

COL215, SUMMER 2023

HARDWARE ASSIGNMENT 2 REPORT

Jakharia Rishit (2022CS11621)

ANUP LAL NAYAK (2022CS51827)

INTRODUCTION

The two parts of this assignment were –

- a) Design and test compute unit, implementation of MAC unit (simple or optimized) for image filtering operation.
- b) Implement FSM (simple or optimized) and integrate it with the hardware design.

PROBLEM DESCRIPTION AS UNDERSTOOD

- A 64*64 image is taken as input provided in row-major format along with a 9*9 filter also provided as a .coe file in the row-major format
- We have to perform matrix operations to filter the image which involves filtering and normalisation
- Then we need to implement as FSM to control the MAC unit
- The output pixels shall now be displayed on the monitor using the vga port

BLOCK DIAGRAMS

Figure 1: Overview of task: filtering

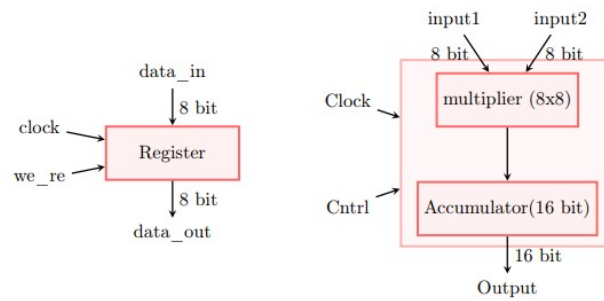
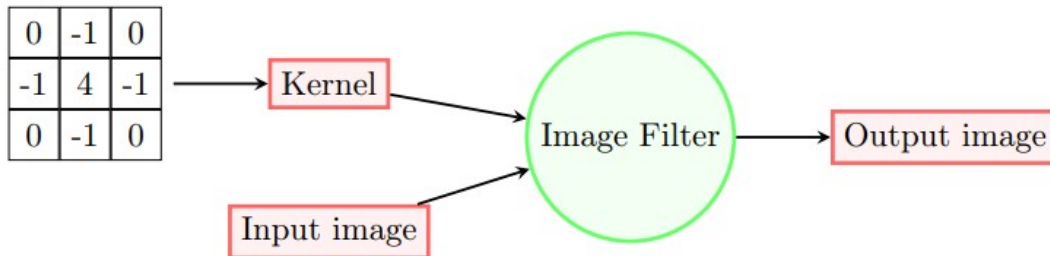


Figure 4: Register and MAC unit

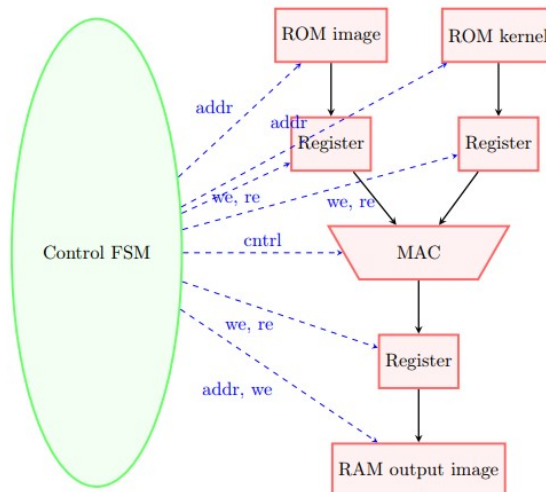


Figure 5: Overview of control path

STRUCTURE ALONG WITH EXPLANATION OF PARTS OF VHDL CODE:

$$O(i, j) = a * I(i - 1, j - 1) + b * I(i - 1, j) + c * I(i - 1, j + 1) \\ + d * I(i, j - 1) + e * I(i, j) + f * I(i, j + 1) \\ + g * I(i + 1, j - 1) + h * I(i + 1, j) + i * I(i + 1, j + 1)$$

– Case I:

$$O(0, 1) = d * I(0, 0) + e * I(0, 1) + f * I(0, 2) \\ + g * I(1, 0) + h * I(1, 1) + i * I(1, 2)$$

– Case II:

$$O(1, 1) = a * I(0, 0) + b * I(0, 1) + c * I(0, 2) \\ + d * I(1, 0) + e * I(1, 1) + f * I(1, 2) \\ + g * I(2, 0) + h * I(2, 1) + i * I(2, 2)$$

