# MP UNIT 6 80386DX Signals, Bus Cycles and 80387 Coprocessor

# **Topics**

 80386DX Signals- Pin Diagram of 80386 and description.

80386DX Bus Cycles- System Clock, Bus States,
 Pipelined and Non-pipelined Bus Cycles.

80387 NDP-

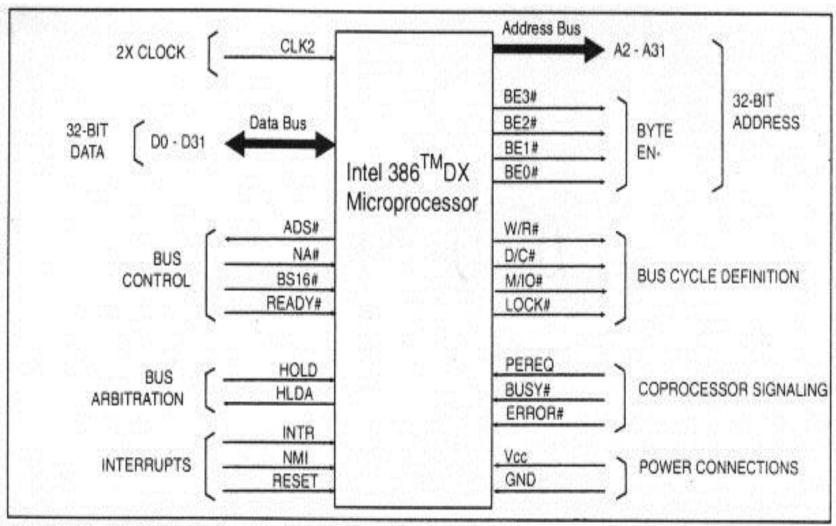
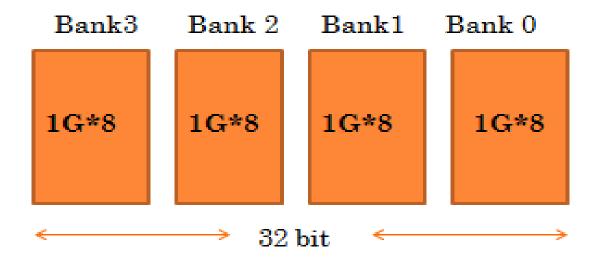


Figure 13-2. 80386 Block Diagram (# indicates active low)

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- <u>CLK2</u>: The input pin provides the basic system clock timing for the operation of 80386.
- <u>D0 D31:</u> These 32 lines act as bidirectional data bus during different access cycles.
- A31 A2: These are upper 30 bit of the 32- bit address bus.
- **BEO to BE3**: (Active Low) The 32- bit data bus supported by 80386 and the memory system of 80386 can be viewed as a 4-byte wide memory access mechanism.



BE0,BE1,BE2 and BE3 are active low signals.

### **Bus Control**

#### **ADS#: (Address Data Strobe)**

Active when issued a valid request.

The address status output pin indicates that the address bus and **Bus Cycle Definition Pins**( W/R#, D/C#, M/IO#, BEO# to BE3# ) are carrying the respective valid signals.

BS16#: The bus size — 16 input pin allows the interfacing of 16 bit devices with the 32 bit wide 80386 data bus.

• **READY#:** The ready signals indicates to the CPU that the **previous bus cycle has been terminated** and **the bus is ready for the next cycle.** The signal is used to insert WAIT states in a bus cycle and is useful for interfacing of slow devices with CPU.

• <u>NA#:</u> Gives address of next instruction if pipelining is enabled. If pipelining is not enabled, this pin is high, if instruction is in waiting state.

### **Bus Arbitration**

• **HOLD**: The Bus hold input pin enables the other bus masters to gain control of the system bus if it is asserted.

 HLDA: The bus hold acknowledge output indicates that a valid bus hold request has been received and the bus has been relinquished by the CPU.

## **Interrupts**

- **INTR:** This interrupt pin is a mask-able interrupt, that can be masked using the IF of the flag register.
- <u>NMI:</u> A valid request signal at the non-mask-able interrupt request input pin internally generates a non-mask-able interrupt of type2.
- <u>RESET:</u> A high at this input pin suspends the current operation and restart the execution from the starting location.

## **Co-Processor Signaling**

 <u>BUSY#:</u> The busy input signal indicates to the CPU that the <u>coprocessor</u> is busy with the allocated task.

• **ERROR#:** The error input pin indicates to the CPU that the coprocessor has encountered an error while executing its instruction.

PEREQ: (Processor extension request)
 Output signal indicates to the CPU to fetch data.

# A bus cycle definition pins

• LOCK#: BUS LOCK is a bus cycle definition pin that indicates that system have locked system bus of other peripherals.

 W/R#: WRITE/READ is a bus cycle definition pin that distinguishes write cycles from read cycles. • <u>D/C#:</u> DATA/CONTROL is a bus cycle definition pin that distinguishes data cycles, either memory or I/O, from control cycles which are: interrupt acknowledge, halt, and instruction fetching.

