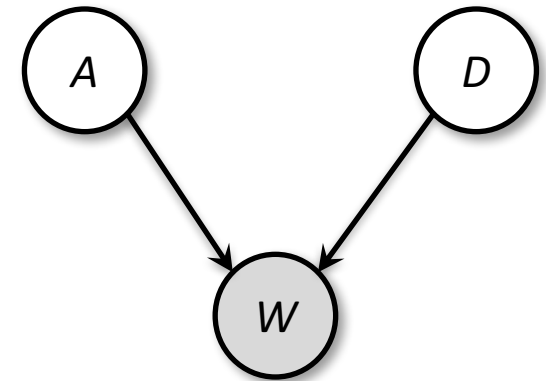
- So far, just graph separation... Not so fast!
  - \* cannot factorise the last canonical graph
- Known as **explaining away**:  
value of Z can give information linking X and Y
  - \* E.g., X and Y are binary coin flips, and Z is whether they land the same side up. Given Z, then X and Y become completely dependent (deterministic).
  - \* A.k.a. Berkson's paradox



**N.b., Marginal dependence  $\neq$  conditional independence!**

# Explaining away

- The washing has fallen off the line (W). Was it aliens (A) playing? Or next door's dog (D)?



A	Prob
0	0.999
1	0.001

D	Prob
0	0.9
1	0.1

A	D	$P(W=1   A,D)$
0	0	0.1
0	1	0.3
1	0	0.5
1	1	0.8

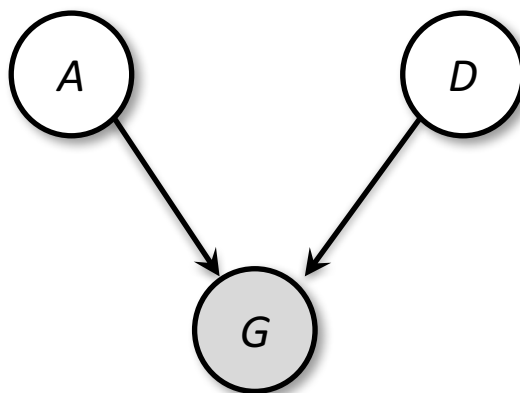
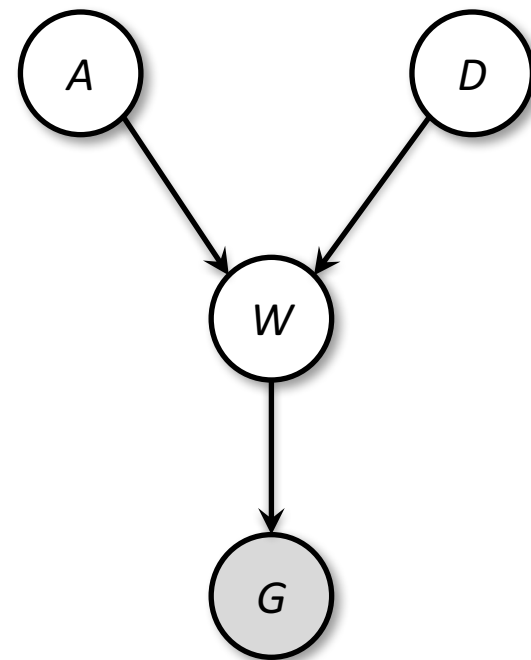
- Results in conditional posterior
  - \*  $P(A=1 | W=1) = 0.004$
  - \*  $P(A=1 | D=1, W=1) = 0.003$
  - \*  $P(A=1 | D=0, W=1) = 0.005$

# Explaining away II

- Explaining away also occurs for *observed children* of the head-head node

\* attempt factorise to test  $A \perp D \mid G$

$$\begin{aligned} P(A, D|G) &= \sum_W P(A)P(D)P(W|A, D)P(G|W) \\ &= P(A)P(D)P(G|A, D) \end{aligned}$$



# “D-separation” Summary

- Marginal and cond. independence can be read off graph structure
  - \* marginal independence relates (loosely) to *causality*: if edges encode causal links, can X affect (cause or be caused by) Y?
  - \* conditional independence less intuitive
- How to apply to larger graphs?
  - \* based on paths separating nodes, i.e., do they contain nodes with head-to-head, head-to-tail or tail-to-tail links?
  - \* can all [undirected!] paths connecting two nodes be blocked by an independence relation?

