

WEC-Sim Webinar #1

BEMIO and MCR

April 18, 2017

Yi-Hsiang Yu and Jennifer van Rij (NREL) Kelley Ruehl (Sandia)

Introduction



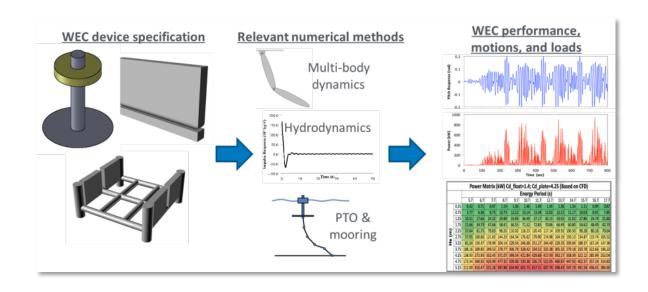
WEC-Sim Team

- Kelley Ruehl (Sandia)
- Yi-Hsiang Yu (NREL)
- Jennifer van Rij (NREL)









Schedule



Advanced Feature Webinars 1hr each

- April 18: bemio and mcr, application for power matrix
- May 24: nl-hydro, b2b, non-hydro and drag
- June 7: pto and control, application for desalination
- July 18: mooring and visualization

Training Courses

- May 1: 1hr WEC-Sim workshop at METS, for new users
- TBD: half-day WEC-Sim code structure course, for advanced users/developers

WEC-Sim Webinar #1



BEMIOBEM Input/Output

Jennifer van Rij (NREL)

BEMIO - Overview



- What is BEMIO?
 - Workflow
 - Purpose
 - History
 - Locations
- BEMIO Functions
 - Read_WAMIT
 - Read_NEMOH
 - Read_AQWA
 - Normalize
 - Combine_BEM
 - Radiation_IRF
 - Radiation_IRF_SS
 - Excitation_IRF
 - Write_H5
 - Plot_BEMIO

- Examples and Usage
 - WAMIT example
 - NEMOH example w/ WAMIT comparison example
 - Data structures
- Possible Improvements
 - Documentation
 - Read AQWA
 - Meshing & visualization
 - Post-processing functions
 - Integration with Nemoh

What is BEMIO



- Workflow: BEM → BEMIO → WEC-Sim
 - The BEMIO (<u>B</u>oundary <u>E</u>lement <u>M</u>ethod <u>I</u>nput/<u>O</u>utput) functions are used to preprocess the BEM hydrodynamic data prior to running WEC-Sim.

Purpose

- Read BEM results from WAMIT, NEMOH, or AQWA.
- Calculate the radiation and excitation impulse response functions (IRFs).
- Calculate state space realization coefficients for the radiation IRF.
- Save the resulting data in Hierarchical Data Format 5 (HDF5).
- Plot typical hydrodynamic data for user verification.

History

 A few python BEMIO legacies... meshing utilities, .h5 file, MATLAB data structure

Locations

- Functions: ...\WEC-Sim\source\functions\BEMIO
- Documentation: http://wec-sim.github.io/WEC-Sim/features.html#bemio

Read_WAMIT



Reads data from a WAMIT output file

```
bemio.m * +

1 - clc; clear all; close all;
2 - hydro = struct();
3

4 - hydro = Read_WAMIT(hydro,'rm3.out',[]);
5 - hydro = Radiation_IRF(hydro,60,[],[],[],[]);
6 - hydro = Radiation_IRF_SS(hydro,[],[]);
7 - hydro = Excitation_IRF(hydro,157,[],[],[],[]);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
```

hydro = Read_WAMIT(hydro, filename, ex_coeff)

hydro - data structure

filename - WAMIT output file

ex_coeff - flag indicating the type of excitation force coefficients to read, 'diffraction' (default, []), 'haskind', or 'rao'

Notes:

- If generalized body modes (currently only a research application) are used, the output directory must also include the *.cfg, *.mmx, and *.hst files.
- If simu.nlHydro = 3 (not implemented yet) will be used, the output directory must also include the .3fk and .3sc files.