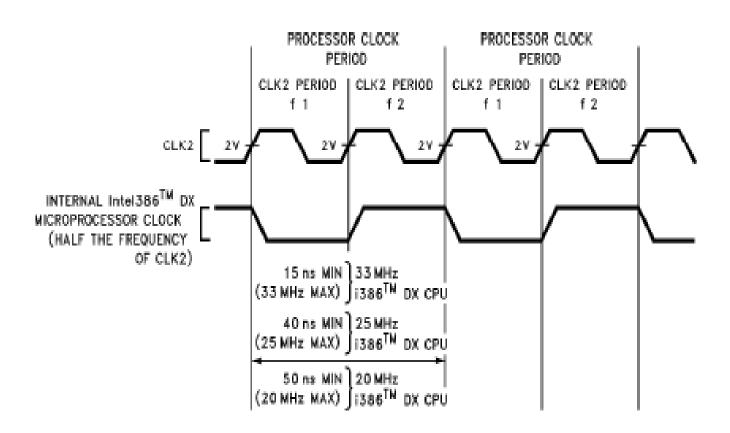
 M/IO#: MEMORY I/O is a bus cycle definition pin that distinguishes memory cycles from input/output cycles.

#### **Power Connection Pins**

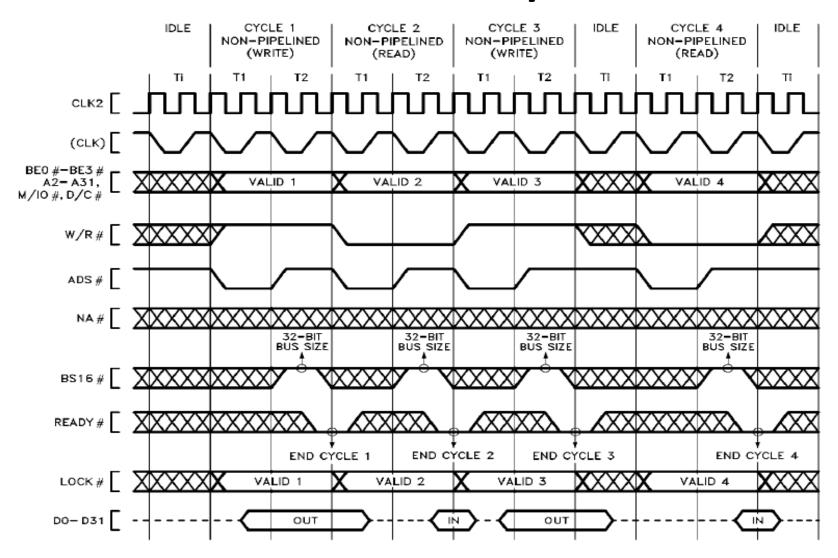
• **VCC:** These are system power supply lines.

• **GND**:

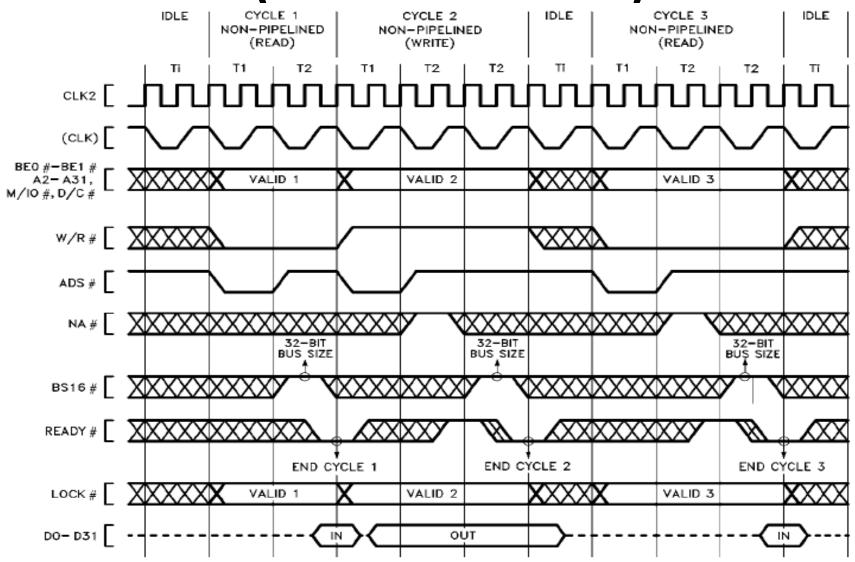
# **System Clock**



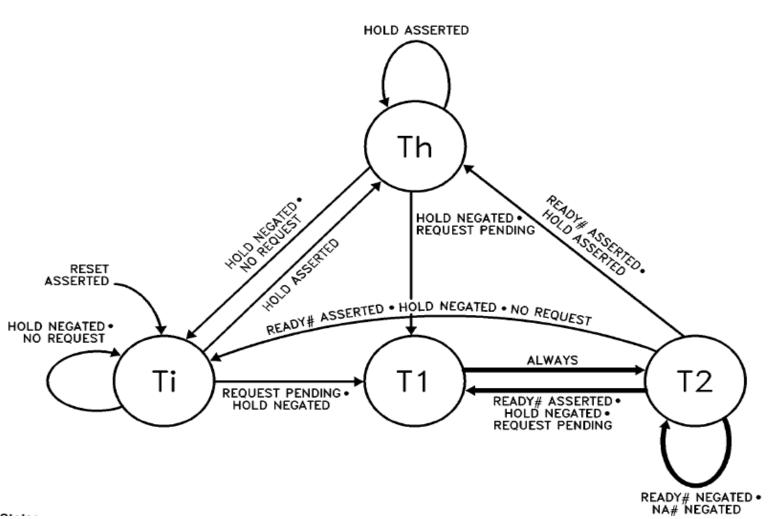
# Non-pipelined read & write cycles (No wait states)



