## Notebook: "Credit Card Fraud Detection"

#### Basic idea of the model:

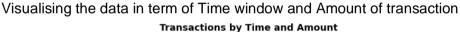
Train the model with only non-fraud transactions. The autoencoder model is expected to learn how to reconstruct only non-fraud transactions. So the model is expected not perform well in reconstructing fraud transactions. So for fraud transactions it is expected to have a large error between the actual transaction and the reconstructed transaction. This large error is the critical parameter used to determine if the transaction is a fraud transaction.

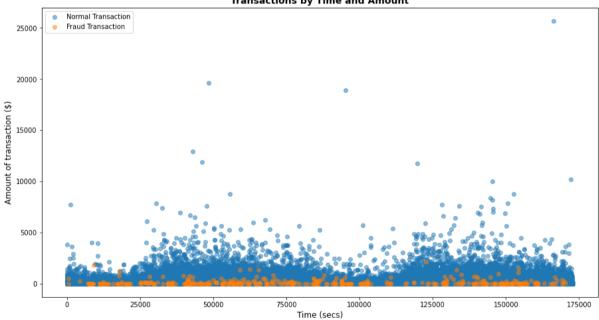
Raw data: 284807 rows x 31 columns Including: Time, V1 - V28, Amount, Class

We see a total of 31 variables.

- features V1 V28 are a result of the PCA transformation and are simply numerical representations.
- Time variable is the amount of time that passed from the time when the first transaction took place.
- Amount is the value in dollars of the transaction
- Class represents if the transaction is tagged as being a fraudulent transaction. 0 indicates the transaction is not fraudulent while a 1 indicates a fraudulent transaction. This will be our target variable.

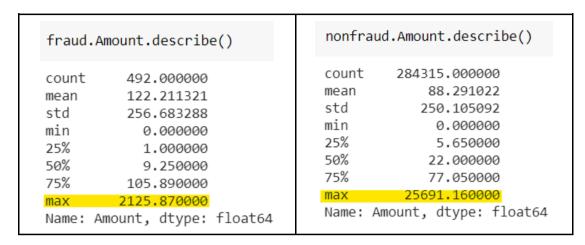
## Pre-processing dataset:





- The graph above has shown that the fraud or non fraud account does not occur at a specific time window, so this indicates that the time does not hold any important information in detecting fraud transactions. Thus, time is removed from the data
- The graph has shown that all the fraud transactions will not have a large transaction amount. (refer to table below)

- The graph showed that the difference between the amount of transactions is large and this will affect the learning of the model. Thus all the amount of transactions is normalized
- The raw data also contain 28 columns of credit card features (V1-V28), all these column have also been normalized



- There are 492 fraud samples and 284315 fraud samples
- Small amount of fraud samples and large amount of non fraud samples

## Split the data into training, validation and test set

- Training Set and Validation set contain only the non-fraud samples
- Test set contain both the fraud and non-fraud dataset
- Batch size = 1000

Dataset	Split percentage	Number of samples
Training Set	70%	209255
Validation Set	10%	18197
Test Set	20%	57355

## **Explanation for the classifier stage:**

1. Use the validation set to find the mean error between actual transaction and reconstructed transaction for only non-fraud sample

```
Preds =
np.vstack([saved_model(V(next(valData)).to(device)).cpu().data.nu
mpy() for i in range(len(valData))])
# Determine the error between the actual account and the
reconstructed account
error = np.mean(abs(X_val - Preds), axis = 1) #axis 1 -> along
row
```

This code has given the mean error for each non-fraud samples in the validation set

- 2. Compute a threshold using the mean error
  - 2 Approaches, chosen approach 2
    - Approach 1: find the max non-fraud samples' mean error and use this as the threshold
      - Ode: threshold = round(max(error), 4)
      - Limitation: the value is too small and is does not able to detect most of the fraud account
      - Result I obtained only able to detect 3 cases out of 492 fraud cases
    - Approach 2: find the mean and standard deviation of the non-fraud samples' mean error and use it as the threshold

```
Ocide: threshold = round((error.mean() + error.std()),
4) #idea from
http://www.datadoz.com/blog/detectingfraud.html
```