Reads data from a NEMOH working folder

```
bemio.m x +

1 - clc; clear all; close all;
2 - hydro = struct();
3
4 - hydro = Read_NEMOH(hydro,'..\RM3\');
5 - hydro = Radiation_IRF(hydro,60,[],[],[],1.9);
6 - hydro = Radiation_IRF_SS(hydro,[],[]);
7 - hydro = Excitation_IRF_(hydro,157,[],[],[],1.9);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
10
11
```

hydro = Read_NEMOH(hydro, filedir)

hydro - data structure

filedir - NEMOH working folder, must include:

- Nemoh.cal
- Mesh/Hydrostatics.dat (or Hydrostatiscs_0.dat, Hydrostatics_1.dat, etc. for multiple bodies)
- Mesh/KH.dat (or KH_0.dat, KH_1.dat, etc. for multiple bodies)
- Results/RadiationCoefficients.tec
- Results/ExcitationForce.tec
- Results/DiffractionForce.tec If simu.nlHydro = 3 will be used
- Results/FKForce.tec If simu.nlHydro = 3 will be used

Notes:

NEMOH website recently updated; https://lheea.ec-nantes.fr/logiciels-et-brevets/nemoh-running-192930.kjsp?RH=1489591054559

Read_AQWA



Reads data from AQWA output files

hydro = Read_AQWA(hydro, ah1_filename, lis_filename)

```
hydro – data structureah1_filename – .AH1 AQWA output filelis_filename – .LIS AQWA output file
```

Normalize



Normalizes NEMOH and AQWA hydrodynamic coefficients in the same manner that WAMIT outputs are normalized. And, if necessary, sorts data according to ascending frequency (WAMIT).

 $C_{{\rm i},j}/\rho g$ - linear stiffness $A_{{\rm i},j}/\rho g$ - added mass $B_{{\rm i},j}/\rho \omega$ - radiation damping $X_i/\rho g$ - exciting forces

hydro = Normalize(hydro)
hydro - data structure

Combine_BEM



Combines multiple BEM outputs into one hydrodynamic 'system.'

```
hydro = Combine_BEM(hydro)
hydro - data structure
```

```
bemio.m * +

1 - clc; clear all; close all;
2 - hydro = struct();
3

4 - hydro = Read_NEMOH(hydro,'..\RM3\');
5 - hydro = Read_WAMIT(hydro,'..\..\WAMIT\RM3\rm3.out',[]);
6 - hydro = Combine_BEM(hydro); % Compare WAMIT
7 - hydro = Radiation_IRF(hydro,60,[],[],[],1.9);
8 - hydro = Radiation_IRF(hydro,1],[]);
9 - hydro = Excitation_IRF(hydro,157,[],[],[],1.9);
10 - Write_H5(hydro)
11 - Plot_BEMIO(hydro)
```

Radiation_IRF



Calculates the normalized radiation impulse response function:

$$\overline{K}_{i,j}(t) = \frac{2}{\pi} \int_0^\infty \frac{B_{i,j}(\omega)}{\rho} \cos(\omega t) d\omega$$

```
bemio.m * +

1 - clc; clear all; close all;
2 - hydro = struct();
3

4 - hydro = Read_WAMIT(hydro,'rm3.out',[]);
5 - hydro = Radiation_IRF(hydro,60,[],[],[],[]);
6 - hydro = Radiation_IRF_SS(hydro,[],[]);
7 - hydro = Excitation_IRF(hydro,157,[],[],[],[]);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
```

hydro = Radiation_IRF(hydro, t_end, n_t, n_w, w_min, w_max)

hydro - data structure

 t_{end} – calculation range for the IRF, where the IRF is calculated from t = 0 to t_{end} , and the default is 100 s

n_t – number of time steps in the IRF, the default is 1001

n_w – number of frequency steps used in the IRF calculation (hydrodynamic coefficients are interpolated to correspond), the default is 1001

w_min – minimum frequency to use in the IRF calculation, the default is the minimum frequency from the BEM data

w_**max** – maximum frequency to use in the IRF calculation, the default is the maximum frequency from the BEM data.