# Non-pipelined read & write cycles (With wait states)

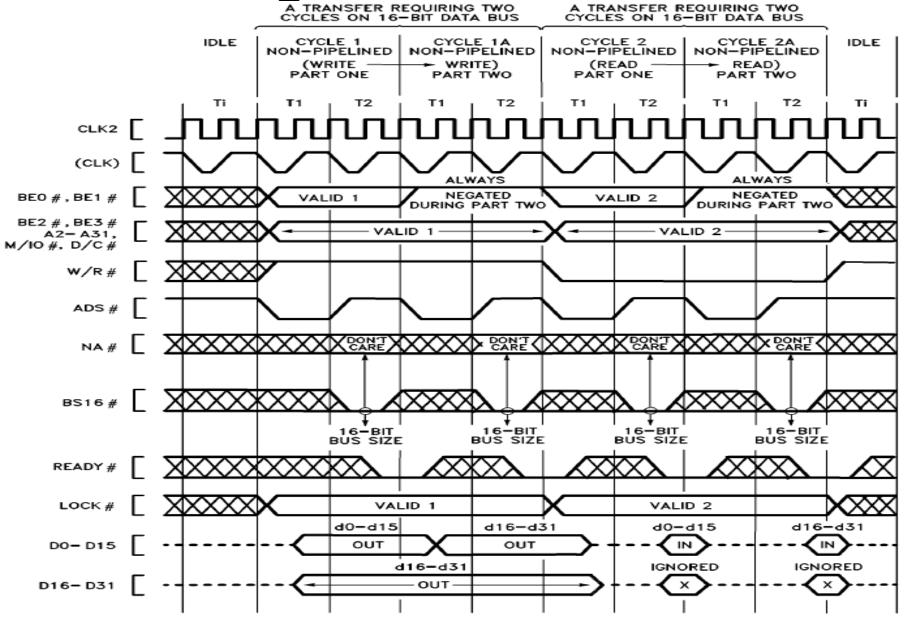


# Bus States (Using non-pipelined address)

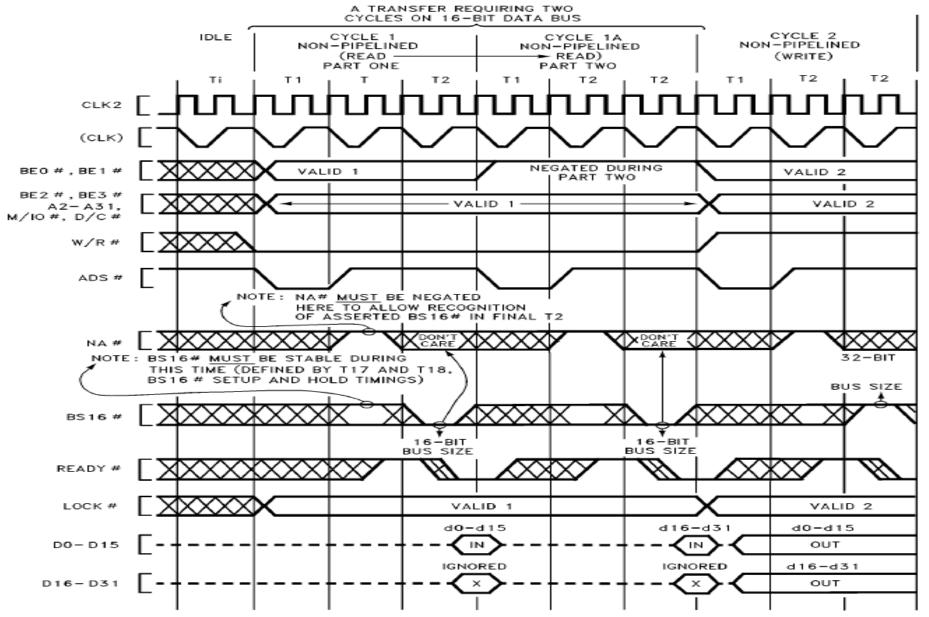


- T1: First clock of a non-pipelined bus cycle (Intel386 DX drives new address and asserts ADS#)
- T2: subsequent clocks of a bus cycle when NA# has not been sampled asserted in the current bus cycle
- Ti: idle state
- Th: Hold acknowledge state (Intel386 DX asserts HLDA)
- The fastest bus cycle consists of two states: T1 and T2.

