

Support Vector Machine

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- What is a classification problem?
- How can it be thought as a prediction problem?
- Support Vector Machine (SVM) as classification technique,
 - Received considerable attention
 - SVM has its roots in Statistical learning theory,
 - Shown promising results in many practical applications.
 - For examples:
 - Handwritten digit recognition,
 - Text categorization,

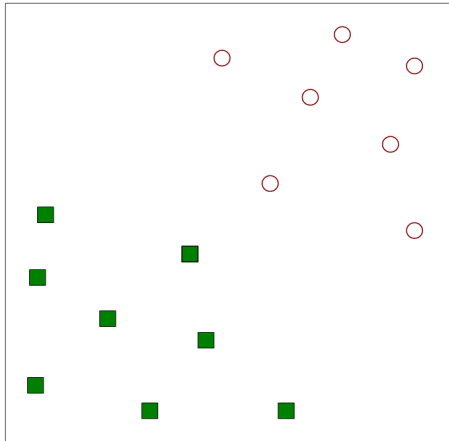


- SVM works very well with
 - High-dimensional data,
 - Avoids the curse of dimensionality problem.
- Another unique aspect of this approach is that
 - it represents the decision boundary using a subset of the training examples, known as the **support vectors**.

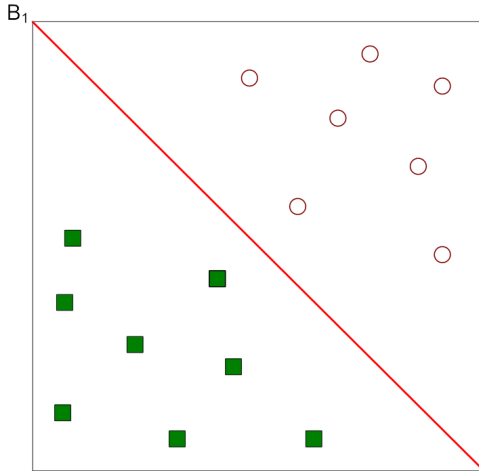
Goal of the SVM

- To find the optimal separating hyperplane
 - which **maximizes the margin** of training data.

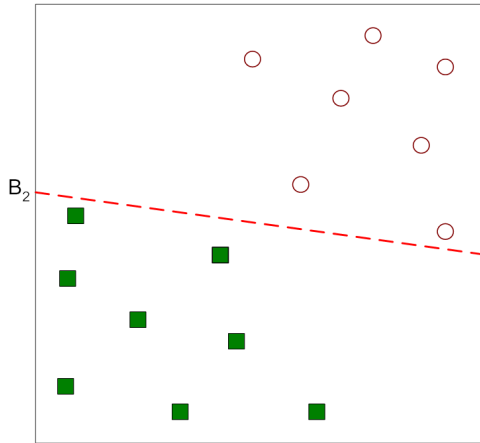
- Find a linear hyperplane (decision boundary) that will separate the data,



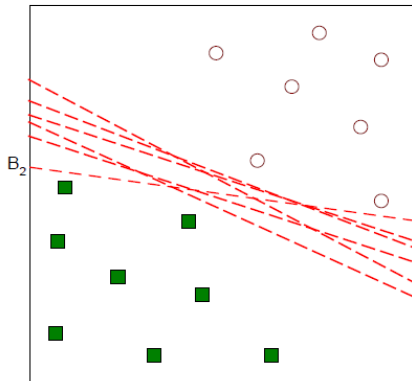
- Identify the right hyper-plane (Scenario-1):



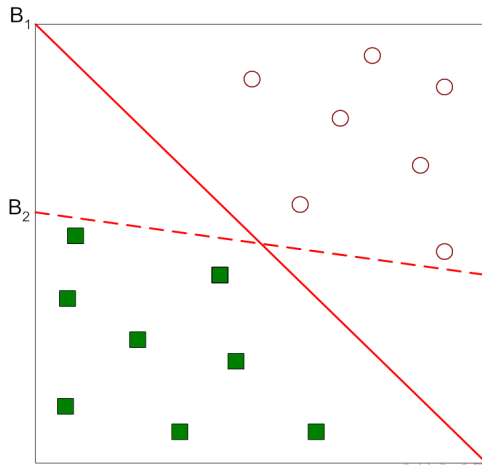
- Identify the right hyper-plane (Scenario-2):



- Identify the right hyper-plane (Scenario-3):



- Which one is better? B1 or B2?
- How do you define better?