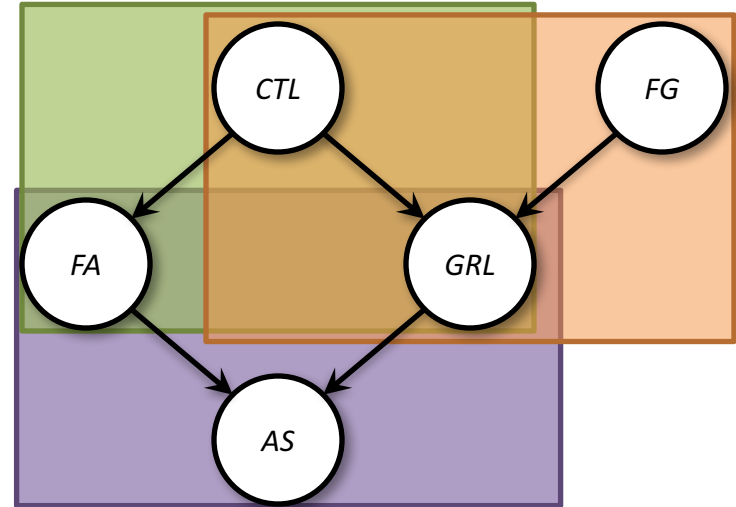
# D-separation in larger PGM

- Consider pair of nodes  
 $FA \perp FG$ ?

Paths:

FA – CTL – GRL – FG

FA – AS – GRL – FG



- Paths can be blocked by independence
- More formally see “**Bayes Ball**” algorithm which formalises notion of d-separation as reachability in the graph, subject to specific traversal rules.

# What's the point of d-separation?

- Designing the graph
  - \* understand what independence assumptions are being made; not just the obvious ones
  - \* informs trade-off between expressiveness and complexity
- Inference with the graph
  - \* computing of conditional / marginal distributions must respect in/dependences between RVs
  - \* affects complexity (space, time) of inference



# Markov Blanket

- For an RV what is the minimal set of other RVs that make it *conditionally independent* from the rest of the graph?
  - \* what conditioning variables can be safely dropped from  $P(X_j \mid X_1, X_2, \dots, X_{j-1}, X_{j+1}, \dots, X_n)$ ?
- Solve using d-separation rules from graph
- Important for predictive inference  
(e.g., in pseudolikelihood, Gibbs sampling, etc)

# Undirected PGMs

*Undirected variant of PGM, parameterised by arbitrary positive valued functions of the variables, and global normalisation.*

*A.k.a. Markov Random Field.*

# Undirected vs directed

## Undirected PGM

- Graph
  - \* Edges undirected
- Probability
  - \* Each node a r.v.
  - \* Each clique  $C$  has “factor”  
 $\psi_C(X_j: j \in C) \geq 0$
  - \* Joint  $\propto$  product of factors

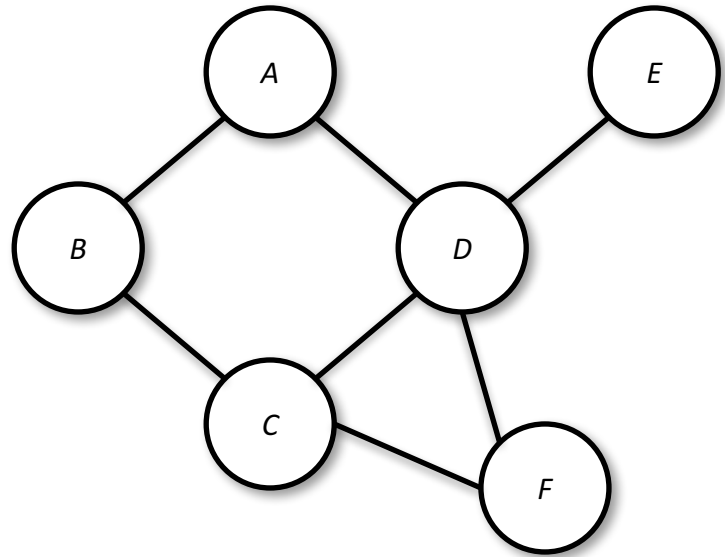
## Directed PGM

- Graph
  - \* Edges directed
- Probability
  - \* Each node a r.v.
  - \* Each node has conditional  
 $p(X_i | X_j \in \text{parents}(X_i))$
  - \* Joint = product of cond'ls