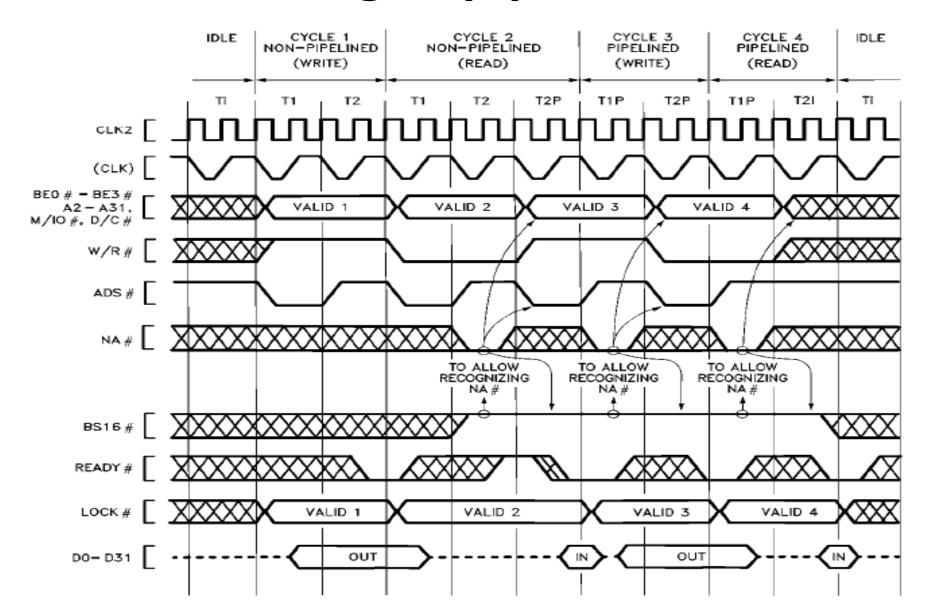
## **Asserting BS16#: No wait states**



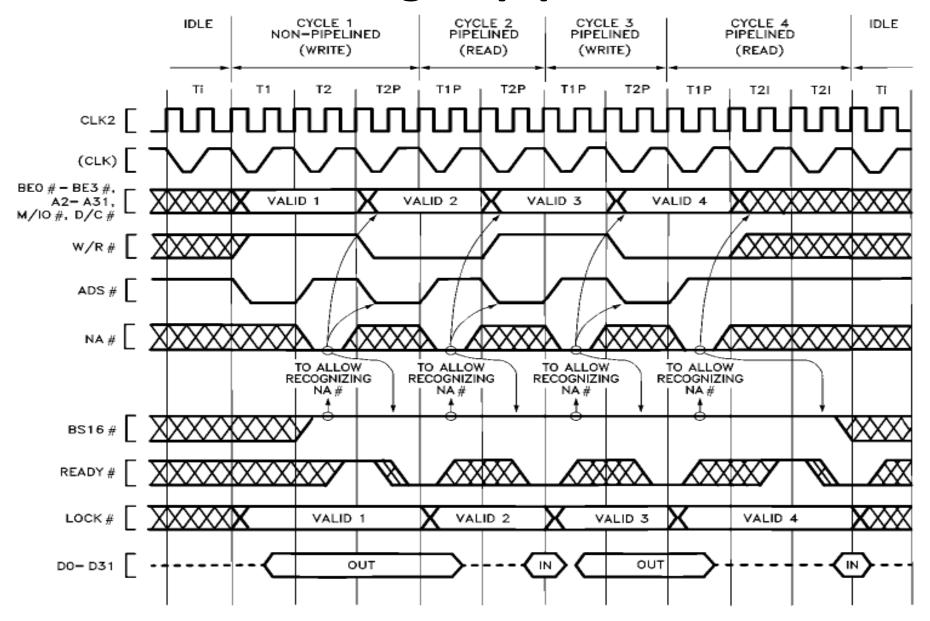
# **Asserting BS16#: Wait states**

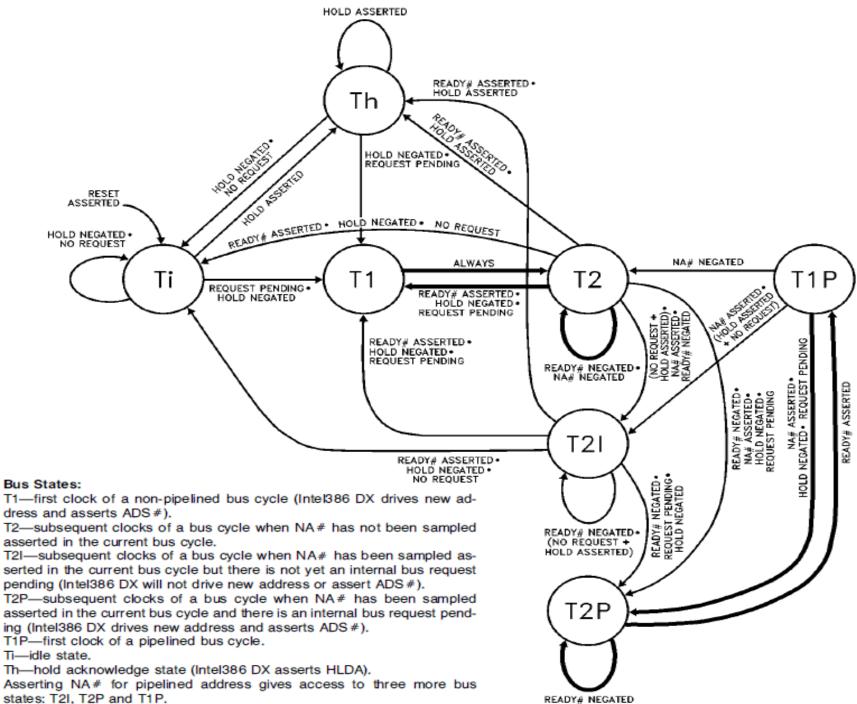


# Transitioning to pipelined address



## Fast Transitioning to pipelined address





Using pipelined address, the fastest bus cycle consists of T1P and T2P.

### 80387: NDP

- Control Register bits for Coprocessor support
- 80387 Register Stack
- Data Types
- Load and Store Instructions
- Trigonometric and Transcendental Instructions
- Interfacing signals of 80386DX with 80387.

### Features: 80387

- High performance 80-Bit Internal Architecture.
- Implements IEEE standard 754-1985 for Binary floating-point arithmetic.
- Expands Intel386DX CPU data types to include 32-, 64-, 80-bit floating point, 32-, 64-bit integers and 18-bit BCD operands.
- Extends Intel386DX CPU instruction set to include Trigonometric, Logarithmic, Exponential and Arithmetic instructions for all data types.