Radiation_IRF_SS



Calculates the state space (SS) realization of the radiation IRF. If this function is used, it must be implemented after the Radiation_IRF function.

```
bemio.m * +

1 - clc; clear all; close all;
2 - hydro = struct();
3
4 - hydro = Read_WAMIT(hydro,'rm3.out',[]);
5 - hydro = Radiation_IRF(hydro,60,[],[],[],[]);
6 - hydro = Radiation_IRF_SS(hydro,[],[]);
7 - hydro = Excitation_IRF(hydro,157,[],[],[],[]);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
```

hydro = Radiation_IRF_SS(hydro, Omax, R2t)

hydro - data structure

Omax – maximum order of the SS realization, the default is 10

R2t – R2 threshold (coefficient of determination) for the SS realization, where **R2** may range from 0 to 1, and the default is 0.95

Calculates the excitation impulse response function:

$$\overline{K}_{i}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{X_{i}(\omega, \beta)}{\rho g} e^{i\omega t} d\omega$$

hydro = Excitation_IRF(hydro, t_end, n_t, n_w, w_min, w_max)

hydro - data structure

t_end - calculation range for the IRF, where the IRF is calculated from t = -t_end to t_end, and the default is 100 s

n_t - number of time steps in the IRF, the default is 1001

n_w - number of frequency steps used in the IRF calculation (hydrodynamic coefficients are interpolated to correspond), the default is 1001

w_min - minimum frequency to use in the IRF calculation, the default is the minimum frequency from the BEM data

w_max - maximum frequency to use in the IRF calculation, the default is the maximum frequency from the BEM data.



Writes the hydro data structure to a .h5 file.

Write_H5(hydro)
hydro - data structure

```
bemio.m * + 1

1 - clc; clear all; close all;
2 - hydro = struct();

4 - hydro = Read_WAMIT(hydro, 'rm3.out', []);
5 - hydro = Radiation_IRF(hydro, 60, [], [], []);
6 - hydro = Radiation_IRF_SS(hydro, [], []);
7 - hydro = Excitation_IRF(hydro, 157, [], [], []);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
```

Plot_BEMIO



Plots the added mass, radiation damping, radiation IRF, excitation force magnitude, excitation force phase, and excitation IRF for each body in the heave, surge and pitch degrees of freedom.

Plot_BEMIO(hydro)

hydro - data structure

```
bemio.m * +

1 - clc; clear all; close all;
2 - hydro = struct();
3

4 - hydro = Read_WAMIT(hydro, 'rm3.out', []);
5 - hydro = Radiation_IRF(hydro, 60, [], [], [], []);
6 - hydro = Radiation_IRF_SS(hydro, [], []);
7 - hydro = Excitation_IRF(hydro, 157, [], [], [], []);
8 - Write_H5(hydro)
9 - Plot_BEMIO(hydro)
```

Examples and Usage



- BEMIO tutorials\WEC-Sim\tutorials\BEMIO
 - WAMIT
 - Cylinder example
 - NEMOH
 - Cylinder w/WAMIT comparison example
 - AQWA
- Data structures
 - BEMIO
 - http://wec-sim.github.io/WEC-Sim/features.html
 - .h5
 - HDFVIEW: https://support.hdfgroup.org/products/java/hdfview/

Possible Future Improvements



- Documentation
- Read_AQWA
- Meshing/visualization functions
- Post-processing functions
- Integration with Nemoh

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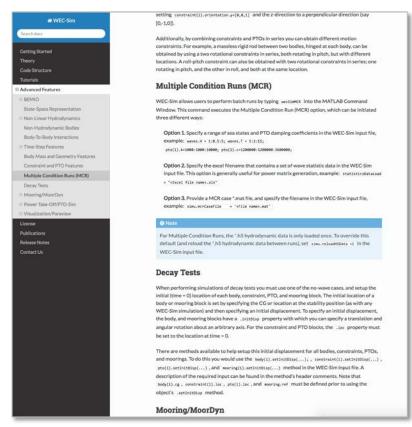
MCR
Multiple Condition Runs

Yi-Hsiang Yu (NREL)

Multiple Condition Runs (MCR)



- WEC-Sim allows users to run multiple cases using wecSimMCR (in the MATLAB Command Window)
- The MATLAB function file (wecSimMCR.m) is located under <WEC-Sim Path>/source/functions.
- Examples are provided in the "WEC-Sim Application" repository https://github.com/WEC-Sim/WEC-Sim_Applications



<u>https://wec-sim.github.io/WEC-</u> <u>Sim/features.html#multiple-condition-runs-mcr</u>

Overview of the MCR Presentation



How does MCR work?

