

MS Project

Estimating model order for 1-D and 2-D cisoid models using adaptively penalizing likelihood rule: Large sample consistency properties

Anupreet Porwal¹

Supervised by: Prof. Amit Mitra¹, Prof. Sharmishtha Mitra¹

¹Department of Mathematics and Statistics
Indian Institute of Technology Kanpur

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1 Introduction

- Model order selection
- PAL rule

2 PAL consistency for 1-D cisoid model

- 1-D cisoid model
- PAL rule for 1-D cisoid
- Consistency of PAL rule
- Numerical examples

3 PAL rule consistency for 2-D Cisoid model

- 2-Dimensional Cisoid Model
- PAL rule for 2-D cisoid model
- Consistency of PAL rule

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Model order selection

- A fundamental problem in time series and signal processing
- Model order estimation determines the **complexity of the model**; allowing further estimation of other real valued model parameters

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- Two kind of estimation approaches:
 - **maximum likelihood method(MLM) based rules**: AIC, BIC, GIC etc.
 - **Data driven approaches**: bootstrapping, cross validation based approaches

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- Two kind of estimation approaches:
 - **maximum likelihood method(MLM) based rules**: AIC, BIC, GIC etc.
 - **Data driven approaches**: bootstrapping, cross validation based approaches
- Focus on MLM based order selection rules

Model order selection-II

- Information criterion rules like AIC[1] and BIC[2, 3] extensively studied
- AIC is not consistent and but is min-max optimal
- while for BIC, probability of correct order selection tends to 1 as $n \rightarrow \infty$ (consistent) but is not min-max optimal

Model order selection-II

- Information criterion rules like AIC[1] and BIC[2, 3] extensively studied
- AIC is not consistent and but is min-max optimal
- while for BIC, probability of correct order selection tends to 1 as $n \rightarrow \infty$ (consistent) but is not min-max optimal
- Ideally, the penalty term in order selection rules should follow
 - 1 for $m \leq m_o$, penalty should be small so that rule's value increases as m increases
 - 2 for $m > m_o$, penalty term should be large such that the rule's value decreases with increasing m

where m is model order and m_o is the true model order

- Introduced by Stoica and Babu[4], where model order estimation based on penalizing adaptively the likelihood
- Possess **Oracle like** properties that are mentioned in previous slide
- PAL based order estimation method shown consistent for non linear real sinusoidal model in [5]
- Here, we investigate the asymptotic statistical properties of the same for **1-D and 2-D cisoid models**
- Simulation examples to compare PAL's performance with other order selection rules for 1-D cisoid models

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1-Dimensional Cisoid model

- Building blocks of Digital signal processing

1-Dimensional Cisoid model

- Building blocks of Digital signal processing
- $\forall t = 1, 2, \dots, n$

$$y_t = \sum_{k=1}^m \alpha_k e^{it\omega_k} + \epsilon_t \quad (1)$$

$$y_t = f(t, \theta_m) + \epsilon_t \quad (2)$$

where

$\theta_m = (\alpha_{1_R}, \alpha_{1_C}, \omega_1, \dots, \alpha_{m_R}, \alpha_{m_C}, \omega_m)'_{3m \times 1}$ = unknown signal parameter vector

α_{j_R} and α_{j_C} denotes the real and the imaginary part of α_j for $j=1, \dots, m$
 m_o = true number of components in the the observed signal

1-Dimensional Cisoid model-Assumptions

- ϵ_t are i.i.d complex valued gaussian with zero mean s.t.

$$\epsilon_t = \epsilon_{t_R} + i\epsilon_{t_C} \quad (3)$$

$$\epsilon_{t_R} \sim \mathcal{N}(0, \sigma^2/2) \quad (4)$$

$$\epsilon_{t_C} \sim \mathcal{N}(0, \sigma^2/2) \quad (5)$$

and ϵ_{t_R} and ϵ_{t_C} are independent

- $\forall k = 1, 2, \dots, m_o : \omega_k \in (0, 2\pi); \omega_j \neq \omega_k, \forall j \neq k$. Furthermore, α_k are bounded
- The true model parameter vector θ_{m_o} is an interior point in the parameter space $\Theta \subset \mathbb{R}^{3m_o}$