- Support transcendental operations for SINE, COSINE, TANGENT, ARCTANGENT and LOGARITHM.
- Built-in Exception handling.
- Operates independently in all modes of 80386.
- Eight 80-bit Numeric registers.
- Available in 68-pin PGA package.
- One version supports 16MHz-33MHz.

# Register use of 8087

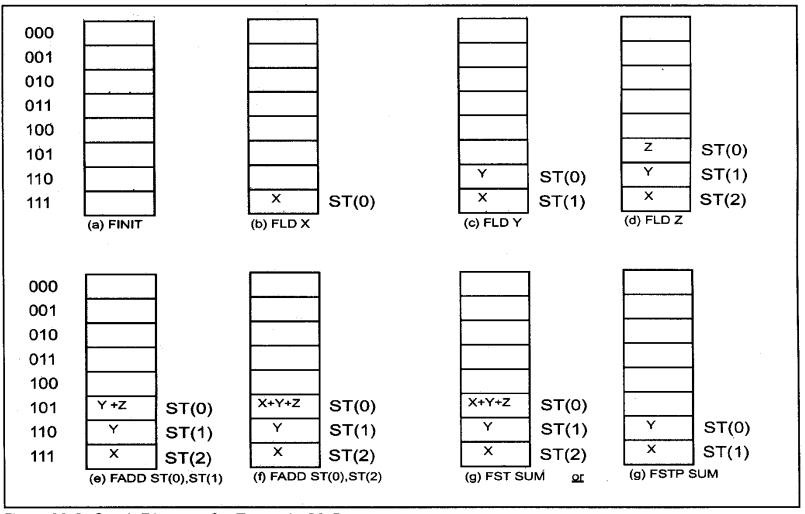


Figure 20-2. Stack Diagram for Example 20-5

# **Register Set**

• Data registers: Eight 80-bit registers.

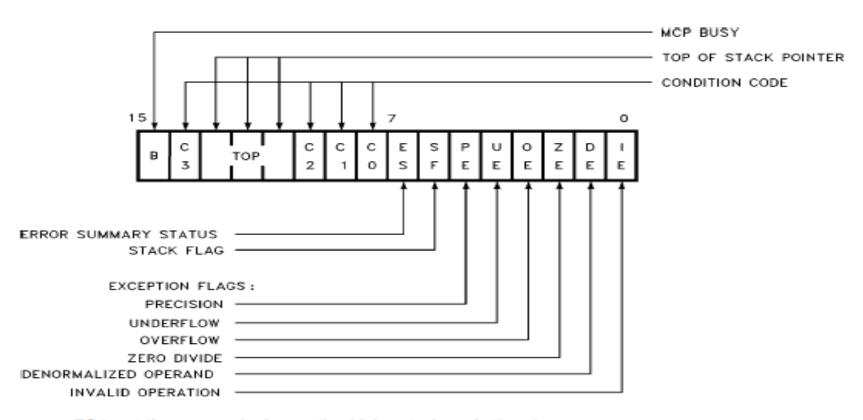
 Tag Word: The tag word marks the content of each numeric data register, two bits for each data register.

• **Status word:** The 16-bit status word reflects the overall state of the MCP (Math Coprocessor).

 Instruction and Data pointers: Two pointer registers allows identification of the failing numeric instruction which supply the address of failing numeric instruction and the address of its numeric memory operand.

 Control Word: Several processing options are selected by loading a control word from memory into the control register.

### MCP Status Word

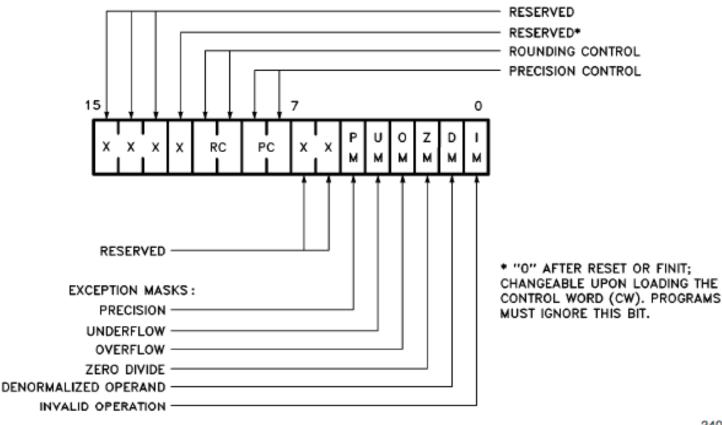


ES is set if any unmasked exception bit is set; cleared otherwise. See Table 2.2 for interpretation of condition code. TOP values:

000 = Register 0 is Top of Stack 001 = Register 1 is Top of Stack

111 = Register 7 is Top of Stack For definitions of exceptions, refer to the section entitled "Exception Handling"

# Control register bits for coprocessor support



#### Precision Control

00-24 bits (single precision)

01—(reserved)

10-53 bits (double precision)

11-64 bits (extended precision)

#### Rounding Control

00-Round to nearest or even

01—Round down (toward -∞)

10-Round up (toward + ∞)

11-Chop (truncate toward zero)

2404

# Control register bits ...

 The low-order byte of this control word configures the MCP error and exception masking.