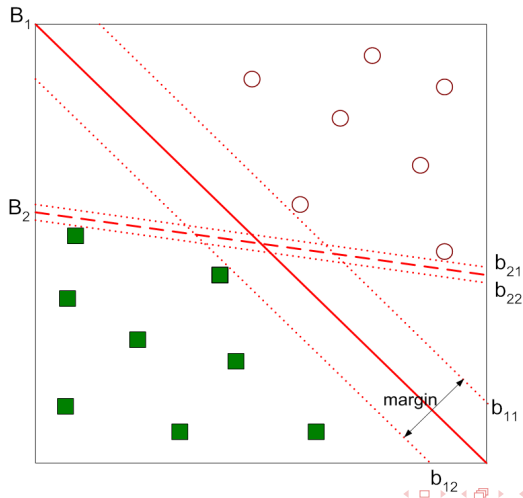


- Decision boundary $B1$ and $B2$;
 - Associated with a pair of hyperplanes, denoted as $(b11, b12)$ and $(b21, b22)$, respectively.
 - $(b11, b21)$ obtained by moving a parallel hyperplane away from the decision boundary until it touches the closest square(s),
 - $(b21, b22)$ obtained by moving the hyperplane until it touches the closest circle(s).
- The distance between these two hyperplanes is known as the **margin** of the classifier.
- In this example, $B1$ turns out to be the **maximum margin hyperplane** of the training instances.

Maximum Margin Hyperplanes



- Find hyperplane maximizes the margin \Rightarrow B1 is better than B2





- Decision boundaries with large margins,
 - Tend to have better generalization errors than those with small margins.
- Intuitively, if the margin is small,
 - Then any slight perturbations to the decision boundary can have quite a significant impact on its classification.
- Classifiers that produce decision boundaries with small margins are therefore more susceptible to model **overfitting** and tend to generalize poorly on previously unseen examples.



- Consider a binary classification problem consisting of N training examples.
- Each example is denoted by (X_i, y_i) ,
- $X_i = (x_{i1}, x_{i2}, x_{i3}, \dots, x_{id})^T$ is the attribute set of the i th example.
- Let $y_i = \{1, -1\}$ denote its class label



Linear SVM: Separable Case

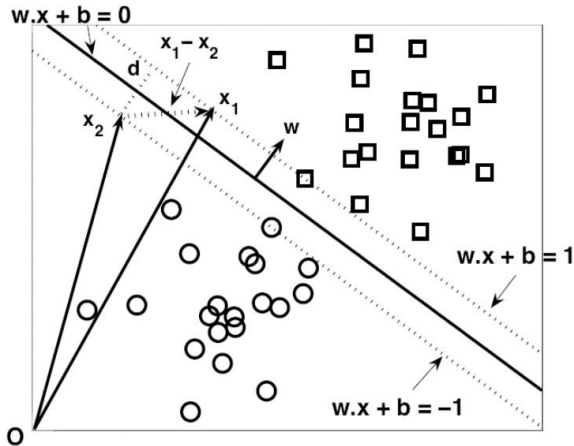
- A linear SVM is a classifier that searches for a hyperplane with the largest margin, (**maximal margin classifier**)

Linear Decision Boundary

- The decision boundary of a linear classifier can be written in the following form:

$$\mathbf{w} \cdot \mathbf{x} + b = 0$$

Linear SVM: Separable Case



Decision boundary and margin of SVM.

Margin of a Linear Classifier



$$\text{Margin} = \frac{2}{\|w\|}$$



- Note that the decision boundary of a linear classifier is:

$$w \cdot x + b = 0$$

- Therefore, the training phase of SVM involves estimating the parameters w and b from the training data.

- The parameters must be chosen such that

$$w \cdot x_i + b \geq 1 \text{ if } y_i = 1$$

$$w \cdot x_i + b \leq -1 \text{ if } y_i = -1$$

or equivalently

$$y_i(w \cdot x_i + b) \geq 1 \text{ for } i=1, 2, 3, \dots, N$$

- SVM imposes additional condition that the margin must be maximal.
- However, maximizing the margin is equivalent to minimizing the following objective function $L(w)$:

$$L(w) = \frac{\|w\|^2}{2}$$



- The learning task in SVM can be formalized as the following constrained optimization problem:

$$\min_{\mathbf{w}} \frac{\|\mathbf{w}\|^2}{2}$$

subject to $y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1, \quad i = 1, 2, \dots, N.$

