Digital Image Processing

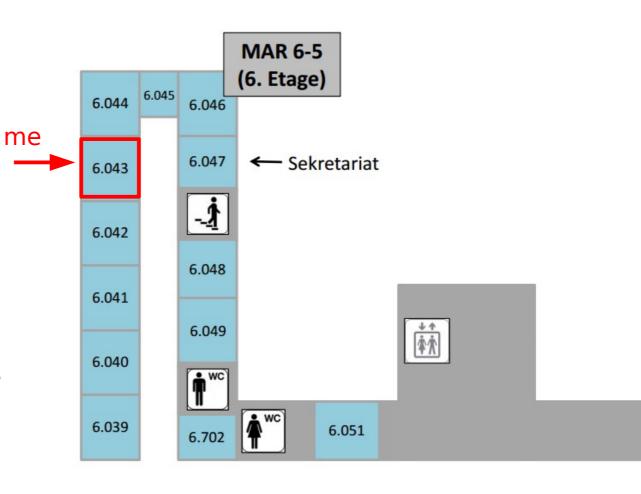
Berlin University of Technology (TUB), Computer Vision and Remote Sensing Group Berlin, Germany



Contact

Andreas Ley

- E-Mail:
 - → andreas.ley@tu-berlin.de
- Office
 - → MAR6.043, March Building, 6th Floor
- Consultation Time
 - → Wednesday, 16:30-17:30 o'clock





Marchstraße 23-



Teaching

- Digital Image Processing

- Image → Image
- Image → Description
- Winter Term

Automatic Image Analysis

- Image → Object Model
- Image → Object Detection
- Summer Term



- Image(s) → 3D Model
- Winter Term

- Projects/Seminars

- Summer Term
- e.g.: Scientific Process in Computer Vision







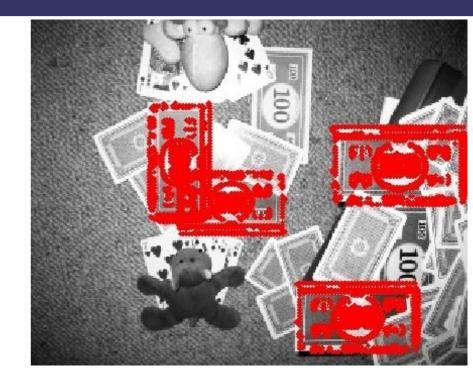
Teaching

- Digital Image Processing

- Image → Image
- Image → Description
- Winter Term

- Automatic Image Analysis

- Image → Object Model
- Image → Object Detection
- Summer Term



- Photogrammetric Computer Vision

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- Winter Term

- Projects/Seminars

- Summer Term
- e.g.: Scientific Process in Computer Vision





Teaching

- Digital Image Processing

- Image → Image
- Image → Description
- Winter Term

Automatic Image Analysis

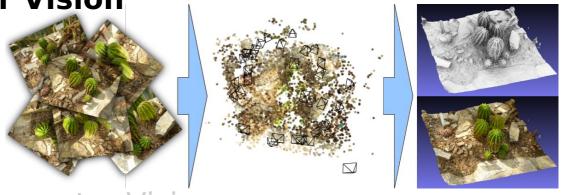
- Image → Object Model
- Image → Object Detection
- Summer Term

Photogrammetric Computer Vision

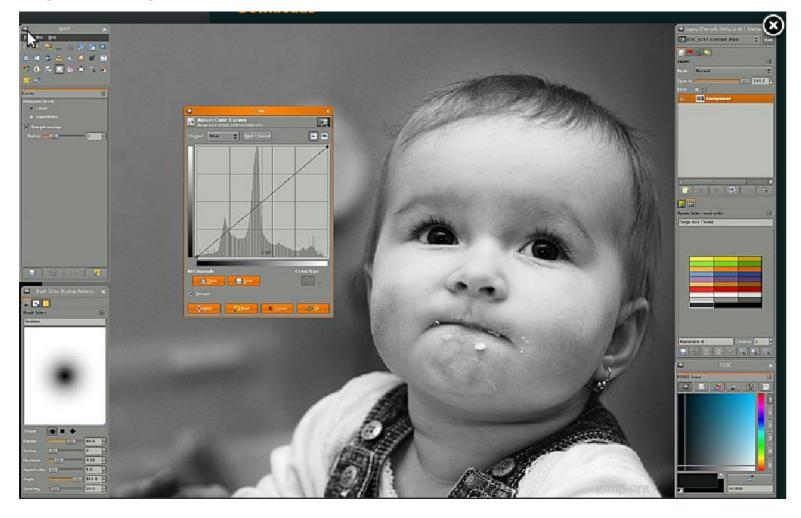
- Image(s) → 3D Model
- Winter Term

- Projects/Seminars

- Summer Term
- e.g.: Scientific Process in Computer Vision



Photoshop, Gimp, ...

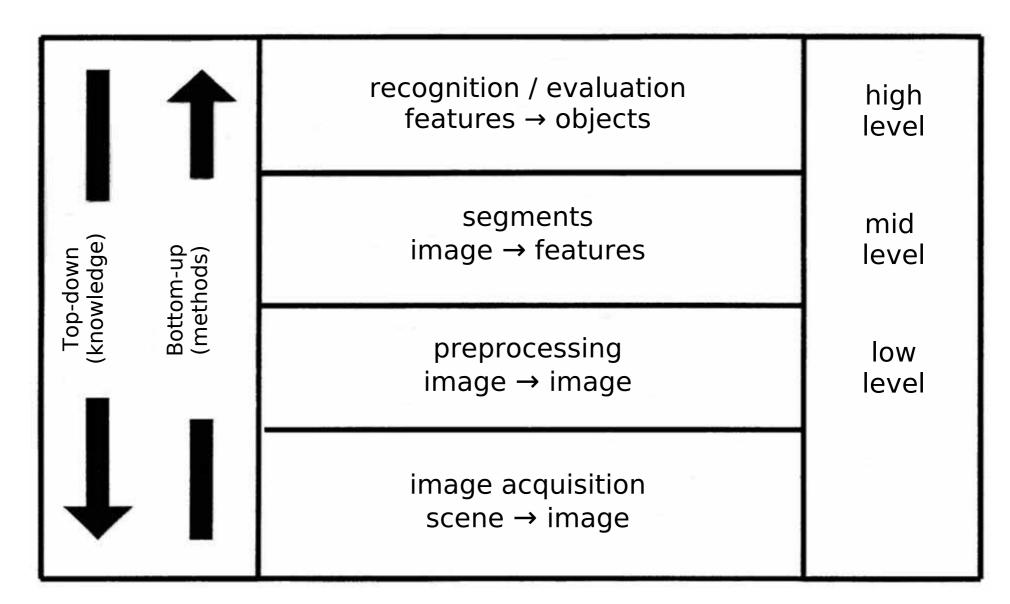


Photoshop, Gimp, ...

