

Statistical Machine Learning

Semester 2, 2017

Workshop #5: Neural Networks

Prepared by: Yasmeen George



THE UNIVERSITY OF
MELBOURNE

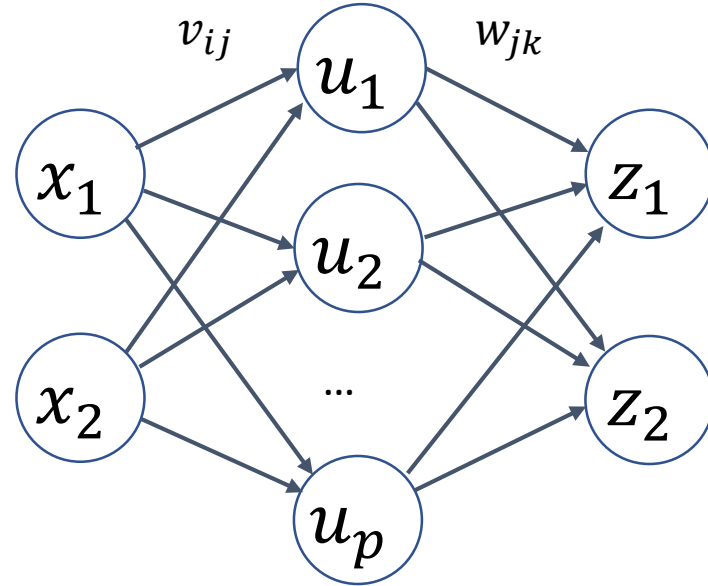
Neural Network Architecture

Given n inputs and p hidden layers,

- How many weights are connected to each hidden neuron ? $m+1$
- How many weights should be trained for the whole hidden layer ? $p*(m+1)$

Given p hidden layers and k output neurons,

- How many weights are connected to each output neuron ? $p+1$
- How many weights should be trained for the whole output layer ? $k*(p+1)$



Input Layer

Hidden Layer

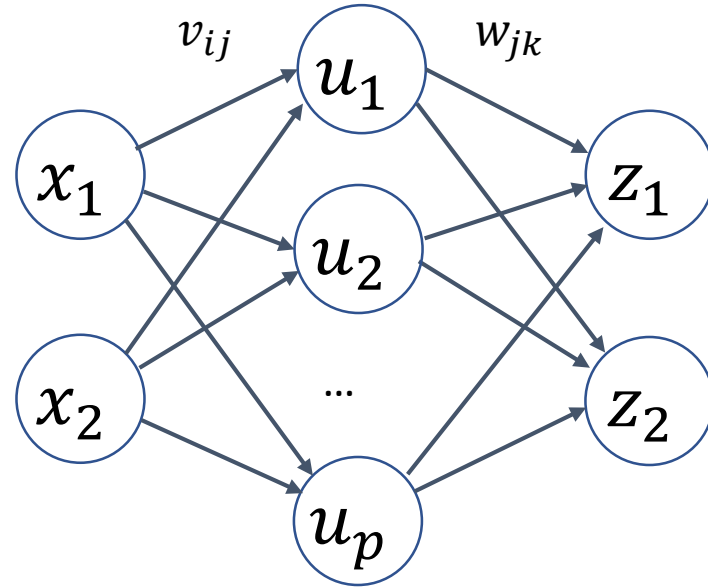
Output Layer

Hidden Layer forward pass calculations:

