

UNIT III

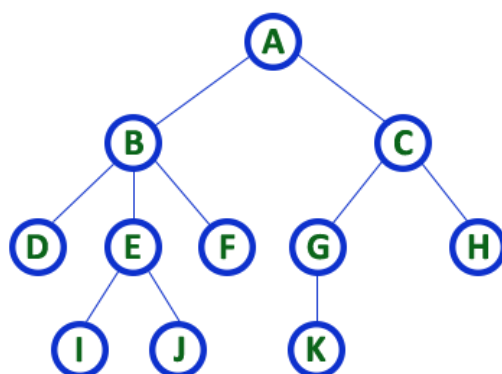
TREES

General trees – Terminology – Representation of trees – Tree traversal- Binary tree – Representation – Expression tree – Binary tree traversal - Threaded Binary Tree - Binary Search Tree – Construction - Searching - Binary Search Tree- Insertion – Deletion - AVL trees – Rotation AVL trees – Insertion – Deletion - B-Trees – Splay trees - Red-Black Trees

Trees

- A In linear data structure, data is organized in sequential order and in non-linear data structure, data is organized in random order. Tree is a very popular data structure used in wide range of applications. A tree data structure can be defined as follows...
- Tree is a non-linear data structure which organizes data in hierarchical structure and this is a recursive definition.
- A tree data structure can also be defined as follows...
- Tree data structure is a collection of data (Node) which is organized in hierarchical structure and this is a recursive definition
- In tree data structure, every individual element is called as Node. Node in a tree data structure, stores the actual data of that particular element and link to next element in hierarchical structure.
- In a tree data structure, if we have N number of nodes then we can have a maximum of N-1 number of links.

Example



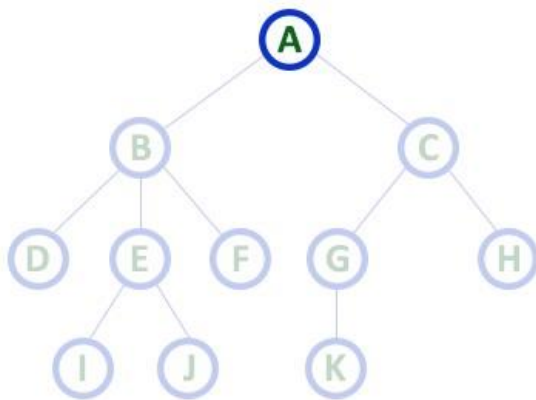
TREE with 11 nodes and 10 edges

- In any tree with 'N' nodes there will be maximum of 'N-1' edges
- In a tree every individual element is called as 'NODE'

Terminology

In a tree data structure, we use the following terminology... 1.

Root

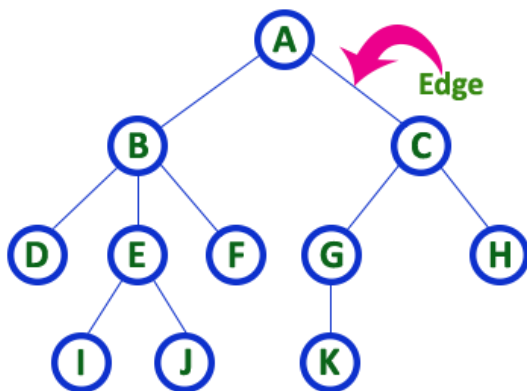


Here 'A' is the 'root' node

- In any tree the first node is called as ROOT node

In a tree data structure, the first node is called as Root Node. Every tree must have root node.

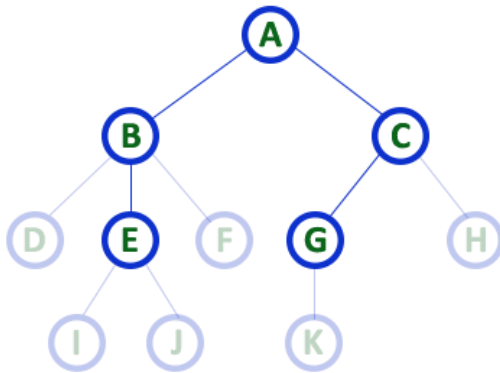
We can say that root node is the origin of tree data structure. In any tree, there must be only one root node. We never have multiple root nodes in a tree. 2. Edge



- In any tree, 'Edge' is a connecting link between two nodes.

In a tree data structure, the connecting link between any two nodes is called as EDGE. In a tree with 'N' number of nodes there will be a maximum of 'N-1' number of edges.

3. Parent

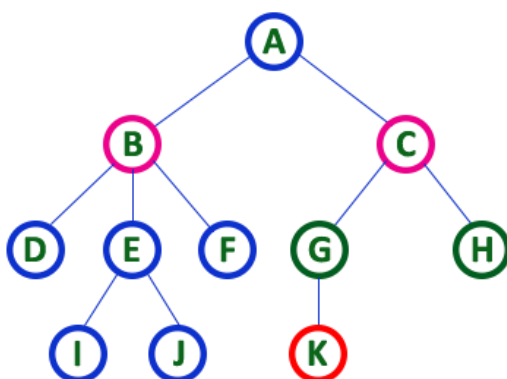


Here A, B, C, E & G are **Parent** nodes

- In any tree the node which has child / children is called '**Parent**'
- A node which is predecessor of any other node is called '**Parent**'

In a tree data structure, the node which is predecessor of any node is called as PARENT NODE. In simple words, the node which has branch from it to any other node is called as parent node. Parent node can also be defined as "The node which has child / children". 4.

Child



Here B & C are **Children** of A

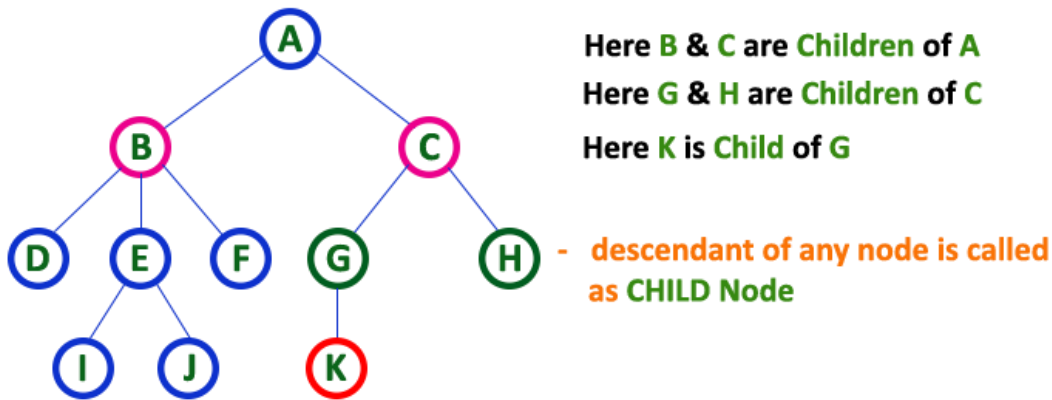
Here G & H are **Children** of C

Here K is **Child** of G

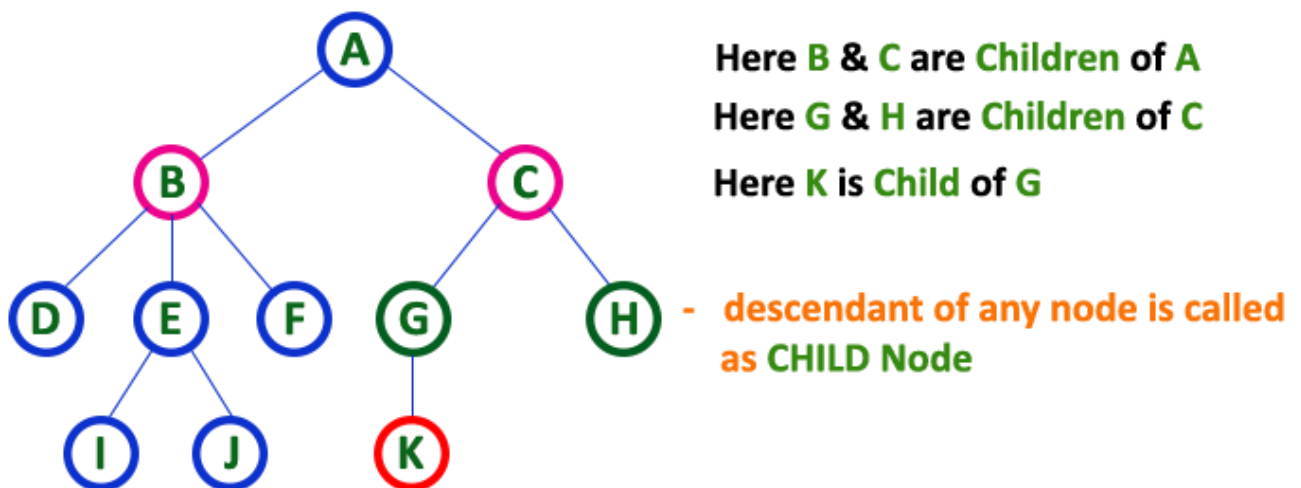
- descendant of any node is called as **CHILD** Node

In a tree data structure, the node which is descendant of any node is called as CHILD Node. In simple words, the node which has a link from its parent node is called as child node. In a tree, any parent node can have any number of child nodes. In a tree, all the nodes except root are child nodes.

5. Siblings



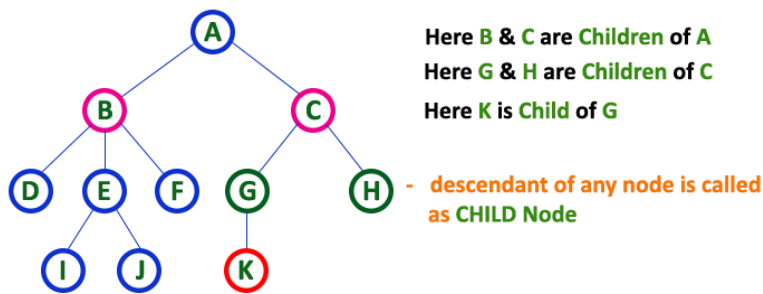
In a tree data structure, nodes which belong to same Parent are called as SIBLINGS. In simple words, the nodes with same parent are called as Sibling nodes. **6. Leaf**



In a tree data structure, the node which does not have a child is called as LEAF Node. In simple words, a leaf is a node with no child.

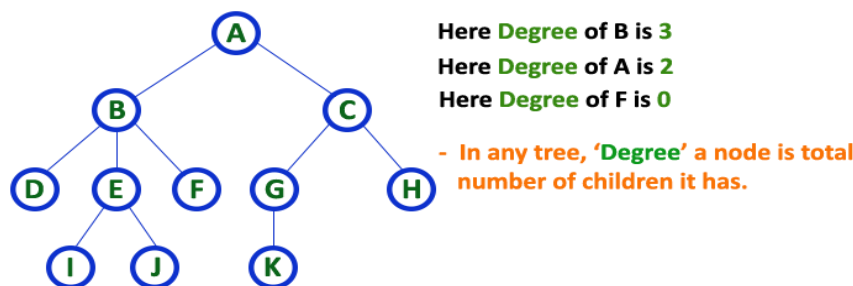
In a tree data structure, the leaf nodes are also called as External Nodes. External node is also a node with no child. In a tree, leaf node is also called as 'Terminal' node.