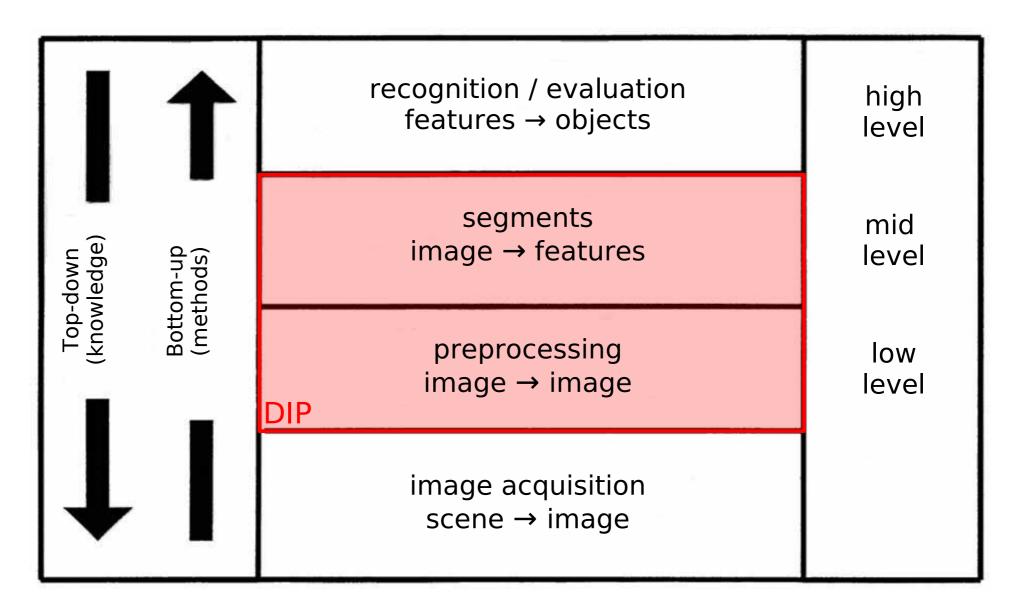


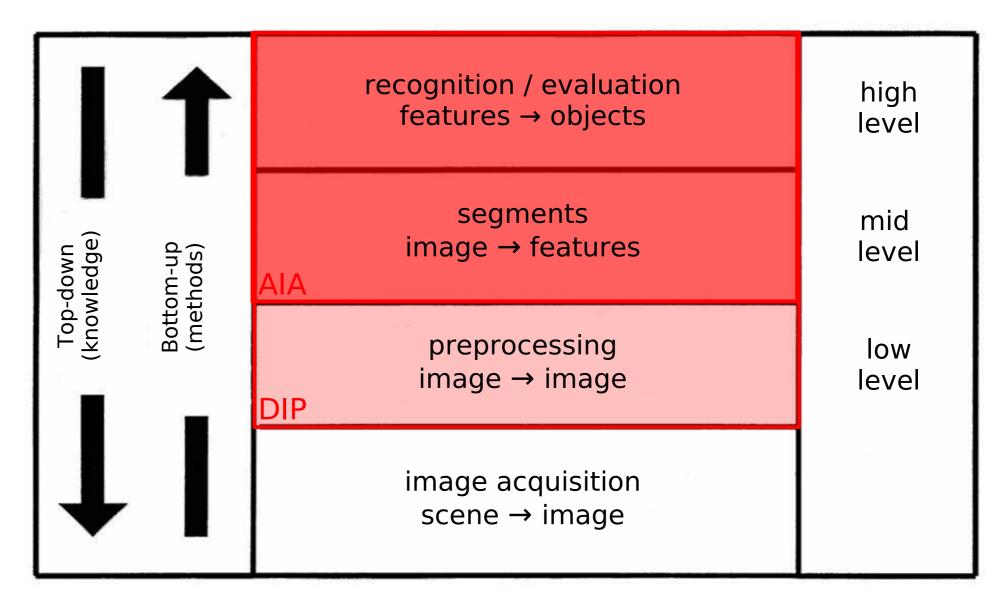
- NOT how to USE it (image editing)
- BUT how it WORKS (image processing)











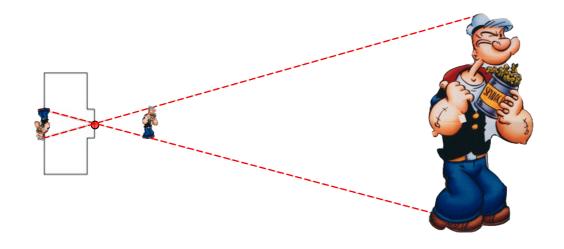


Motivation & Introduction



Motivation & Introduction

Image formation and geometric image transformations



Motivation & Introduction Image formation and geometric image transformations

Mask-/Filter Techniques Convolution in Spatial Domain







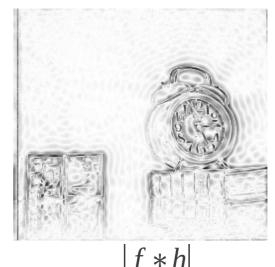
Berlin University of Technology

Motivation & Introduction
Image formation and geometric image transformations
Mask-/Filter Techniques
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Fourier Transform
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Smoothing / Low-Pass Filtering
Edge Extraction / High-Pass Filtering



f(x,y)



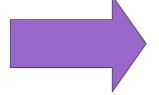


(colours inverted



Motivation & Introduction Image formation and geometric image transformations Mask-/Filter Techniques Convolution in Spatial Domain Fourier Transform Convolution via Frequency Domain Smoothing / Low-Pass Filtering Edge Extraction / High-Pass Filtering **Image Restoration**





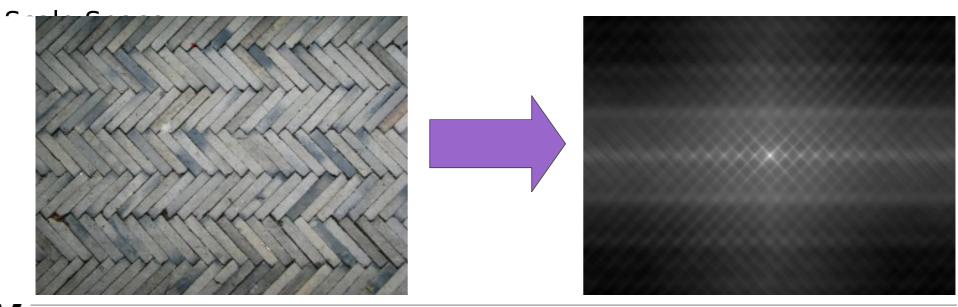






Motivation & Introduction
Image formation and geometric image transformations
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Fourier Transform
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Edge Extraction / High-Pass Filtering
Image Restoration