	Х	Х	PM	UM	ОМ	ZM	DM	IM
15	7	6	5	4	3	2	1	0

- 5 Precision mask
- 4 Underflow mask
- 3 Overflow mask
- 2 Zero Divide mask
- 1 Denormalized operand mask
- 0 Invalid operation mask

## Control register bits ...

 The high-order byte configures operating mode of MCP, including precision and rounding

	R	C	PC				
15 12	11	10	9	8	7 0		

#### **Precision Control (Bits 9,8)**

00 – 24 bits (single precision)

01 – Reserved

10 – 53 bits (double precision)

11 – 64 bits (extended precision)

#### **Rounding Control (Bits 11, 10)**

00 - Round to nearest or even

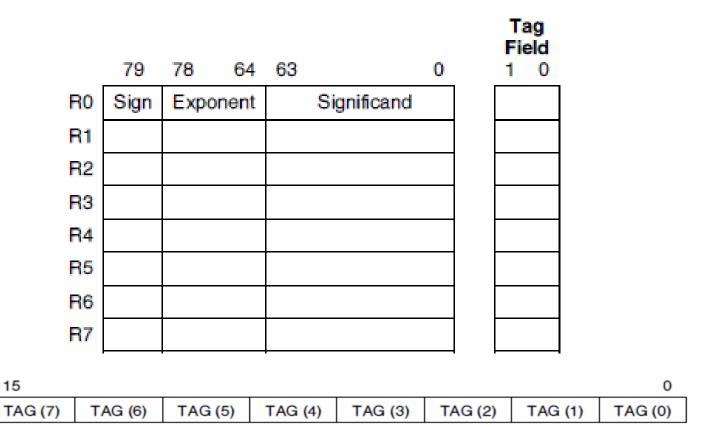
01 – Round down (toward -∞)

10 − Round up (toward  $+\infty$ )

11 – Chop (Truncate toward zero)

6 bits are reserved (Bits 6, 7, 12, 13, 14 & 15)

# 80387 Register Stack



#### TAG VALUES:

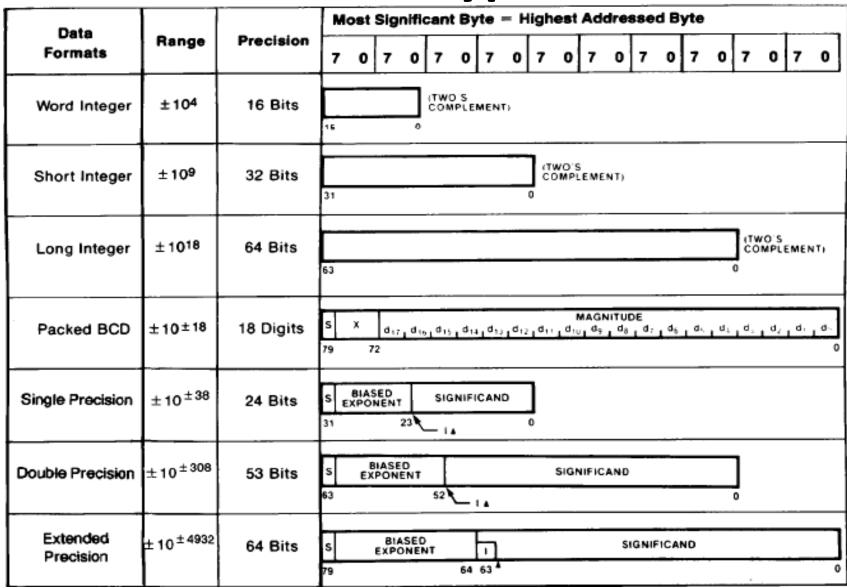
15

00 = Valid

10 = QNaN, SNaN, Infinity, Denormal and Unsupported Formats

11 = Empty

# **Data Types**



#### **Instruction Set**

- Data transfer instructions
- Non-transcendental instructions
- Comparison instructions
- Transcendental instructions
- Constant instructions
- Processor Control instructions

## **Data transfer instructions**

Real Transfers		
FLD FST Store real FSTP Store real and pop FXCH Exchange registers		
Integer Transfers		
FILD Integer load FIST Integer store FISTP Integer store and pop		
Packed Decimal Transfers		
FBLD Packed decimal (BCD) load Packed decimal (BCD) store and pop		

Mnemonic	Description
FLD m32fp	Push m32fp onto the FPU register stack.
FLD m64fp	Push m64fp onto the FPU register stack.
FLD m80fp	Push m80fp onto the FPU register stack.
FLD ST(i)	Push ST(i) onto the FPU register stack.

#

Instruction	64-Bit Mode	Compat/Leg Mode	Description
FST m32fp	Valid	Valid	Copy $ST(0)$ to $m32fp$ .
FST m64fp	Valid	Valid	Copy $ST(0)$ to $m64fp$ .
FST ST(i)	Valid	Valid	Copy $ST(0)$ to $ST(i)$ .
FSTP m32fp	Valid	Valid	Copy $ST(0)$ to $m32fp$ and pop register stack.
FSTP m64fp	Valid	Valid	Copy ST(0) to <i>m64fp</i> and pop register stack.
FSTP m80fp	Valid	Valid	Copy $ST(0)$ to $m80fp$ and pop register stack.
FSTP ST(i)	Valid	Valid	Copy ST(0) to ST(i) and pop register stack.

Instruction	Description	
FBSTP m80bcd	Store $ST(0)$ in m80bcd and pop $ST(0)$ .	