7. Internal Nodes



In a tree data structure, the node which has atleast one child is called as INTERNAL Node. In simple words, an internal node is a node with atleast one child. In a tree data structure, nodes other than leaf nodes are called as Internal Nodes. The root node is also said to be Internal Node if the tree has more than one node. Internal nodes are also called as 'Non-Terminal' nodes.

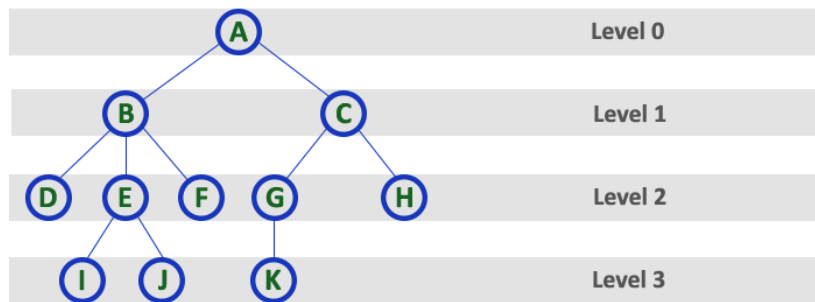
8. Degree



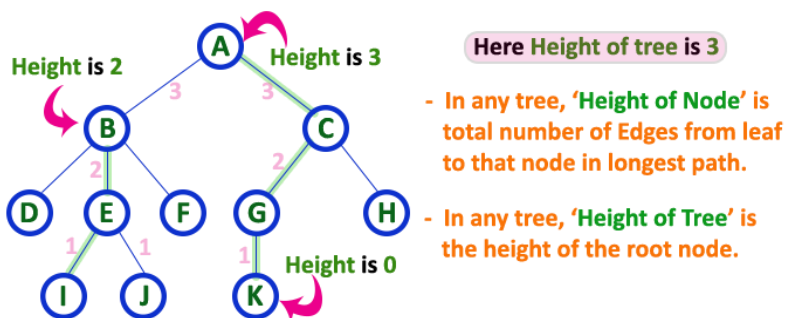
In a tree data structure, the total number of children of a node is called as DEGREE of that Node. In simple words, the Degree of a node is total number of children it has. The highest degree of a node among all the nodes in a tree is called as 'Degree of Tree'

9. Level

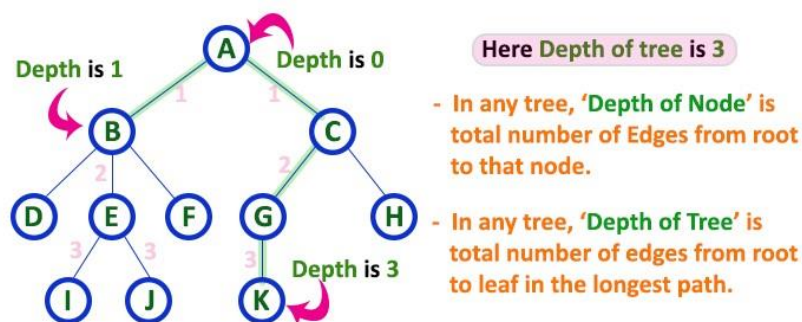
In a tree data structure, the root node is said to be at Level 0 and the children of root node are at Level 1 and the children of the nodes which are at Level 1 will be at Level 2 and so on... In simple words, in a tree each step from top to bottom is called as a Level and the Level count starts with '0' and incremented by one at each level (Step).



10. Height

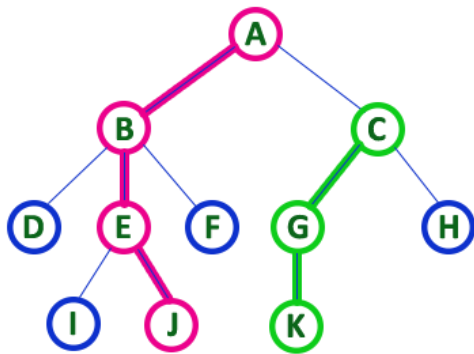


In a tree data structure, the total number of edges from leaf node to a particular node in the longest path is called as HEIGHT of that Node. In a tree, height of the root node is said to be height of the tree. In a tree, height of all leaf nodes is '0'. **11. Depth**



In a tree data structure, the total number of edges from root node to a particular node is called as DEPTH of that Node. In a tree, the total number of edges from root node to a leaf node in the longest path is said to be Depth of the tree. In simple words, the highest depth of any leaf node in a tree is said to be depth of that tree. In a tree, depth of the root node is '0'.

12. Path



- In any tree, 'Path' is a sequence of nodes and edges between two nodes.

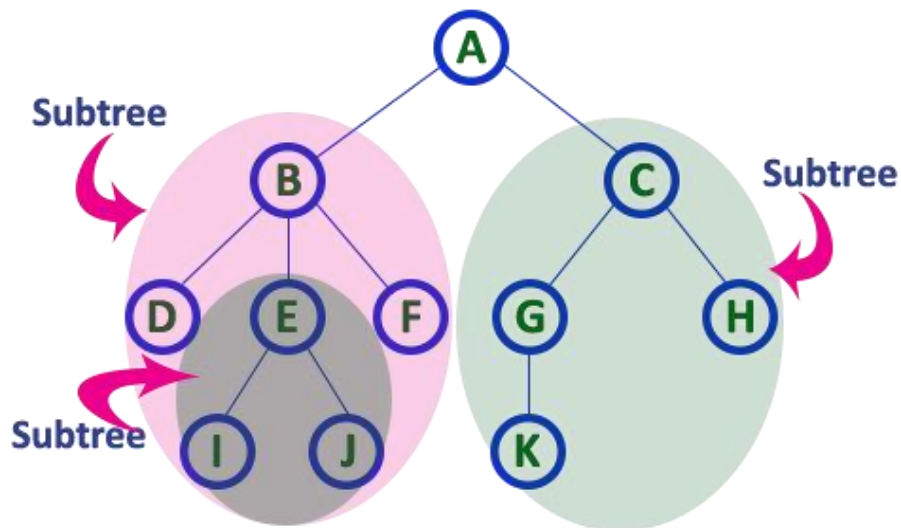
Here, 'Path' between A & J is

A - B - E - J

Here, 'Path' between C & K is

C - G - K

In a tree data structure, the sequence of Nodes and Edges from one node to another node is called as PATH between that two Nodes. Length of a Path is total number of nodes in that path. In below example the path A - B - E - J has length 4. 13. Sub Tree



In a tree data structure, each child from a node forms a subtree recursively. Every child node will form a subtree on its parent node.

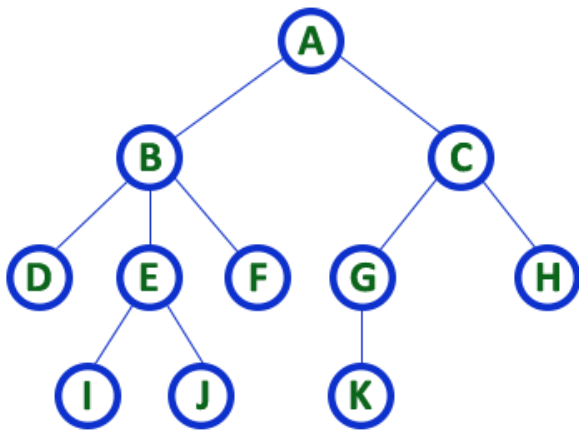
Tree Representations

A tree data structure can be represented in two methods. Those methods are as follows...

- List Representation

- Left Child - Right Sibling Representation

Consider the following tree...

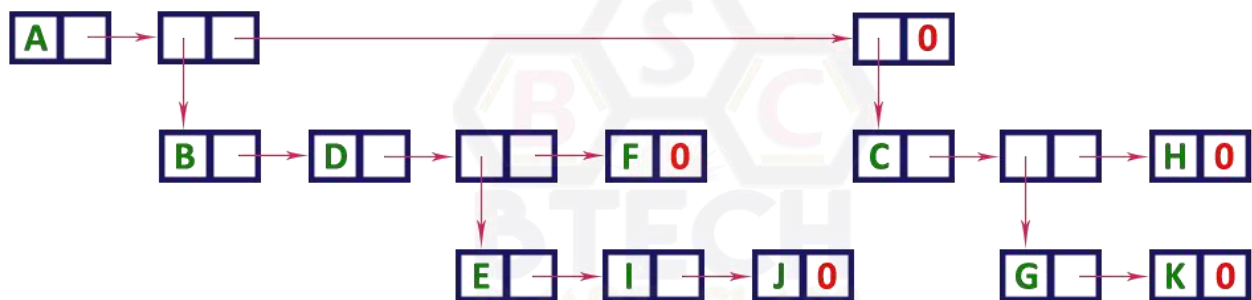


TREE with 11 nodes and 10 edges

- In any tree with '**N**' nodes there will be maximum of '**N-1**' edges
- In a tree every individual element is called as '**NODE**'

1. List Representation

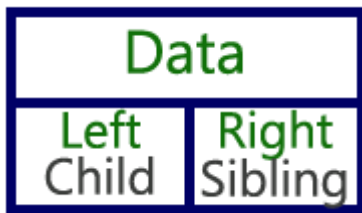
In this representation, we use two types of nodes one for representing the node with data and another for representing only references. We start with a node with data from root node in the tree. Then it is linked to an internal node through a reference node and is linked to any other node directly. This process repeats for all the nodes in the tree. The above tree example can be represented using List representation as follows...



2. Left Child - Right Sibling Representation

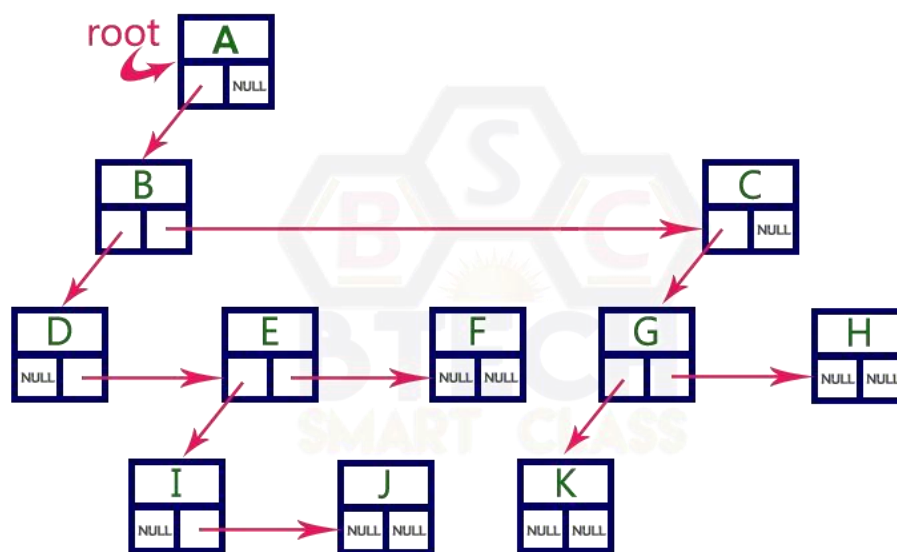
In this representation, we use list with one type of node which consists of three fields namely Data field, Left child reference field and Right sibling reference field. Data field stores the actual value of a node, left reference field stores the address of the left child and right

reference field stores the address of the right sibling node. Graphical representation of that node is as follows...



