

# COMP90051 Statistical Machine Learning

Semester 2, 2017

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## 2. Statistical Schools



THE UNIVERSITY OF  
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Adapted from slides by Ben Rubinstein

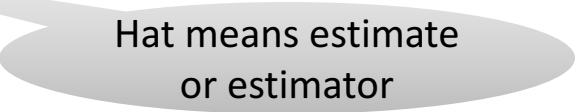
# Statistical Schools of Thought

Remainder of lecture is to provide intuition into how algorithms in this subject come about and inter-relate

Based on Berkeley CS 294-34 tutorial slides by Ariel Kleiner

# Frequentist Statistics

- Abstract problem
  - \* Given:  $X_1, X_2, \dots, X_n$  drawn i.i.d. from some distribution
  - \* Want to: identify unknown distribution
- Parametric approach (“**parameter estimation**”)
  - \* Class of **models**  $\{p_\theta(x): \theta \in \Theta\}$  indexed by **parameters**  $\Theta$  (could be a real number, or vector, or ....)
  - \* Select  $\hat{\theta}(x_1, \dots, x_n)$  some function (or **statistic**) of data
- Examples
  - \* Given  $n$  coin flips, determine probability of landing heads
  - \* Building a classifier is a very related problem



Hat means estimate  
or estimator

# How do Frequentists Evaluate Estimators?

- **Bias:**  $B_{\theta}(\hat{\theta}) = E_{\theta}[\hat{\theta}(X_1, \dots, X_n)] - \theta$
- **Variance:**  $Var_{\theta}(\hat{\theta}) = E_{\theta}[(\hat{\theta} - E_{\theta}[\hat{\theta}])^2]$ 
  - \* **Efficiency:** estimate has minimal variance

Subscript  $\theta$   
means data really  
comes from  $p_{\theta}$

$\hat{\theta}$  still function of  
data

- Square loss vs bias-variance

$$E_{\theta}[(\theta - \hat{\theta})^2] = [B(\theta)]^2 + Var_{\theta}(\hat{\theta})$$

- **Consistency:**  $\hat{\theta}(X_1, \dots, X_n)$  converges to  $\theta$  as  $n$  gets big

... more on this later in the subject ...

# Is this “*Just Theoretical*”™ ?

- Recall Lecture 1 →
- Those evaluation metrics? They’re just estimators of a performance parameter
- Example: error
- Bias, Variance, etc. indicate quality of approximation

COMP90051 Machine Learning (S2 2017)

L1

## Evaluation (Supervised Learners)

- How you measure quality depends on your problem!
- Typical process
  - \* Pick an **evaluation metric** comparing label vs prediction
  - \* Procure an independent, labelled **test set**
  - \* “Average” the evaluation metric over the test set
- Example evaluation metrics
  - \* Accuracy, Contingency table, Precision-Recall, ROC curves
- When data poor, **cross-validate**

22

# Maximum-Likelihood Estimation

- A **general principle** for designing estimators
- Involves **optimisation**
- $\hat{\theta}(x_1, \dots, x_n) = \operatorname{argmax}_{\theta \in \Theta} \prod_{i=1}^n p_{\theta}(x_i)$ 
  - \* Question: Why a *product*?



Fischer

# Example I: Normal

- Know data comes from Normal distribution with variance 1 but unknown mean; find mean

- MLE for mean

- \*  $p_{\theta}(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}(x - \theta)^2\right)$

- \* Maximising likelihood yields  $\hat{\theta} = \frac{1}{n} \sum_{i=1}^n x_i$

- Exercise: derive MLE for *variance*  $\sigma^2$  based on

$$p_{\theta}(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2\sigma^2}(x - \mu)^2\right) \text{ with } \theta = (\mu, \sigma^2)$$

## Example II: Bernoulli

- Know data comes from Bernoulli distribution with unknown parameter (e.g., biased coin); find mean
- MLE for mean

- \*  $p_{\theta}(x) = \begin{cases} \theta, & \text{if } x = 1 \\ 1 - \theta, & \text{otherwise} \end{cases} = \theta^x (1 - \theta^{1-x})$

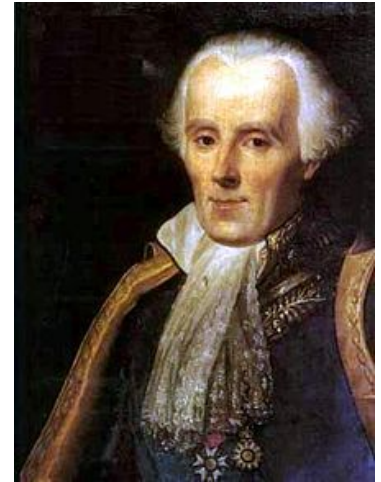
- \* Maximising likelihood yields  $\hat{\theta} = \frac{1}{n} \sum_{i=1}^n x_i$



# MLE 'algorithm'

1. given data  $x_1, \dots, x_n$  **define** probability distribution,  $p_\theta$ , assumed to have **generated the data**
2. express likelihood of data,  $\prod_{i=1}^n p_\theta(x_i)$   
(usually its **logarithm... why?**)
3. optimise to find *best* (most likely) parameters  $\hat{\theta}$ 
  1. take partial derivatives of log likelihood wrt  $\theta$
  2. set to 0 and solve  
(failing that, use iterative gradient method)