PAL rule for 1-D cisoid

Consider the two Generalized likelihood ratios,

$$r_m = 2 \ln \left[\frac{f_{m-1}(y, \hat{\theta}_{m-1}^*)}{f_0(y, \hat{\theta}_0^*)} \right] \quad \rho_m = 2 \ln \left[\frac{f_{\tilde{m}}(y, \hat{\theta}_{\tilde{m}}^*)}{f_{m-1}(y, \hat{\theta}_{m-1}^*)} \right]$$

where,

$\hat{\theta}_k^* = (\hat{\theta}_k, \hat{\sigma}_k^2)$ = M.L.E. of underlying signal and noise parameter vector θ_k^*
 $f_0(y, \hat{\theta}_0^*)$ = p.d.f of y when M_0 is the model i.e., $f(\theta_0) = 0$

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 $f_0(y, \hat{\theta}_0^*)$ = p.d.f of y when M_0 is the model i.e., $f(\theta_0) = 0$

The PAL rule can then be defined using the GLR ratios as follows:

$$PAL(m) = -2 \ln(f_m(y, \hat{\theta}_m^*)) + (3m + 1) \ln(3\tilde{m} + 1) \frac{\ln(r_m + 1)}{\ln(\rho_m + 1)} \quad (6)$$

$$\hat{m} =_{m \in \{1, 2, \dots, \tilde{m}\}} [PAL(m)] \quad (7)$$

where \tilde{m} is the maximum number of cisoid components

Consistency of PAL rule

Lemma 1

Under the assumptions A1-A3, $\forall m \leq m_o$, as $n \rightarrow \infty$

$$\hat{\sigma}_m^2 = \sigma^2 + \sum_{j=1}^{m_o} \alpha_j^H \alpha_j - \sum_{j=1}^m \hat{\alpha}_j^H \hat{\alpha}_j + o(1) \text{ a.s.} \quad (8)$$

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Lemma 2

Under A1-A3, for any integer $k \geq 1$

$$\hat{\sigma}_{m_o+k}^2 = \hat{\sigma}_{m_o}^2 - \sum_{j=1}^k \frac{I_\epsilon(\hat{\omega}_{m_o+j})}{n} + o\left(\frac{\ln n}{n}\right) \text{ a.s. as } n \rightarrow \infty \quad (9)$$

where $I_\epsilon(\omega)$ corresponds to periodogram of underlying white noise process and $\hat{\omega}_{m_o+1}, \hat{\omega}_{m_o+2}, \dots, \hat{\omega}_{m_o+k}$ are the k largest frequencies corresponding to $I_\epsilon(\omega)$

Lemma 3

Under assumptions A1-A3, r_m satisfies

$$r_m = \begin{cases} 0 & m = 1 \\ O(n) & 2 \leq m \leq \tilde{m} \end{cases} \quad (10)$$

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Lemma 4

Under the assumptions A1-A3, ρ_m satisfies

$$\rho_m = \begin{cases} O(n) & m \leq m_o \\ O_p(1) & m = m_o + 1, m_o + 2, \dots, \tilde{m} \end{cases} \quad (11)$$

Consistency of PAL rule-III

Theorem

Under A1-A3, if m_o is true order ($m_o \leq \tilde{m}$) and \hat{m} is the estimated model order using PAL rule then

$$P(\hat{m} \neq m_o) \rightarrow 0 \text{ as } n \rightarrow \infty \quad (12)$$

Consistency of PAL rule-III

Theorem

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$$P(\hat{m} \neq m_o) \rightarrow 0 \text{ as } n \rightarrow \infty \quad (12)$$

Sketch of the Proof: Consider two cases:

Case I-**Underestimation** ($m \leq m_o$): Show that

$$\frac{1}{n}(PAL(m) - PAL(m_o)) \rightarrow 2 \ln \left(1 + \frac{\sum_{j=m+1}^{m_o} \alpha_j^H \alpha_j}{\sigma^2} \right) \text{ a.s.} \quad (13)$$

as $n \rightarrow \infty$ where R.H.S. is a strictly positive and bounded quantity. Use it to show

$$P(\hat{m} < m_o) = P(PAL(m) < PAL(m_o) \text{ for some } m < m_o) \quad (14)$$

$$\leq \sum_{m=1}^{m_o-1} P\left(\frac{1}{n}(PAL(m) - PAL(m_o)) < 0\right) \rightarrow 0 \quad (15)$$

Sketch of proof- Continued

Case II-**Overestimation** ($m > m_o$): Using the asymptotic theory of likelihood ratios(see [6,7]) show that $\frac{1}{\ln(n)} \left(2n \ln \left(\frac{\hat{\sigma}_m^2}{\hat{\sigma}_{m_o}^2} \right) \right) = o_p(1)$

Use this to show:

$$P \left(\frac{1}{\ln n} \left(PAL(m) - PAL(m_o) \right) > 0 \right) \rightarrow 1 \text{ as } n \rightarrow \infty \quad (16)$$

Thus,

$$P(\hat{m} > m_o) = P(PAL(m) < PAL(m_o) \text{ for some } m > m_o) \quad (17)$$

$$\leq \sum_{m=m_o+1}^{\tilde{m}} P \left(\frac{1}{\ln n} (PAL(m) - PAL(m_o)) < 0 \right) \rightarrow 0 \quad (18)$$

as $n \rightarrow \infty$. This implies

$$P(\hat{m} \neq m_o) \rightarrow 0 \text{ as } n \rightarrow \infty \quad (19)$$

Numerical examples

Example

Simulation example

$$y_t = \sum_{k=1}^m \alpha_k e^{it\omega_k} + \epsilon_t$$

$$\alpha_1 = 3 + i2, \quad \alpha_2 = 2 + i1.66, \quad \alpha_3 = 1.75 + i$$

$$\omega_1 = 0.8\pi, \quad \omega_2 = 1.2\pi, \quad \omega_3 = 1.4\pi$$

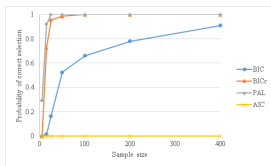
ϵ_t are i.i.d complex valued gaussian with zero mean s.t.

$$\epsilon_t = \epsilon_{t_R} + i\epsilon_{t_C} \tag{20}$$

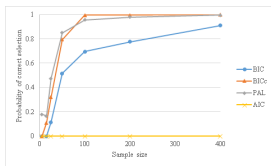
$$\epsilon_{t_R} \sim \mathcal{N}(0, \sigma^2/2) \tag{21}$$

$$\epsilon_{t_C} \sim \mathcal{N}(0, \sigma^2/2) \tag{22}$$

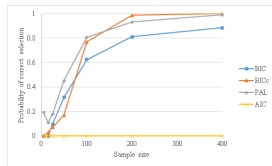
ϵ_{t_R} and ϵ_{t_C} are independent



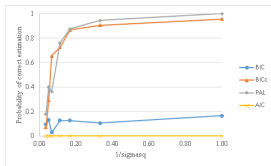
(a) $\sigma^2 = 1$



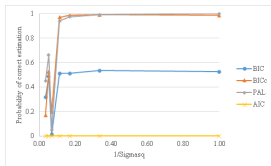
(b) $\sigma^2 = 15$



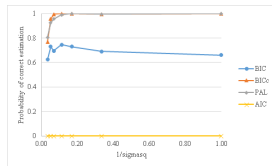
(c) $\sigma^2 = 30$



(d) *Sample size = 25*



(e) *Sample size = 50*



(f) *Sample size = 100*

Figure: (a)-(c): Plot of the probability of correct estimation of model order against different sample size for fixed values of variance of noise; (d)-(f) plot the probability of correct estimation with different values of σ^2 for fixed sample sizes of 25, 50 and 100