In this representation, every node's data field stores the actual value of that node. If that node has left child, then left reference field stores the address of that left child node otherwise that field stores NULL. If that node has right sibling then right reference field stores the address of right sibling node otherwise that field stores NULL.

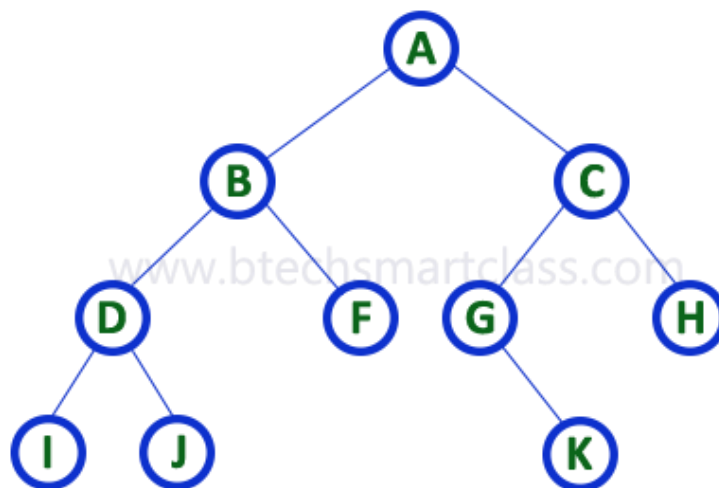
The above tree example can be represented using Left Child - Right Sibling representation as follows...



Binary Tree

- In a normal tree, every node can have any number of children. Binary tree is a special type of tree data structure in which every node can have a maximum of 2 children. One is known as left child and the other is known as right child.
- **A tree in which every node can have a maximum of two children is called as Binary Tree.**
- In a binary tree, every node can have either 0 children or 1 child or 2 children but not more than 2 children.

Example



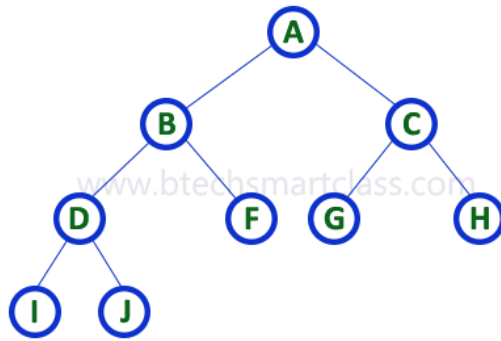
There are different types of binary trees and they are...

1. Strictly Binary Tree

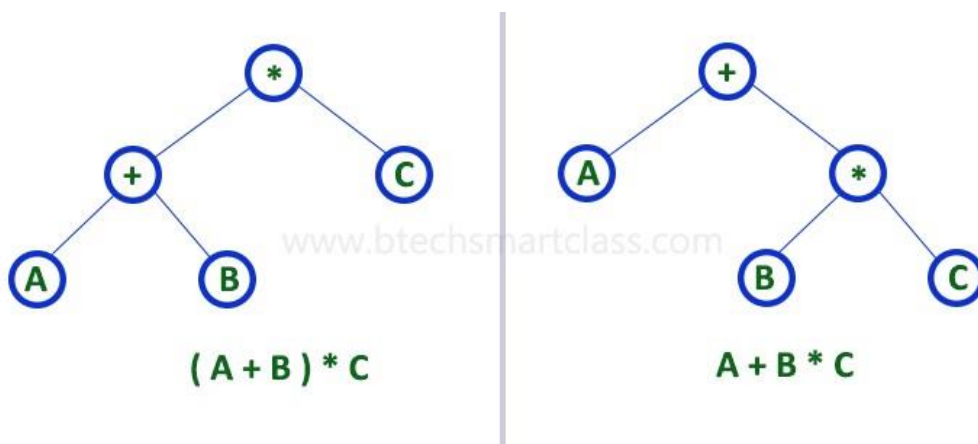
In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none. That means every internal node must have exactly two children. A strictly Binary Tree can be defined as follows...

A binary tree in which every node has either two or zero number of children is called Strictly Binary Tree

Strictly binary tree is also called as Full Binary Tree or Proper Binary Tree or 2-Tree



Strictly binary tree data structure is used to represent mathematical expressions. Example

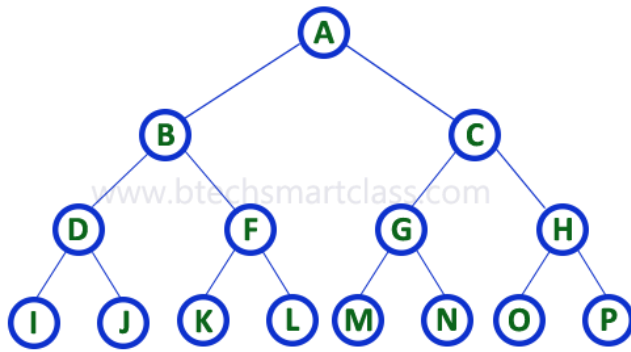


2. Complete Binary Tree

In a binary tree, every node can have a maximum of two children. But in strictly binary tree, every node should have exactly two children or none and in complete binary tree all the nodes must have exactly two children and at every level of complete binary tree there must be $2^{\text{level number}}$ of nodes. For example at level 2 there must be $2^2 = 4$ nodes and at level 3 there must be $2^3 = 8$ nodes.

A binary tree in which every internal node has exactly two children and all leaf nodes are at same level is called Complete Binary Tree.

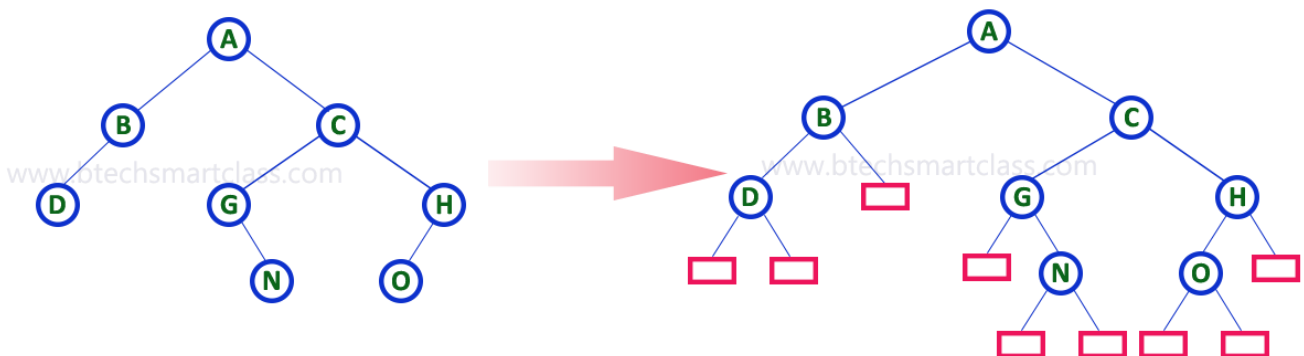
Complete binary tree is also called as Perfect Binary Tree



3. Extended Binary Tree

A binary tree can be converted into Full Binary tree by adding dummy nodes to existing nodes wherever required.

The full binary tree obtained by adding dummy nodes to a binary tree is called as Extended Binary Tree.



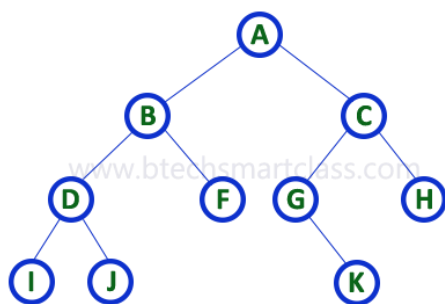
In above figure, a normal binary tree is converted into full binary tree by adding dummy nodes (In pink colour).

Binary Tree Representations

A binary tree data structure is represented using two methods. Those methods are as follows...

- Array Representation
- Linked List Representation

Consider the following binary tree...



1. Array Representation

In array representation of binary tree, we use a one dimensional array (1-D Array) to represent a binary tree.

Consider the above example of binary tree and it is represented as follows...



To represent a binary tree of depth 'n' using array representation, we need one dimensional array with a maximum size of $2^{n+1} - 1$.

It is found that if n is the number or index of a node, then its left child occurs at $(2n + 1)$ th position & right child at $(2n + 2)$ th position of the array. If any node does not have any of its child, then null value is stored at the corresponding index of the array.

2. Linked List Representation

We use double linked list to represent a binary tree. In a double linked list, every node consists of three fields. First field for storing left child address, second for storing actual data and third for storing right child address.

In this linked list representation, a node has the following structure...



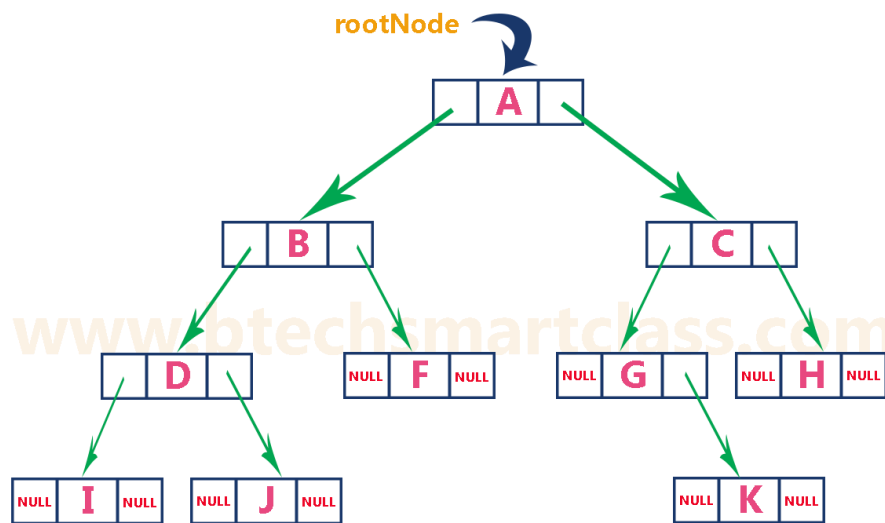
Struct node

```
{  
struct node * lc;  
int data; struct  
node * rc;  
};
```

Creating TREE

```
struct node * buildtree(int n);  
  
{  
    struct node * temp=NULL;  
  
    if( a[n] != NULL)  
  
    { temp = (struct node *) malloc(sizeof(struct node));  
  
    temp->lc=buildtree(2n + 1); temp-> data= a[n];  
  
    temp->rc=buildtree(2n + 2);  
  
    } return temp;  
  
}
```

The above example of binary tree represented using Linked list representation is shown as follows...