Texture

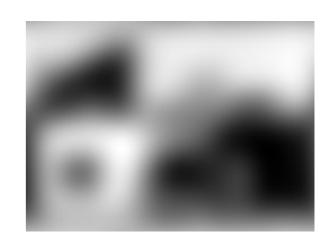


Motivation & Introduction
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Edge Extraction / High-Pass Filtering
Image Restoration
Texture

Scale Space



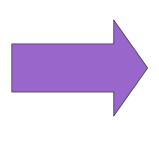


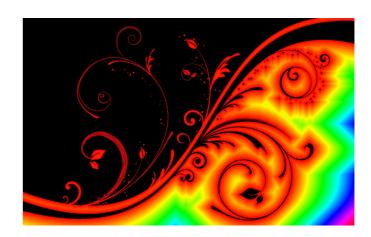


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Mathematical Morphology











Motivation & Introduction Image formation and geometric image transformations Mask-/Filter Techniques Convolution in Spatial Domain

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Image Restoration

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Mathematical Morphology

Graphical Models

 $\Phi(x_i, y_i)$

Motivation & Introduction Image formation and geometric image transformations Mask-/Filter Techniques Convolution in Spatial Domain Fourier Transform Convolution via Frequency Domain Smoothing / Low-Pass Filtering Edge Extraction / High-Pass Filtering **Image Restoration Texture** Scale Space Mathematical Morphology **Graphical Models Extraction of Salient Points**





Motivation & Introduction Image formation and geometric image transformations

Mask-/Filter Techniques

Convolution in Spatial Domain

Fourier Transform

Convolution via Frequency Domain

Smoothing / Low-Pass Filtering

Edge Extraction / High-Pass Filtering

Image Restoration

Texture

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Mathematical Morphology

Graphical Models

Extraction of Salient Points

Extraction of Areas / Segmentation

Imaga Transformations



Motivation & Introduction

Image formation and geometric image transformations

Mask-/Filter Techniques

Convolution in Spatial Domain

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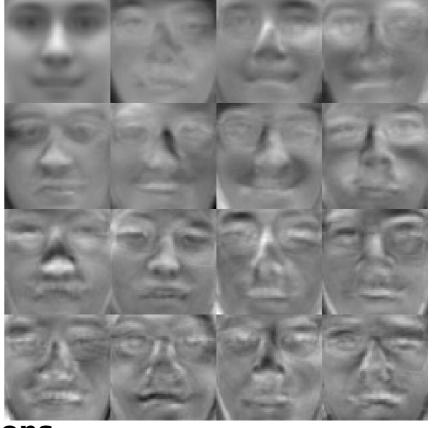
Mathematical Morphology

Graphical Models

Extraction of Salient Points

Extraction of Areas / Segmentation

Image Transformations / Representations



Motivation & Introduction Image formation and geometric image transformations Mask-/Filter Techniques Convolution in Spatial Domain **Fourier Transform** Convolution via Frequency Domain Smoothing / Low-Pass Filtering Edge Extraction / High-Pass Filtering **Image Restoration Texture** Scale Space Mathematical Morphology **Graphical Models Extraction of Salient Points** Extraction of Areas / Segmentation Image Transformations / Representations

Outlook / Invited Talks







How are you gonna learn it?

1. Visit lectures

- Every week (ER 164, Monday, 14-18 o'clock)

2. Visit exercises

- Every two weeks (H 1028, Tuesday, 16-18 o'clock)

3. Doing homework

- Consultation time: MAR6.043, Wednesday, 16:30-17:30 o'clock

4. ASK QUESTIONS!

- Always! But: Ask me, not your neighbour

5. (Read further material)

- As often as possible

Material

Books

- Petrou: Image Processing The Fundamentals
- Gonzalez, Woods: Digital Image Processing
- Jähne: Digital Image Processing
- Sonka et al.: Image Processing, Analysis, and Machine Vision

Articles

 Scientific paper: www.ieeexplore.com (free download within TU-network)

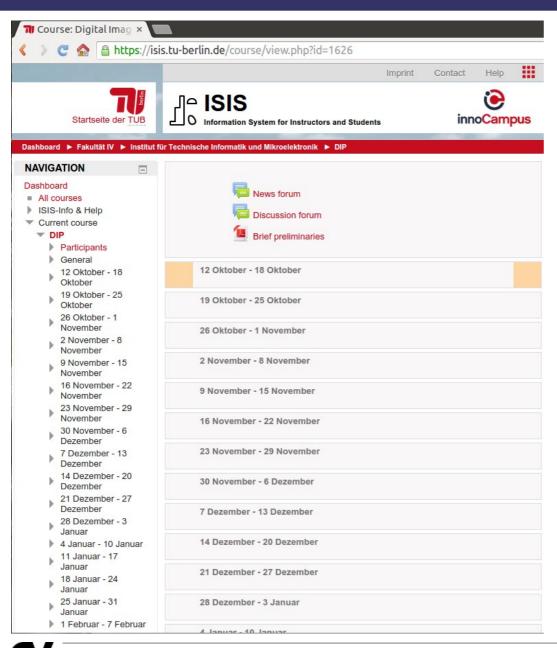
Informations

WWW

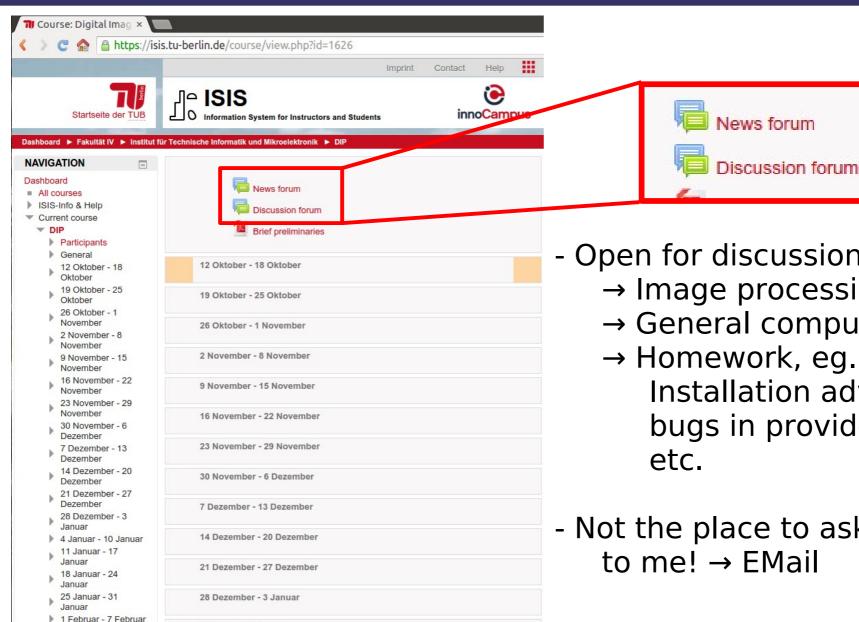
- Information, important announcements:
 - → http://www.cv.tu-berlin.de Announcements: 'Lectures'

→ Slides and other material: **ISIS2**

Information



Information



- Open for discussions about
 - → Image processing topics
 - → General computer vision
 - → Homework, eg. Installation advices, bugs in provided code,
- Not the place to ask questions to me! → EMail

Exams

Mid-term:

Near the middle of the term: 10.12.2019

• Room: tba

• Duration: 16 pm, 45 min

In place of an exercise

No grade, but pass is necessary to take part at the final exam

Final:

• At the end of the term: **17.02.2020**

• Room: HE 101

Duration: 17-20 o'clock (90 min)

Questions in English, answers are check marks (multiple choice)

What to do?

