```
sketch_feb14a.ino
MANAGER
                                  // defining pins for ultrasonic sensor
                             1
                                  const int trigPin = 19;
                             2
                                  const int echoPin = 18;
Installed
                             3
                                  const int led = 17;
                             4
All
                             5
                                  //defining variables duration and distance
                             6
TMRh20
                                  long duration;
                              7
stalled
                                  int distance;
                              8
ver, OSI layer 2 library for
                              9
(+) modules. Core library for
                             10
                                  void setup() {
(+) communication. Simple...
                                     // put your setup code here, to run once:
                             11
                                   // intializing baud rate
                             12
                                   Serial.begin(115200)
      REMOVE
                             13
                                   pinMode(trigPin, OUTPUT);
                             14
                                   pinMode(led,OUTPUT);
                             15
                                   pinMode(echoPin,INPUT);
                             16
                                   }
                             17
                             18
                                   void loop() {
                             19
                                     // put your main code here, to run repeatedly:
                             20
                                    digitalWrite(trigPin,LOW);
                             21
                                     delayMicroseconds(2);
                             22
                                     digitalWrite(trigPin,HIGH);
                             23
                                    delay(10);
                             24
                                     digitalWrite(trigPin,LOW);
                             25
                                     duration= pulseIn(echoPin,HIGH);
                             26
                                     distance = duration*(0.034 / 2.0);
                             27
                             28
                                     if (distance<=15) { digitalwrite(led,HIGH);}</pre>
                             29
                                     else { digitalwrite(led,LOW);}
                             30
                             31
                                     Serial.print("Distance");
                             32
```

Serial.println(distance);

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