Binary Tree Traversals

In any binary tree displaying order of nodes depends on the traversal method.

Displaying (or) visiting order of nodes in a binary tree is called as Binary Tree Traversal.

There are three types of binary tree traversals.

1. In - Order Traversal
2. Pre - Order Traversal
3. Post - Order Traversal

Until all nodes are traversed –

- **Step 1** – Recursively traverse left subtree.
- **Step 2** – Visit root node.
- **Step 3** – Recursively traverse right subtree.

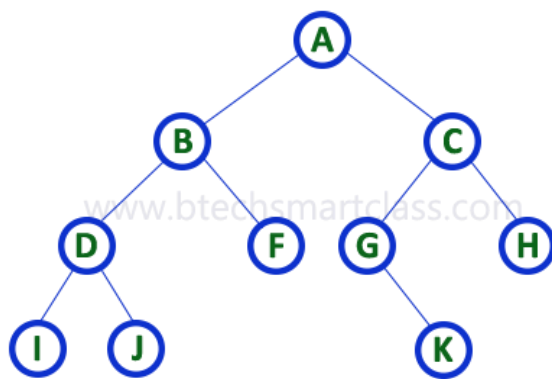
Algorithm

The algorithm for inorder traversal is as follows.

```
void inorder(struct node * root);
```

```
{  
if(root != NULL)  
{  
inorder(root->lc); printf("%d\t",root-  
>data); inorder(root->rc);  
}  
}
```

Consider the following binary tree...



In In-Order traversal, the root node is visited between left child and right child. In this traversal, the left child node is visited first, then the root node is visited and later we go for visiting right child node. This in-order traversal is applicable for every root node of all subtrees in the tree. This is performed recursively for all nodes in the tree.

In the above example of binary tree, first we try to visit left child of root node 'A', but A's left child is a root node for left subtree. so we try to visit its (B's) left child 'D' and again D is a root for subtree with nodes D, I and J. So we try to visit its left child 'I' and it is the left most child. So first we visit 'I' then go for its root node 'D' and later we visit D's right child 'J'. With this we have completed the left part of node B. Then visit 'B' and next B's right child 'F' is visited. With this we have completed left part of node A. Then visit root node 'A'. With this we have completed left and root parts of node A. Then we go for right part of the node A. In right of A again there is a subtree with root C. So go for left child of C and again it is a subtree with root G. But G does not have left part so we visit 'G' and then visit G's right child

K. With this we have completed the left part of node C. Then visit root node 'C' and next visit C's right child 'H' which is the right most child in the tree so we stop the process.

That means here we have visited in the order of **I - D - J - B - F - A - G - K - C - H** using InOrder Traversal.

**In-Order Traversal for above example of binary tree is
I - D - J - B - F - A - G - K - C - H**

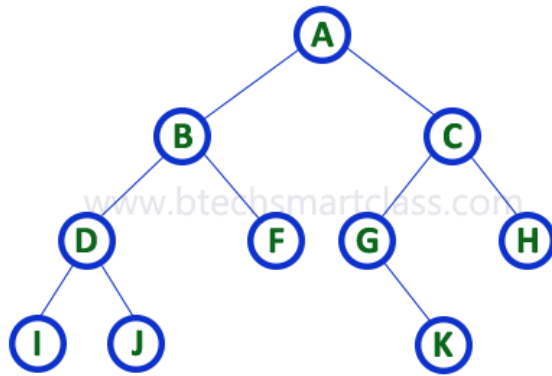
2. Pre-Order Traversal

Until all nodes are traversed –

- Step 1 – Visit root node.
- Step 2 – Recursively traverse left subtree. □ Step 3 – Recursively traverse right subtree.

```
void preorder(struct node * root);  
{  
if(root != NULL)  
{  
printf("%d\t",root->data);  
preorder(root->lc); preorder(root->rc);  
}  
}
```

Consider the following binary tree...



In Pre-Order traversal, the root node is visited before left child and right child nodes. In this traversal, the root node is visited first, then its left child and later its right child. This preorder traversal is applicable for every root node of all subtrees in the tree.

In the above example of binary tree, first we visit root node 'A' then visit its left child 'B' which is a root for D and F. So we visit B's left child 'D' and again D is a root for I and J. So we visit D's left child 'I' which is the left most child. So next we go for visiting D's right child 'J'. With this we have completed root, left and right parts of node D and root, left parts of node B. Next visit B's right child 'F'. With this we have completed root and left parts of node A. So we go for A's right child 'C' which is a root node for G and H. After visiting C, we go for its left child 'G' which is a root for node K. So next we visit left of G, but it does not have left child so we go for G's right child 'K'. With this we have completed node C's root and left parts. Next visit C's right child 'H' which is the right most child in the tree. So we stop the process.

That means here we have visited in the order of **A-B-D-I-J-F-C-G-K-H** using Pre-Order Traversal.

**Pre-Order Traversal for above example binary tree is
A - B - D - I - J - F - C - G - K - H**

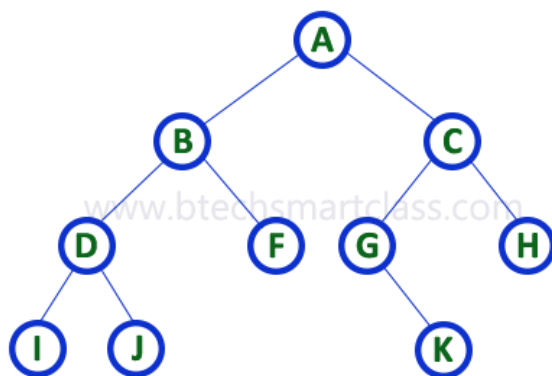
Post-order Traversal

Until all nodes are traversed –

- Step 1 – Recursively traverse left subtree.
- Step 2 – Recursively traverse right subtree.
- Step 3 – Visit root node.

```
void postorder(struct node * root);  
{  
if(root != NULL)  
{  
postorder(root->lc);  
postorder(root->rc);  
printf("%d\t",root->data);  
}  
}
```

Consider the following binary tree...



In Post-Order traversal, the root node is visited after left child and right child. In this traversal, left child node is visited first, then its right child and then its root node. This is recursively performed until the right most node is visited.

Here we have visited in the order of I - J - D - F - B - K - G - H - C - A using Post-Order Traversal.

Post-Order Traversal for above example binary tree is I

- J - D - F - B - K - G - H - C - A

Threaded Binary Tree

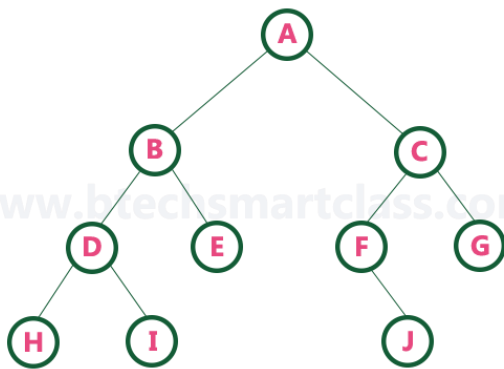
A binary tree is represented using array representation or linked list representation. When a binary tree is represented using linked list representation, if any node is not having a child we use NULL pointer in that position. In any binary tree linked list representation, there are more number of NULL pointer than actual pointers. Generally, in any binary tree linked list representation, if there are $2N$ number of reference fields, then $N+1$ number of reference fields are filled with NULL ($N+1$ are NULL out of $2N$). This NULL pointer does not play any role except indicating there is no link (no child).

A. J. Perlis and C. Thornton have proposed new binary tree called "*Threaded Binary Tree*", which make use of NULL pointer to improve its traversal processes. In threaded binary tree, NULL pointers are replaced by references to other nodes in the tree, called *threads*.

Threaded Binary Tree is also a binary tree in which all left child pointers that are NULL (in Linked list representation) points to its in-order predecessor, and all right child pointers that are NULL (in Linked list representation) points to its in-order successor.

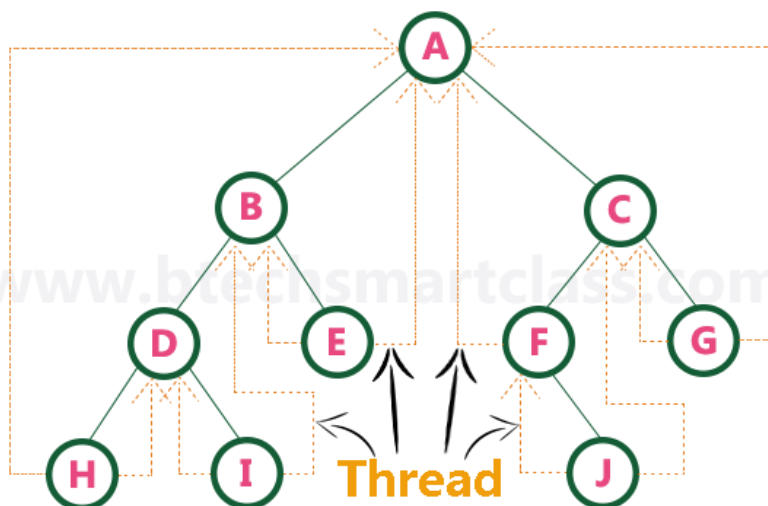
If there is no in-order predecessor or in-order successor, then it point to root node.

Consider the following binary tree...



To convert above binary tree into threaded binary tree, first find the in-order traversal of that tree... In-order traversal of above binary tree... H - D - I - B - E - A - F - J - C - G

When we represent above binary tree using linked list representation, nodes H, I, E, F, J and G left child pointers are NULL. This NULL is replaced by address of its in-order predecessor, respectively (I to D, E to B, F to A, J to F and G to C), but here the node H does not have its inorder predecessor, so it points to the root node A. And nodes H, I, E, J and G right child pointers are NULL. This NULL pointers are replaced by address of its in-order successor, respectively (H to D, I to B, E to A, and J to C), but here the node G does not have its in-order successor, so it points to the root node A. Above example binary tree become as follows after converting into threaded binary tree.



In above figure threads are indicated with dotted links.

Binary Search Tree

In a binary tree, every node can have maximum of two children but there is no order of nodes based on their values. In binary tree, the elements are arranged as they arrive to the tree, from top to bottom and left to right.

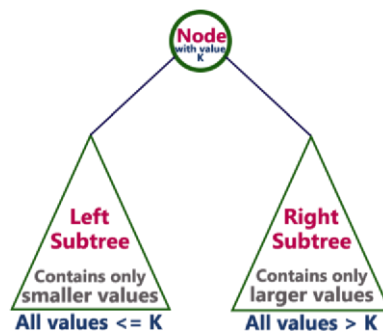
A binary tree has the following time complexities...