**Key difference = normalisation**

# Undirected PGM formulation

- Based on notion of
  - \* **Clique**: a set of fully connected nodes (e.g., A-D, C-D, C-D-F)
  - \* **Maximal clique**: largest cliques in graph (not C-D, due to C-D-F)
- Joint probability defined as



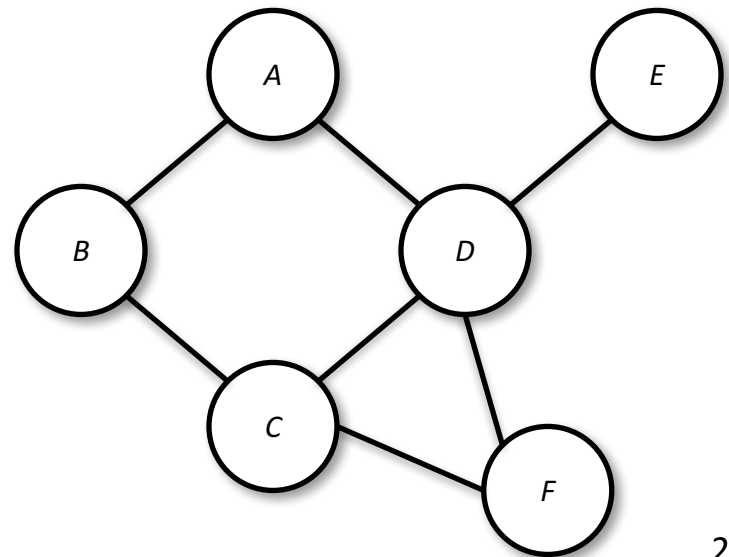
$$P(a, b, c, d, e, f) = \frac{1}{Z} \psi_1(a, b) \psi_2(b, c) \psi_3(a, d) \psi_4(d, c, f) \psi_5(d, e)$$

- \* where  $\psi$  is a positive function and  $Z$  is the normalising 'partition' function

$$Z = \sum_{a,b,c,d,e,f} \psi_1(a, b) \psi_2(b, c) \psi_3(a, d) \psi_4(d, c, f) \psi_5(d, e)$$

# d-separation in U-PGMs

- Good news! Simpler dependence semantics
  - \* conditional independence relations = graph connectivity
  - \* if all paths between nodes in set  $X$  and  $Y$  pass through an observed nodes  $Z$  then  $X \perp Y | Z$
- For example  $B \perp D | \{A, C\}$
- Markov blanket of node = its immediate neighbours