$$r_j = v_{0j} + \sum_{i=1}^2 x_i v_{ij} = \sum_{i=0}^2 x_i v_{ij}$$

$$u_j = g(r_j)$$

$$g(r) = \tanh(r) = \frac{e^r - e^{-r}}{e^r + e^{-r}}$$



Input Layer

Hidden Layer

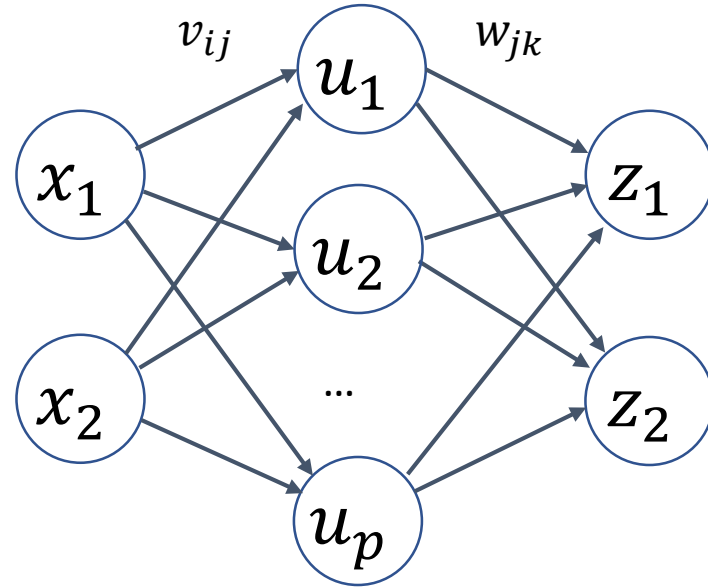
Output Layer

Output Layer forward pass calculations:

$$s_k = w_{0k} + \sum_{j=1}^p u_j w_{jk} = \sum_{j=0}^p u_j w_{jk}$$

$$z_k = f(s_k)$$

$$f(s) = \frac{1}{1 + e^{-s}}$$

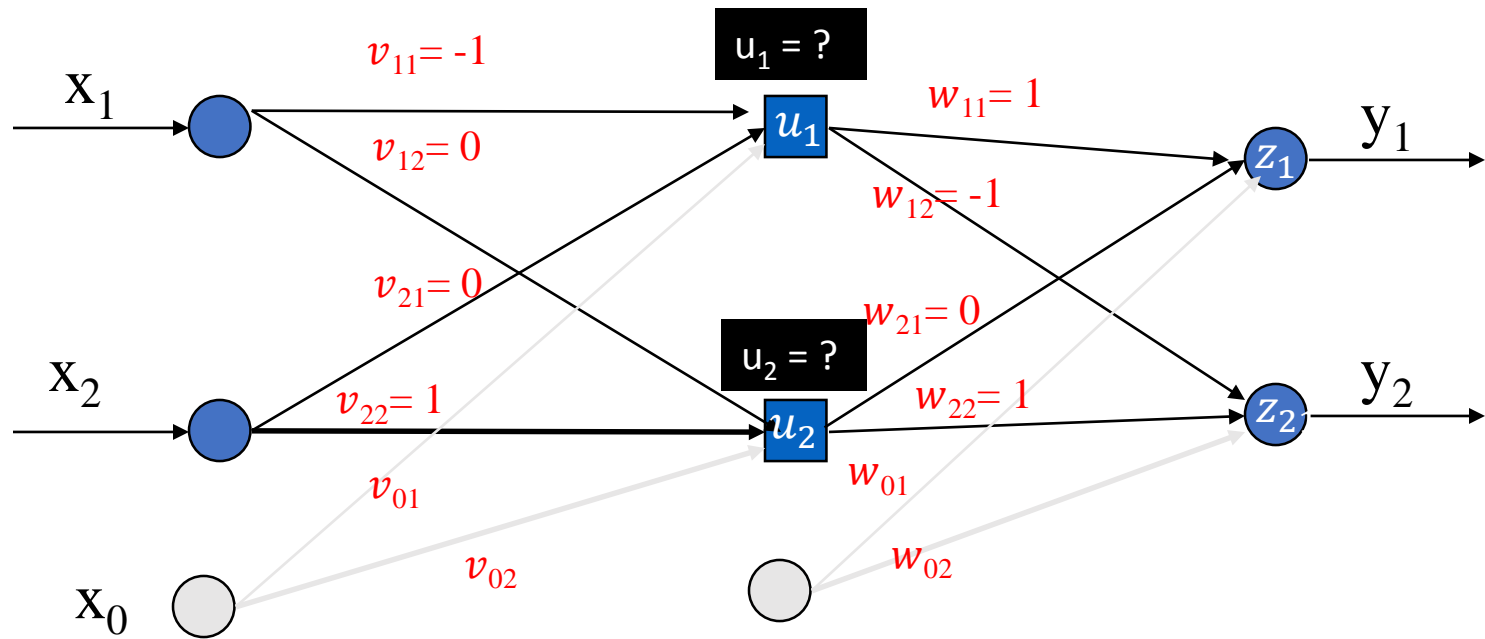


Input Layer

Hidden Layer

Output Layer

An example: (Forward pass) – hidden calculations



Use “tanh” activation function (i.e. $g(a) = \tanh(a)$)

Have input $[0 \ 1]$ with target $[1 \ 0]$.