1. Search Operation - $O(n)$
2. Insertion Operation - $O(1)$
3. Deletion Operation - $O(n)$

To enhance the performance of binary tree, we use special type of binary tree known as **Binary Search Tree**. Binary search tree mainly focus on the search operation in binary tree. Binary search tree can be defined as follows...

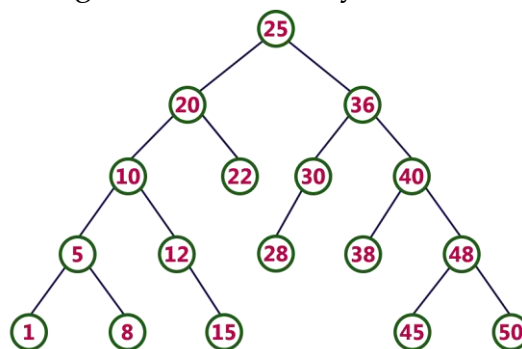
Binary Search Tree is a binary tree in which every node contains only smaller values in its left subtree and only larger values in its right subtree.

In a binary search tree, all the nodes in left subtree of any node contains smaller values and all the nodes in right subtree of that contains larger values as shown in following figure...



Example

The following tree is a Binary Search Tree. In this tree, left subtree of every node contains nodes with smaller values and right subtree of every node contains larger values.



Every Binary Search Tree is a binary tree but all the Binary Trees need not to be binary search trees.

Operations on a Binary Search Tree

The following operations are performed on a binary search tree...

1. Search
2. Insertion
3. Deletion

Search Operation in BST

In a binary search tree, the search operation is performed with **$O(\log n)$** time complexity. The search operation is performed as follows...

- **Step 1:** Read the search element from the user
- **Step 2:** Compare, the search element with the value of root node in the tree.
- **Step 3:** If both are matching, then display "Given node found!!!" and terminate the function
- **Step 4:** If both are not matching, then check whether search element is smaller or larger than that node value.
- **Step 5:** If search element is smaller, then continue the search process in left subtree.
- **Step 6:** If search element is larger, then continue the search process in right subtree.
- **Step 7:** Repeat the same until we found exact element or we completed with a leaf node
- **Step 8:** If we reach to the node with search value, then display "Element is found" and terminate the function.
- **Step 9:** If we reach to a leaf node and it is also not matching, then display "Element not found" and terminate the function.

Insertion Operation in BST

In a binary search tree, the insertion operation is performed with $O(\log n)$ time complexity. In binary search tree, new node is always inserted as a leaf node. The insertion operation is performed as follows...

- **Step 1:** Create a newNode with given value and set its **left** and **right** to **NULL**.
- **Step 2:** Check whether tree is Empty.
- **Step 3:** If the tree is **Empty**, then set **root** to **newNode**.
- **Step 4:** If the tree is **Not Empty**, then check whether value of newNode is **smaller** or **larger** than the node (here it is root node).
- **Step 5:** If newNode is **smaller** than or **equal** to the node, then move to its **left** child. If newNode is **larger** than the node, then move to its **right** child.
- **Step 6:** Repeat the above step until we reach to a **leaf** node (e.i., reach to **NULL**).
- **Step 7:** After reaching a leaf node, then insert the newNode as **left child** if newNode is **smaller or equal** to that leaf else insert it as **right child**.

Deletion Operation in BST

In a binary search tree, the deletion operation is performed with $O(\log n)$ time complexity. Deleting a node from Binary search tree has following three cases...

- **Case 1:** Deleting a Leaf node (A node with no children)
- **Case 2:** Deleting a node with one child
- **Case 3:** Deleting a node with two children

Case 1: Deleting a leaf node

We use the following steps to delete a leaf node from BST...

- **Step 1:** Find the node to be deleted using **search operation**
- **Step 2:** Delete the node using **free** function (If it is a leaf) and terminate the function.

Case 2: Deleting a node with one child

We use the following steps to delete a node with one child from BST...

- **Step 1: Find** the node to be deleted using **search operation**
- **Step 2:** If it has only one child, then create a link between its parent and child nodes.
- **Step 3:** Delete the node using **free** function and terminate the function.

Case 3: Deleting a node with two children

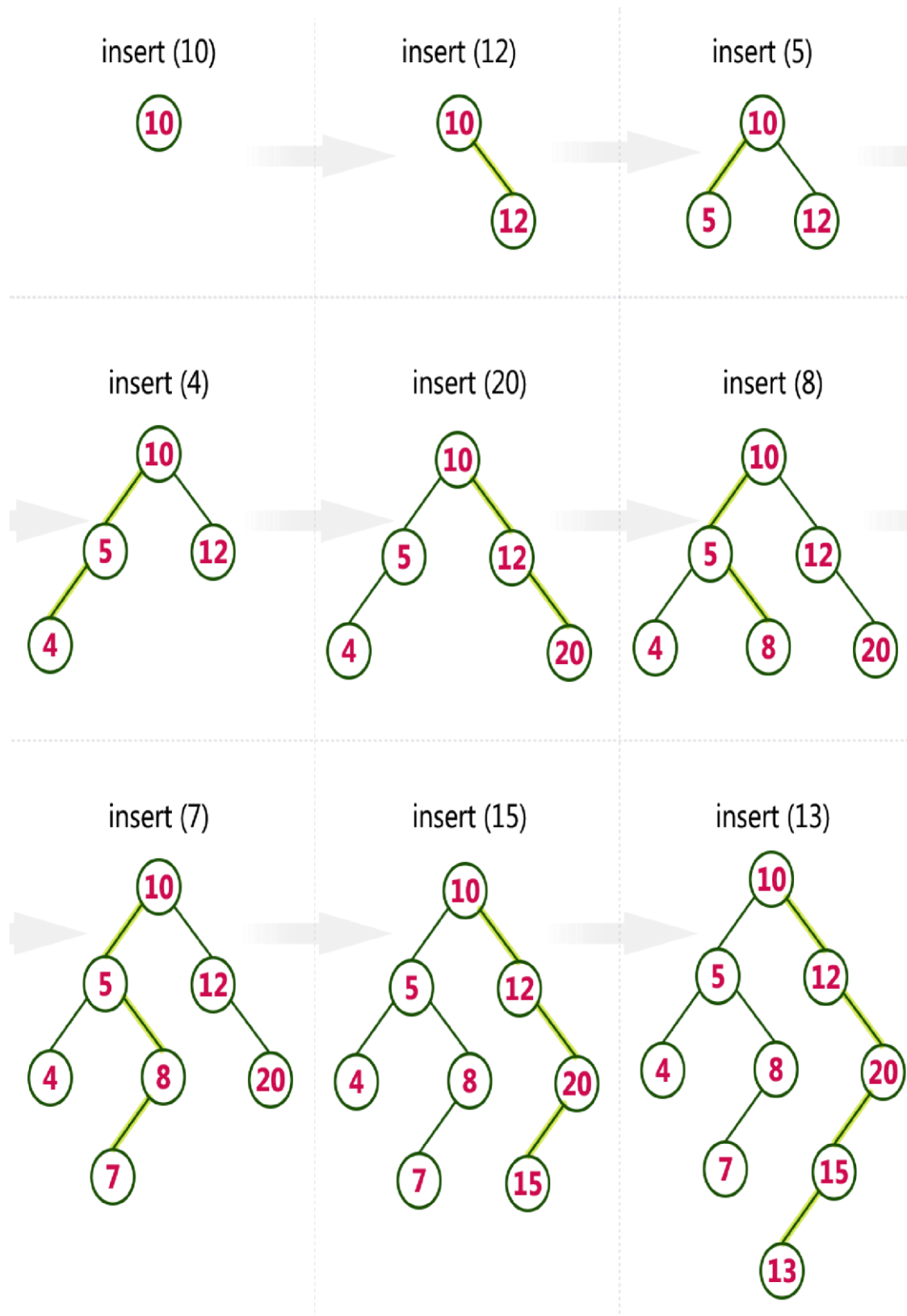
We use the following steps to delete a node with two children from BST...

- **Step 1: Find** the node to be deleted using **search operation**
- **Step 2:** If it has two children, then find the **largest** node in its **left subtree** (OR) the **smallest** node in its **right subtree**.
- **Step 3: Swap** both **deleting node** and node which found in above step.
- **Step 4:** Then, check whether deleting node came to **case 1** or **case 2** else goto steps 2 □
Step 5: If it comes to **case 1**, then delete using case 1 logic.
- **Step 6:** If it comes to **case 2**, then delete using case 2 logic.
- **Step 7:** Repeat the same process until node is deleted from the tree. **Example**

Construct a Binary Search Tree by inserting the following sequence of numbers...

10,12,5,4,20,8,7,15 and 13

Above elements are inserted into a Binary Search Tree as follows..



AVL Tree

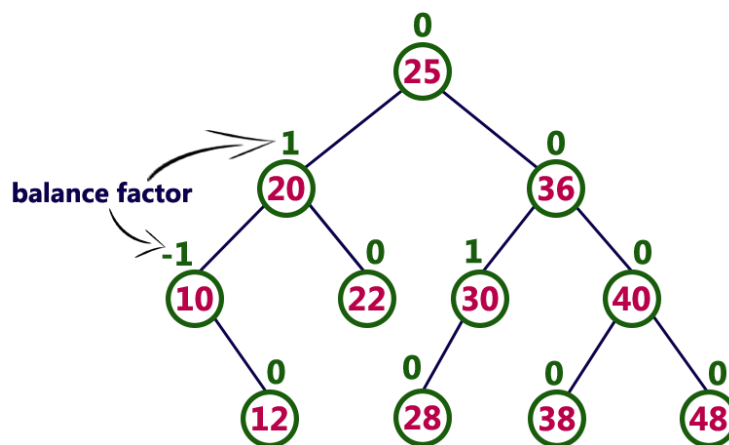
AVL tree is a self balanced binary search tree. That means, an AVL tree is also a binary search tree but it is a balanced tree. A binary tree is said to be balanced, if the difference between the heights of left and right subtrees of every node in the tree is either -1, 0 or +1. In other words, a binary tree is said to be balanced if for every node, height of its children differ by at most one. In an AVL tree, every node maintains an extra information known as balance factor. The AVL tree was introduced in the year of 1962 by **Adelson-Velsky and Landis**.

An AVL tree is defined as follows...

An AVL tree is a balanced binary search tree. In an AVL tree, balance factor of every node is either -1, 0 or +1.

Balance factor of a node is the difference between the heights of left and right subtrees of that node. The balance factor of a node is calculated either height of left subtree - height of right subtree (OR) height of right subtree - height of left subtree. In the following explanation, we are calculating as follows...

Balance factor = heightOfLeftSubtree - heightOfRightSubtree Example



The above tree is a binary search tree and every node is satisfying balance factor condition. So this tree is said to be an AVL tree.