- This is a convex optimization problem which can be solved by Lagrange multiplier method.
- The new objective function is known as the Lagrangian for the optimization problem:

$$L_P = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \lambda_i \left(y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 \right)$$



- To minimize the Lagrangian, we must take the derivative of L_p with respect to \mathbf{w} and b and set them zero:

$$\frac{\partial L_p}{\partial \mathbf{w}} = 0 \implies \mathbf{w} = \sum_{i=1}^N \lambda_i y_i \mathbf{x}_i,$$

$$\frac{\partial L_p}{\partial b} = 0 \implies \sum_{i=1}^N \lambda_i y_i = 0.$$

- The Karush-Kuhn-Tucker (KKT) condition:

$$\lambda_i \geq 0,$$

$$\lambda_i [y_i (\mathbf{w} \cdot \mathbf{x}_i + b) - 1] = 0$$



- Dual formulation of the optimization problem:

$$L_D = \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \mathbf{x}_i \cdot \mathbf{x}_j$$

- The decision boundary can be expressed as follows:

$$\left(\sum_{i=1}^N \lambda_i y_i \mathbf{x}_i \cdot \mathbf{x} \right) + b = 0.$$



- Consider the two-dimensional data set which contains eight training instances.
- Let $\mathbf{w} = (w_1, w_2)$ and b denote the parameters of the decision boundary. We can solve for w_1 and w_2 in the following way:

$$w_1 = \sum_i \lambda_i y_i x_{i1} = 65.5621 \times 1 \times 0.3858 + 65.5621 \times -1 \times 0.4871 = -6.64.$$

$$w_2 = \sum_i \lambda_i y_i x_{i2} = 65.5621 \times 1 \times 0.4687 + 65.5621 \times -1 \times 0.611 = -9.32.$$

- The bias term b can be computed for each support vector:

$$b^{(1)} = 1 - \mathbf{w} \cdot \mathbf{x}_1 = 1 - (-6.64)(0.3858) - (-9.32)(0.4687) = 7.9300.$$

$$b^{(2)} = -1 - \mathbf{w} \cdot \mathbf{x}_2 = -1 - (-6.64)(0.4871) - (-9.32)(0.611) = 7.9289.$$

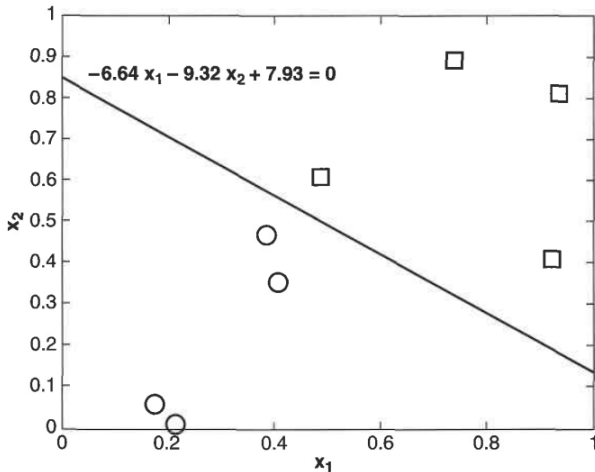
- Averaging these values, we obtain $\mathbf{b} = 7.93$.

Learning a Linear SVM Model: Example



x_1	x_2	y	Lagrange Multiplier
0.3858	0.4687	1	65.5261
0.4871	0.611	-1	65.5261
0.9218	0.4103	-1	0
0.7382	0.8936	-1	0
0.1763	0.0579	1	0
0.4057	0.3529	1	0
0.9355	0.8132	-1	0
0.2146	0.0099	1	0

Learning a Linear SVM Model: Example



Example of a linearly separable data set.



- Once the parameters of the decision boundary are found, a test instance \mathbf{z} is classified as follows:

$$f(\mathbf{z}) = \text{sign}(\mathbf{w} \cdot \mathbf{z} + b) = \text{sign}\left(\sum_{i=1}^N \lambda_i y_i \mathbf{x}_i \cdot \mathbf{z} + b\right)$$

- If $f(\mathbf{z}) = 1$, then the test instance is classified as a positive class; otherwise, it is classified as a negative class.

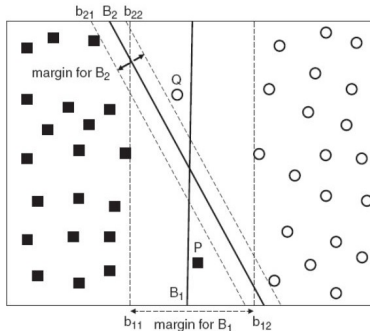


- When it is not possible to separate the training data linearly.
- SVM to construct a linear decision boundary even in situations,
 - Where the classes are not linearly separable.

