

What is MEX?

MEX-functions are programs written in C, C++, or Fortran code that are callable from MATLAB. We will focus on C.

MEX provides C functions to manipulate $\ensuremath{\mathrm{MATLAB}}$ variables, for example

C/MEX	Meaning	
mxCreateDoubleMatrix	Create a 2D double array	
mxGetPr	Get pointer to array data	
mxGetDimensions	Get array dimensions	
mxGetClassID	Determine variable's datatype	

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Words of Warning



My advice:

- Try to optimize your M-code first
- 2 Consider porting the entire application to C/C++
- Use MEX to substitute only the bottleneck M-functions

Getting Started

Hello, world!

hello.c

Getting Started

On the MATLAB console, compile hello.c with

```
>> mex hello.c
```

Compiling requires that you have a C compiler and that MATLAB is configured to use it. Use "mex -setup" to change compiler settings.

Once the MEX-function is compiled, we can call it just like any M-file function:

```
>> hello
Hello, world!
```

Beware that compiled MEX files might not be compatible between different platforms or different versions of MATLAB .

Let's take a closer look at the line

"mxArray" is a type for representing a Matlab variable, and the arguments are:

C/MEX	Meaning
nlhs	Number of output variables
plhs	Array of mxArray pointers to the output variables
nrhs	Number of input variables
prhs	Array of mxArray pointers to the input variables
Notation:	"lhs" = "left-hand side" (output variables) "rhs" = "right-hand side" (input variables)

Let's take a closer look at the line

"mxArray" is a type for representing a Matlab variable, and the arguments are:

C/MEX	M-code equivalent
nlhs	nargout
plhs	varargout
nrhs	nargin
prhs	varargin

```
Notation: "lhs" = "left-hand side" (output variables) 
 "rhs" = "right-hand side" (input variables)
```

Suppose our MEX-function is called as

```
[X,Y] = mymexfun(A,B,C)
```

Then mexFunction

receives the following information:

```
 \begin{array}{lll} nlhs = 2 & nrhs = 3 \\ plhs [0] \ points \ to \ X & prhs [0] \ points \ to \ A \\ plhs [1] \ points \ to \ Y & prhs [1] \ points \ to \ B \\ prhs [2] \ points \ to \ C \\ \end{array}
```

The output variables are initially unassigned; it is the responsibility of the MEX-function to create them. So for the example

$$[X,Y] = mymexfun(A,B,C)$$

it is our responsibility to create X and Y.

If nlhs = 0, the MEX-function is still allowed return one output variable, in which case plhs [0] represents the "ans" variable.

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normalizecols

Objective: Given matrix A, construct matrix B according to

$$B_{m,n}=A_{m,n}/\left\|A_{n}\right\|_{p}$$

where $||A_n||_p$ is the ℓ^p norm of the *n*th column.

normalizecols.m

M-function implementation

```
function B = normalizecols(A, p)

if nargin < 2 % Was p not specified?
   p = 2; % Set default value for p
end

[M, N] = size(A);
B = zeros(M, N);

for n = 1:N % Build matrix B column-by-column
   B(:,n) = A(:,n) / norm(A(:,n), p);
end</pre>
```

normalizecols: Converting to MEX

We will convert normalizecols.m to MEX. Let's start with hello.c as a template...

normalizecols.c

MEX-function implementation

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normalizecols: Converting to MEX

The first step is to figure out the calling syntax. Let's look at

```
B = normalizecols(A, p)
```

This calling syntax in MEX representation is

```
nlhs = 1 nrhs = 2
```

plhs[0] points to B prhs[0] points to A

prhs[1] points to p

For clarity, it is a good idea to define

normalizecols: Converting to MEX

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Be on the defensive and check inputs. We can use mexErrMsgTxt to abort with an error message.

normalizecols.c

MEX-function implementation

```
#include "mex.h" /* Always include this */
#define A_IN prhs[0]
#define P_IN prhs[1]
#define B_OUT plhs[0]
int nrhs, const mxArray *prhs[]) /* Inputs */
   if (nrhs < 1 \mid | nrhs > 2)
      mexErrMsqTxt("Must have either 1 or 2 input arguments.");
   if(nlhs > 1)
      mexErrMsqTxt("Too many output arguments.");
   /* ... */
```

We should also verify the datatype of the input variables.