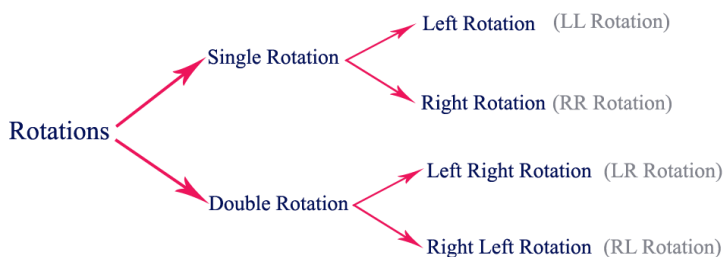
Every AVL Tree is a binary search tree but all the Binary Search Trees need not to be AVL trees.

AVL Tree Rotations

In AVL tree, after performing every operation like insertion and deletion we need to check the **balance factor** of every node in the tree. If every node satisfies the balance factor condition then we conclude the operation otherwise we must make it balanced. We use **rotation** operations to make the tree balanced whenever the tree is becoming imbalanced due to any operation. Rotation operations are used to make a tree balanced.

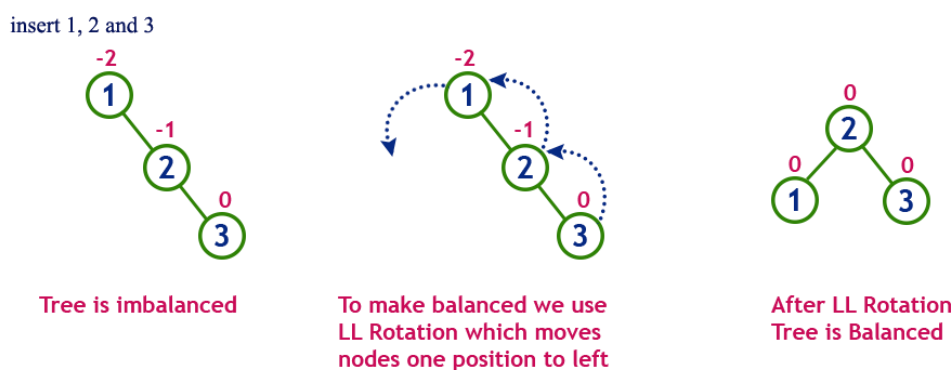
Rotation is the process of moving the nodes to either left or right to make tree balanced.

There are **four** rotations and they are classified into **two** types.



Single Left Rotation (LL Rotation)

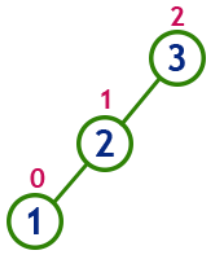
In LL Rotation every node moves one position to left from the current position. To understand LL Rotation, let us consider following insertion operations into an AVL Tree...



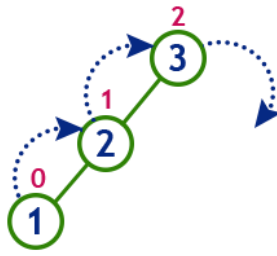
Single Right Rotation (RR Rotation)

In RR Rotation every node moves one position to right from the current position. To understand RR Rotation, let us consider following insertion operations into an AVL Tree...

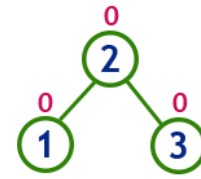
insert 3, 2 and 1



Tree is imbalanced
because node 3 has balance factor 2



To make balanced we use
RR Rotation which moves
nodes one position to right

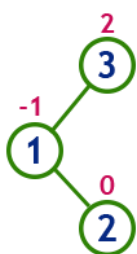


After RR Rotation
Tree is Balanced

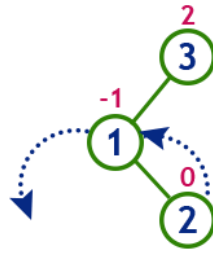
Left Right Rotation (LR Rotation)

The LR Rotation is combination of single left rotation followed by single right rotation. In LR Rotation, first every node moves one position to left then one position to right from the current position. To understand LR Rotation, let us consider following insertion operations into an AVL Tree...

insert 3, 1 and 2

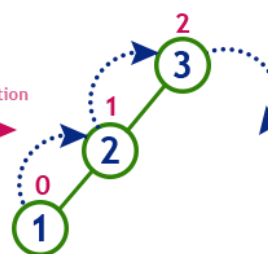


Tree is imbalanced
because node 3 has balance factor 2



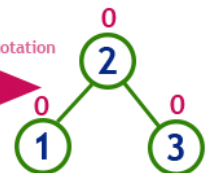
LL Rotation

After LL Rotation



RR Rotation

After RR Rotation

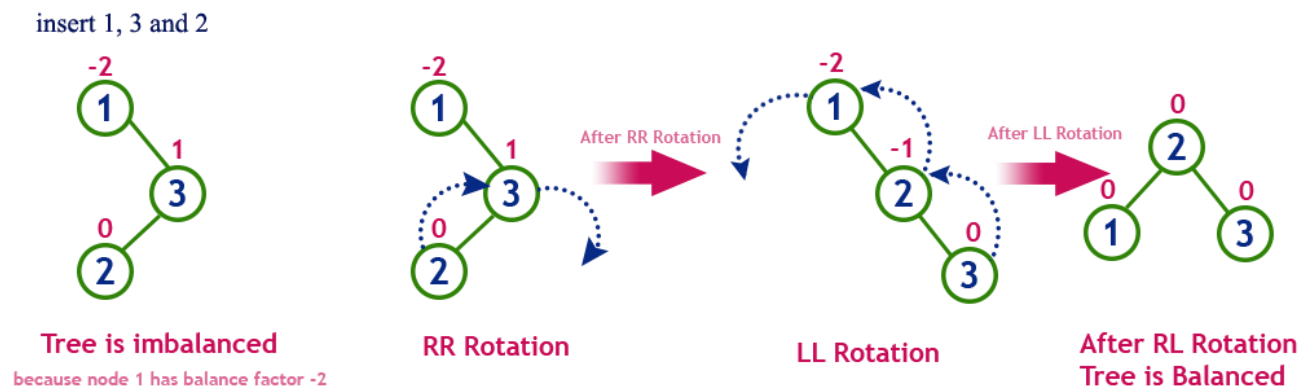


After LR Rotation
Tree is Balanced

Right Left Rotation (RL Rotation)

The RL Rotation is combination of single right rotation followed by single left rotation. In RL Rotation, first every node moves one position to right then one position to left from the

current position. To understand RL Rotation, let us consider following insertion operations into an AVL Tree...



Operations on an AVL Tree

The following operations are performed on an AVL tree...

1. Search
2. Insertion
3. Deletion

Search Operation in AVL Tree

In an AVL tree, the search operation is performed with $O(\log n)$ time complexity. The search operation is performed similar to Binary search tree search operation. We use the following steps to search an element in AVL tree...

- **Step 1:** Read the search element from the user
- **Step 2:** Compare, the search element with the value of root node in the tree.
- **Step 3:** If both are matching, then display "Given node found!!!" and terminate the function
- **Step 4:** If both are not matching, then check whether search element is smaller or larger than that node value.
- **Step 5:** If search element is smaller, then continue the search process in left subtree.
- **Step 6:** If search element is larger, then continue the search process in right subtree.

- **Step 7:** Repeat the same until we found exact element or we completed with a leaf node
- **Step 8:** If we reach to the node with search value, then display "Element is found" and terminate the function.
- **Step 9:** If we reach to a leaf node and it is also not matching, then display "Element not found" and terminate the function.

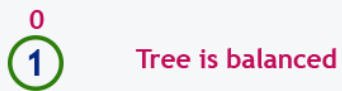
Insertion Operation in AVL Tree

In an AVL tree, the insertion operation is performed with **$O(\log n)$** time complexity. In AVL Tree, new node is always inserted as a leaf node. The insertion operation is performed as follows...

- **Step 1:** Insert the new element into the tree using Binary Search Tree insertion logic.
- **Step 2:** After insertion, check the **Balance Factor** of every node.
- **Step 3:** If the **Balance Factor** of every node is **0 or 1 or -1** then go for next operation.
- **Step 4:** If the **Balance Factor** of any node is other than **0 or 1 or -1** then tree is said to be imbalanced. Then perform the suitable **Rotation** to make it balanced. And go for next operation.

Example: Construct an AVL Tree by inserting numbers from 1 to 8.

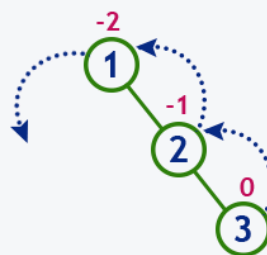
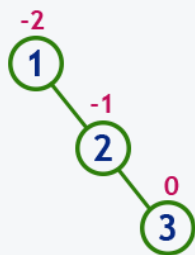
insert 1



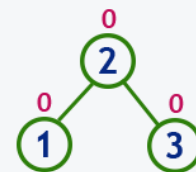
insert 2



insert 3



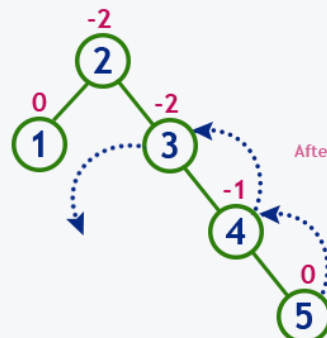
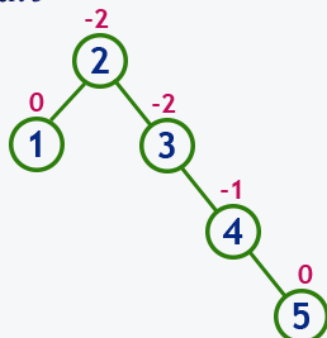
After LL Rotation