Linear SVM: Nonseparable Case



- Similar example except two new points P and Q
- B_1 misclassifies the examples while B_2 classifies them correctly
- It does not mean that B_2 is better decision boundary than B_1
- Because new examples may correspond to noise
- B_1 may be preferred over B_2 as it has wider margin and so is less susceptible to overfitting



Decision boundary of SVM for the nonseparable case.



- The previous SVM method (seperable case) constructs decision boundary which is mistake-free
- so we should examine how the formulation can be modified to learn a decision boundary that is tolerable to small training errors
- This introduces a SVM method known as soft margin approach
- To do this the learning method must consider the trade-off between the width of the margin and the no of traning errors



- The method introduces positive valued slack variables into the constraints of the linear SVM separable optimization problem, i.e.,

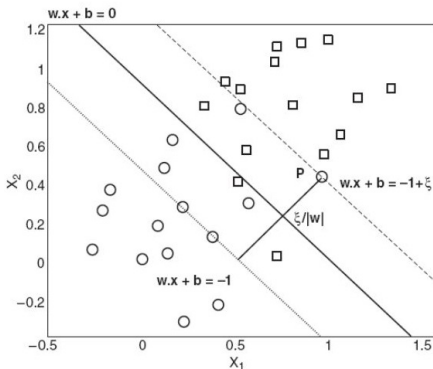
$$\mathbf{w} \cdot \mathbf{x}_i + b \geq 1 - \xi_i \text{ if } y_i = 1,$$

$$\mathbf{w} \cdot \mathbf{x}_i + b \leq -1 + \xi_i \text{ if } y_i = -1,$$

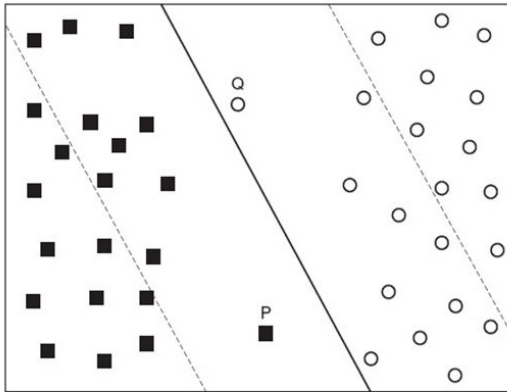
where $\forall i : \xi_i > 0$.

To understand let us consider the following figure

- P is one of the instances that violates the constraints of the linear SVM separable optimization problem
- $w \cdot x + b = -1$ is hyperplane
- So, ξ provides an estimate of the error of the decision boundary on the training example P



Linear SVM: Nonseparable Case



A decision boundary that has a wide margin but large training error.



- The modified objective function is given by the following equation:

$$f(\mathbf{w}) = \frac{\|\mathbf{w}\|^2}{2} + C \left(\sum_{i=1}^N \xi_i \right)^k,$$

- The Lagrangian for this constrained optimization problem can be written as follows:

$$L_P = \frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^N \xi_i - \sum_{i=1}^N \lambda_i \{y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 + \xi_i\} - \sum_{i=1}^N \mu_i \xi_i,$$



- The inequality constraints can be transformed into equality constraints using the following KKT conditions::

$$\begin{aligned}\xi_i &\geq 0, \quad \lambda_i \geq 0, \quad \mu_i \geq 0, \\ \lambda_i \{y_i(\mathbf{w} \cdot \mathbf{x}_i + b) - 1 + \xi_i\} &= 0, \\ \mu_i \xi_i &= 0.\end{aligned}$$

- Setting the first-order derivative of \mathbf{L} with respect to w , b , and (ξ) to zero would result in the following equations:

$$\frac{\partial L}{\partial w_j} = w_j - \sum_{i=1}^N \lambda_i y_i x_{ij} = 0 \implies w_j = \sum_{i=1}^N \lambda_i y_i x_{ij}.$$

$$\frac{\partial L}{\partial b} = - \sum_{i=1}^N \lambda_i y_i = 0 \implies \sum_{i=1}^N \lambda_i y_i = 0.$$

$$\frac{\partial L}{\partial \xi_i} = C - \lambda_i - \mu_i = 0 \implies \lambda_i + \mu_i = C.$$