# Directed to undirected

- Directed PGM formulated as

$$P(X_1, X_2, \dots, X_k) = \prod_{i=1}^k Pr(X_i | X_{\pi_i})$$

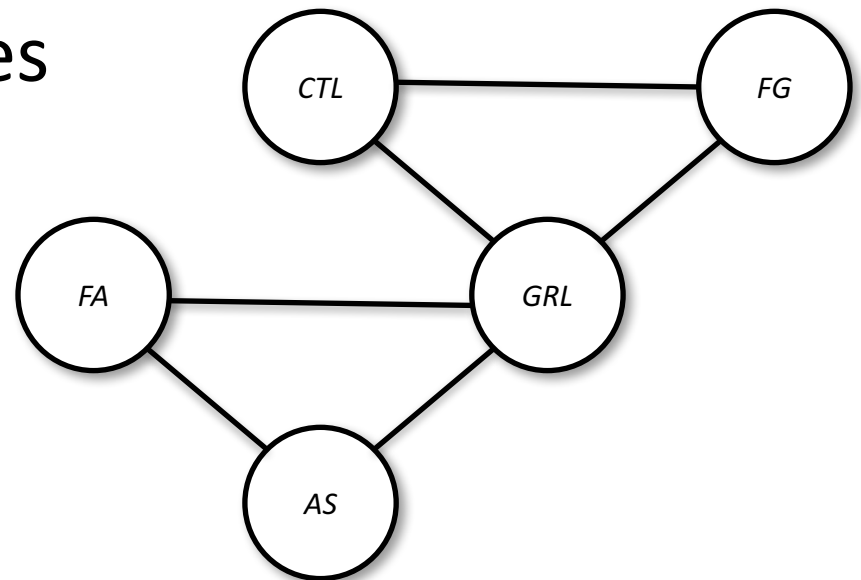
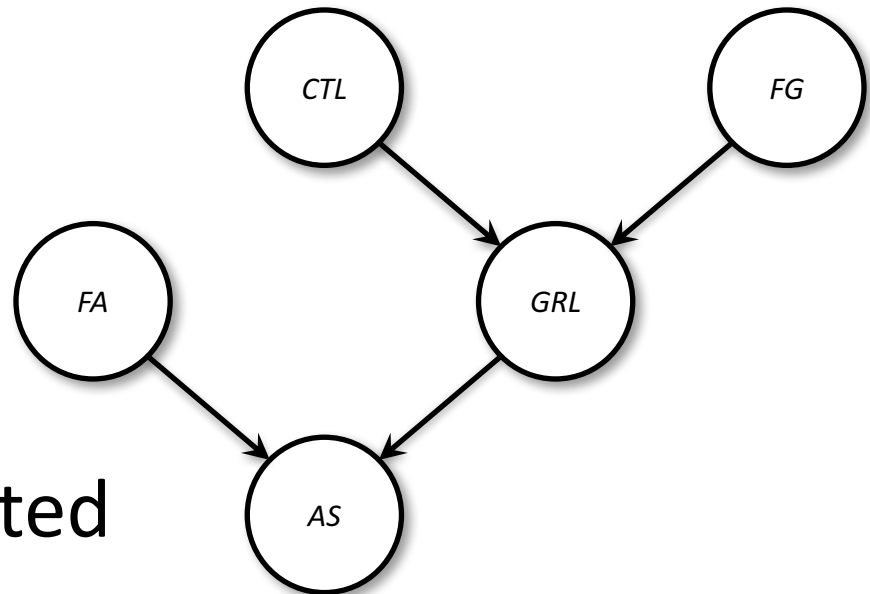
where  $\pi$  indexes parents.

- Equivalent to U-PGM with
  - \* each conditional probability term is included in one factor function,  $\psi_c$
  - \* clique structure links *groups of variables*, i.e.,  $\{\{X_i\} \cup X_{\pi_i}, \forall i\}$
  - \* normalisation term trivial,  $Z = 1$

1. copy nodes

2. copy edges, undirected

3. 'moralise' parent nodes



# Why U-PGM?

- Pros

- \* generalisation of D-PGM
- \* simpler means of modelling without the need for per-factor normalisation
- \* general inference algorithms use U-PGM representation (supporting both types of PGM)

- Cons

- \* (slightly) weaker independence
- \* calculating global normalisation term ( $Z$ ) intractable in general (but tractable for chains/trees, e.g., CRFs)

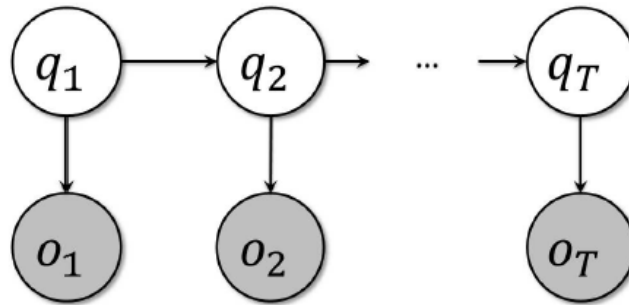


# Example PGMs

*The hidden Markov model (HMM);  
lattice Markov random field (MRF)*

# The HMM (and Kalman Filter)

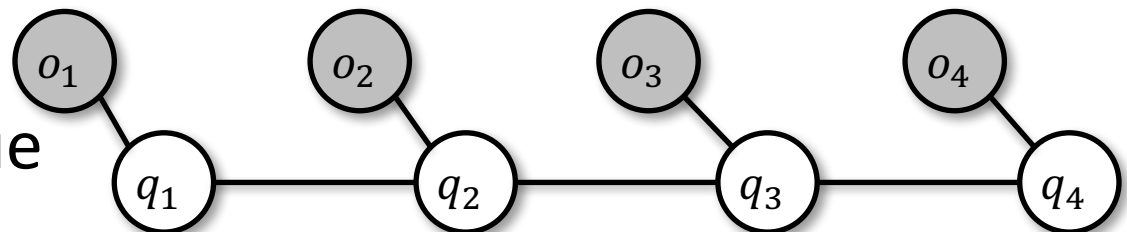
- Sequential observed **outputs** from hidden **state**