All biases set to 1

- $r_1 = -1 \times 0 + 0 \times 1 + 1 = 1 \rightarrow u_1 = \tanh(r_1) = \tanh(1) = \mathbf{0.76}$
- $r_2 = 0 \times 0 + 1 \times 1 + 1 = 2 \rightarrow u_2 = \tanh(r_2) = \tanh(2) = \mathbf{0.97}$

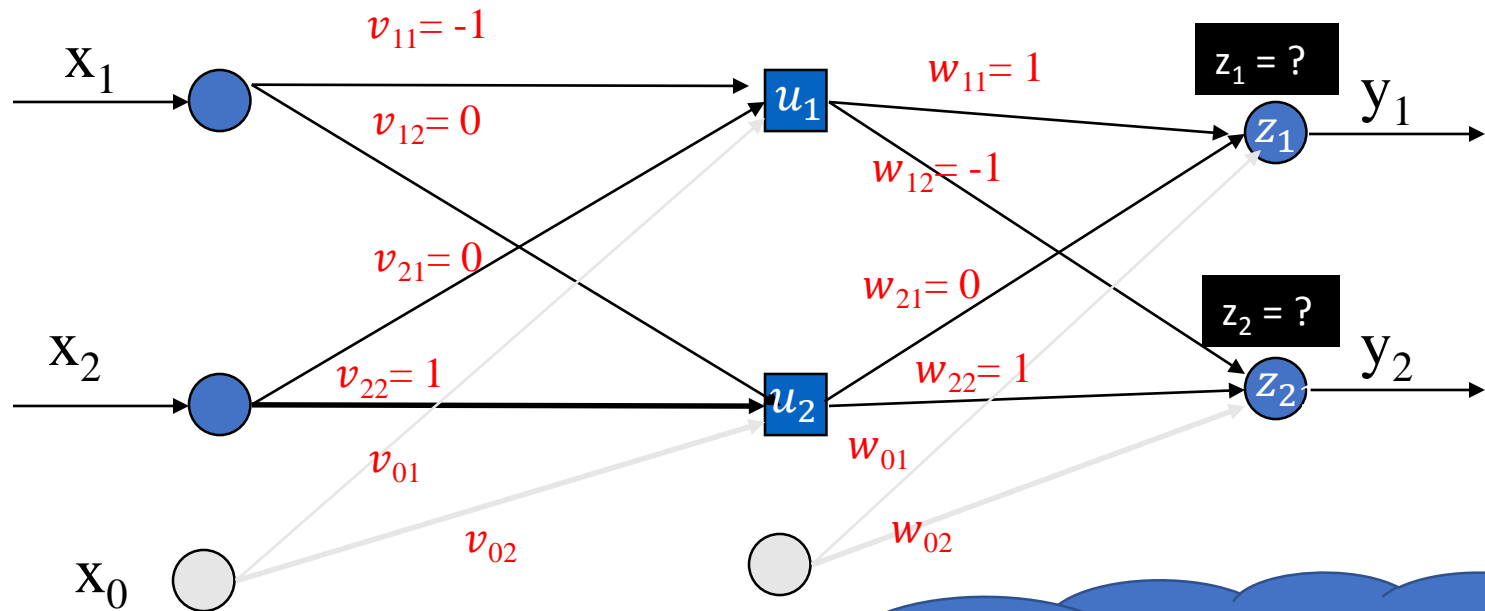
Weight Matrix V

$[p \times (m+1)]$

v_{ij}	i = 0	i = 1	i = 2
j=1	1	-1	0
j=2	1	0	1

$$\begin{matrix} \text{Input vector } x \\ [1 \ 0 \ 1]' \end{matrix} \times \begin{matrix} [m+1 \times 1] \\ [1 \ 0 \ 1]' \end{matrix} = \begin{matrix} \text{Vector } r \\ [p \times 1] \\ [1 \ 2]' \end{matrix}$$

An example: (Forward pass) – output calculations



Use identity activation function (i.e. $g(a) = a$)

Have input [0 1] with target [1 0].

