

- d) Explain the procedure for designing a FIR filter using the Kaiser window.

OR

What is impulse invariant technique? Obtain the mapping formula for the impulse invariant transformation.

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**EC-603**

**B.E. VI Semester**

Examination, December 2016

**Digital Signal Processing**

*Time : Three Hours*

*Maximum Marks : 70*

- www.rgpvonline.in **Note:** i) Answer five questions. In each question part A, B, C is compulsory and D part has internal choice.  
 ii) All parts of each question are to be attempted at one place.  
 iii) All questions carry equal marks, out of which part A and B (Max. 50 words) carry 2 marks, part C (Max. 100 words) carry 3 marks, part D (Max. 400 words) carry 7 marks.  
 iv) Except Numericals, Derivation, Design and Drawing etc.

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### Unit-I

1. a) Define and explain discrete time linear time invariant system.
- b) Determine if the following system is time invariant or time variant  $y(n) = x(n) \cos \omega_0 n$
- c) Explain and differentiate the following :
  - i) Causal versus noncausal system
  - ii) Linear Versus nonlinear system
- d) Show that for a linear time invariant system, if the input sequence is  $x(n)$  and impulse response is  $h(n)$ , then the

output  $y(n)$  is given by 
$$y(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$

[2]

OR

Determine the output  $y(n)$  of a relaxed linear time invariant system with impulse response  $h(n) = a^n u(n)$ ,  $|a| < 1$  when the input is a unit step sequence that is  $x(n) = u(n)$

**Unit-II**

2. a) Define Z-transform and explain its use.
- b) Define Region of convergence and explain the significance of ROC in Z-plane.
- c) Determine the Z-transform of the signal

$$x(n) = \left(\frac{1}{2}\right)^n u(n).$$

- d) State and prove the following properties of Z-transform.
  - i) Time shifting
  - ii) Convolution

OR

Determine the system function and the unit sample response of the system described by the difference

$$\text{equation } y(n) = \frac{1}{2} y(n-1) + 2x(n).$$

**Unit-III**

3. a) Define DFT for a sequence  $x(n)$ .
- b) Define circular convolution. What is the difference between circular and linear convolutions.

[3]

- c) State and prove the following property of DFT.
  - i) Periodicity
  - ii) Linearity
- d) A finite duration sequence of length  $L$  is given as

$$x(n) = \begin{cases} 1 & 0 \leq n \leq L-1 \\ 0 & \text{otherwise} \end{cases}$$

Determine the N-point DFT of this sequence for  $N \geq L$

OR

Compute the DFT of the four point sequence  $x(n) = (0 \ 1 \ 2 \ 3)$

**Unit-IV**

4. a) Why is FFT called so?
- b) State the computational requirements of FFT.
- c) Explain the difference between decimation in time and decimation in frequency FFT algorithm.
- d) Draw the flow graph of an eight point decimation in time FFT algorithm.

OR

Given  $x(n) = \{1, 2, 3, 4, 4, 3, 2, 1\}$  find  $X(k)$  using decimation in time FFT algorithm.

**Unit-V**

5. a) Define FIR filter and IIR filter.
- b) Compare FIR filter with IIR filters.
- c) What is bilinear transformation method of designing IIR filter? Explain.