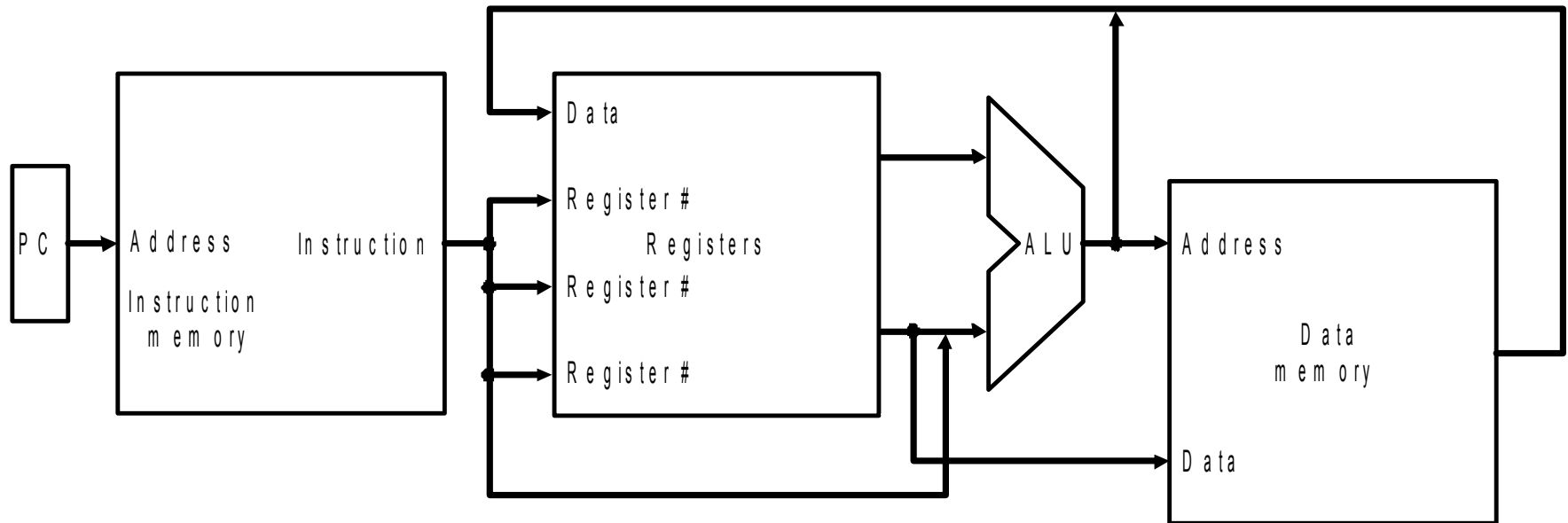