All biases set to 1

Weight Matrix W

[k x (p+1)]

w_{jk}	j = 0	j = 1	j = 2
k=1	1	1	0
k=2	1	-1	1



Input vector u

[p+1 x 1]
[1 0.67 0.97]'

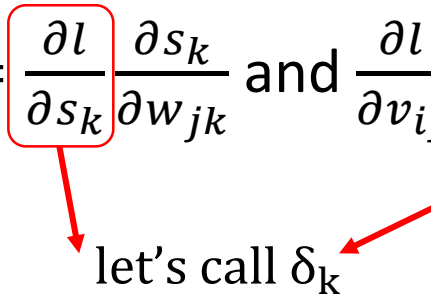
Vector s

[k x 1]
[2.64 1.3]'

Back to tutorial to fill in
`compute_forward(x,V,W)` &
`ann_predict(X,V,W)` functions

- $s_1 = 1 \times 0.67 + 0 \times 0.97 + 1 = 2.64 \rightarrow z_1 = s_1 = \mathbf{2.64}$
- $s_2 = -1 \times 0.67 + 1 \times 0.97 + 1 = 1.3 \rightarrow z_2 = s_2 = \mathbf{1.3}$

Backpropagation update rule : (1)

- Discrepancy $l = 0.5 \cdot \sum_{k=1}^c (y_k - z_k)^2$
- Partial derivatives $\frac{\partial l}{\partial w_{jk}} = \frac{\partial l}{\partial s_k} \frac{\partial s_k}{\partial w_{jk}}$ and $\frac{\partial l}{\partial v_{ij}} = \frac{\partial l}{\partial s_k} \frac{\partial s_k}{\partial v_{ij}}$


let's call δ_k

- $\delta_k = \frac{\partial l}{\partial s_k} = -(y_k - z_k) z_k (1 - z_k)$

- $\frac{\partial l}{\partial w_{jk}} = \delta_k u_j$

- $\frac{\partial l}{\partial v_{ij}} = g'(r_j) x_i \sum_{k=1}^c \delta_k w_{jk}$

Stochastic Gradient Descent update rule:

$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} - \eta \nabla D(\boldsymbol{\theta}^{(t)})$$

$$w_{jk}^{(t+1)} = w_{jk}^{(t)} - \eta \frac{\partial D}{\partial w_{jk}}$$

$$v_{ij}^{(t+1)} = v_{ij}^{(t)} - \eta \frac{\partial D}{\partial v_{ij}}$$

Backpropagation update rule: (2)

- Discrepancy $l = -\sum_{k=1}^c y_k \log(z_k) - (1 - y_k) \log(1 - z_k)$

- Partial derivatives $\frac{\partial l}{\partial w_{jk}} = \frac{\partial l}{\partial s_k} \frac{\partial s_k}{\partial w_{jk}}$ and $\frac{\partial l}{\partial v_{ij}} = \frac{\partial l}{\partial s_k} \frac{\partial s_k}{\partial v_{ij}}$
let's call δ_k

- $\delta_k = \frac{\partial l}{\partial s_k} = (z_k - y_k)$

- $\frac{\partial l}{\partial w_{jk}} = \delta_k u_j$

- $\frac{\partial l}{\partial v_{ij}} = g'(r_j) x_i \sum_{k=1}^c \delta_k w_{jk}$