I: Answering theoretic questions

II: Implementation of methods for processing digital images

How?

Individual work (no group work)
Programming Language: C++ [and OpenCV 2.4 or 3.0]
Completion of provided software packages

- Class descriptions (header files): given
- Includes: given
- Basic functionality: given
- Specific functions: Your task!

Goal?

Practising, Learning. No grades!
But pass is necessary to take part at the final exam



"Grades"

```
+++ more than just a correct solution (efficient, clever, cool, ...)
```

- ++ correct solution
- + some minor errors, but still acceptable
- not acceptable → re-work (within 1 week, parallel to new assignment!)
- - failed: you are not allowed to write the exam!



Theoretical Part:

- Questions in these slides
- Answer in PDF form

Practical Part:

- Questions also in these slides
- Download zip-file from isis
 - Contains bunch of source code files and possibly images
 - Dip[1-6].cpp contains empty/placeholder functions
 - Fill in/complete those functions
- Algorithms more important than well-written code (but try!)

Submission:

- Due 2 weeks later
- Via isis
- One zip-file with: PDF, source code files, input and (if applicable) output images



- Next meeting in two weeks
- BEFORE Tuesday, 16 o'clock:
 - Hand in your solution via ISIS
 - Solution includes (red denotes mandatory material):
 - → A single .zip file (no rar, 7z, ...) containing
 - → No subdirectories (unless in original zip file)
 - → All files of the provided material
 - i.e. all .h and .cpp files, CMakeLists.txt
 - But no executables, object files, stdafx.h, ...!
 - → Input and output images (if applicable)
 - → Pdf-file with
 - → Student name, and student ID
 - → Short discussion / presentation of your solution
 - → Answers to theoretical questions

Don't break my automated tests:

- Do not modify:
 - → headers, behaviour of given functions, file names, tests
- Only modify the Dip[1-6].cpp file
 - (Unless specified otherwise)
- Do not rename files, use subdirectories in zip file, use a format other than .zip, ...

It has to work on my machine:

- Code that doesn't compile won't be checked
- Do not use absolute paths to headers, images, and other files
- If unsure, check with VM

Plagiarism is considered a failure:

- Submitting solutions from previous years is plagiarism too
- You immediately fail the homework criterion



Plagiarism

- We will look (maybe sporadically) for plagiarism
- If we find plagiarism in your homework submissions:
 - You will immediately fail the homework criterion and can't take the exam!
 - No second chances!
 - → I don't care that you [insert lame excuse here]

Plagiarism

- "I didn't have the time"
- "I can't do it myself"
- "I accidentally send the wrong file"
- "I could do it myself, but my english is not as good as that on wikipedia"
- "Where I'm from, even the professors do it"
- "I can totally explain how the other student's name is also on my submission"
- "But it's my work, the other student [1 year ago built a time machine and] copied from me"
 - → Trust us, we have heard it all before



Plagiarism

- "But I didn't know about it"
 - → I just told you
 - → Even if you truly didn't know:
 - → Courts ruled (multiple times) that it is still plagiarism and enforceable.
- "Ok, you caught me, but you didn't catch others.
 That is unfair treatment!"
 - → Courts usually rule that it doesn't matter. The others just got lucky.

See e.g. https://kops.uni-konstanz.de/handle/123456789/37223





So what is Plagiarism?

As a rule of thumb:

- → DO NOT COPY!
- → Your submission must be your own, unique solution.
- → Just do your homework yourself and you'll be fine.
- It's plagiarism if you copy from
 - → The internet (even if it's google translated from another language)
 - → Other students (same or past years)
- It's also plagiarism if you let s.b. else do your homework.



So what is Plagiarism?

- It's plagiarism even if you didn't ctrl+c/v but retyped it.
- It's still plagiarism if you only changed individual words/variable names or only made other marginal changes.
- Letting others help you is ok. But:
 - → If "help" means they dictate what to type, it's again plagiarism.

Plagiarism

If we find any of those, or s.th. in the same spirit, you will immediately fail the homework criterion and can't take the exam!



Programming Environment

Programming Environment

You will need a couple of tools and libraries installed. Two options:

Install on your OS

You'll need:

- C++ compiler
 - → gcc/llvm/msvc
- cmake (optionally)
- OpenCV library
- Eigen library (PCV only)
- IDE (recommended)
 - → Code::Blocks/xCode/ Visual Studio
- Usually easy on linux, hard on windows

Use our virtual machine

- Install VirtualBox
- Download our VM image
- Contains:
 - → Linux
 - → All libraries and tools preinstalled
- Also serves as a reference
 - → Code has to work here