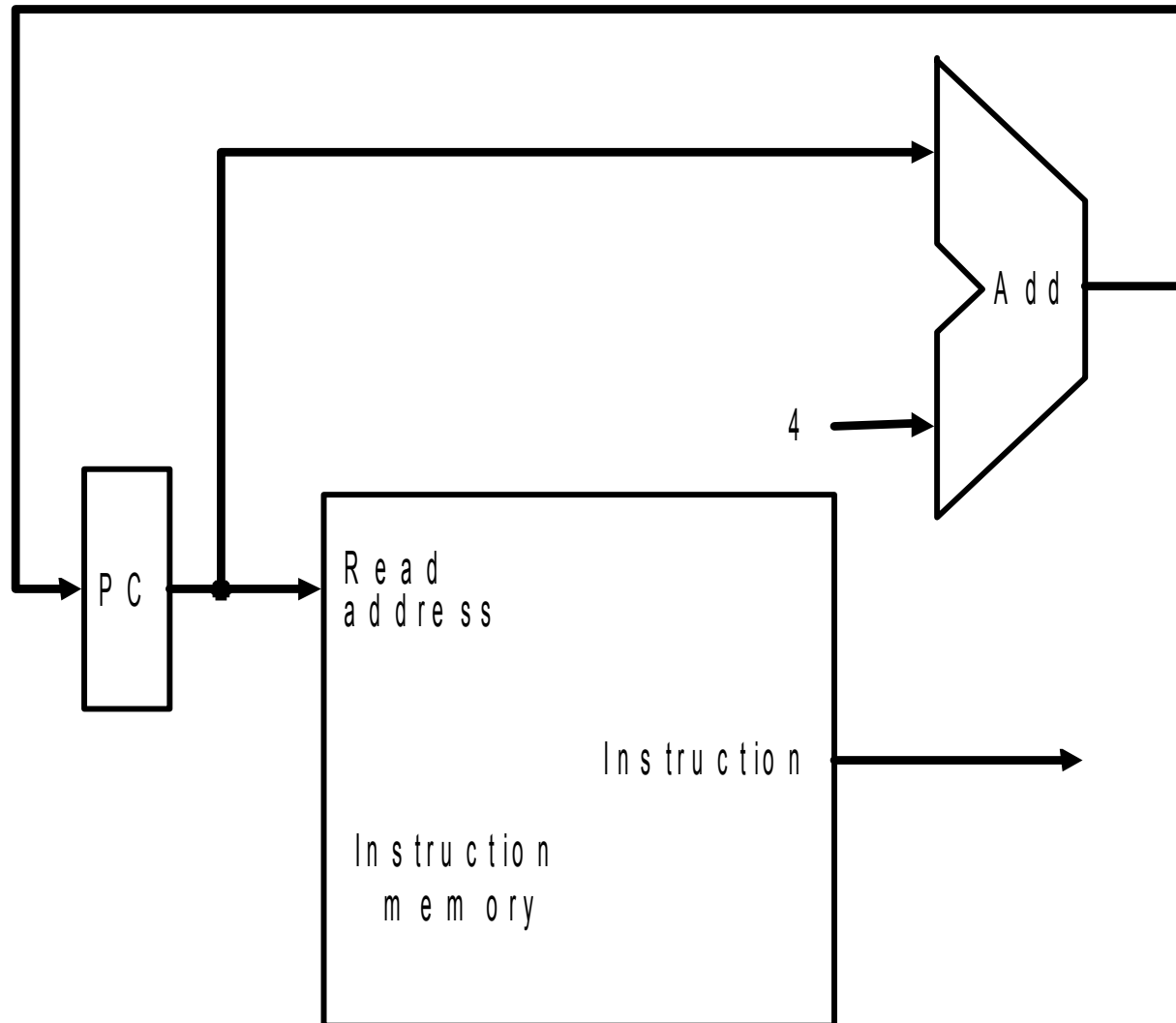