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2-Dimensional Cisoid Model

- Widespread application in texture analysis

2-Dimensional Cisoid Model

- Widespread application in texture analysis
- $\forall s, t$ such that $1 \leq s \leq S; 1 \leq t \leq T$

$$y(s, t) = \sum_{k=1}^m \alpha_k e^{i(s\beta_k + t\omega_k)} + \epsilon(s, t) \quad (23)$$

$$y(s, t) = f(s, t, \theta_m) + \epsilon(s, t) \quad (24)$$

$\theta_m = (\alpha_{1R}, \alpha_{1C}, \beta_1, \omega_1, \dots, \alpha_{mR}, \alpha_{mC}, \beta_m, \omega_m)'_{4m \times 1}$: vector of unknown signal parameters

m_o = True number of components in the the observed signal.

2-Dimensional Cisoid Model-Assumptions

- $\epsilon(s, t)$ are i.i.d complex valued gaussian with zero mean s.t.

$$\epsilon(s, t) = \epsilon_R(s, t) + i\epsilon_C(s, t) \quad (25)$$

$$\epsilon_R(s, t) \sim \mathcal{N}(0, \sigma^2/2) \quad (26)$$

$$\epsilon_C(s, t) \sim \mathcal{N}(0, \sigma^2/2) \quad (27)$$

and $\epsilon_R(s, t)$ and $\epsilon_C(s, t)$ are independent.

- $\forall k = 1, 2, \dots, m_o : (\beta_k, \omega_k) \in (0, 2\pi) \times (0, 2\pi)$;
where (β_k, ω_k) are pairwise different i.e. $\omega_j \neq \omega_k$ or $\beta_j \neq \beta_k, \forall j \neq k$.
Furthermore, $\forall k = 1, 2, \dots, m_o : \alpha_k$ are bounded
- The true model parameter vector θ_{m_o} is an interior point in the parameter space $\Theta \subset \mathbb{R}^{4m_o}$

PAL rule for 2-D cisoid model

Using the two Generalized likelihood ratios defined before, the **PAL rule** for this model can then be defined as follows:

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$$\hat{m} =_{m \in \{1, 2, \dots, \tilde{m}\}} [PAL(m)] \quad (29)$$

where \tilde{m} is the maximum number of components in the model

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where \tilde{m} is the maximum number of components in the model

Remark: Let $\{\Psi_i\}$ be a sequence of rectangles s.t.

$$\Psi = \{(s, t) \in \mathbb{Z}^2 | 1 \leq s \leq S_i, 1 \leq t \leq T_i\} \quad (30)$$

Then, sequence of subsets $\{\Psi_i\}$ is said to tend to infinity as $i \rightarrow \infty$ if

$$\lim_{i \rightarrow \infty} \min(S_i, T_i) \rightarrow \infty \text{ and } 0 < \lim_{i \rightarrow \infty} \left(\frac{S_i}{T_i} \right) < \infty \quad (31)$$

To simplify notation, omit subscript i . Thus, $\Psi(S, T) \rightarrow \infty$ implies both S and T tend to infinity as a function of i , and roughly at the same rate

Consistency of PAL rule

Lemma 1

Under the assumptions A1-A3, $\forall m \leq m_o$, as $\Psi(S, T) \rightarrow \infty$

$$\hat{\sigma}_m^2 = \sigma^2 + \sum_{j=1}^{m_o} \alpha_j^H \alpha_j - \sum_{j=1}^m \hat{\alpha}_j^H \hat{\alpha}_j + o(1) \text{ a.s.} \quad (32)$$

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Lemma 2

Under A1-A3, for any integer $k \geq 1$, as $\Psi(S, T) \rightarrow \infty$

$$\hat{\sigma}_{m_o+k}^2 = \hat{\sigma}_{m_o}^2 - \sum_{j=1}^k \frac{I_\epsilon(\hat{\beta}_{m_o+j}, \hat{\omega}_{m_o+j})}{ST} + o\left(\frac{(\ln(ST) \ln S \ln T)^{1/2}}{ST}\right) \text{ a.s.} \quad (33)$$

where $I_\epsilon(\beta, \omega)$ corresponds to periodogram of underlying white noise process and $(\hat{\beta}_{m_o+1}, \hat{\omega}_{m_o+1}), (\hat{\beta}_{m_o+2}, \hat{\omega}_{m_o+2}), \dots, (\hat{\beta}_{m_o+k}, \hat{\omega}_{m_o+k})$ are the k largest frequencies corresponding to $I_\epsilon(\beta, \omega)$