- $= (1 - u_j^2) x_i \sum_{k=1}^c \delta_k w_{jk}$

- $= (1 - u_j^2) x_i \delta_1 w_{j1} + (1 - u_j^2) x_i \delta_1 w_{j1}$

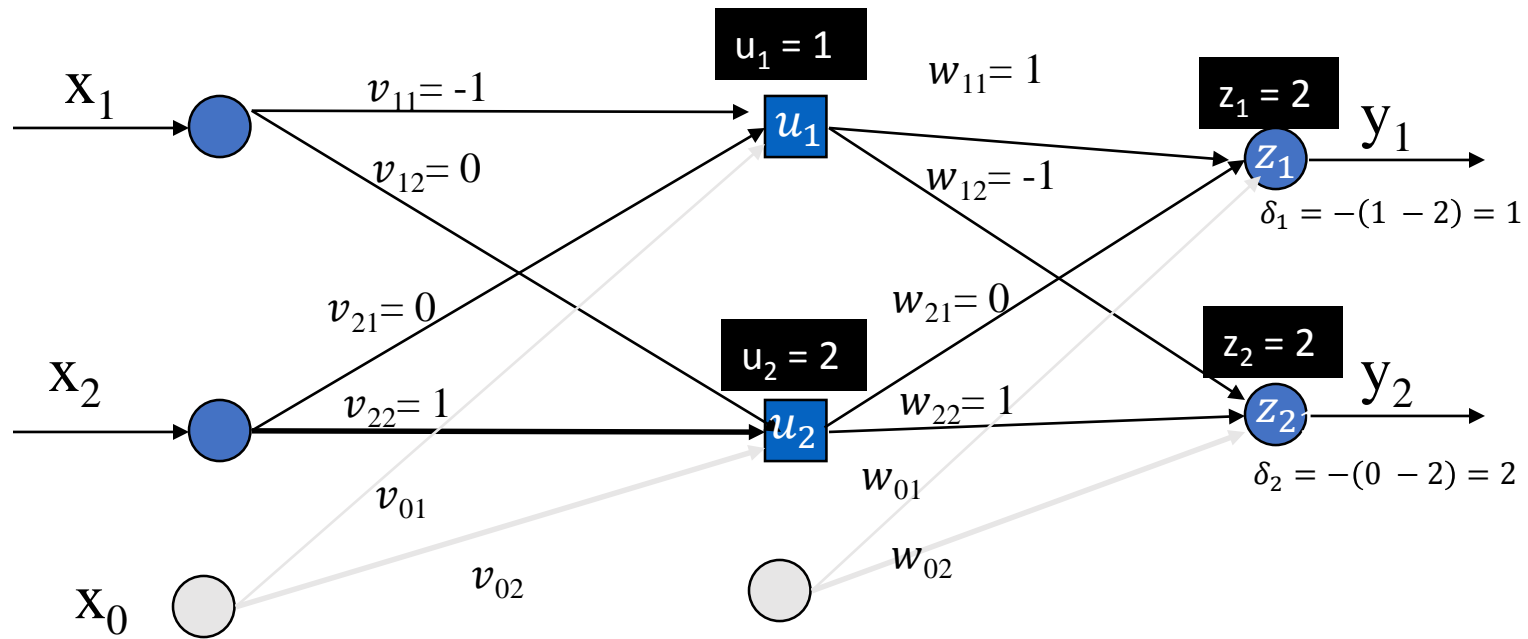
Stochastic Gradient Descent update rule:

$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} - \eta \nabla D(\boldsymbol{\theta}^{(t)})$$