❑ MIPS Instruction Set Processor

Basic Abstract View of the Data Path

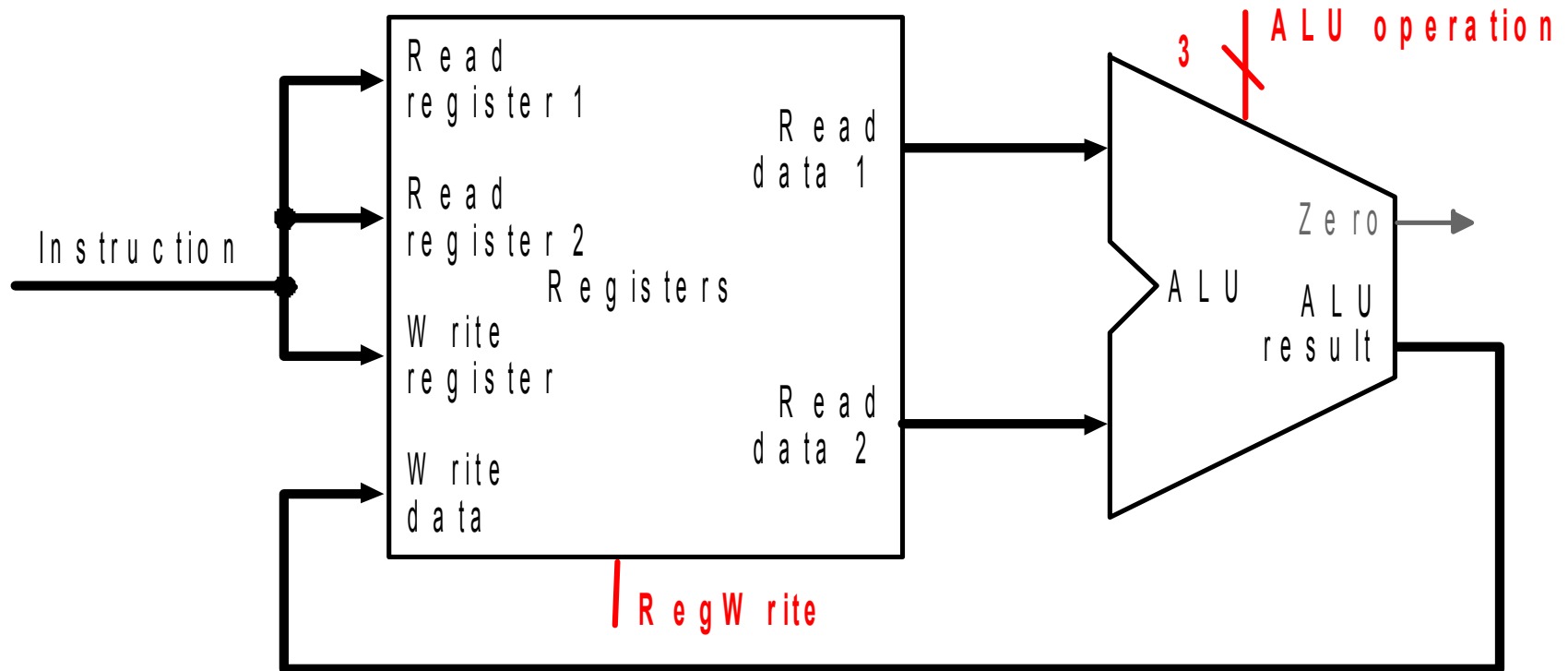


Shows common functions for most instructions

Data Path for Instruction Fetching

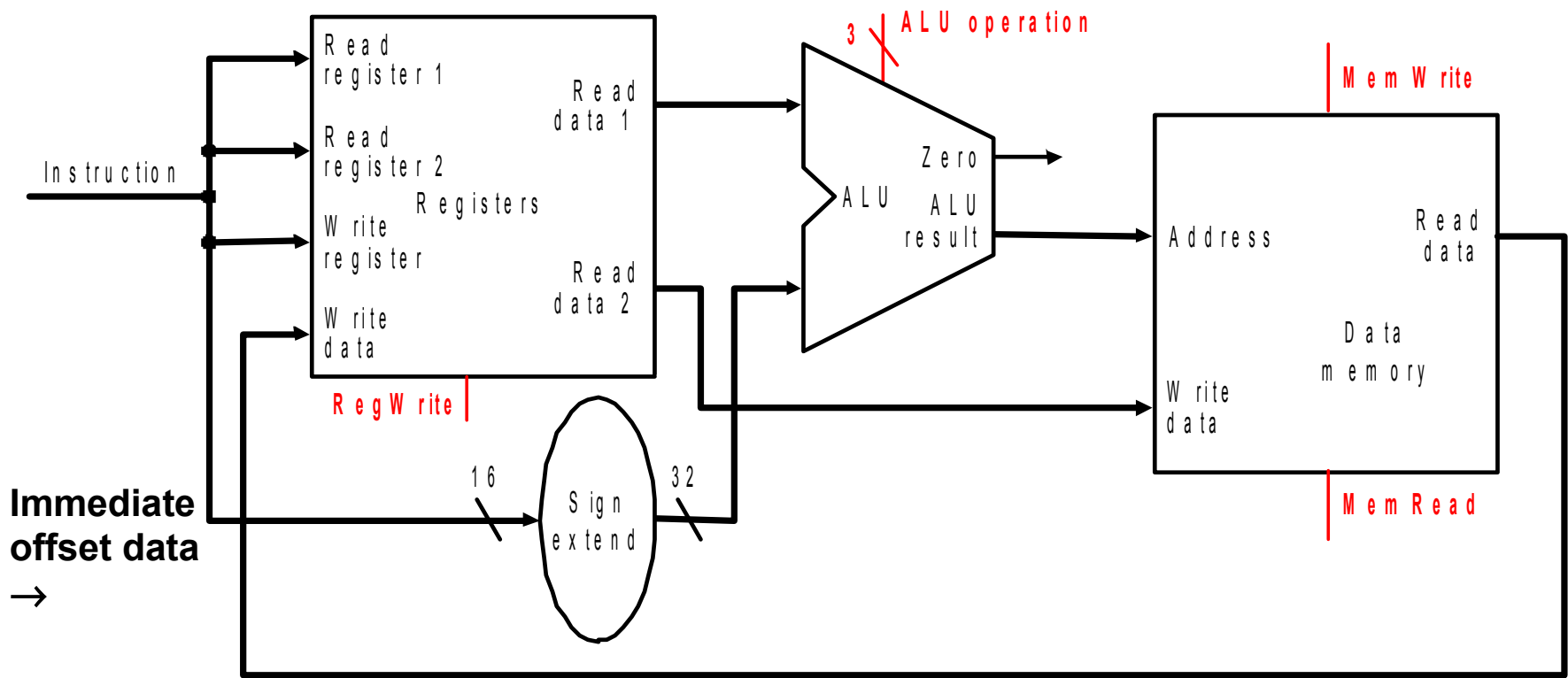