$A = \{a_{ij}\}$  transition probability matrix;  $\forall i : \sum_j a_{ij} = 1$   
 $B = \{b_i(o_k)\}$  output probability matrix;  $\forall i : \sum_k b_i(o_k) = 1$   
 $\Pi = \{\pi_i\}$  the initial state distribution;  $\sum_i \pi_i = 1$

- The **Kalman filter** same with continuous Gaussian r.v.'s

- A **CRF** is the undirected analogue

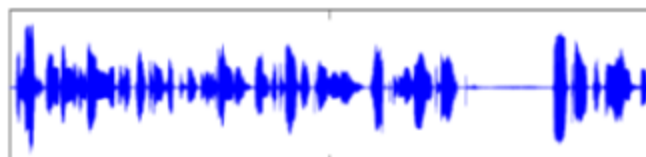


# HMM Applications

- NLP – **part of speech tagging**: given words in sentence, infer hidden parts of speech

“I love Machine Learning” → noun, verb, noun, noun

- **Speech recognition**: given waveform, determine phonemes



- Biological sequences: classification, search, **alignment**
- Computer vision: identify who's walking in video, **tracking**

# Fundamental HMM Tasks

HMM Task	PGM Task
<b>Evaluation.</b> Given an HMM $\mu$ and observation sequence $O$ , determine likelihood $\Pr(O \mu)$	Probabilistic inference
<b>Decoding.</b> Given an HMM $\mu$ and observation sequence $O$ , determine most probable hidden state sequence $Q$	MAP point estimate
<b>Learning.</b> Given an observation sequence $O$ and set of states, learn parameters $A, B, \Pi$	Statistical inference

# Computer Vision

*Hidden square-lattice Markov random fields*

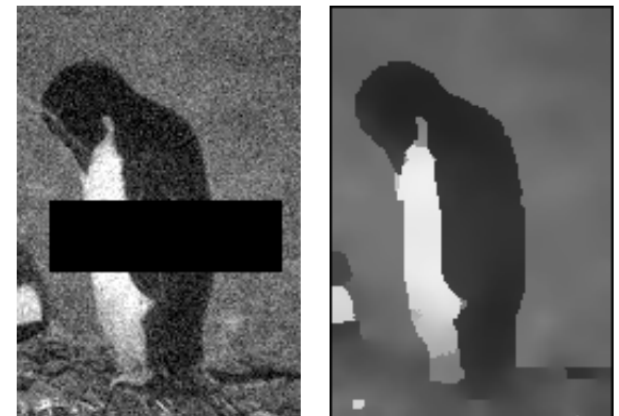
# Pixel labelling tasks in Computer Vision



Semantic labelling (Gould et al. 09)



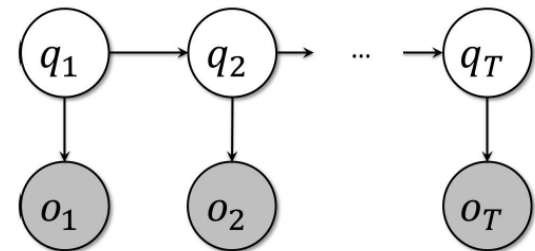
Interactive figure-ground segmentation (Boykov & Jolly 2011)



Denoising (Felzenszwalb & Huttenlocher 04)

