Anurag Sahu

BTech 4th year IIIT Hyderabad.

EDUCATION

IIIT HYDERABAD

B.Tech. and M.S. by Research Hyderabad, India

Expected Graduation: 2022

CONTACT

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LINKS

Github:// AnuragSahu LinkedIn:// Anurag-Sahu Quora:// Anurag-Sahu CodeChef:// anuragsahu 3-Star(Highest Rating: 1721)

COURSEWORK

Operating Systems
Artificial Intelligence
Algorithms
Statistical Methods in AI
Optimization Methods
Computer Vision
Mobile Robotics
Digital Image processing
Computation Complexity Theory
Introduction to Databases
Computer Networks
Structured Systems Analysis and Design
Distributed Systems

SKILLS

PROGRAMMING

- Python
- C++ Matlab
- Git MySQL

OTHER HOBBIES

- Riding
- Creating and Capturing Memories
- DIYing

EXPERIENCE

DEEP VIDYA AI PVT. LTD. | COMPUTER VISION INTERN

- Conducting Research on new Treds in AI/ML.
- Performing Experiments using Different CV/DL Algorithms.
- Engaging in content creation for Deep learning and Computer Vision Courses.

RESEARCH EXPERIENCE

ROBOTICS RESEARCH CENTER, IIIT HYDERABAD

- Working under **Professor K Madhav Krishna** on Deep learning Applications on Warehouses.
- Made a synthetic warehouses for training the DL/RL models so that the models can be trained with and without supervision.
- Paper "RackLay: Multi-Layer Layout Estimation for Warehouse Racks",
- Dataset "WareSynth: Synthetic warehouse Generation Pipeline." **Project Page**

PUBLICATIONS

UNDER REVIEW IN INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS 2021

- RackLay: Multi-Layer Layout Estimation for Warehouse Racks, Given a monocular colour image of a warehouse rack, predict the bird's-eye view layout for each shelf in the rack. arXiv Link, Project page

EXTRACURRICULAR ACTIVITES

WRITING ON ONLINE PLATFORMS | QUORA (500 K+ VIEWS)

frequent writeups on Quora about various topics like

- Technology
- Image and signal processing
- Collages

JP MORGAN AND CHASE | VIRTUAL INTERNSHIP PROGRAM

May 2020 - June 2020

- Establishing Financial Data Feeds
- Frontend Web Development
- Data Visualization with Perspective

ACADEMIC PROJECTS

- Point Cloud Reconstruction from 2D Images.
- Stereo Dense Reconstruction 3d point cloud out of 2d.
- Visual Odometry recovering trajectory using camera.
- Localization Using EKF Correcting the robot's estimated path.
- TIC-TAC-TOE Bot Playing Xtreme Tic-Tac-Toe.
- 2D Game, 3D Game and 3D infinite Runner game in OpenGL, WebGL.
- Matlab Image processing to remove noise from Images and sound.
- Shell and Changing xv36 Operating System for new features.
- Al MDP Utility generator.