- The dual Lagrangian:

$$\begin{aligned} L_D &= \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \mathbf{x}_i \cdot \mathbf{x}_j + C \sum_i \xi_i \\ &\quad - \sum_i \lambda_i \left\{ y_i \left(\sum_j \lambda_j y_j \mathbf{x}_i \cdot \mathbf{x}_j + b \right) - 1 + \xi_i \right\} \\ &\quad - \sum_i (C - \lambda_i) \xi_i \\ &= \sum_{i=1}^N \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \mathbf{x}_i \cdot \mathbf{x}_j, \end{aligned}$$



Nonlinear SVM

- Applying SVM to data sets that have nonlinear decision boundaries.
- The trick here is to transform the data from its original coordinate space in x into a new space $O(x)$,
 - A linear decision boundary can be used to separate the instances in the transformed space.
- After doing the transformation,
 - We can apply a linear decision boundary in the transformed space.
- The **kernel trick** is a method for computing similarity in the transformed space using the original attribute set.



- The learning task for a nonlinear SVM can be formalized as the following optimization problem:

$$\begin{aligned} \min_{\mathbf{w}} \quad & \frac{\|\mathbf{w}\|^2}{2} \\ \text{subject to} \quad & y_i(\mathbf{w} \cdot \Phi(\mathbf{x}_i) + b) \geq 1, \quad i = 1, 2, \dots, N. \end{aligned}$$

- Dual Lagrangian for the constrained optimization problem:

$$L_D = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j)$$



- Once the λ_i 's are found using quadratic programming techniques, the parameters w and b can be derived using the following equations:

$$\mathbf{w} = \sum_i \lambda_i y_i \Phi(\mathbf{x}_i)$$
$$\lambda_i \left\{ y_i \left(\sum_j \lambda_j y_j \Phi(\mathbf{x}_j) \cdot \Phi(\mathbf{x}_i) + b \right) - 1 \right\} = 0,$$

- A test instance \mathbf{z} can be classified using the following equation:

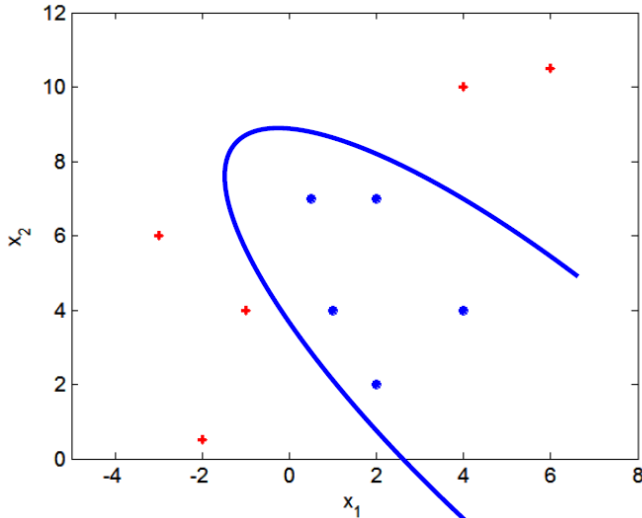
$$f(\mathbf{z}) = \text{sign}(\mathbf{w} \cdot \Phi(\mathbf{z}) + b) = \text{sign} \left(\sum_{i=1}^n \lambda_i y_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{z}) + b \right)$$



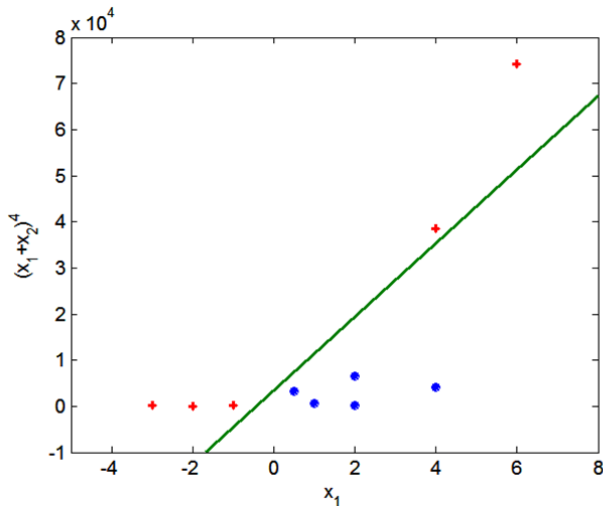
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- What if decision boundary is not linear?