### Non-transcendental instructions

Operation	Instructions
Addition	FADD, FADDP, FIADD
Subtraction	FSUB, FSUBP, FISUB, FSUBR (Reverse Subtract), FSUBRP, FISUBR
Multiplication	FMUL, FMULP, FIMUL
Division	FDIV, FDIVP, FIDIV, FDIVR (Reverse Division), FDIVRP, FIDIVR
Other operations	FSQRT, FSCALE, FPREM (Partial Reminder), FPREM1, FRNDINT (Round to Integer), FXTRACT (Extract Exponent and Mantissa), FABS (Absolute Value), FCHS (Change Sign)

Mnemonic	Description
FSUB m32fp	Subtract m32fp from ST(0) and store result in ST(0).
FSUB m64fp	Subtract m64fp from ST(0) and store result in ST(0).
FSUB ST(0), ST( <u>i</u> )	Subtract ST(i) from ST(0) and store result in ST(0).
FSUB ST(i), ST(0)	Subtract ST(0) from ST(i) and store result in ST(i).
FSUBP ST(i̯), ST(0)	Subtract $ST(0)$ from $ST(i)$ , store result in $ST(i)$ , and pop register stack.
FSUBP	Subtract $ST(0)$ from $ST(1)$ , store result in $ST(1)$ , and pop register stack.
FISUB m32int	Subtract m32int from ST(0) and store result in ST(0).
FISUB m16int	Subtract m16int from ST(0) and store result in ST(0).

Mnemonic	Description
FSUBR m32fp	Subtract ST(0) from m32fp and store result in ST(0).
FSUBR m64fp	Subtract ST(0) from m64fp and store result in ST(0).
FSUBR ST(0), ST(i)	Subtract ST(0) from ST(i) and store result in ST(0).
FSUBR ST(i), ST(0)	Subtract ST(i) from ST(0) and store result in ST(i).
FSUBRP ST(i), ST(0)	Subtract $ST(i)$ from $ST(0)$ , store result in $ST(i)$ , and pop register stack.
FSUBRP	Subtract ST(1) from ST(0), store result in ST(1), and pop register stack.
FISUBR m32int	Subtract ST(0) from m32int and store result in ST(0).
FISUBR m16int	Subtract ST(0) from m16int and store result in ST(0).

Mnemonic	Description
FMUL m32fp	Multiply ST(0) by m32fp and store result in ST(0)
FMUL m64fp	Multiply ST(0) by m64fp and store result in ST(0)
FMUL ST(0), ST( <u>i</u> )	Multiply ST(0) by ST(i) and store result in ST(0)
FMUL ST(i), ST(0)	Multiply ST(i) by ST(0) and store result in ST(i)
FMULP ST(i̯), ST(0)	Multiply ST(i) by ST(0), store result in ST(i), and pop the register stack
FMULP	Multiply ST(1) by ST(0), store result in ST(1), and pop the register stack
FIMUL m32int	Multiply ST(0) by m32int and store result in ST(0)
FIMUL m16int	Multiply ST(0) by m16int and store result in ST(0)

Mnemonic	Description
FDIV m32fp	Divide ST(0) by m32fp and store result in ST(0).
FDIV m64fp	Divide ST(0) by m64fp and store result in ST(0).
FDIV ST(0), ST(i)	Divide ST(0) by ST(i) and store result in ST(0).
FDIV ST(i), ST(0)	Divide ST(i) by ST(0) and store result in ST(i).
FDIVP ST(i), ST(0)	Divide ST(i) by ST(0), store result in ST(i), and pop the register stack.
FDIVP	Divide ST(1) by ST(0), store result in ST(1), and pop the register stack.
FIDIV m32int	Divide ST(0) by m32int and store result in ST(0).
FIDIV m16int	Divide ST(0) by m64int and store result in ST(0).

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Mnemonic	Description
FDIVR m32fp	Divide m32fp by ST(0) and store result in ST(0)
FDIVR m64fp	Divide m64fp by ST(0) and store result in ST(0)
FDIVR ST(0), ST( <u>i</u> )	Divide ST(i) by ST(0) and store result in ST(0)
FDIVR ST(i̯), ST(0)	Divide ST(0) by ST(i) and store result in ST(i)
FDIVRP ST(i), ST(0)	Divide ST(0) by ST(i), store result in ST(i), and pop the register stack
FDIVRP	Divide ST(0) by ST(1), store result in ST(1), and pop the register stack
FIDIVR m32int	Divide m32int by ST(0) and store result in ST(0)
FIDIVR m16int	Divide m16int by ST(0) and store result in ST(0)

Mnemonic	Description
FSQRT	Computes square root of ST(0) and stores the result in ST(0).

Mnemonic	Description
FSCALE	Scale <u>ST(</u> 0) by ST(1).

Mnemonic	Description
FPREM	Replace <u>ST(0)</u> with the remainder obtained from dividing ST(0) by ST(1).

Mnemonic	Description
FPREM1	Replace ST(0) with the IEEE remainder obtained from dividing ST(0) by ST(1).

Mnemonic	Description
FRNDINT	Round <u>ST(</u> 0) to an integer.

Mnemonic	Description
FXTRACT	Separate value in ST(0) into exponent and mantissa, store exponent in ST(0), and
	push the mantissa onto the registerstack.

Mnemonic	Description
FABS	Replace ST with its absolute value.