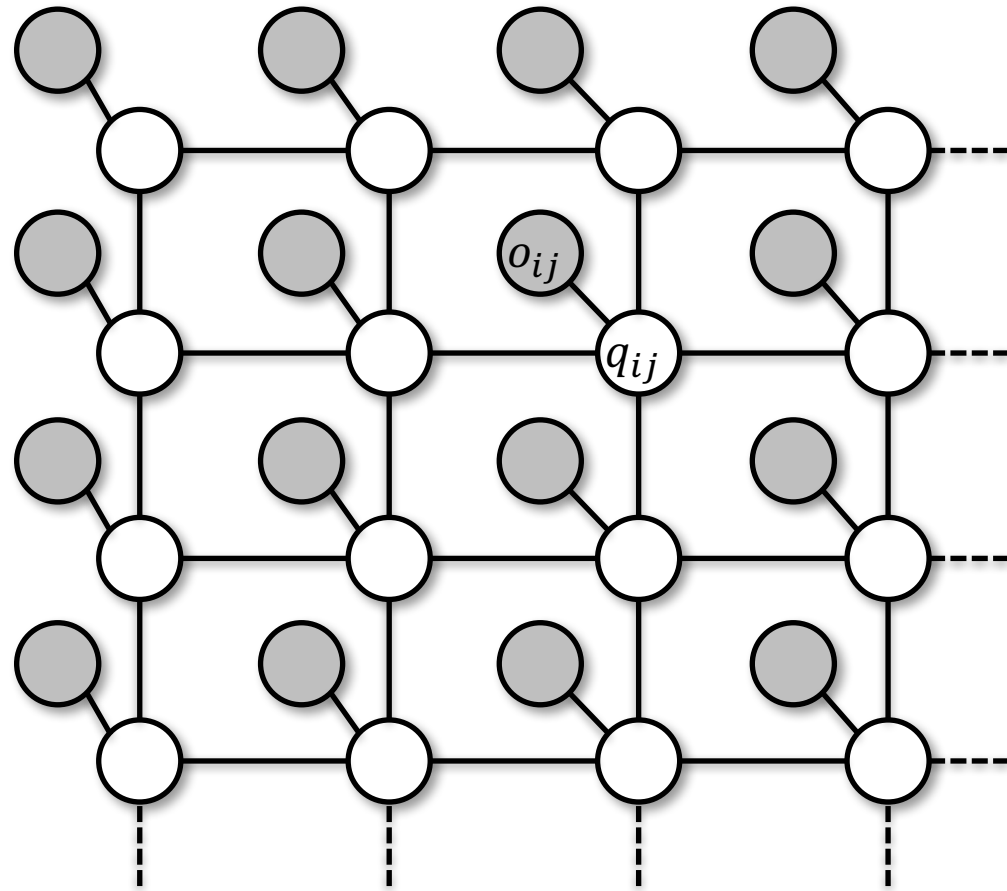
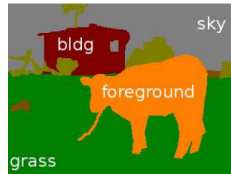
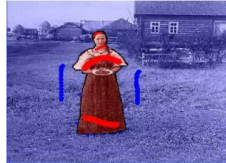
# What these tasks have in common

- Hidden state representing semantics of image
  - \* Semantic labelling: Cow vs. tree vs. grass vs. sky vs. house
  - \* Fore-back segment: Figure vs. ground
  - \* Denoising: Clean pixels
- Pixels of image
  - \* What we observe of hidden state
- Remind you of HMMs?



# A hidden square-lattice MRF

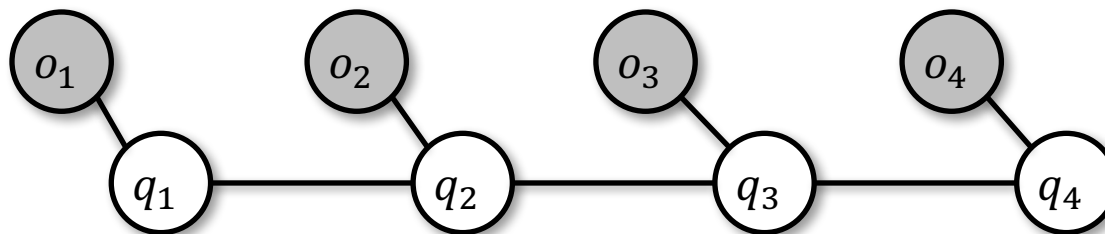
- **Hidden states:**  
square-lattice model
  - \* Boolean for two-class states
  - \* Discrete for multi-class
  - \* Continuous for denoising
- **Pixels:** observed outputs
  - \* Continuous e.g. Normal





# Application to sequences: CRFs

- Conditional Random Field: Same model applied to sequences
  - \* observed outputs are words, speech, amino acids etc
  - \* states are tags: part-of-speech, phone, alignment...
- CRFs are discriminative, model  $P(Q/O)$ 
  - \* versus HMM's which are generative,  $P(Q,O)$
  - \* undirected PGM more general and expressive



# Summary

- Notion of independence, 'd-separation'
  - \* marginal vs conditional independence
  - \* explaining away, Markov blanket
  - \* undirected PGMs & relation to directed PGMs
- Share common training & prediction algorithms (coming up next!)