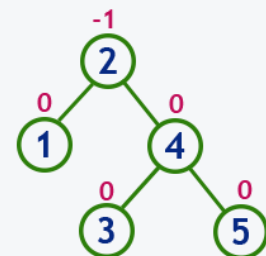
insert 4

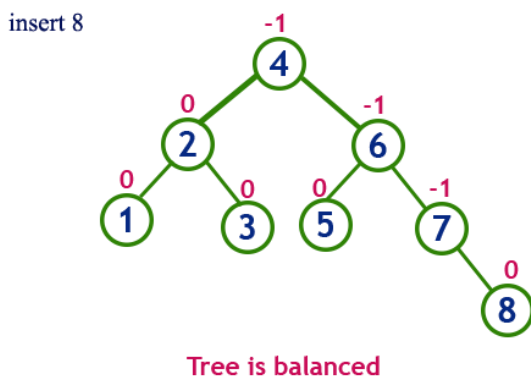
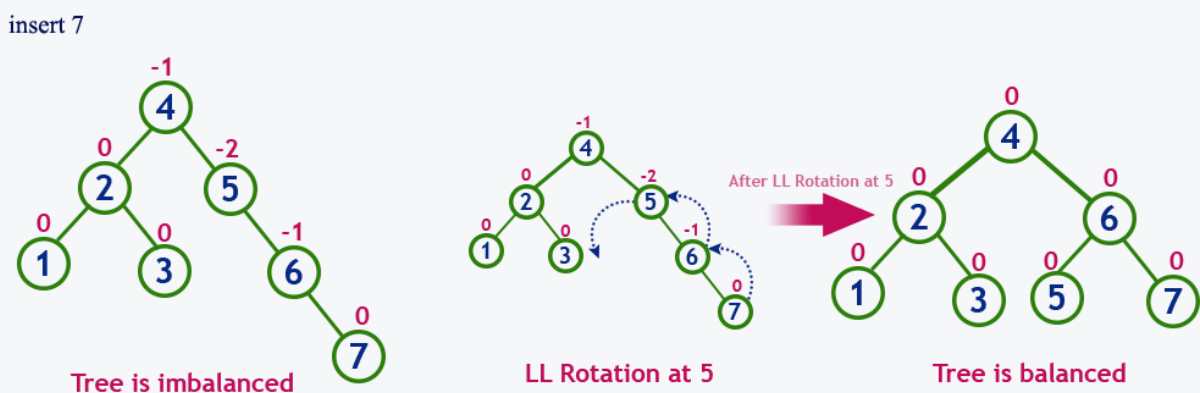
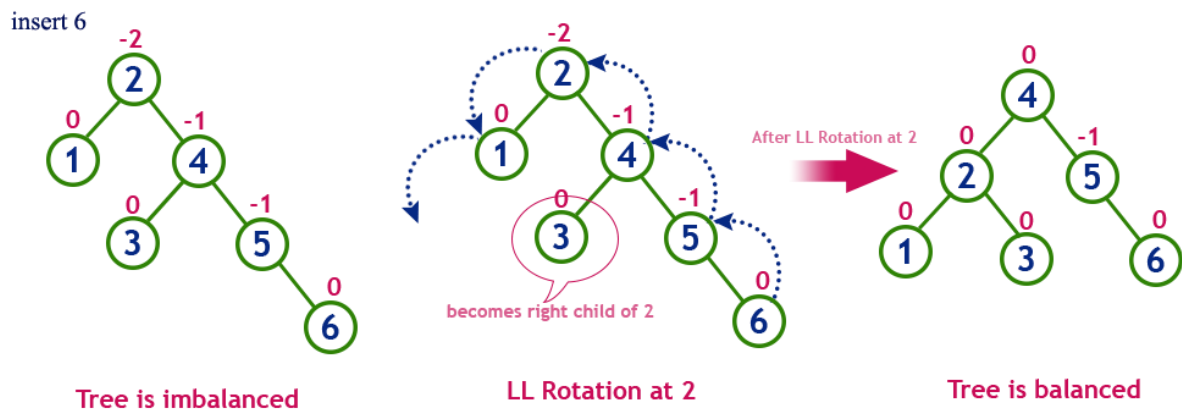


insert 5



After LL Rotation at 3





Deletion Operation in AVL Tree

In an AVL Tree, the deletion operation is similar to deletion operation in BST. But after every deletion operation we need to check with the Balance Factor condition. If the tree is balanced after deletion then go for next operation otherwise perform the suitable rotation to make the tree Balanced.

Splay Tree

- Splay tree is another variant of binary search tree. In a splay tree, the recently accessed element is placed at the root of the tree. A splay tree is defined as follows...
- Splay Tree is a self - adjusted Binary Search Tree in which every operation on an element rearrange the tree so that the element is placed at the root position of the tree.
- In a splay tree, every operation is performed at root of the tree. All the operations on a splay tree are involved with a common operation called "Splaying".
- **Splaying an element is the process of bringing it to the root position by performing suitable rotation operations.**
- In a splay tree, splaying an element rearrange all the elements in the tree so that splayed element is placed at root of the tree.

With the help of splaying an element we can bring most frequently used element closer to the root of the tree so that any operation on those element performed quickly. That means the splaying operation automatically brings more frequently used elements closer to the root of the tree.

Every operation on a splay tree performs the splaying operation. For example, the insertion operation first inserts the new element as it inserted into the binary search tree, after insertion the newly inserted element is splayed so that it is placed at root of the tree. The search operation in a splay tree is search the element using binary search process then splay the searched element so that it placed at the root of the tree.

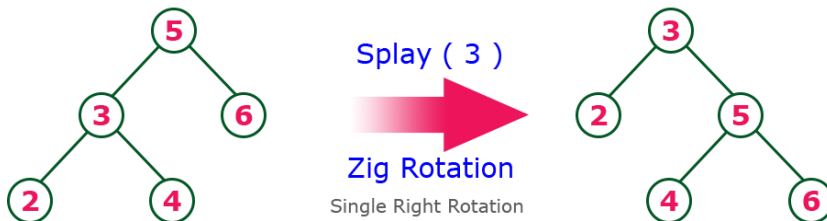
In a splay tree, to splay any element we use the following rotation operations...

Rotations in Splay Tree

1. Zig Rotation
2. Zag Rotation
3. Zig - Zig Rotation
4. Zag - Zag Rotation
5. Zig - Zag Rotation
6. Zag - Zig Rotation

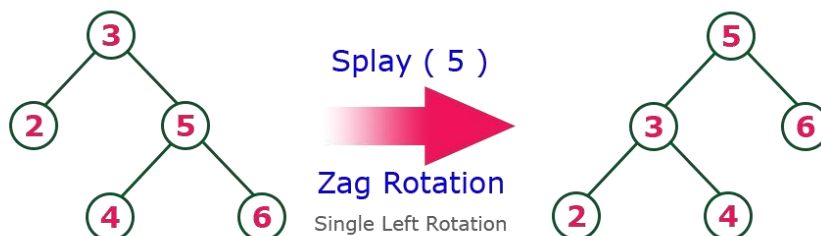
Zig Rotation

The Zig Rotation in a splay tree is **similar to the single right rotation in AVL Tree** rotations. In zig rotation every node moves one position to the right from its current position. Consider the following example...



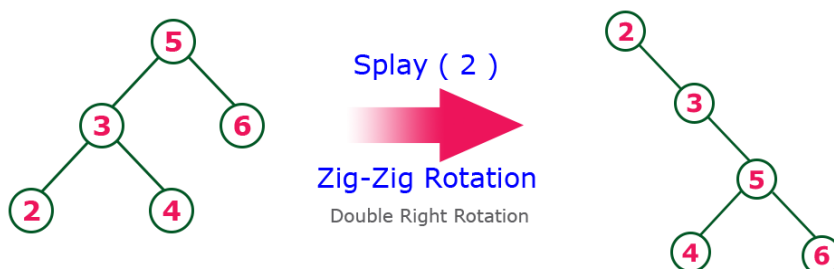
Zag Rotation

The Zag Rotation in a splay tree is similar to the single left rotation in AVL Tree rotations. In zag rotation every node moves one position to the left from its current position. Consider the following example...



Zig-Zig Rotation

The Zig-Zig Rotation in a splay tree is a double zig rotation. In zig-zig rotation every node moves two position to the right from its current position. Consider the following example...



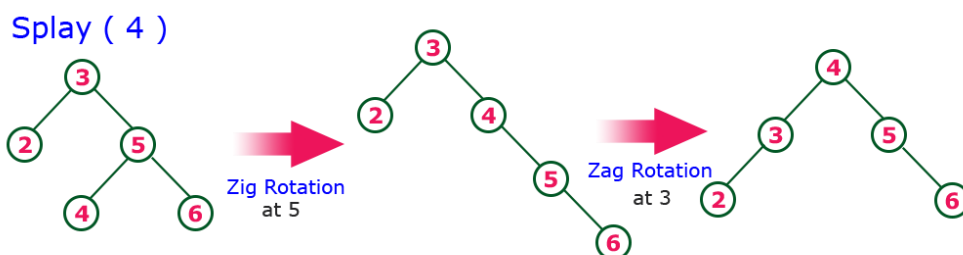
Zag-Zag Rotation

The Zag-Zag Rotation in a splay tree is a double zag rotation. In zag-zag rotation every node moves two position to the left from its current position. Consider the following example...

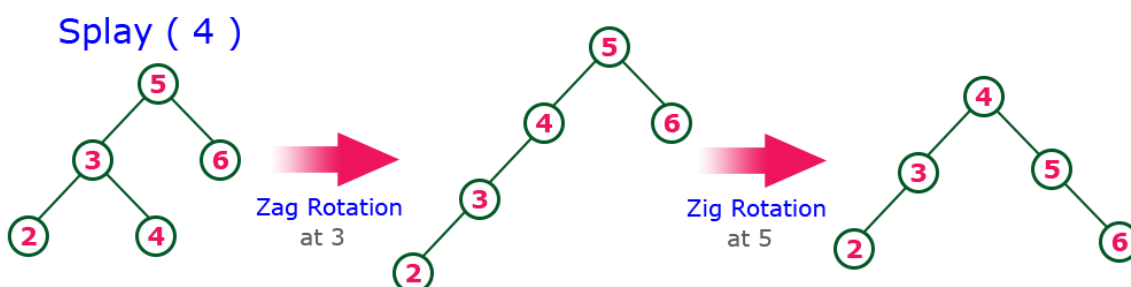


Zig-Zag Rotation

The Zig-Zag Rotation in a splay tree is a sequence of zig rotation followed by zag rotation. In zig-zag rotation every node moves one position to the right followed by one position to the left from its current position. Consider the following example...



Zag-Zig Rotation



The Zag-Zig Rotation in a splay tree is a sequence of zag rotation followed by zig rotation. In zag-zig rotation every node moves one position to the left followed by one position to the right from its current position. Consider the following example...

Note

Every Splay tree must be a binary search tree but it is need not to be balanced tree.

Insertion Operation in Splay Tree

The insertion operation in Splay tree is performed using following steps...

- Step 1: Check whether tree is Empty.
- Step 2: If tree is Empty then insert the newNode as Root node and exit from the operation.
- Step 3: If tree is not Empty then insert the newNode as a leaf node using Binary Search tree insertion logic.
- Step 4: After insertion, Splay the newNode

Deletion Operation in Splay Tree

In a Splay Tree, the deletion operation is similar to deletion operation in Binary Search Tree. But before deleting the element first we need to splay that node then delete it from the root position then join the remaining tree.

Red-Black Trees

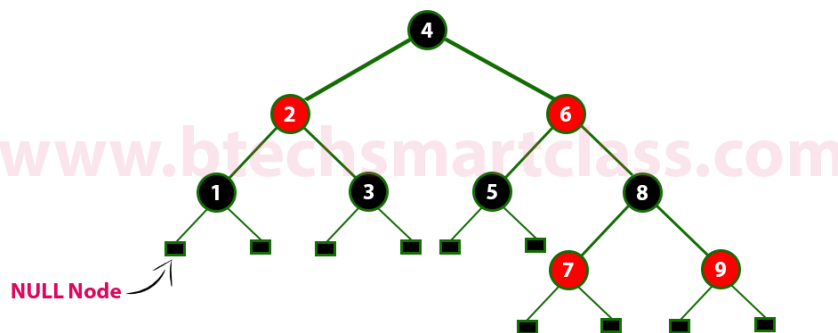
- Red - Black Tree is another variant of Binary Search Tree in which every node is colored either RED or BLACK. We can define a Red Black Tree as follows...
- **Red Black Tree is a Binary Search Tree in which every node is colored eigther RED or BLACK.**
- In a Red Black Tree the color of a node is decided based on the Red Black Tree properties. Every Red Black Tree has the following properties.