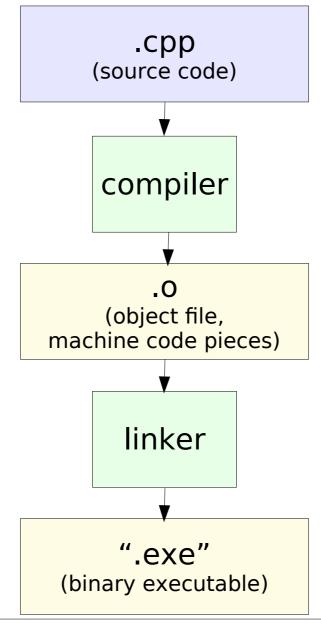
or

Virtual Machine Setup

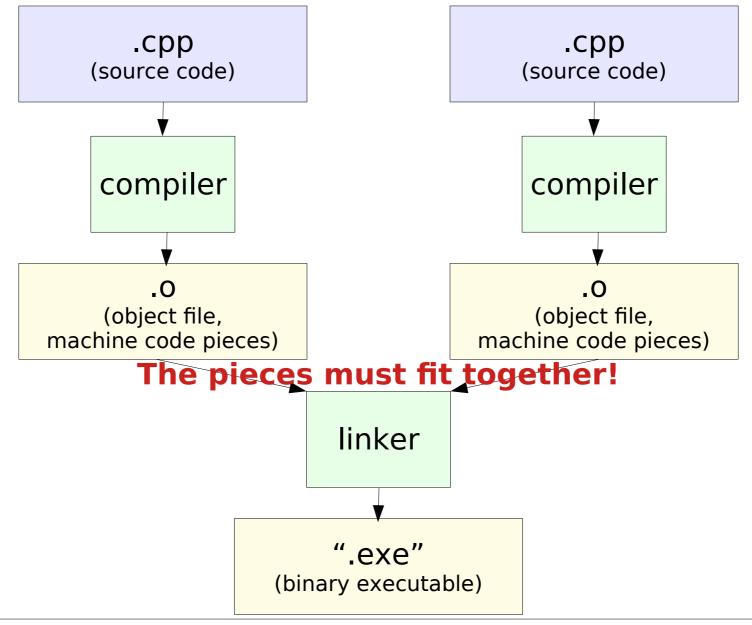
- Download from here (.ova image file)
- Install VirtualBox
- Open main Virtual Box window "Oracle VM VirtualBox Manager"
- Select "File" → "Import Appliance..."
- Select .ova image
- Tick "Reinitialize the MAC address of all network cards"
- Hit "Import"
- After import, select the "CVTeachingMachine" from the list of VMs and hit "Start"

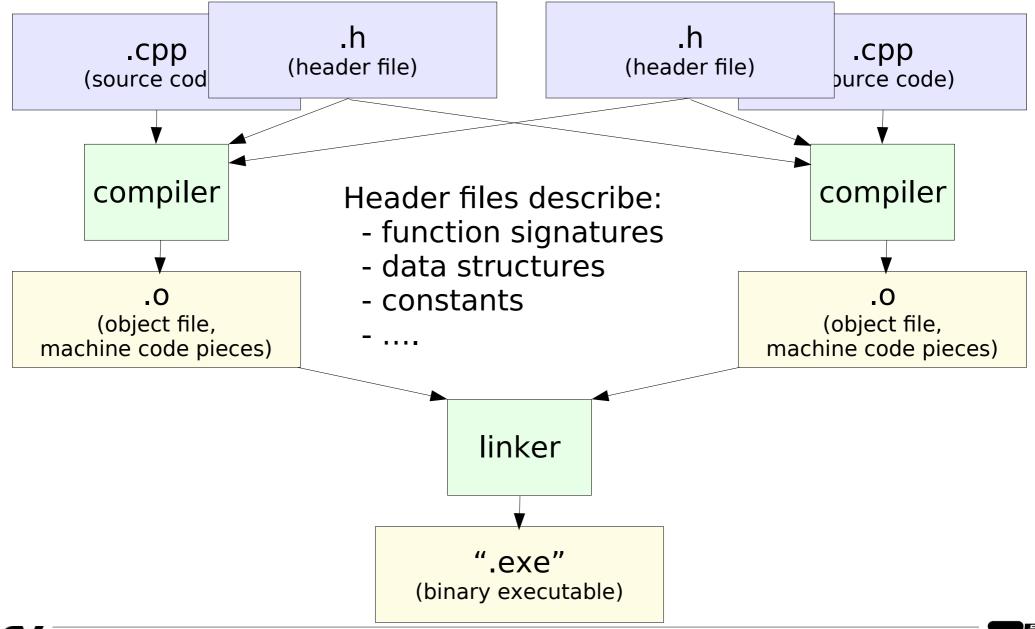


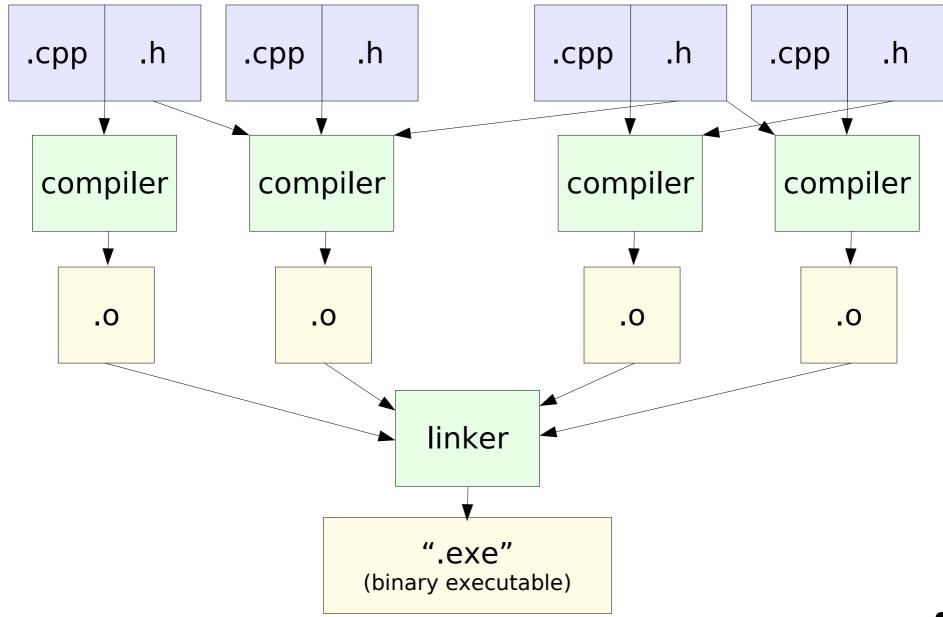
Building process

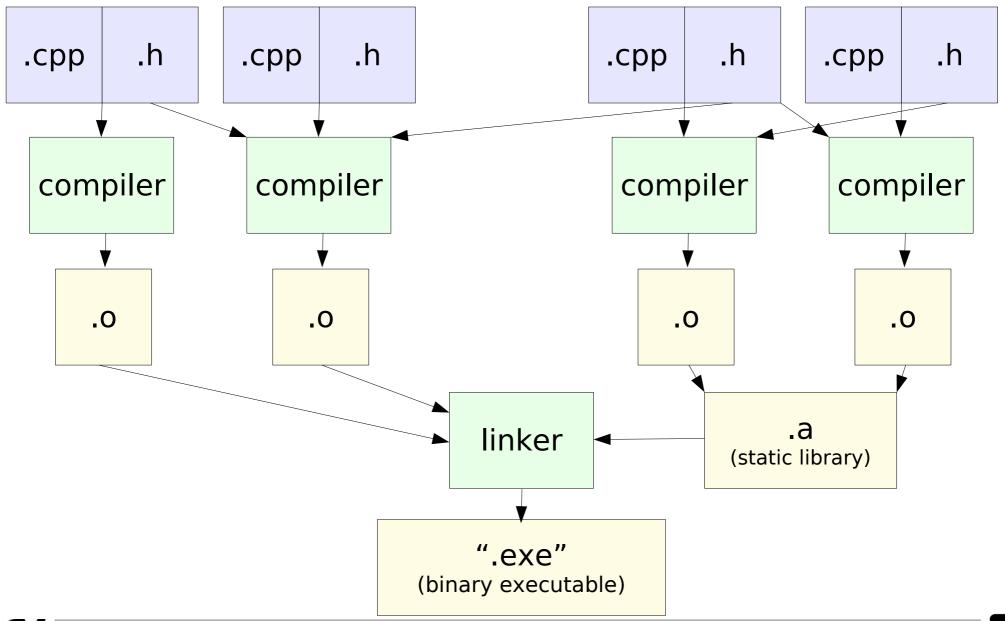












CMAKE

We use CMAKE

- · CMake builds project files for common build systems
- · Some IDEs can directly open *CMake* files