Basic Data Path for R-type Instruction



Red lines are for control signals generated by the controller

Adding the Data Path for lw & sw Instruction



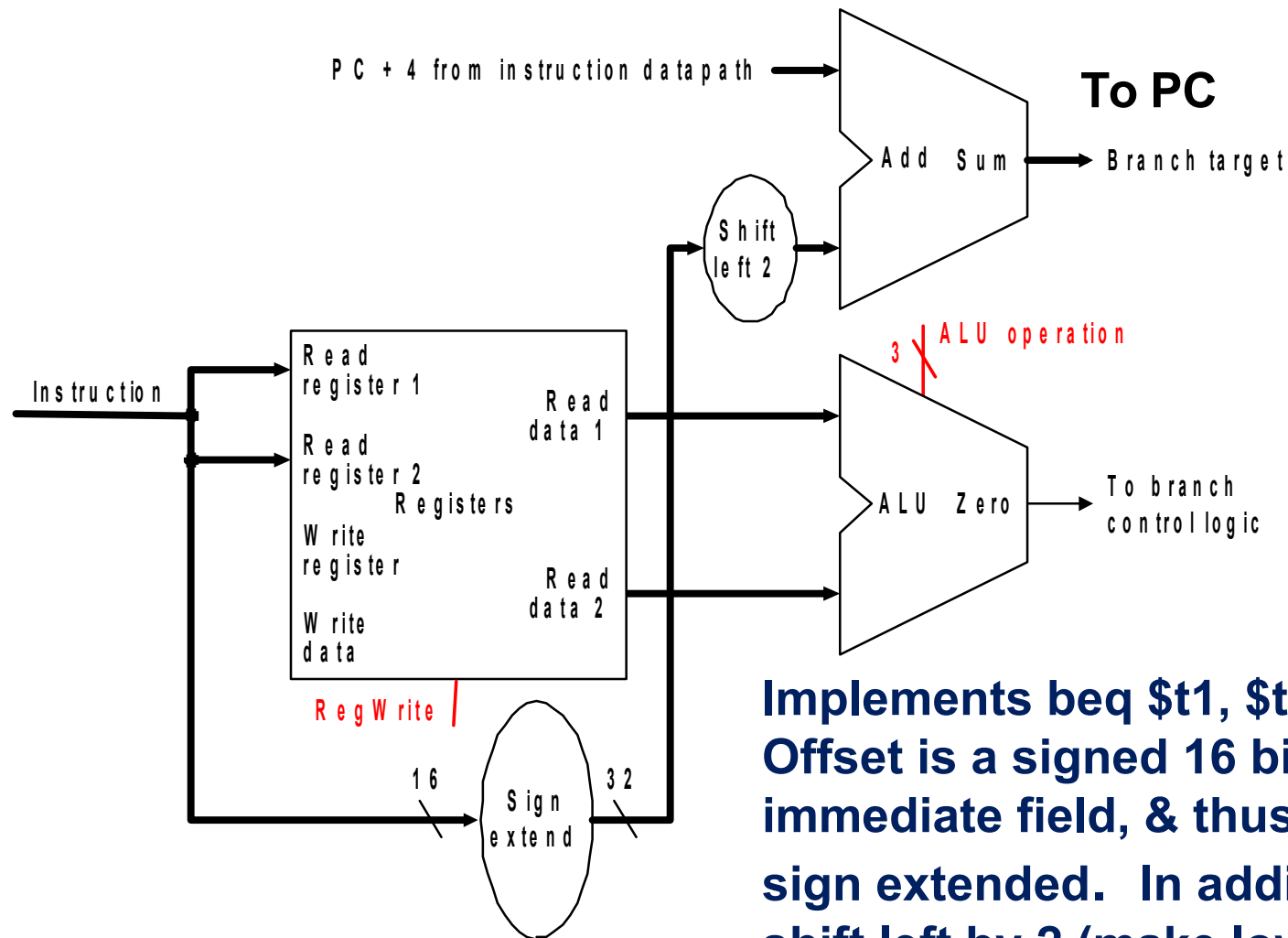
Implements:

`lw $t1, offset_value($t2)`

`sw $t1, offset_value($t2)`

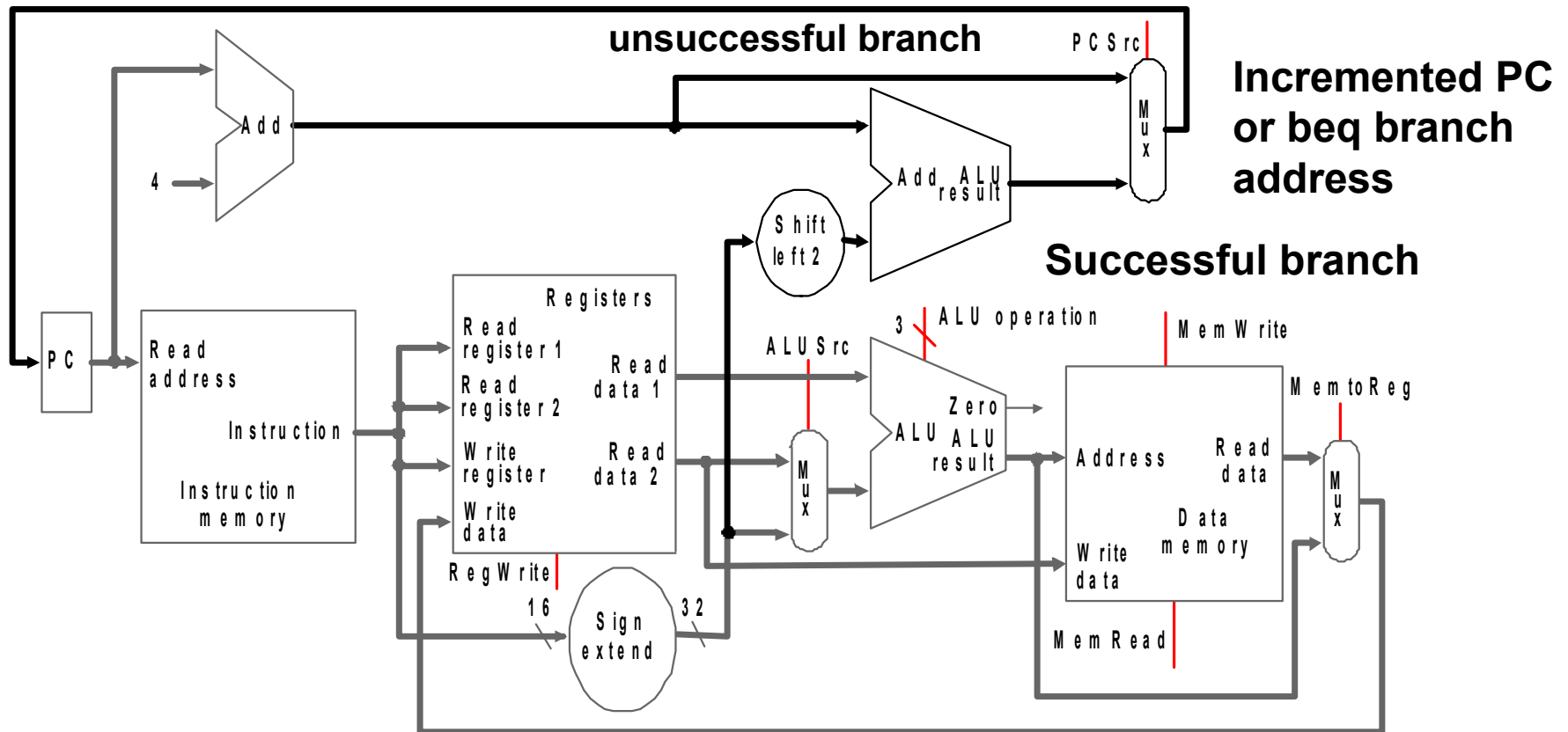
The offset value is a 16-bit signed immediate field & must be sign extended to 32 bits

Adding the Data Path for beq Instruction



Implements beq \$t1, \$t2, offset
Offset is a signed 16 bit immediate field, & thus must be sign extended. In addition we shift left by 2 (make low bits are 00) to address to a word boundary

Putting It All Together



j instruction to be added later

Need control circuits to drive control lines in red.

Two control units will be designed: ALU Control & “Main Control

Instruction	RegDst	RegWrite	ALUSrc	MemRead	MemWrite	MemToReg	PCSrc	ALU operation
R-format	1	1	0	0	0	0	0	0000 (and) 0001 (or) 0010 (add) 0110 (sub)
lw	0	1	1	1	0	1	0	0010 (add)
sw	X	0	1	0	1	X	0	0010 (add)
beq	x	0	0	0	0	X	1 or 0	0110 (sub)

Control

- ❑ **We next add the control unit that generates**
 - write signal for each state element
 - control signals for each multiplexer
 - ALU control signal
- ❑ **Input to control unit: instruction opcode and function code**