- Transform data into higher dimensional space





SVM has many desirable qualities that make it one of the most widely used classification algorithms. Following is a summary of the general characteristics of SVM:

- The SVM learning problem can be formulated as a **convex optimization problem**,
 - In which efficient algorithms are available to find the **global minimum** of the objective function.
 - Other classification methods, such as **rule-based classifiers and artificial neural networks**,
 - Employ a **greedy based strategy** to search the hypothesis space.
 - Such methods tend to find only **locally optimum solutions**.



- SVM performs **capacity control**,
 - By maximizing the margin of the decision boundary.
 - Nevertheless, the user must still provide other parameters such as the type of kernel function to use and the cost function C for introducing each slack variable.
- SVM can be applied to **categorical data**,
 - By introducing **dummy variables** for each categorical attribute value present in the data.
 - For example, if Marital Status has three values (Single, Married, Divorced), we can introduce a binary variable for each of the attribute values.



Sample Python Code to implement SVM for the following Data and Class Label.

```
x1 = [1,5,1.5,8,1,9]    x2 = [2,8,1.8,8,0.6,11]
y = [0,1,0,1,0,1]
```

Comment is Shown by :

:Importing svm Python Libraries

```
import numpy as np
```

```
import matplotlib.pyplot as plt
```

```
from sklearn import svm
```

:Plotting of training data

```
x1 = [1,5,1.5,8,1,9]
```

```
x2 = [2,8,1.8,8,0.6,11]
```

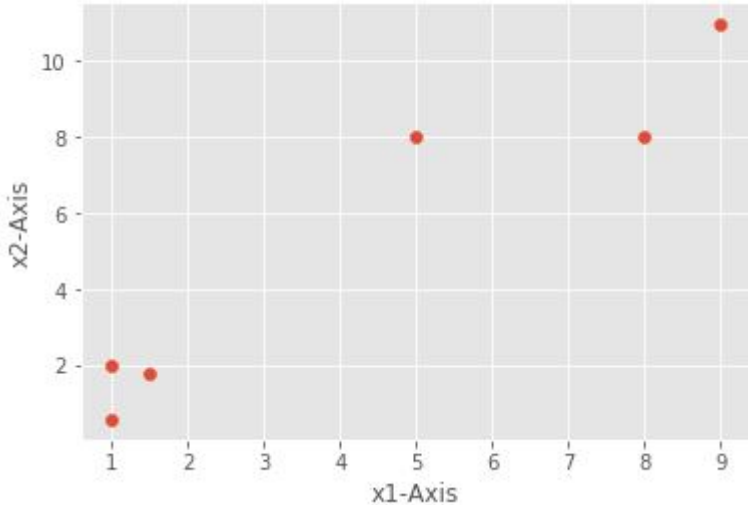
```
plt.xlabel("x1-Axis")
```

```
plt.ylabel("x2-Axis")
```

```
plt.scatter(x1,x2)
```

```
plt.show()
```

SVM : Sample Code





```
:Data Initialization
:X = Data, Y= Label
X = np.array ([[1,2],[5,8],[1.5,1.8],[8,8],[1,0.6],[9,11]])
Y = [0,1,0,1,0,1]

:importing LinearSVC
clf=svm.LinearSVC()

:Fitting the model
clf.fit(X,Y)

:Obtaining Coefficient Vector
w=clf.coef_[0]

:Obtaining Learning Rate
a = -w[0]/w[1]
```



```
:X-scale for Hyperplane
```

```
XX=np.linspace(0,10)
```

```
YY = a * XX - clf.intercept_[0]/w[1]
```

```
:Plotting training data
```

```
plt.scatter(X[:,0],X[:,1],c=Y)
```

```
plt.show()
```

```
:Plotting Hyperplane
```

```
plt.xlabel("x1-Axis")
```

```
plt.ylabel("x2-Axis")
```

```
plt.plot(XX,YY)
```

```
plt.show()
```

```
:Test Data
```

```
X_pred=np.array([[3,4],[6,9],[0.43,0.89]])
```



```
: Declaring an Array to store predicted class label
: If Predicted class Belongs to 0, Denote by Color = Red &
  Marker = +
: If Predicted class Belongs to 1, Denote by Color = blue &
  Marker = ^

for i in range(len(X_pred)):
    temp=clf.predict(X_pred)
    if temp[i]==0:
        plt.scatter(X_pred[i,0],X_pred[i,1], color='r',
                    marker='p')
    else :
        plt.scatter(X_pred[i,0],X_pred[i,1], color='b', marker='^')
plt.show()
```

SVM : Sample Code