- In filtering, we are first using 9 clock cycles to read the filter.coe file kernel and store its values in f1, f2, f3.. f9. These 9 clock cycles are depicted by the changing value of j in our code
- For each output pixel, we are using 9 clock cycles (depicted by the signal k) to read the image.coe file indexes which are required for the calculation of ith output pixel
- Below is an excerpt from the code showing that after j exceeds 9, that is after the .coe file is read, we move to the image.coe reading, also, given the value of k, we are handling the corner cases by modifying the value of i, that is the index of radress variable
- And as shown in the 3rd figure, we calculate the value “calc” after the assing of 9 clock cycles

```
IF (j < 10) THEN
  IF (j = 0) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f0 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 1) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f1 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 2) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f4 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 3) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f7 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 4) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f2 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 5) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f5 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 6) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f8 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 7) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f3 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 8) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f6 <= to_integer(signed(filterdata));
    j <= j + 1;
  ELSIF (j = 9) THEN
    filteraddress <= STD_LOGIC_VECTOR(to_unsigned(j, 4));
    f9 <= to_integer(signed(filterdata));
    j <= j + 1;
  END IF;
END IF;
```

```
IF (j > 9) THEN
  IF k = 0 THEN
    IF (new_sig >= 0 AND new_sig < 4096) THEN
      IF type1 = '0' THEN
        raddress <= STD_LOGIC_VECTOR(to_unsigned(new_sig, 12));
        type1 <= '1';
      ELSE
        a4 <= to_integer(unsigned(data));
        type1 <= '0';
        new_sig <= i;
        k <= 1;
      END IF;
    ELSE
      a4 <= 0;
      new_sig <= i;
      k <= 1;
    END IF;
  END IF;
```

```
IF k = 10 THEN
  IF type1 = '0' THEN
    calc <= f1 * a1 + f2 * a2 + f3 * a3 + f4 * a4 + f5 * a5 + f6 * a6 + f7 * a7 + f8 * a8 + f9 * a9;
    type1 <= '1';
  ELSE
    type1 <= '0';
    IF (to_integer(signed(max)) < calc) THEN
      max <= STD_LOGIC_VECTOR(to_signed(calc, 20));
    END IF;
    IF (to_integer(signed(min)) > calc) THEN
      min <= STD_LOGIC_VECTOR(to_signed(calc, 20));
    END IF;
```

- e) After all the output pixel values are calculated, a new normalisation process starts, We use the normalisation formula that they have given and write the normalised value in ram

$$New_I(i, j) = (I(i, j) - old_min) * \frac{new_max - new_min}{old_max - old_min} + new_min$$

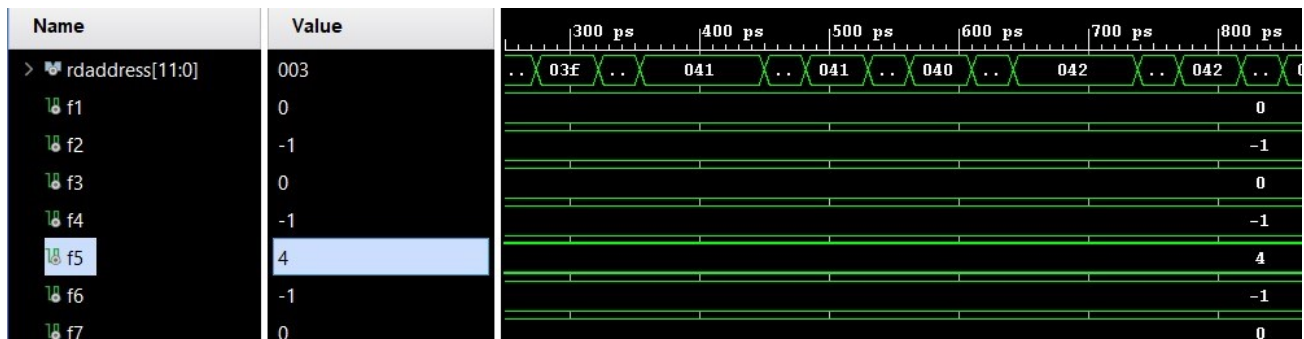
```

IF anup = 1 THEN
    rdaddress <= STD_LOGIC_VECTOR(to_unsigned(i, 12));
    anup <= anup + 1;
ELSIF anup = 2 THEN
    normValue <= (to_integer(signed(data_out)) - to_integer(signed(min))) * 255/difference;
    wr <= '1';
    anup <= anup + 1;
ELSE
    rdaddress <= STD_LOGIC_VECTOR(to_unsigned(i, 12));
    calculated <= STD_LOGIC_VECTOR(to_unsigned(normValue, 20));
    wr <= '0';
    anup <= 1;
END IF;

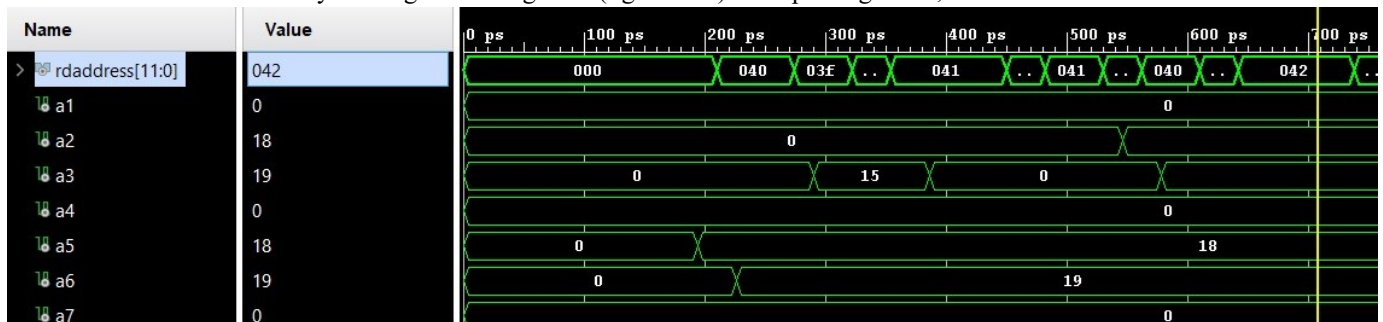
```

SIMULATION SCREENSHOTS:

- a. Correctly reading from kernel and finding values of f1,f2.. f9



- b. Correctly reading from image.coe (lighthouse) and updating data1, data2...data9 values



- c. Correctly calculating minimum and maximum for normalisation calculation