Control Unit

❑ Divided into two parts

■ Main Control Unit

- Input: 6-bit opcode
- Output: all control signals for Muxes, RegWrite, MemRead, MemWrite and a 2-bit ALUOp signal

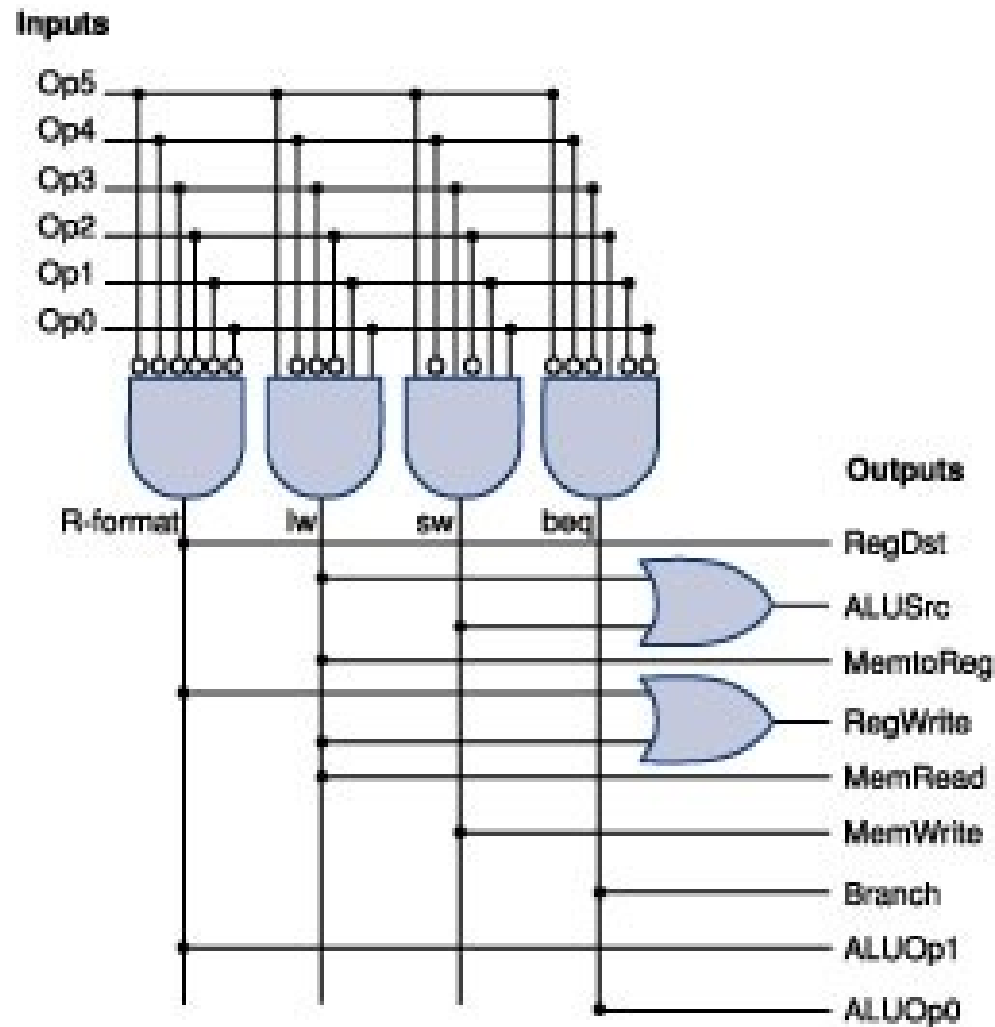
■ ALU Control Unit

- Input: 2-bit ALUOp signal generated from Main Control Unit and 6-bit instruction function code
- Output: 4-bit ALU control signal

Truth Table for Main Control Unit

Input or output	Signal name	R-format	lw	sw	beq
Inputs	Op5	0	1	1	0
	Op4	0	0	0	0
	Op3	0	0	1	0
	Op2	0	0	0	1
	Op1	0	1	1	0
	Op0	0	1	1	0
Outputs	RegDst	1	0	X	X
	ALUSrc	0	1	1	0
	MemtoReg	0	1	X	X
	RegWrite	1	1	0	0
	MemRead	0	1	0	0
	MemWrite	0	0	1	0
	Branch	0	0	0	1
	ALUOp1	1	0	0	0
	ALUOp0	0	0	0	1

