

# ANUJITH MURALEEDHARAN

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## EDUCATION

### Rajiv Gandhi Institute of Technology

August 2018 – August 2022

*Bachelor of Technology in Electronics and Communication Engineering GPA: 8.16/10*

*Kottayam, India*

### Amrita Vidyalayam

April 2014 – March 2017

*Class XII AISSCE, CBSE; 85% ; Class X AISSE, CBSE; 9.8/10.0*

*Pandalam, India*

## RESEARCH EXPERIENCE

### Indian Institute of Science

August 2023 – Present

*I3D LAB, Research Associate Guided by Prof. Pradipta Biswas*

*Bangalore, India*

- Co-authored a journal paper focusing on a computer vision-based autonomous aircraft taxiing system.
- Served as lead author on a short paper on the rehabilitation of individuals with Severe Speech and Motor Impairments (SSMI).
- Involved in an ISRO-funded project focused on developing a Mixed Reality (MR) environment using Unity customized for the astronaut cockpit, aligning with preparations for the upcoming Gaganyaan mission.
- Developed a novel computer vision algorithm for localizing stamp locations and devised a segmentation model for hand and forearm identification, enhancing precision in robotic interactions for Eye-gaze controlled robots, prioritizing safety inspired by Asimov's Laws.

### Rajiv Gandhi Institute of Technology

Jan 2021 – June 2022

*CASP LAB, Undergraduate Research Assistant Guided by Prof. Manju Manuel*

*Kottayam, India*

- Assisted in the FPGA implementation research focused on a Convolutional Neural Network (CNN) accelerator using a modified Booth multiplier and Wallace tree adder on the UniWiG architecture.
- Conducted comprehensive literature review and comparative analysis of existing FPGA implementations
- Developed a functional prototype of a 3D hologram with gesture controller using Raspberry Pi 4, employing unique algorithms with OpenCV and MediaPipe.
- Explored optimization techniques for the Pepper's Ghost phenomenon, including acrylic sheet tilt angle and thickness variation, to enhance image quality

## PUBLICATIONS

### Eye-Gaze-Enabled Assistive Robotic Stamp Printing System for Individuals with SSMI

March 2024

[[https://drive.google.com/file/d/1M8BGHj2CGJxLX8PAPL79frMIxsQu2T2A/view?usp=drive\\_link](https://drive.google.com/file/d/1M8BGHj2CGJxLX8PAPL79frMIxsQu2T2A/view?usp=drive_link)]

- Developed the User Interface to facilitate user interaction and control over the robotic system
- Utilized MATLAB for conducting simulations to validate system behavior and performance.
- Executed inverse kinematics calculations to ensure precise positioning of the manipulator and found homogeneous transformation matrix for accurate spatial mapping.

### Developing a computer vision based system for autonomous taxiing of aircraft

December 2023

[<https://doi.org/10.3846/aviation.2023.20588>]

- Developed state space kinematic model for the robot and formulated an algorithm for sensor fusion.
- Integrated proximity sensors with object detection models to enhance the robot's perception capabilities.
- Designed and assessed the performance of four controllers (LQR, PD, Stanley, SMC) to identify the most effective one for precise trajectory tracking.

## TEACHING EXPERIENCE

### Undergraduate Course Assistant, RIT Kottayam

August 2020 – May 2021

*Introduction to Electronics Engineering BE10104*

*Kottayam, India*

- Diodes (intrinsic and extrinsic semiconductors), PN junction diodes, and their characteristics.
- BJT structure, operation principles, configurations (common base, common emitter), input/output characteristics, biasing techniques, and amplifier applications.
- Discussed diode circuits (series/parallel), rectifiers (half-wave/full-wave), voltage multipliers, clipper/clamper circuits, and power supply design including capacitor filters and zener voltage regulators.
- Conducted first Internal examinations and evaluated assignments

## PROFESSIONAL EXPERIENCE

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### NSS Indian Institute of Technology, Roorkee

July - August 2023

*Industrial Training*

*Remote*

- Completed 6 Weeks (60 hours) Industrial Training on Machine Learning and Artificial Intelligence.

## AWARDS

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### Technoxian World Robotics Championship

July 2023

*AICRA*

- Participated in innovation contest in which around 150 teams participated
- Selected for presentation at Noida NCR, India

### Graduate Aptitude Test in Engineering (GATE)

February 2023

*IIT Kanpur*

- Achieved an overall rank within the top 1.58 percentile among 70,361 candidates registered in the Electronics and Communication Engineering stream.
- Provisionally selected for M.Tech. Programme after written Test and Interview on offline mode under (RA/RAP) category
- Offered admission to M.Tech. Programme in IIT Madras and IIT Kharagpur

## PROGRAMMING SKILLS

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**Languages:** Python, C/C++, C#, JavaScript, SQL

**Tools:** VS Code, Sublime Text Editor, CATIA V5, ROS, ROS-2, AutoDesk, RoboGuide, Fusion 360, Ansys, GIT, Unity

**Frameworks:** Linux, TensorFlow, PyTorch, OpenCV, NumPY

## SERVICE

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### Prominence

January 2021

*Chief Organizer*

*Department TechFest*

- Organized a competition on fastest line follower robot with a total participation of 10 teams. The objective of the robot is to efficiently navigate through a predefined course by detecting and tracking a black line.
- Conducted a seminar on Solar Electric Propulsion
- Conducted a workshop on Advanced Driver Assistance Systems (ADAS)