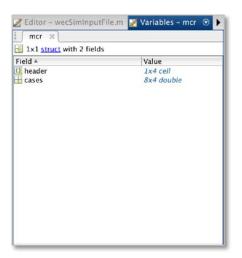
- Examples of running MCR
 https://github.com/WEC-Sim/WEC-Sim_Applications/tree/master/RM3_MCR
 - Specify a range of sea states and PTO damping coefficients
 - Using an excel file that contains a set of wave statistic data
 - User define option

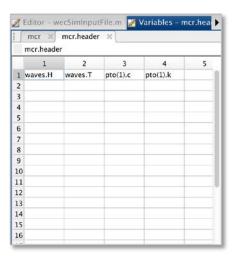
 MCR user defined function (userDefinedFunctionsMCR.m) and Post-processing

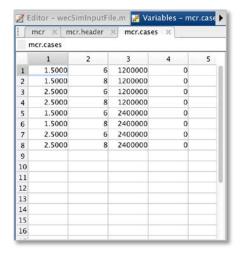
How Does MCR Work?



- Create a mcr function that includes all the parameters that is needed to run all multiple cases one after another automatically.
- mcr function includes:
 - mcr.header: the name of the parameters and functions
 - mcr.cases: the given value or "option" for the parameters and functions







How Does MCR Work?



wecSimMCR will then execute wecSim.m file for each given case

```
wecSimInputFile.m ×
                      wecSimMCR.m × userDefinedFunctionsMCR.m × +
                    if (length(pto(n).c)>1 || length(pto(n).k)>1)
                        numConditions=numConditions+2;
48 -
                        name = sprintf('pto(%i).c', n);
49 -
                        mcr.header{numConditions-1} = name;
                        name = sprintf('pto(%i).k', n);
50 -
                        mcr.header{numConditions } = name;
51 -
                       len = length(mcr.cases(:,1)); kkk = 0;
53 -
                        for l2=1:length(pto(n).k)
55 -
                            for l1=1:length(pto(n).c)
                                kkk=kkk+1;
56 -
                                mcr.cases(len*(kkk-1)+1:len*(kkk-1)+len,1:numConditions-2) = mcr.cases(1:len,1:numConditions-2);
57 -
58 -
                                mcr.cases(len*(kkk-1)+1:len*(kkk-1)+len, numConditions-1) = pto(n).c(l1);
59 -
                                mcr.cases(len*(kkk-1)+1:len*(kkk-1)+len,
                                                                          numConditions) = pto(n).k(l2);
60 -
61 -
                    end
62 -
63 -
                end: clear i j k l1 l2 m n name nseed kkk len numConditions
64 -
65 -
67
       % % Check to see if changing h5 file between runs
       % % If one of the MCR headers is body(#).h5File, then the hydro data will be
       % % loaded from the h5 file for each condition run.
       % % reloadHydroDataFlag = true;
       % if isempty(cell2mat(regexp(mcr.header, 'body\(\d+\).h5File')))
             reloadHvdroDataFlag = false:
              clear hydroData
        % Run WEC-Sim
        warning('off','MATLAB:DELETE:FiteNotFound'); delete('mcrCase*.mat')

for imcr=1:length(mcr.cases(:,1))

            if exist('userDefinedFunctionsMCR.m','file') == 2; userDefinedFunctionsMCR; end
              Store hydrodata in memory for reuse in future runs.
            recoadhoData == 0 && imcr == 1
                                                         % Off->'0', On->'1', (default = 0)
82 -
                for ii = 1:simu.numWecBodies
83 -
84 -
                    hydroData(ii) = body(ii).hydroData;
       end; clear imcr ans hydroData
88
89
```

 For each case, wecSim.m will overwrite the default parameters using the parameters and options described in the mcr function.