Lemma 3

Under assumptions A1-A3, r_m satisfies

$$r_m = \begin{cases} 0 & m = 1 \\ O(ST) & 2 \leq m \leq \tilde{m} \end{cases} \quad (34)$$

Consistency of PAL rule-II

Lemma 3

Under assumptions A1-A3, r_m satisfies

$$r_m = \begin{cases} 0 & m = 1 \\ O(ST) & 2 \leq m \leq \tilde{m} \end{cases} \quad (34)$$

Lemma 4

Under the assumptions A1-A3, ρ_m satisfies

$$\rho_m = \begin{cases} O(ST) & m \leq m_o \\ O_p(1) & m = m_o + 1, m_o + 2, \dots, \tilde{m} \end{cases} \quad (35)$$

Consistency of PAL rule-III

Theorem

Under A1-A3, if m_o is true order ($m_o \leq \tilde{m}$) and \hat{m} is the estimated model order using PAL rule then

$$P(\hat{m} \neq m_o) \rightarrow 0 \text{ as } \Psi(S, T) \rightarrow \infty \quad (36)$$

Consistency of PAL rule-III

Theorem

Under A1-A3, if m_o is true order ($m_o \leq \tilde{m}$) and \hat{m} is the estimated model order using PAL rule then

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Sketch of the Proof: Consider two cases:

Case I-**Underestimation** ($m \leq m_o$): Show that

$$\frac{1}{ST}(PAL(m) - PAL(m_o)) \rightarrow 2 \ln \left(1 + \frac{\sum_{j=m+1}^{m_o} \alpha_j^H \alpha_j}{\sigma^2} \right) \text{ a.s.} \quad (37)$$

as $\Psi(S, T) \rightarrow \infty$ where R.H.S. is a strictly positive and bounded quantity. Use it to show

$$P(\hat{m} < m_o) = P(PAL(m) < PAL(m_o) \text{ for some } m < m_o) \quad (38)$$

$$\leq \sum_{m=1}^{m_o-1} P\left(\frac{1}{ST}(PAL(m) - PAL(m_o)) < 0\right) \rightarrow 0 \quad (39)$$

Sketch of proof- Continued

Case II-**Overestimation** ($m > m_o$): Using the asymptotic theory of likelihood ratios(see [6,7]) show that $\frac{1}{\ln(ST)} \left(2ST \ln \left(\frac{\hat{\sigma}_m^2}{\hat{\sigma}_{m_o}^2} \right) \right) = o_p(1)$

Use this to show:

$$P \left(\frac{1}{\ln(ST)} \left(PAL(m) - PAL(m_o) \right) > 0 \right) \rightarrow 1 \text{ as } \Psi(S, T) \rightarrow \infty \quad (40)$$

Thus,

$$P(\hat{m} > m_o) = P(PAL(m) < PAL(m_o) \text{ for some } m > m_o) \quad (41)$$

$$\leq \sum_{m=m_o+1}^{\tilde{m}} P \left(\frac{1}{\ln(ST)} (PAL(m) - PAL(m_o)) < 0 \right) \rightarrow 0 \quad (42)$$

as $\Psi(S, T) \rightarrow \infty$. This implies

$$P(\hat{m} \neq m_o) \rightarrow 0 \text{ as } \Psi(S, T) \rightarrow \infty \quad (43)$$

Conclusion

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- Simulation tests suggests PAL performs **equally well or better than** other popular order selection rules
- As sample size increase or signal to noise ratio increases(with decrease in noise variance), the **probability of correct estimation using PAL based approach goes to 1**
- Outlook
 - PAL consistency for chirp signal model
 - High SNR consistency of PAL based order selection rule

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