Main Control Unit



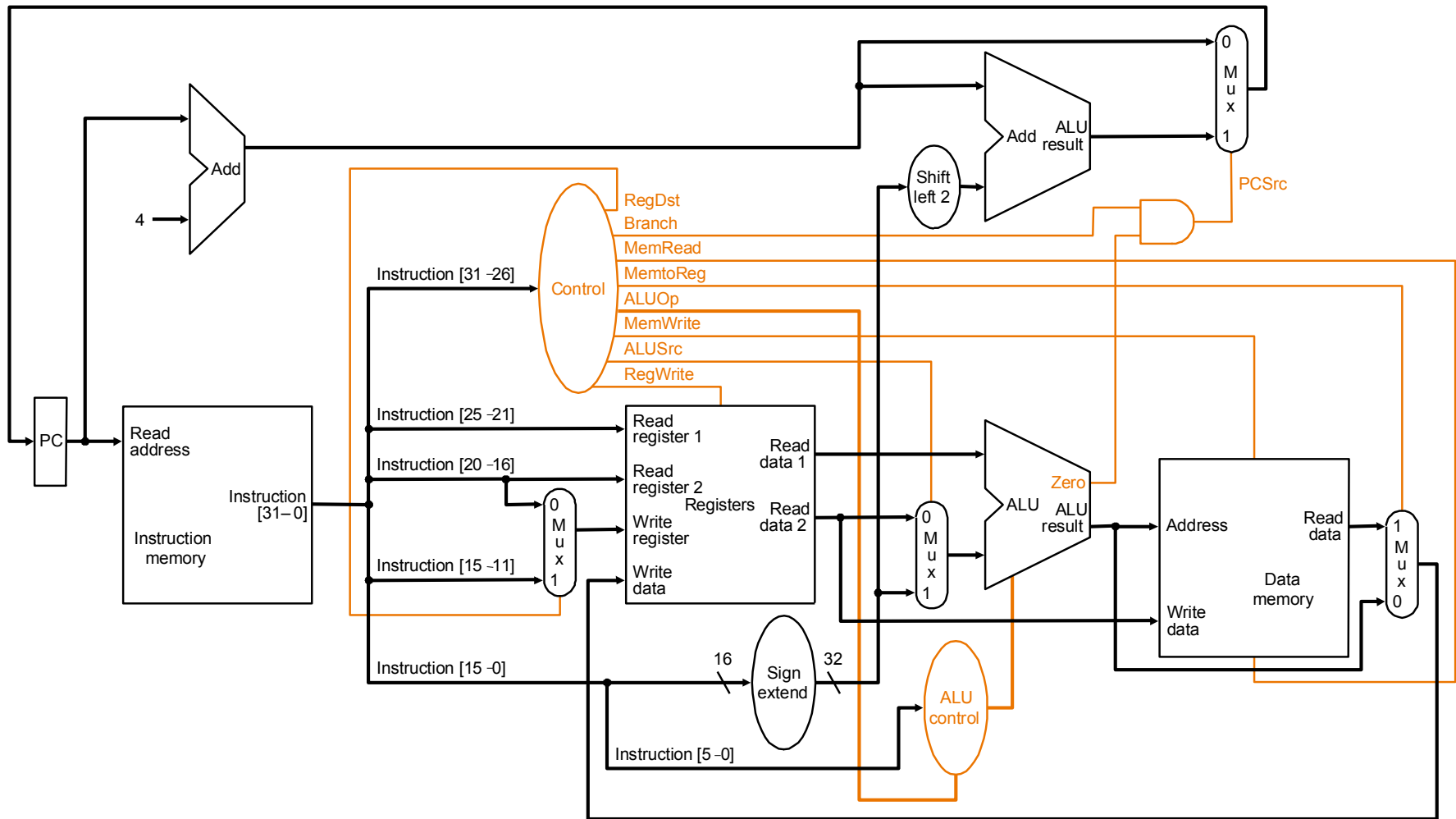
ALU Control Unit

- ❑ **Must describe hardware to compute 4-bit ALU control input given**
 - 2-bit ALUOp signal from Main Control Unit
 - function code for arithmetic
- ❑ **Describe it using a truth table (can turn into gates):**

ALU Control bits

Instruction opcode	ALUOp	Instruction operation	Funct field	Desired ALU action	ALU control input
LW	00	load word	XXXXXX	add	0010
SW	00	store word	XXXXXX	add	0010
Branch equal	01	branch equal	XXXXXX	subtract	0110
R-type	10	add	100000	add	0010
R-type	10	subtract	100010	subtract	0110
R-type	10	AND	100100	and	0000
R-type	10	OR	100101	or	0001
R-type	10	set on less than	101010	set on less than	0111