MCR Options



This command executes the Multiple Condition Run (MCR) option, which can be initiated three different ways:

- Option 1- Specify a range of sea states and PTO damping coefficients in the WEC-Sim input file.
- Option 2- Specify the excel filename that contains a set of wave statistic data in the WEC-Sim input file.
- Option 3- Provide a MCR case *.mat file, and specify the filename in the WEC-Sim input file.

MCR: Option 1



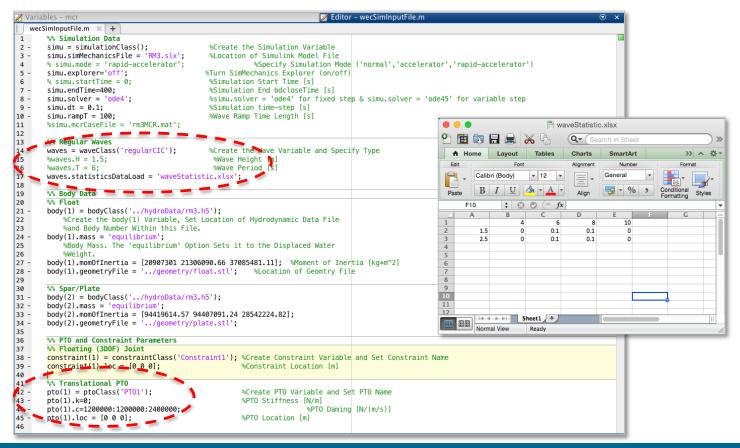
- Specify a range of sea states and PTO damping coefficients in the WEC-Sim input file
- Example: waves.H = 1.5:1:2.5; waves.T = 6:2:8; pto(1).c=1200000:1200000:2400000

```
Editor – wecSimInputFile.m
   wecSimInputFile.m × +
       % Simulation Data
       simu = simulationClass();
                                                %Create the Simulation Variable
       simu.simMechanicsFile = 'RM3.slx';
                                                %Location of Simulink Model File
       % simu.mode = 'rapid-accelerator';
                                                          %Specify Simulation Mode ('normal', 'accelerator', 'rapid-accelerator')
       simu.explorer='off';
                                               %Turn SimMechanics Explorer (on/off)
        % simu.startTime = 0;
                                                %Simulation Start Time [s]
       simu.endTime=400:
                                                %Simulation End bdcloseTime [s]
       simu.solver = 'ode4':
                                                %simu.solver = 'ode4' for fixed step & simu.solver = 'ode45' for variable step
                                                %Simulation time-step [s]
       simu.dt = 0.1;
        simu.rampT = 100;
                                                %Wave Ramp Time Length [s]
        %simu.mcrCaseFile = 'rm3MCR.mat';
       Regular Waves
        waves = waveClass('regularCIC'):
                                                %Create the Wave Variable and Specify Type
        waves.H = 1.5:1:2.5;
                                                      %Wave Height [m]
        waves.T = 6:2:8:
                                                    %Wave Period [s]
17
       % Body Data
       body(1) = bodyClass('hydroData/rm3.h5');
21
            %Create the body(1) Variable, Set Location of Hydrodynamic Data File
22
23 -
24
            %and Body Number Within this File.
       body(1).mass = 'equilibrium';
            %Body Mass. The 'equilibrium' Option Sets it to the Displaced Water
25
        body(1).momOfInertia = [20907301 21306090.66 37085481.11]; %Moment of Inertia [kg*m^2]
27 -
       body(1).geometryFile = 'geometry/float.stl'; %Location of Geomtry File
29
       body(2) = bodyClass('hydroData/rm3.h5');
       body(2).mass = 'equilibrium';
       body(2).momOfInertia = [94419614.57 94407091.24 28542224.82];
33 -
       body(2).geometryFile = 'geometry/plate.stl';
34
        %% PTO and Constraint Parameters
       % Floating (3DOF) Joint
       constraint(1) = constraintClass('Constraint1'); %Create Constraint Variable and Set Constraint Name
        constraint(1).loc = [0 0 0];
                                                        %Constraint Location [m]
       Translational PTO
        pto(1) = ptoClass('PT01');
                                                        %Create PTO Variable and Set PTO Name
        pto(1).k=0;
                                                        %PTO Stiffness [N/m]
        pto(1).c=1200000:1200000:2400000:
                                                                        %PTO Daming [N/(m/s)]
        pto(1).loc = [0 0 0];
```