- o This is a better approach as the threshold is a larger number
- Result: it is able to detect more fraud cases. But also using this threshold it will now detect more non-fraud as fraud.
- But compare to not detecting fraud account, this threshold has given a better result compared to approach 1
- 3. Repeat the same process to find the mean error for each sample in the test set which contain both fraud and non-fraud transaction
- 4. Use the threshold to compute the predicted label for each sample
  - If mean error > threshold => fraud transaction. (class label = 1)
  - Mean error <= threshold => non-fraud (class label = 0)
  - Code:

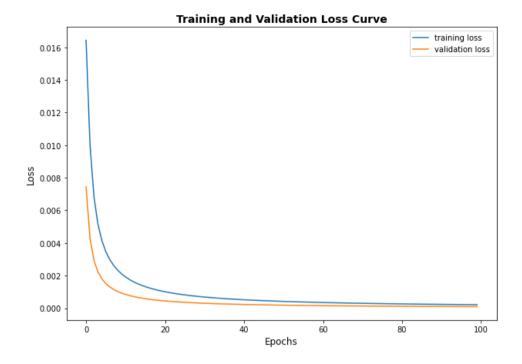
```
y_testpred = []
for idx, err in enumerate (test_error):
    # if difference btw the actual account and the
reconstructed account is > threshold == fraud
    if err > threshold: class_pred = 1
    else: class_pred = 0
    y_testpred.append(class_pred)
```

#### Model:

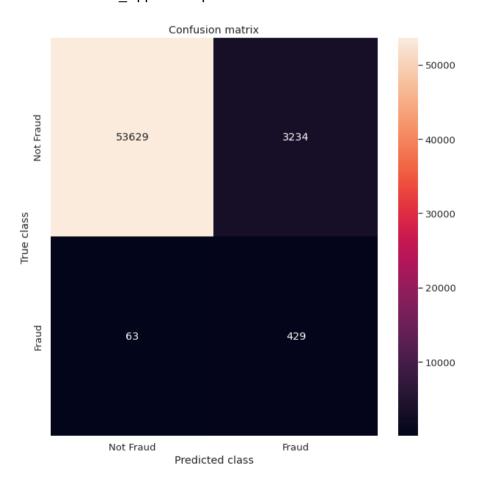
## Approach 1:

```
class Autoencoder(nn.Module):
   def init (self):
       super(Autoencoder, self). init ()
        self.fc1 = nn.Linear(29, 19)
        self.fc2 = nn.Linear(19, 9)
        self.fc3 = nn.Linear(9 , 19)
        self.fc4 = nn.Linear(19,29)
       self.tanh = nn.Tanh()
        self.drop = nn.Dropout(0.05)
   def forward(self, data):
       x = self.tanh(self.fc1(data))
       x = self.tanh(self.fc2(x))
       x = self.drop(x)
       x = self.tanh(self.fc3(x))
       out = self.fc4(x)
       return (out)
```

```
model = Autoencoder().to(device)
lr = 1e-4
nepochs = 100
loss = nn.MSELoss()
optimizer = torch.optim.Adam(model.parameters(), lr=lr)
```



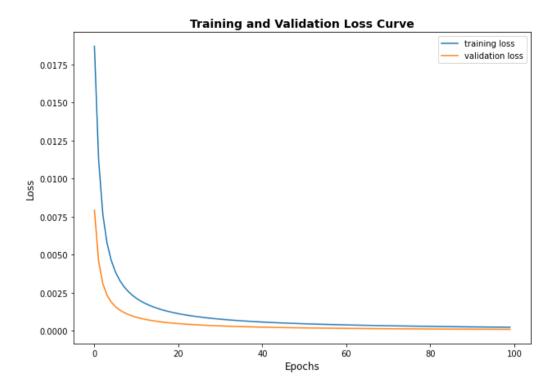
Saved model: "Autoencoder\_Approach1.pth"