Example on linux with make:

Create out-of-source build directory and setup debug build:

mkdir build cd build cmake .. -DCMAKE_BUILD_TYPE=Debug

Once setup, build with make:

make -j

Use "-DCMAKE BUILD TYPE=Release" for faster release build.



C++ - Tools

- C++ programs can be build with only command line tools
 - e.g., gcc, clang
- Integrated Development Environment (IDE) is strongly recommended
 - Syntax Highlighting
 - Integrated build system
 - Debugger
 - Auto-Complete
 - ...
 - Linux:
 - → Kdevelop
 - Mac OS:
 - → Xcode

- Windows:
 - → Visual Studio
- Cross-Platform:
 - → Code::Blocks, Eclipse, QtCreator, Visual Studio Code, ...

CMAKE + Code::Blocks

Example on linux with Code::Blocks:

Create out-of-source build directory and setup debug build project structure for Code::Blocks:

```
mkdir build
cd build
cmake .. -DCMAKE_BUILD_TYPE=Debug \
-G "CodeBlocks - Unix Makefiles"
```

Once setup, open project in Code::Blocks.

This is the recommended way in the VM!

CMAKE Executables

Cmake is configured to build two executables:

./main:

→ The actual "demo" program that showcases the algorithm

./test:

- → Runs small tests to check correctness of implementation
- → These tests **must** succeed for homework to pass as correct

These two executables are exposed in some IDEs as different build/debug targets:

→ For debugging, select which one you want to run

Also remember to set program arguments (e.g. path to test images)

→ Code::Blocks: Project → Set program's arguments...



Syntax and Pitfalls

C++ for Programmers

- This is not a course about programming
- If you can't code (yet):
 - Tons of tutorials and videos on the internet
- If you can code (python, java, js, matlab, ...)
 - → You should be fine, even without c++ skills
 - → Most homework is "fill in the gaps"-style
 - → But: C++ has a couple of non-trivial quirks
 - → Let's look at those

C++

```
Python
```

```
1 #include <opencv2/opencv.hpp>
 2 #include <opencv2/highgui.hpp>
 4 #include <iostream>
 6 int main()
 7 {
       std::cout << "Hello World" << std::endl;</pre>
 9
       cv::Mat image = cv::imread("image.png");
10
11
12
       cv::imshow("img", image);
13
       cv::waitKey(0);
14
15
16
       return 0;
17 }
```

```
1 import cv2
 2
 6 def main():
      print("Hello World")
 9
      image = cv2.imread("image.png")
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      cv2.imshow("img", image)
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       name == " main ":
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```

C++

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15
16 if __name__ == "__main__":
17    main()
```

- Which .h files to include
- Path relative to file or search paths given to compiler
- Linker still needs to link against lib

C++

```
1 #include <opencv2/opencv.hpp>
 2 #include <opencv2/highgui.hpp>
 4 #include <iostream>
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13
14
      cv2.waitKey(0)
15
16 if
       name == " main ":
17
      main()
```

- Function
- No parameters
- Return type int
- "main" function gets called when program is executed

C++

```
1 #include <opencv2/opencv.hpp>
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     print("Hello World")
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     cv2.imshow("img", image)
     cv2.waitKey(0)
      name == " main ":
     main()
```

- Scopes / Code blocks with { }
- Indentation is ignored
- Multiple instructions in one line possible

C++

Python

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```

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      image = cv2.imread("image.png")
      cv2.imshow("img", image)
      cv2.waitKey(0)
16 if __name__ == "__main__":
17 main()
```

Semicolon ';' after every instruction mandatory

C++

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3
4 #include <iostream>
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```

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```

- Namespaces prevent identifiers from clashing
- Namespace name forms a prefix with a double colon
- "using namespace std;" (with std/cv/...) gives default access
 - → Only do this in .cpp files





C++

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```

- String literals must be delimited by double quotation marks (" ")
- Single quotation marks ('') for single characters only

C++

```
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16 if __name__ == "__main__":
17    main()
```

- C++ is strongly typed
- All variables must have known type at compilation time
- Type must be specified when variable is declared
 - → Same holds for function parameters
 - → And function return values



C++ - Types

C++

Python

```
5 float sqrt(float x, unsigned iters) {
6    float result = x / 2;
7    for (unsigned i = 0; i < iters; i++)
8        result = (result + x / result) / 2;
9    return result;
10 }

5 def sqrt(x, iters):
6    result = x / 2
7    for i in range(0, iters):
8        result = (result + x / result) / 2
9    return result;
10 }
</pre>
```

- Types can be basic types (int, float, ...) or more complex data structures (e.g. classes)
- Compiler checks compatibility (at compilation time)

Some important types:

bool	Boolean value	true, false
int	Signed integer number	-1, 2, 1337
unsigned	Non-negative integer number	0u, 1u, 12345u
char	Single character	'a', 'b', 'C'
float	32-bit floating point number	1.0f, 4.0f, 1e-2f
double	64-bit floating point number	1.0, 2.0, 3e-4

C++ - Types

C++

Python

```
5 float sqrt(float x, unsigned iters) {
6    float result = x / 2;
7    for (unsigned i = 0; i < iters; i++)
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9    return result;
10 }

5 def sqrt(x, iters):
6    result = x / 2
7    for i in range(0, iters):
8        result = (result + x / result) / 2
9    return result;
10</pre>
```

- Types can be basic types (int, float, ...) or more complex data structures (e.g. classes)
- Compiler checks compatibility (at compilation time)

Some important classes:

std::string	String (text)	#include <string></string>
std::vector <type></type>	Dynamic array. Type of elements must be specified inside < >	#include <vector></vector>
std::list <type></type>	Linked list	#include <list></list>
std::unique_ptr <type></type>	Smart pointer (more later)	#include <memory></memory>
std::shared_ptr <type></type>	Smart pointer (more later)	#include <memory></memory>

C++ - Types

Implicit type casts:

```
→ "1+2" → "3" (int)
```

- → "1+2.5f" → "3.5f" (float)
- → "1 / 2.0" → "0.5" (double)
- Some pitfalls:
 - → "10 / 4" → "2" (int)
 - \rightarrow "0u 1u" \rightarrow "4294967295" (unsigned) (hardware dependent)
 - → "2e9f + 1" → "2e9f" (float, unchanged)

C++ - Operators

The usual suspects	a + b, a – b, a / b, a * b
Modulo	a % b
Bitshift by b left, right	a << b, a >> b
Increment / decrement	a++, a
Assignment	a = b
Compute and assign	a += b, a -= b, a *= b, a /= b, a %= b
Type cast	(float) b
Force float division	a / (float) b

C++ - Boolean Expressions

Equal	a == b
Not equal	a != b
Greater, lesser	a > b, a < b
Greater equal, lesser equal	a >= b, a <= b
Assign b to a and check if unequal to zero	a = b

C++ - Boolean Operators

For booleans For all bits in an integer

Operation	Logical	Bitwise
not	!a	~a
and	a && b	a & b
or	a b	a b
xor	a != b	a ^ b

C++ - Operators

Operators can be overloaded by classes:

printing in STL

```
std::cout

<p
```

vector math in Eigen

```
10     Eigen::Matrix3f A = ...;
11     Eigen::Vector3f b = ...;
12
13     Eigen::Vector3f c = A * b;
```

C++ - Flow Control

Boolean expression must be in parantheses

```
if (a == b) {
    DoSomething_A();
    DoSomething_B();
    DoSomething_C();
}
```

Multiple conditional instructions scoped into { }

Single conditional instruction can be without { }

```
if (a == b)
DoSomething_A();
DoSomething_B();
DoSomething_C();

These are equivalent!

if (a == b)
DoSomething_A();
DoSomething_B();
DoSomething_B();
DoSomething_C();
```

Python users be warned: **Indentation is ignored!**





C++ - Flow Control

Boolean expression must be in parantheses

```
10    if (a == b) {
11         DoSomething_A();
12         DoSomething_B();
13         DoSomething_C();
14    }
```

Multiple conditional instructions scoped into { }

Single conditional instruction can be without { }

```
10     if (a == b)
11         DoSomething_A();
12     DoSomething_B();
13     DoSomething_C();
```

Counts as "no conditional instructions"

```
if (authorized);
reveal_secret();
```

Python users be warned: **Indentation is ignored!**





C++ - While Loops

- "While" and "do-while" loops very similar to "if"
- Same indentation pitfall for python users!

C++ - For Loops

Classical for loop with three part header:

Initialization (of loop counter)

Modification of loop variable

```
for (unsigned i = 0; i < 10; i++)
std::cout << i << std::endl;</pre>
```

Loop-condition (loops while true, checked at beginning)

C++ - Ranged For

Shorthand to iterate over containers

```
10     std::vector<int> coolNumbers = { 42, 1337, 31337};
11
12     for (int i : coolNumbers)
        std::cout << i << std::endl;</pre>
```

If modifications are to be made:

```
10    std::vector<int> coolNumbers = { 42, 1337, 31337};
11
12    for (int &i : coolNumbers)
13    i *= 2;
```



C++ - continue/break

- In all types of loops:
 - → "break;"
 - → immediately jumps out of the loop
 - → "continue;"
 - → skips the rest of this loop iteration
 - continues with next loop iteration

C++ - Functions

```
Return type

("void" for none) Function name Parameters with types

| 10 int computeAnswerToUltimateQuestion(float lots, unsigned of, const std::string &data) | 11 {
| 12 | std::this_thread::sleep_for(std::chrono::years(7'500'000'000)); | return 42; | 14 }

| Specify return value (also skips rest of function) | Pass complex objects as "const reference" to prevent copy
```

C++ - Value vs Reference

```
int a = 0;
int b = a;
b = 42;
// a still 0
```

"b" is just a copy of a

```
10    int a = 0;
11    int &b = a;
12    b = 42;
13    // a also 42
```

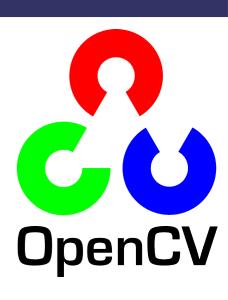
"b" is a reference to a (alias of the same instance)

Function parameters work exactly the same! (Useful for returning more than one result)

```
10 void func(int b) {
11    b = 42;
12 }
13
14 // ...
15    int a = 0;
16    func(a);
17    // a still 0
```

```
10 void func(int &b) {
11    b = 42;
12 }
13
14 // ...
15    int a = 0;
16    func(a);
17    // a also 42
```

- One of most common image processing libs
- Open source (BSD)
- C/C++, Python, Java interfaces
- Supported: Windows, Linux, Mac OS, iOS, Android
- Strong focus on real-time applications
- Multi-core processing, hardware acceleration
- 47 thousand people in user community
- 9 million downloads



OpenCV API Reference

- Introduction
 - API Concepts
- core. The Core Functionality
 - Basic Structures
 - Basic C Structures and Operations
 - Dynamic Structures
 - Operations on Arrays
 - Drawing Functions
 - XML/YAML Persistence
 - XML/YAML Persistence (C API)
 - Clustering
 - Utility and System Functions and Macros
 - OpenGL interoperability
- imgproc. Image Processing
 - Image Filtering
 - Geometric Image Transformations
 - Miscellaneous Image Transformations
 - Histograms
 - Structural Analysis and Shape Descriptors
 - Motion Analysis and Object Tracking
 - Feature Detection
 - Object Detection
- highqui, High-level GUI and Media I/O
 - User Interface
 - Reading and Writing Images and Video
 - Qt New Functions
- · video. Video Analysis
 - Motion Analysis and Object Tracking
- calib3d, Camera Calibration and 3D Reconstruction
 - Camera Calibration and 3D Reconstruction
- · features2d. 2D Features Framework
 - Feature Detection and Description
 - Common Interfaces of Feature Detectors
 - Common Interfaces of Descriptor Extractors
 - Common Interfaces of Descriptor Matchers
 - Common Interfaces of Generic Descriptor Matchers
 - Drawing Function of Keypoints and Matches
 - Object Categorization
- · objdetect. Object Detection
 - Cascade Classification
 - Latent SVM
- ml. Machine Learning
 - Statistical Models
 - Normal Bayes Classifier
 - K-Nearest Neighbors

- Support Vector Machines
- Decision Trees
- Boosting
- Gradient Boosted Trees
- Random Trees
- Extremely randomized trees
- Expectation Maximization
- Neural Networks
- MLData
- flann. Clustering and Search in Multi-Dimensional Spaces
 - Fast Approximate Nearest Neighbor Search
 - Clustering
- gpu. GPU-accelerated Computer Vision
 - GPU Module Introduction
 - Initalization and Information
 - Data Structures
 - Operations on Matrices
 - Per-element Operations
 - Image Processing
 - Matrix Reductions
 - Object Detection
 - Feature Detection and Description
 - Image Filtering
 - Camera Calibration and 3D Reconstruction
 - Video Analysis
- photo. Computational Photography
 - Inpainting
 - Denoising
- stitching, Images stitching
 - Stitching Pipeline
 - References
 - High Level Functionality

 - Features Finding and Images Matching
 - Rotation Estimation
 - Autocalibration
 - Images Warping
 - Seam Estimation
 - Exposure Compensation
 - Image Blenders
- nonfree, Non-free functionality
 - Feature Detection and Description
- contrib. Contributed/Experimental Stuff
 - Stereo Correspondence
 - FaceRecognizer Documentation
 - Retina Documentation

- OpenFABMAP
- · legacy. Deprecated stuff
 - Motion Analysis
 - Expectation Maximization
 - Histograms
 - Planar Subdivisions (C API)
 - Feature Detection and Description
 - Common Interfaces of Descriptor Extractors
 - Common Interfaces of Generic Descriptor Matchers
- ocl. OpenCL-accelerated Computer Vision
 - OpenCL Module Introduction
 - Data Structures and Utility Functions
 - Data Structures
 - Operations on Matrics
 - Matrix Reductions
 - Image Filtering
 - Image Processing
 - ml.Machine Learning
 - Object Detection
 - Feature Detection And Description
 - Video Analysis
- Camera Calibration and 3D Reconstruction
- superres. Super Resolution
- Super Resolution
- viz. 3D Visualizer
 - Viz
 - Widget



How to install.... further information:

→ General: http://opencv.org/

→ Tutorials: http://docs.opencv.org/2.4/doc/tutorials/tutorials.html

→ Docu: http://docs.opencv.org/2.4.13/

- → www.giyf.com
- → Discussion forum on ISIS