MCR: Option 2



- Specify the excel filename that contains a set of wave statistic data in the WEC-Sim input file.
- This option is generally useful for power matrix generation, example: waves.statisticsDataLoad = "<Excel file name>.xlsx"



MCR: Option 3



- Provide a MCR case *.mat file, and specify the filename in the WEC-Sim input file, example: simu.mcrCaseFile = '<File name>.mat'
- Option 3 overrules Option 2 & Option 1

```
🌠 Editor – wecSimInputFile.m
   wecSimInputFile.m × +
       %% Simulation Data
       simu = simulationClass();
                                               %Create the Simulation Variable
       simu.simMechanicsFile = 'RM3.slx';
                                               %Location of Simulink Model File
                                                          %Specify Simulation Mode ('normal', 'accelerator', 'rapid-accelerator')
       % simu.mode = 'rapid-accelerator';
       simu.explorer='off';
                                              %Turn SimMechanics Explorer (on/off)
       % simu.startTime = 0;
                                               %Simulation Start Time [s]
                                               %Simulation End bdcloseTime [s]
       simu.endTime=400;
                                               %simu.solver = 'ode4' for fixed step & simu.solver = 'ode45' for variable step
       simu.dt = 0.1;
                                             Simulation time-step [s]
       simu.rampT = 100;
                                               %Wave Ramo Time Length [s]
        simu.mcrCaseFile = 'mcrExample.mat';
        % Regular Waves
      waves = waveClass('regularCIC');
                                                ≰reate the Wave Variable and Specify Type
        waves.H = 1.5;
                                               %Wave Height [m]
15 -
                                               %Wave Period [s]
       waves.T = 8;
17
18
       %% Body Data
       % Float
19
20 -
       body(1) = bodyClass('../hydroData/rm3.h5');
21
            %Create the body(1) Variable, Set Location of Hydrodynamic Data File
22
            %and Body Number Within this File.
23 -
       body(1).mass = 'equilibrium';
24
            %Body Mass. The 'equilibrium' Option Sets it to the Displaced Water
25
26 -
       body(1).momOfInertia = [20907301 21306090.66 37085481.11]; %Moment of Inertia [kg*m^2]
       body(1).geometryFile = '../geometry/float.stl'; %Location of Geomtry File
29
        % Spar/Plate
       body(2) = bodyClass('../hydroData/rm3.h5');
31 -
       body(2).mass = 'equilibrium';
32 -
       body(2).momOfInertia = [94419614.57 94407091.24 28542224.82];
33 -
       body(2).geometryFile = '../geometry/plate.stl';
34
        %% PTO and Constraint Parameters
36
        % Floating (3DOF) Joint
37 -
       constraint(1) = constraintClass('Constraint1'); %Create Constraint Variable and Set Constraint Name
38 -
       constraint(1).loc = [0 0 0];
                                                       %Constraint Location [m]
39
        % Translational PTO
41 -
       pto(1) = ptoClass('PT01');
                                                       %Create PTO Variable and Set PTO Name
       pto(1).k=0;
                                                       %PTO Stiffness [N/m]
43 -
       pto(1).c=1200000;
                                                       %PTO Daming [N/(m/s)]
       pto(1).loc = [0 0 0];
                                                       %PTO Location [m]
```

MCR user defined function & Post-processing



- "userDefinedFunctionsMCR.m" file allows user to add post processing script
 - To analyze the simulation results and create plots automatically
 - To save the SELECTED data from each simulation in different name to
 - Avoid overwriting the output *.mat file under the output folder
 - Minimize the size of the output data for MCR simulations
- imcr is the indexing number for each case

Run multiple MCR cases by using additional instance of MATLAB

Thank you!



Upcoming scheduled webinars and training courses...

Advanced Feature Webinars 1hr each

- May 24: nl-hydro, b2b, non-hydro and drag
- June 7: PTO and control, application for desalination
- **July 18:** Mooring and visualization

Training Courses

May 1: 1hr WEC-Sim workshop at METS, for new users