C/MEX	Meaning
mxIsDouble(A_IN)	True for a double array
mxIsComplex(A_IN)	True if array is complex
mxIsSparse(A_IN)	True if array is sparse
<pre>mxGetNumberOfDimensions(A_IN)</pre>	Number of array dimensions
<pre>mxGetNumberOfElements(A_IN)</pre>	Number of array elements

For simplicity, let's require that A is a real 2D full double matrix.

We want to allow two calling syntaxes

```
B = normalizecols(A) % nrhs == 1 (use p = 2.0)

B = normalizecols(A, p) % nrhs == 2
```

We can determine which way normalizecols was called by checking nrhs. If nrhs = 2, then we should also check the datatype of p.

normalizecols.c

MEX-function implementation

```
#include "mex.h" /* Always include this */
#define A_IN
            prhs[0]
#define P_IN prhs[1]
#define B_OUT plhs[0]
int nrhs, const mxArray *prhs[]) /* Inputs */
   double p:
   /*** Check inputs ***/
   if(nrhs < 1 \mid \mid nrhs > 2)
       mexErrMsqTxt("Must have either 1 or 2 input arguments.");
   if(n) hs > 1)
       mexErrMsqTxt("Too many output arguments.");
   if (mxIsComplex (A_IN) | mxGetNumberOfDimensions (A_IN) != 2
       | mxIsSparse(A_IN) | !mxIsDouble(A_IN))
       mexErrMsgTxt("Sorry! A must be a real 2D full double matrix.");
   if (nrhs == 1) /* Was p not specified? */
       p = 2.0; /* Set default value for p */
   else
       if (mxIsComplex(P_IN) | !mxIsDouble(P_IN)
           | | mxGetNumberOfElements(P_IN) != 1)
           mexErrMsqTxt("p must be a double scalar.");
       else
           p = mxGetScalar(P_IN); /* Get the value of p */
```

normalizecols: Reading Input A

Now that the inputs are verified, we can safely interpret A as a real 2D full double matrix.

The elements of A are stored contiguously in memory in column-major format,

```
A[m + M*n] corresponds to A(m+1,n+1)
```

normalizecols: Creating Output B

Output variables must be created by the MEX-function. We can create B by

```
double *B;

/*** Create the output matrix ***/
B_OUT = mxCreateDoubleMatrix(M, N, mxREAL);
B = mxGetPr(B_OUT); /* Get pointer to B's data */
```

The interface is now set up!

normalizecols.c

MEX-function implementation

```
#include "mex.h" /* Always include this */
#define A_IN prhs[0]
#define P_IN prhs[1]
#define B_OUT plhs[0]
int nrhs, const mxArray *prhs[]) /* Inputs */
   double p. *A. *B:
   int M. N:
   /*** Check inputs ***/
   /* ... */
    /*** Read matrix A ***/
   M = mxGetM(A_IN): /* Get the dimensions of A */
   N = mxGetN(A_IN);
   A = mxGetPr(A_IN); /* Get pointer to A's data */
   /*** Create the output matrix ***/
   B_OUT = mxCreateDoubleMatrix(M, N, mxREAL);
   B = mxGetPr(B_OUT); /* Get pointer to B's data */
   /* TODO: Do the computation itself */
   DoComputation (B, A, M, N, p);
```

normalizecols: DoComputation

All that remains is to code the computation itself.

```
#include <math.h>
void DoComputation(double *B, double *A, int M, int N, double p)
    double colnorm:
    int m, n;
    for (n = 0; n < N; n++)
        /* Compute the norm of the nth column */
        for (m = 0, colnorm = 0.0; m < M; m++)
            colnorm += pow(A[m + M*n], p);
        colnorm = pow(fabs(colnorm), 1.0/p);
        /* Fill the nth column of B */
        for (m = 0; m < M; m++)
            B[m + M*n] = A[m + M*n]/colnorm;
```

normalizecols: M-code vs. MEX

The MEX implementation is certainly more complicated than the M-function. So did our hard work pay off?

Runtime (s) with p = 2.7:

Input A	M-function	MEX-function	MEX-function*
1000×1000	0.2388	0.0963	0.0927
2000×2000	0.9479	0.3656	0.3599
3000×3000	2.1976	0.8896	0.8550
4000×4000	3.9033	1.5816	1.5128

^{*}With minor optimizations

More Information

Please see Writing MATLAB C/MEX Code on my webpage www.math.ucla.edu/~getreuer



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