```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newlmg);
   waitKey(0);
```

```
#include <iostream>
                                                 Includes all opency headers
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
    namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newImg);
   waitKey(0);
```

```
#include <iostream>
#include <opencv2/opencv.hpp>
                                                 To use opency namespace.
using namespace std;
                                                 Otherwise put cv:: in front
using namespace cv;
int main(int argc, char** argv){
                                                 of all opency functions etc.
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newImg);
   waitKey(0);
```

```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
                                  Reads an image from the path provided
   Mat img = imread( argv[1] );
                                  in the first command line argument
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newlmg);
   waitKey(0);
```



```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example"); ► Creates a window with the ID "example"
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newlmg);
   waitKey(0);
```

```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example");
                                                Displays the content of img
   imshow( "example", img);
                                                in the window "example"
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newImg);
   waitKey(0);
```



```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1] );
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
                                   Creates a matrix of same size as img
   fancyFunction(img, newImg);
                                   containing one channel of 32bit floats
   imwrite("coolResult.png", newImg);
   waitKey(0);
```

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```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
                                  The use of smart pointers in Mat allows
   fancyFunction(img, newImg);
                                  to use function arguments as output
   imwrite("coolResult.png", newImg);
   waitKey(0);
```

```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1] );
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newImg);
                                                       Writes image to disk
   waitKey(0);
```



```
#include <iostream>
#include <opencv2/opencv.hpp>
using namespace std;
using namespace cv;
int main(int argc, char** argv){
   Mat img = imread( argv[1]);
   // show image
   namedWindow( "example");
   imshow( "example", img);
   Mat newImg( img.rows, img.cols, CV_32FC1 );
   // do something fancy
   fancyFunction(img, newImg);
   imwrite("coolResult.png", newImg);
                                   Stops execution until key is pressed
```

Matrix generation, some examples:

```
Mat M1 = Mat(2, 3, CV_32FC1);  // creates 2x3 matrix of floats (one channel)
Mat M2 = Mat(3, 2, CV_64FC2);  // creates 3x2 matrix of doubles (two channels)
Mat M3 = Mat(3, 3, CV_8UC3);  // creates 3x3 matrix of uint (three channels)
Mat M4 = Mat::zeros(3, 3, CV_32FC1);  // creates 3x3 matrix of floats, all set to 0
Mat M5 = Mat::ones(3, 3, CV_32FC1);  // creates 3x3 matrix of floats, all set to 1
Mat M6 = (Mat_{float})(3,3) << 1, 2, 3, 4, 5, 6, 7, 8, 9);
```

Accessing matrix data (the easy way)

```
M1.at < float > (row, column) = 22.0 / 7.0;

M2.at < Vec2d > (row, column) = Vec2d(0,1);

int s = M3.at < Vec3b > (row, column)[0];
```





<u>Accessing Image data - The hard way</u>

```
float sum( Mat& img ){
    float s = 0.0;
    for(int y=0; y < img.rows; y++){
        uchar* data = img.ptr<uchar>(y);
        for(int x=0; x < img.cols; x++) {
            s += data[x];
        }
    }
    return s;
}</pre>
```

1. Exercise

C++ and OpenCV

OpenCV-functions, that might be useful:

```
→ Images I/O:
   → imread(...), imwrite(...)
→ Color conversion:
   → cvtColor(...), e.g. CV_BGR2GRAY
→ Type conversion:
   → M.convertTo(...)
→ Matrix creation:
   → Mat(...), Mat::zeros(...), Mat::eye(...)
→ Setting/Getting elements of a matrix:
   → M.at<T>(...)
→ Matrix multiplication:
   → M1 * M2
→ Matrix multiplication (component-wise):
   → M1.multiply(M2)
```

1. Exercise - Part I: Theory

1. What is a digital image?

2. What does the paradigm "bottom-up processing" mean?

3. State at least three fundamentally different image sources!

1. Exercise - Part II: Practical

C++ and OpenCV

Given:

- CMake based build system (CMakeLists.txt)
- Main function (main.cpp)
- Test function (test.cpp)
- Function declaration (Dip1.h)
- Basic functionality (Dip1.cpp)

Todo:

- [Setup VM]
- Optionally: [Install programming environment directly]
- Dip1.cpp
 - Mat Dip1::doSomethingThatMyTutorIsGonnaLike(Mat&)
 - → Do something (reasonable)

Deadline:

Next meeting at 29.10.2019, 16pm



1. Exercise - Part II: Given

```
FILE: test.cpp
int main(int argc, char** argv)
```

- Main function
 - → Usage:
 - → ./test path_to_image
 - → Calls test_doSomethingThatMyTutorIsGonnaLike(...)
 - → Which calls dip1::doSomethingThatMyTutorIsGonnaLike(..)

1. Exercise - Part II: To Do

Mat doSomethingThatMyTutorIsGonnaLike(Mat& img)

img : input image

return : output image

→ does something cool... (hopefully)