

DARSHAN KUMAR JAJORIA

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Education

Indian Institute of Technology (BHU) Varanasi <i>Bachelor of Technology in Civil Engineering</i>	Sep. 2021 – May 2025
Bhartiya Navjeevan Vidyapeeth Sr.Sec.School, Jaipur, Rajasthan <i>Intermediate</i>	2020
Indo Kids Academy, Jaipur, Rajasthan <i>High School</i>	2018
	<i>Percentage- 89.80</i>
	<i>Percentage- 82.83</i>

Technical Skills

Languages & Technologies: Python, SQL, Pandas, NumPy

Area of Interest: Embedded Systems, Computer Vision, Self-driving Technologies, IoT

Interpersonal Skills: Team Work, Problem-Solving, Leadership, Technical Mentorship, Networking

Experience

Rinex	May 2023 - July 2023
Machine Learning Intern Python, SMOTE, Keras, TensorFlow	
<ul style="list-style-type: none">Designed dynamic prediction windows, enabling early intervention and enhancing student success prediction.Engineered 7 features, refined to 5, and optimized performance with SMOTE, scaling, and correlation adjustments.DNN performed best(Accuracy 76%, F1-score 0.74) over Logistic Regression, KNN, DT, Random Forest, XGBoost.	

Projects

Shivaay Controls KiCAD, STM32 CubeIDE	March 2024
<ul style="list-style-type: none">Designed the motor controller circuit using STM32 microcontroller, IR2110 drivers, and IRF1407 MOSFETs.Created the PCB layout in KiCAD, ensuring proper placement for efficient power and thermal management.Developed motor control firmware with six-step commutation, PWM, and speed regulation using hall/encoder signals.Tested and optimized performance, fine-tuning parameters for efficiency and reliable operation. (Test Video)	
Computer Vision for Autonomous EV Python, OpenCV, TensorFlow	February 2023
<ul style="list-style-type: none">Developed and fine-tuned YOLOv5 models for real-time detection, optimizing vehicular perception and navigation.Engineered data pipelines using TensorFlow for efficient preprocessing and augmentation of large datasets.Developed DeepLabV3+ with Xception backbone to enhance road detection and support vehicle path planning.Integrated deep learning models with ROS for low-latency inference in autonomous cars. (Github)-(Test Videos)	
Electric Vehicle Performance Monitoring System Arduino IDE, SoftwareSerial.h	November 2023
<ul style="list-style-type: none">Developed a real-time monitoring system using speed and current sensors to measure key vehicle parameters.Transmitted sensor data via Bluetooth to an onboard mobile app designed with MIT App Inventor.Designed an I2C-based interface for real-time in-vehicle data visualization on a display unit.Integrated MQTT protocol in the app to upload performance data to a website for remote monitoring.	

Leadership / Extracurricular

Team AVERERA	July 2023 – July 2024
<i>Project Manager SHIVAAY</i>	<i>IIT (BHU)</i>
<ul style="list-style-type: none">Managed and supervised the technical development, administration, and finances of a team of 18 active members.Secured sponsorship and mentorship from RIGOL Technologies and e-con Systems to facilitate industrial collaboration.Enhanced the efficiency of the Urban Concept Vehicle "SHIVAAY" to 144 km/kWh on campus roads.	

Honours & Achievements

- Secured **1st** Place in **Technical Innovation & Carbon Footprint Reduction** at Shell Eco-Marathon 2025, Qatar.
- Secured **6th** Position in On-track Award with **83.6 km/kWHR** in battery electric category **SEM ASIA 2025**, Qatar.
- Secured **1st** Position in Carbon Footprint Reduction Award at **Shell Eco-Marathon 2023**, organized in Indonesia.
- Secured **6th** Position globally in the Shell Eco-Marathon Autonomous Programming Competition 2023.
- Achieved **SAE level 3** autonomy on Team AVERERA's test vehicle using a **3D-LiDAR** and Pure Pursuit.
- Won **\$100** Wild Card Prize at **ALTIRE Global** Student Contest, February 2024.