Properties of Red Black Tree

- Property #1: Red - Black Tree must be a Binary Search Tree.
- Property #2: The ROOT node must colored BLACK.

- Property #3: The children of Red colored node must colored BLACK. (There should not be two consecutive RED nodes).
- Property #4: In all the paths of the tree there must be same number of BLACK colored nodes.
- Property #5: Every new node must inserted with RED color.
- Property #6: Every leaf (e.i. NULL node) must colored BLACK. Example

The following is a Red Black Tree which created by inserting numbers from 1 to 9.



The above tree is a Red Black tree and every node is satisfying all the properties of Red Black Tree.

Every Red Black Tree is a binary search tree but all the Binary Search Trees need not to be Red Black trees.

Insertion into RED BLACK Tree:

- In a Red Black Tree, every new node must be inserted with color RED.
- The insertion operation in Red Black Tree is similar to insertion operation in Binary Search Tree. But it is inserted with a color property.
- After every insertion operation, we need to check all the properties of Red Black Tree. If all the properties are satisfied then we go to next operation otherwise we need to perform following operation to make it Red Black Tree.
 - Recolor
 - Rotation followed by Recolor

The insertion operation in Red Black tree is performed using following steps...

- Step 1: Check whether tree is Empty.
- Step 2: If tree is Empty then insert the newNode as Root node with color Black and exit from the operation.
- step 3: If tree is not Empty then insert the newNode as a leaf node with Red color.
- Step 4: If the parent of newNode is Black then exit from the operation.
- Step 5: If the parent of newNode is Red then check the color of parent node's sibling of newNode.
- Step 6: If it is Black or NULL node then make a suitable Rotation and Recolor it.
- Step 7: If it is Red colored node then perform Recolor and Recheck it. Repeat the same until tree becomes Red Black Tree.

Example

Create a RED BLACK Tree by inserting following sequence of number
8, 18, 5, 15, 17, 25, 40 & 80.

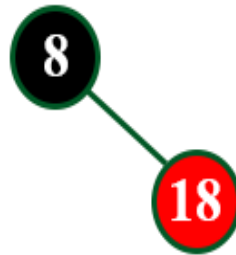
insert (8)

Tree is Empty. So insert newNode as Root node with black color.



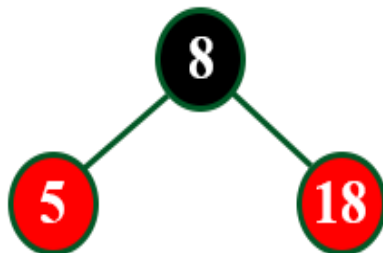
insert (18)

Tree is not Empty. So insert newNode with red color.



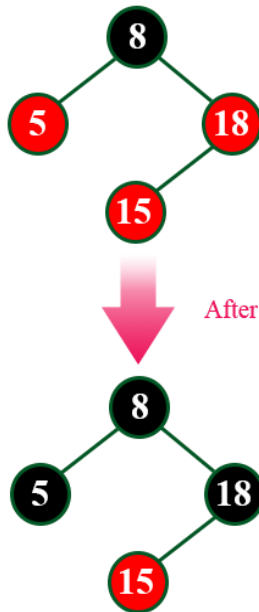
insert (5)

Tree is not Empty. So insert newNode with red color.



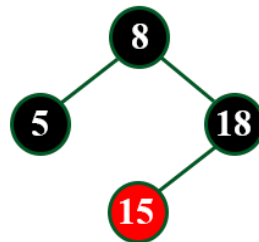
insert (15)

Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (18 & 15). The newnode's parent sibling color is Red and parent's parent is root node. So we use RECOLOR to make it Red Black Tree.

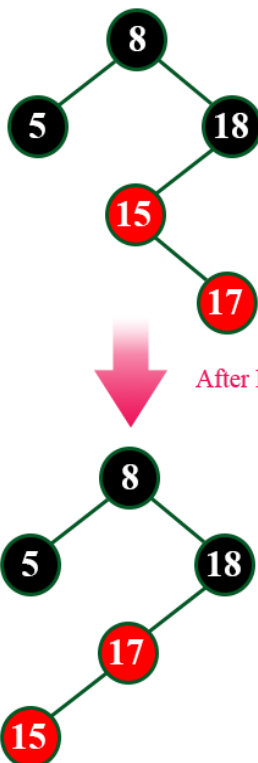
After RECOLOR



After Recolor operation, the tree is satisfying all Red Black Tree properties.

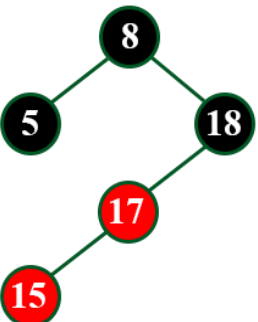
insert (17)

Tree is not Empty. So insert newNode with red color.

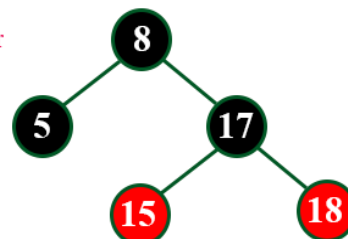


Here there are two consecutive Red nodes (15 & 17). The newnode's parent sibling is NULL. So we need rotation. Here, we need LR Rotation & Recolor.

After Left Rotation

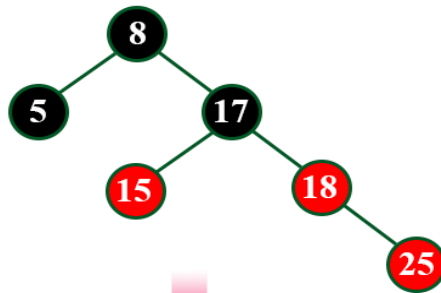


After Right Rotation & Recolor



insert (25)

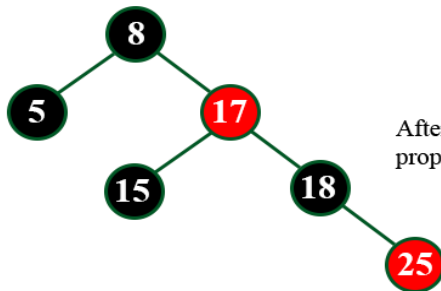
Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (18 & 25).
The newnode's parent sibling color is Red
and parent's parent is not root node.
So we use RECOLOR and Recheck.



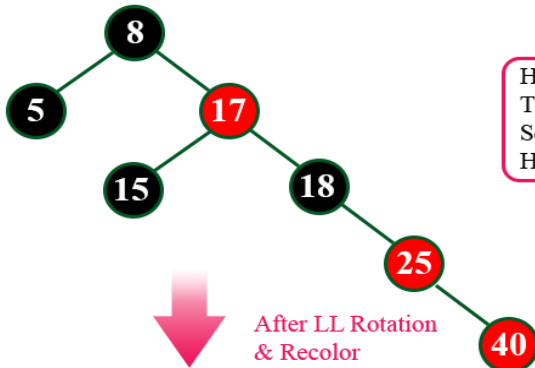
After Recolor



After Recolor operation, the tree is satisfying all Red Black Tree properties.

insert (40)

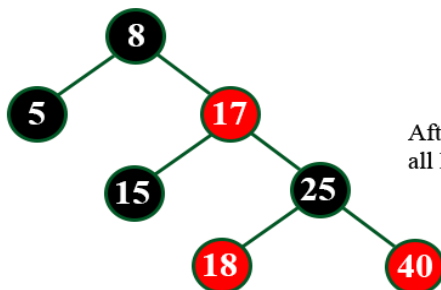
Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (25 & 40).
The newnode's parent sibling is NULL
So we need a Rotation & Recolor.
Here, we use LL Rotation and Recheck.



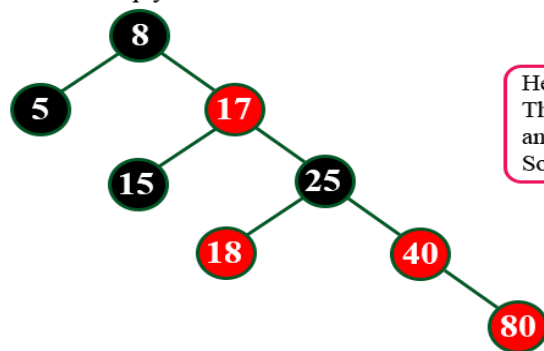
After LL Rotation
& Recolor



After LL Rotation & Recolor operation, the tree is satisfying all Red Black Tree properties.

insert (80)

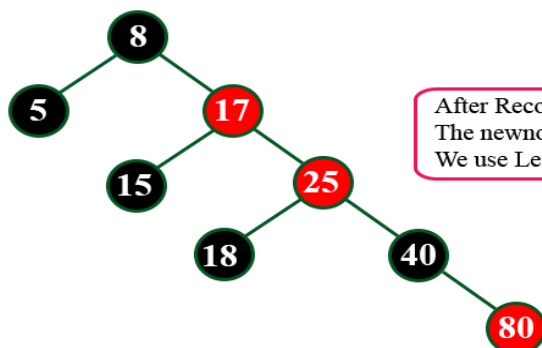
Tree is not Empty. So insert newNode with red color.



Here there are two consecutive Red nodes (40 & 80). The newnode's parent sibling color is Red and parent's parent is not root node. So we use RECOLOR and Recheck.



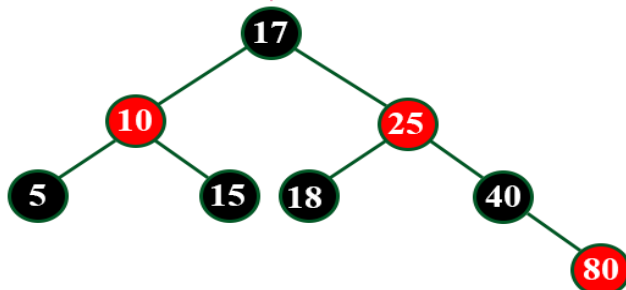
After Recolor



After Recolor again there are two consecutive Red nodes (17 & 25). The newnode's parent sibling color is Black. So we need Rotation. We use Left Rotation & Recolor.



After Left Rotation & Recolor



Finally above tree is satisfying all the properties of Red Black Tree and it is a perfect Red Black tree.

Deletion Operation in Red Black Tree

In a Red Black Tree, the deletion operation is similar to deletion operation in BST. But after every deletion operation we need to check with the Red Black Tree properties. If any of the property is violated then make suitable operation like Recolor or Rotation & Recolor.