$$w_{jk}^{(t+1)} = w_{jk}^{(t)} - \eta \frac{\partial D}{\partial w_{jk}}$$

$$v_{ij}^{(t+1)} = v_{ij}^{(t)} - \eta \frac{\partial D}{\partial v_{ij}}$$

An example: (Backward pass) – output layer



Have input [0 1] with target [1 0]. Learning rate $\eta = 0.1$

$$k=1, j=1 \rightarrow w_{11} = 1 - 0.1 * 1 * 1 = 0.9$$

$$k=1, j=2 \rightarrow w_{21} = 0 - 0.1 * 1 * 2 = -0.2$$

$$k=1, j=0 \rightarrow w_{01} = 1 - 0.1 * 1 * 1 = 0.9$$

$$k=2, j=1 \rightarrow w_{12} = -1 - 0.1 * 2 * 1 = -1.2$$

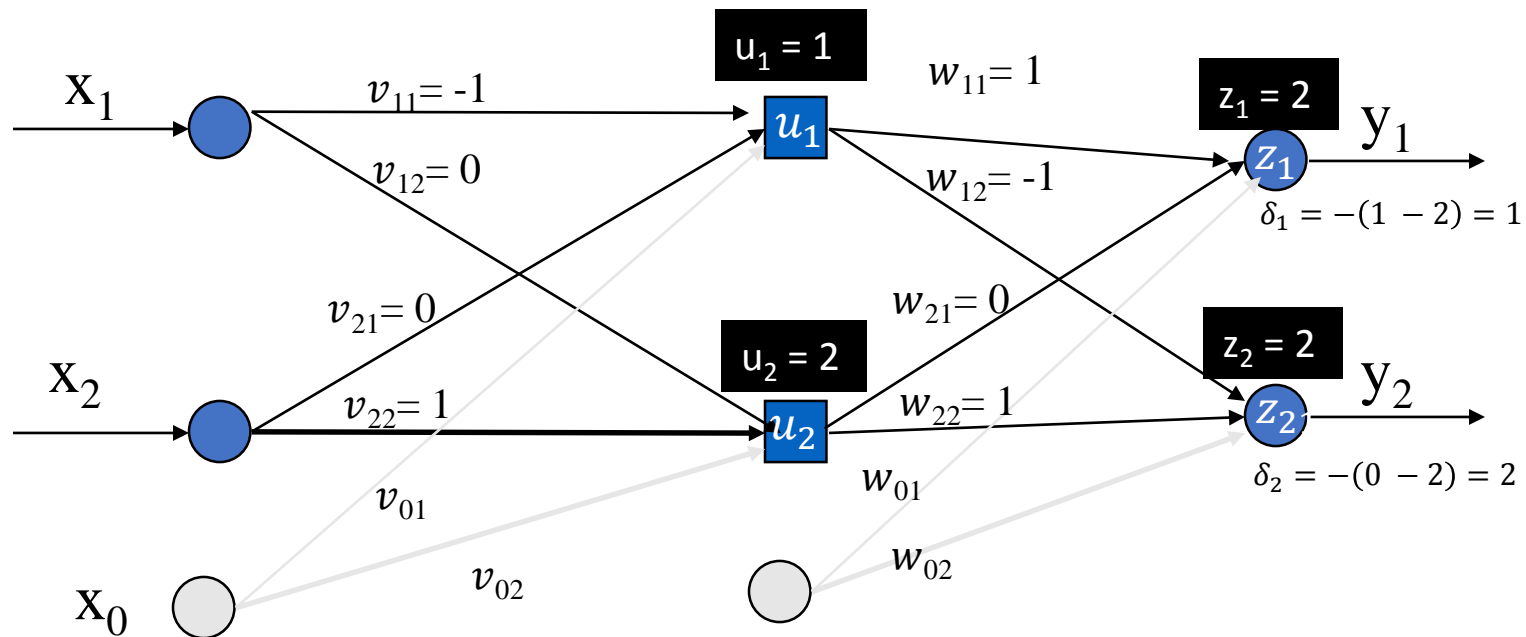
$$k=2, j=2 \rightarrow w_{22} = 1 - 0.1 * 2 * 2 = 0.6$$

$$k=2, j=0 \rightarrow w_{02} = 1 - 0.1 * 2 * 1 = 0.8$$

$$\delta_k = -(y_k - z_k) \left(\frac{\partial f_k}{\partial s_k} = 1 \right)$$

$$\begin{aligned} w_{jk}^{(t+1)} &= w_{jk}^{(t)} - \eta \frac{\partial D}{\partial w_{jk}} \\ &= w_{jk}^{(t)} - \eta \delta_k u_j \end{aligned}$$

An example: (Backward pass) – hidden layer



Have input [0 1] with target [1 0]. Learning rate $\eta = 0.1$

$$\delta_k = -(y_k - z_k) \left(\frac{\partial f_k}{\partial s_k} = 1 \right)$$

$$\begin{aligned} j=1, i=1 &\rightarrow v_{11} = -1 - 0.1 * -1 * 0 = -1 \\ j=1, i=2 &\rightarrow v_{21} = 0 - 0.1 * -1 * 1 = 0.1 \\ j=1, i=0 &\rightarrow v_{01} = 1 - 0.1 * -1 * 1 = 1 \end{aligned}$$

$$\begin{aligned} v_{ij}^{(t+1)} &= v_{ij}^{(t)} - \eta \frac{\partial D}{\partial v_{ij}} \\ &= v_{ij}^{(t)} - \eta x_i \sum_{k=1}^c \delta_k w_{jk} \end{aligned}$$