	Mnemonic	Description
FC	:HS	Complements sign of ST(0)

## **Comparison Instructions**

FCOM	Compare real
FCOMP	Compare real and pop
FCOMPP	Compare real and pop twice
FICOM	Integer compare
FICOMP	Integer compare and pop
FTST	Test
FUCOM	Unordered compare real
FUCOMP	Unordered compare real and pop
FUCOMPP	Unordered compare real and pop twice
FXAM	Examine

Table 4-6. Condition Code Resulting from Comparisons

Order	C3 (ZF)	C2 (PF)	C0 (CF)	80386 Conditional Branch
ST > Operand	0	0	0	JA
ST < Operand	0	0	1	JB
ST = Operand	1	0	0	JE
Unordered	1	1	1	JP

	#
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Mnemonic	Description
FCOM m32fp	Compare ST(0) with m32fp.
FCOM m64fp	Compare ST(0) with m64fp.
FCOM ST( <u>i</u> )	Compare ST(0) with ST(i).
FCOM	Compare ST(0) with ST(1).
FCOMP m32fp	Compare ST(0) with m32fp and pop register stack.
FCOMP m64fp	Compare ST(0) with m64fp and pop register stack.
FCOMP ST(i)	Compare ST(0) with ST(i) and pop register stack.
FCOMP	Compare ST(0) with ST(1) and pop register stack.
FCOMPP	Compare ST(0) with ST(1) and pop register stack twice.

Mnemonic	Description
FTST	Compare ST(0) with 0.0.

Mnemonic	Description
FUCOM ST(i)	Compare <u>ST(</u> 0) with ST( <u>i</u> ).
FUCOM	Compare ST(0) with ST(1).
FUCOMP ST(j)	Compare ST(0) with ST(i) and pop register stack.
FUCOMP	Compare ST(0) with ST(1) and pop register stack.
FUCOMPP	Compare ST(0) with ST(1) and pop register stack twice.

Mnemonic	Description
FXAM	Classify value or number in <u>ST(</u> 0).

FXAM Results				
Class	C3	C2	CO	
Unsupported	0	0	0	
NaN	0	0	1	
Normal finite number	0	1	0	
Infinity	0	1	1	
Zero	1	0	0	
Empty	1	0	1	
Denormal number	1	1	0	

#### Transcendental instructions

**FSIN** 

**FCOS** 

FSINCOS

**FPTAN** 

**FPATAN** 

F2XM1

FYL2X

FYL2XP1

Sine

Cosine

Sine and cosine

Tangent of ST

Arctangent of ST(1)/ST

 $2^{x}-1$ 

 $Y \bullet log_2X$ ; Y is ST(1), X is ST

 $Y \cdot log_2(X + 1);$  Y is ST(1), X is ST

#### **Constant Instructions**

FLDZ	Load + 0.0
FLD1	Load + 1.0
FLDPI	Load $\pi$
FLDL2T	Load log₂10
FLDL2E	Load log₂ <i>e</i>
FLDLG2	Load log₁₀2
FLDLN2	Load log <sub>e</sub> 2

#### **Processor Control Instructions**

FINIT/FNINIT

FLDCW

FSTCW/FNSTCW

FSTSW/FNSTSW

FSTSW AX/FNSTSW AX

FCLEX/FNCLEX

FSTENV/FNSTENV

FLDENV

FSAVE/FNSAVE

FRSTOR

FINCSTP

**FDECSTP** 

**FFREE** 

FNOP

**FWAIT** 

Initialize processor

Load control word

Store control word

Store status word

Store status word to AX

Clear exceptions

Store environment

Load environment

Save state

Restore state

Increment stack pointer

Decrement stack pointer

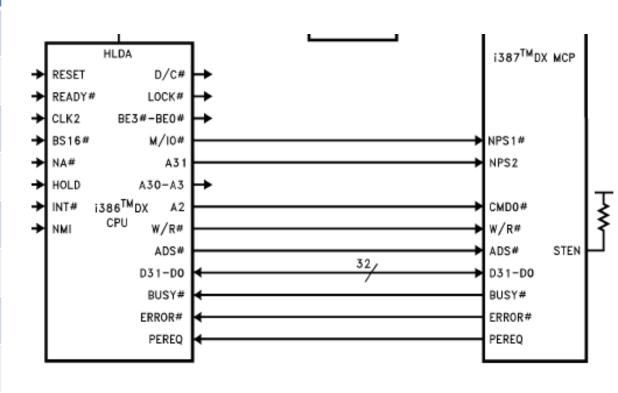
Free register

No operation

CPU Wait

# Interfacing Signals of 80386DX with 80387

80386	80387
Pin	Pin
M/IO#	NPS1#
A31	NPS2
A2	CMD0#
W/R#	W/R#
ADS#	ADS#
D31-D0	D31-D0
BUSY#	BUSY#
ERROR#	ERROR#
PEREQ	PEREQ



# 80387 Pin Description

RESETIN	Immediate termination of present operation	
BUSY	Output indicates coprocessor is executing a command.	
ERROR	Output indicates an unmasked error condition has occurred.	
PEREQ	If output is high, ready to transfer data. If output is low, data is being transferred to or from / PEACK	
CMD0	Command line for control of 80387 operations	
NPS1 & NPS2	Inputs indicates 80386 is performing an ESC instruction. No data transfer unless these lines are selected.	
READY	End of bus cycle signals this input pin. Bus ready.	
READYO	Write cycles last 2 clocks, read cycles last 3 clocks, and then terminates. Can drive READY.	
HLDA	Input informs coprocessor of 80386 bus control.	
STEN	Status enable, serves as a chip select.	
V <sub>ss</sub>	Systems ground connection.	
v <sub>cc</sub>	Systems +5 volt power supply.	