# Bayesian Statistics



Laplace

- Probabilities correspond to **beliefs**
- Parameters
  - \* Modeled as r.v.'s having distributions
  - \* Prior belief in  $\theta$  encoded by **prior distribution**  $P(\theta)$
  - \* Write likelihood of data  $P(X)$  as conditional  $P(X|\theta)$
  - \* Rather than point estimate  $\hat{\theta}$ , Bayesians update belief  $P(\theta)$  with observed data to  $P(\theta|X)$  the **posterior distribution**

# More Detail (Probabilistic Inference)

- Bayesian machine learning
  - \* Start with prior  $P(\theta)$  and likelihood  $P(X|\theta)$
  - \* Observe data  $X = x$
  - \* Update prior to posterior  $P(\theta|X = x)$
- We'll later cover tools to get the posterior
  - \* **Bayes Theorem**: reverses order of conditioning

$$P(\theta|X = x) = \frac{P(X = x|\theta)P(\theta)}{P(X = x)}$$

- \* **Marginalisation**: eliminates unwanted variables

$$P(X = x) = \sum_t P(X = x, \theta = t)$$



Bayes

# Example

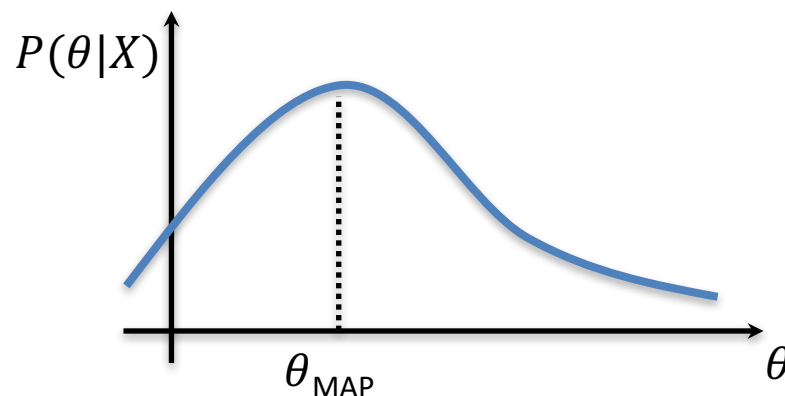
- We model  $X|\theta$  as  $N(\theta, 1)$  with prior  $N(0,1)$
- Suppose we observe  $X=1$ , then update posterior

$$\begin{aligned} P(\theta|X=1) &= \frac{P(X=1|\theta)P(\theta)}{P(X=1)} \\ &\propto P(X=1|\theta)P(\theta) \\ &= \left[ \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{(1-\theta)^2}{2}\right) \right] \left[ \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{\theta^2}{2}\right) \right] \\ &\propto N(0.5, 0.5) \end{aligned}$$

NB: allowed to push **constants** out front and “ignore” as these get taken care of by normalisation

# How Bayesians Make Point Estimates

- They don't, unless forced at gunpoint!
  - \* The posterior carries full information, why discard it?
- But, there are common approaches
  - \* Posterior mean  $E_{\theta|X}[\theta] = \int \theta P(\theta|X) d\theta$
  - \* Posterior mode  $\operatorname{argmax}_{\theta} P(\theta|X)$  (**max a posteriori** or MAP)



# MLE in Bayesian context

- MLE formulation: find parameters that best fit data

$$\hat{\theta} = \operatorname{argmax}_{\theta} P(X = x|\theta)$$

- Consider the **MAP** under a Bayesian formulation

$$\hat{\theta} = P(\theta|X = x)$$

$$= \operatorname{argmax}_{\theta} \frac{P(X = x|\theta)P(\theta)}{P(X = x)}$$

$$= \operatorname{argmax}_{\theta} P(X = x|\theta)P(\theta)$$

- Difference is **prior**  $P(\theta)$ ; assumed *uniform* for MLE

# Parametric vs Non-Parametric Models

Parametric	Non-Parametric
Determined by fixed, finite number of parameters	Number of parameters grows with data, potentially infinite
Limited flexibility	More flexible
Efficient statistically and computationally	Less efficient

*Examples to come! There are non/parametric models in both the frequentist and Bayesian schools.*

# Generative vs. Discriminative Models

- $X$ 's are instances,  $Y$ 's are labels (supervised setting!)
  - \* Given: i.i.d. data  $(X_1, Y_1), \dots, (X_n, Y_n)$
  - \* Find model that can predict  $Y$  of new  $X$
- Generative approach
  - \* Model full joint  $P(X, Y)$
- Discriminative approach
  - \* Model conditional  $P(Y|X)$  only
- Both have pro's and con's

*Examples to come! There are generative/discriminative models in both the frequentist and Bayesian schools.*



# Summary

- Philosophies: frequentist vs. Bayesian
- Principles behind many learners:
  - \* MLE
  - \* Probabilistic inference, MAP
- Discriminative vs. Generative models