Putting It All Together Again

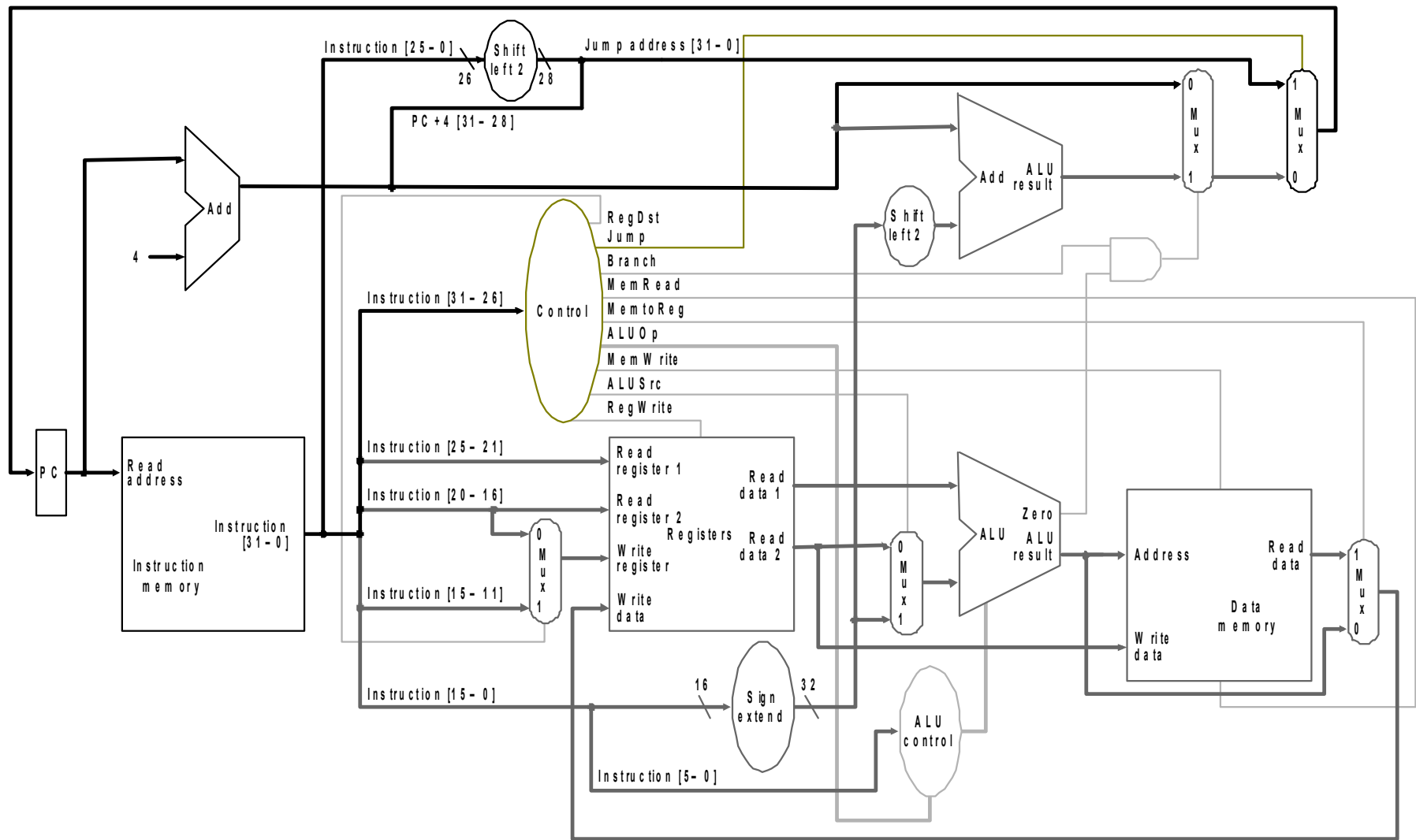


Use this for R-type, memory, & beq instructions scenarios.

Addition of the Unconditional Jump

- ❑ **We now add one more op code to our single cycle design:**
 - Op code 2: “j”
 - The format is op field 28-31 is a “2”
 - Remaining 26 low bits is the immediate target address
- ❑ **The full 32 bit target address is computed by concatenating:**
 - Upper 4 bits of PC+4
 - 26 bit immediate field of the jump instruction
 - Bits 00 in the lowest positions (word boundary)
 - See text chapter 3, p. 150
- ❑ **An additional control line from the main controller will have to be generated to select this “new” instruction**
- ❑ **A two bit shifter is also added to get the two low order zeros**

Final Design with jump Instruction



Thanks!!