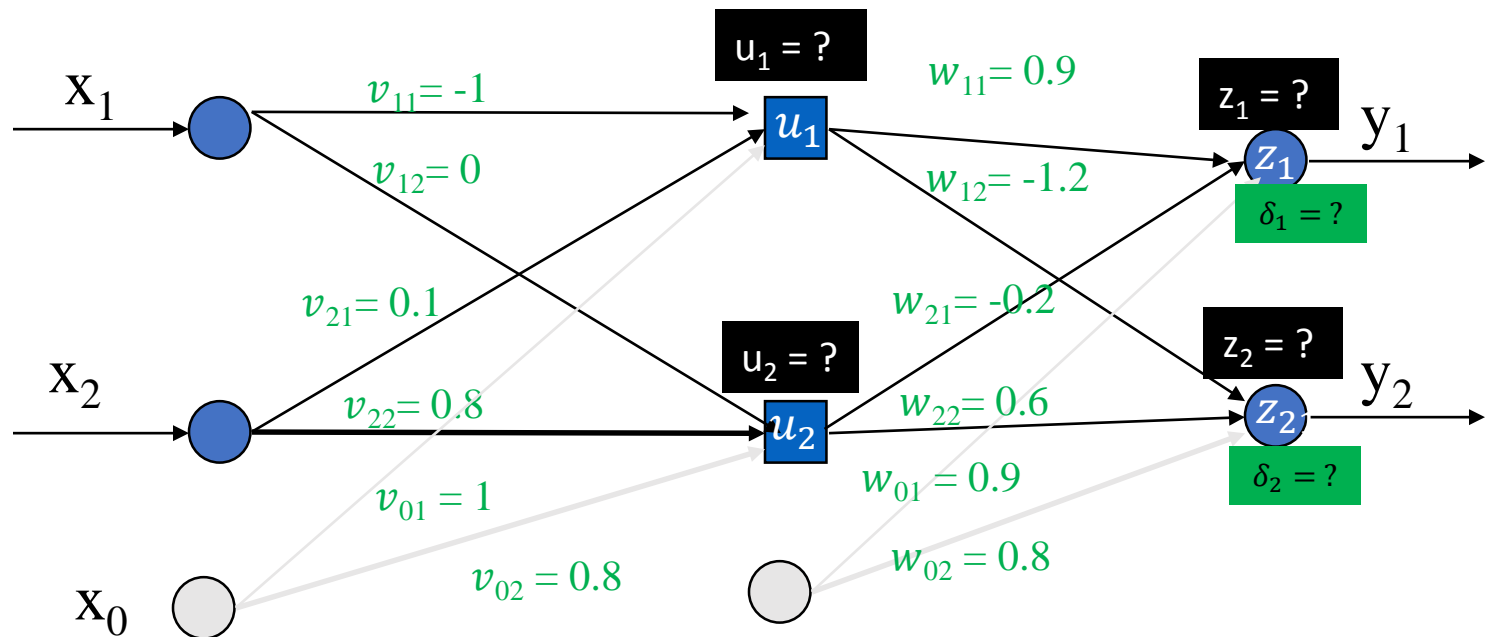
$$\begin{aligned} j=2, i=1 &\rightarrow v_{12} = 0 - 0.1 * 2 * 0 = 0 \\ j=2, i=2 &\rightarrow v_{22} = 1 - 0.1 * 2 * 1 = 0.8 \\ j=2, i=0 &\rightarrow v_{02} = 1 - 0.1 * 2 * 1 = 0.8 \end{aligned}$$

Note: use old weights w_{jk}

$$\sum_{k=1}^c \delta_k w_{1k} = 1 \times 1 + -1 \times 2 = -1$$

$$\sum_{k=1}^c \delta_k w_{2k} = 0 \times 1 + 1 \times 2 = 2$$

An example: updated weights after ONE iteration



Back to tutorial to fill in
`update_params(x,y,V,W,eta)` &
`ann_train(X,y,V0,W0)` functions