## Approach 2:

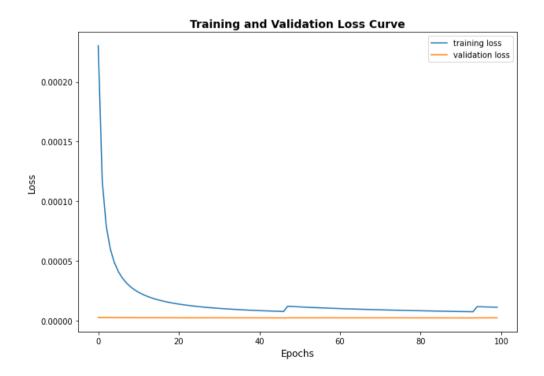
```
class Autoencoder(nn.Module):
   def init (self):
        super(Autoencoder, self).__init__()
        # Layers in the model
        self.fc1 = nn.Linear(29, 22)
        self.fc2 = nn.Linear(22, 15)
        self.fc3 = nn.Linear(15, 10)
        self.fc4 = nn.Linear(10, 15)
        self.fc5 = nn.Linear(15, 22)
        self.fc6 = nn.Linear(22, 29)
        # Activation function
        self.tanh = nn.Tanh()
        # Dropout
        self.drop = nn.Dropout(0.05)
   def forward(self, x):
       out1 = self.tanh(self.fc1(x))
        out2 = self.tanh(self.fc2(out1))
        out3 = self.tanh(self.fc3(out2))
        out4 = self.drop(out3)
        out5 = self.tanh(self.fc4(out4))
        out6 = self.tanh(self.fc5(out5))
        out7 = self.fc6(out6)
        return (out7)
```

```
model = Autoencoder().to(device)
lr = 1e-4
nepochs = 100
loss = nn.MSELoss()
optimizer = torch.optim.Adam(model.parameters(), lr=lr)
```



## Approach 2 - different learning rate

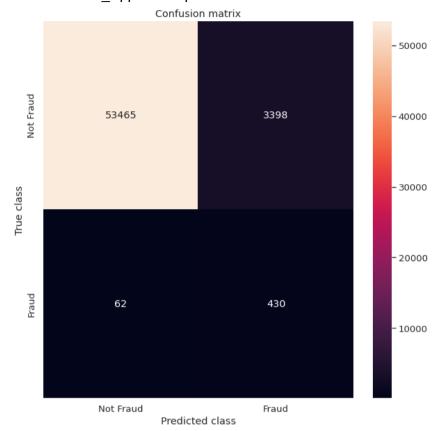
```
model = Autoencoder().to(device)
lr = 1e-2
nepochs = 100
loss = nn.MSELoss()
optimizer = torch.optim.Adam(model.parameters(), lr=lr)
```



The validation set is not learning

## Chosen learning rate 1e-4, 100 epochs

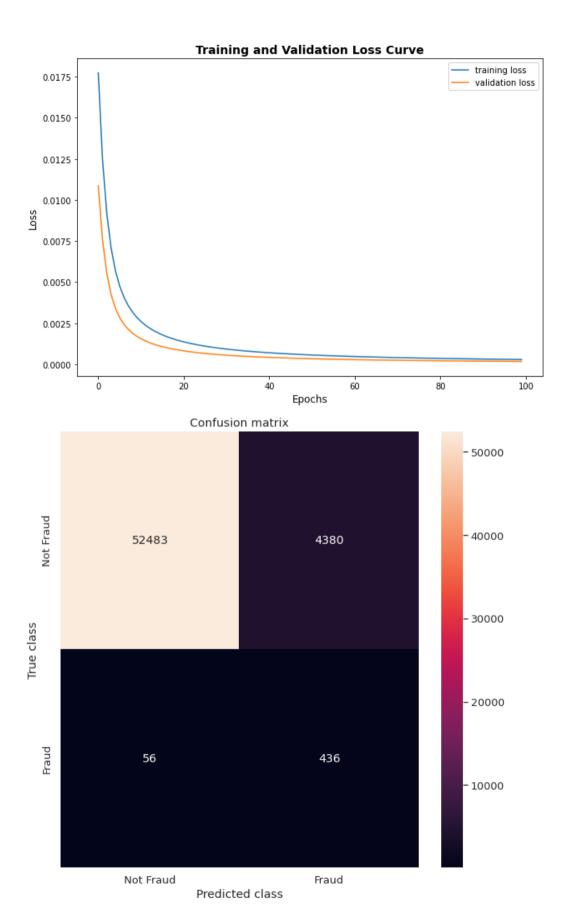
Saved model: "Autoencoder\_Approach2.pth"



## Approach 3:

Saved Model: "Autoencoder\_Approach3.pth"

```
# Approach 3
class Autoencoder(nn.Module):
    def init (self):
        super(Autoencoder, self). init ()
        # Layers in the model
        self.fc1 = nn.Linear(29, 14)
        self.fc2 = nn.Linear(14, 7)
        self.fc3 = nn.Linear(7, 14)
        self.fc4 = nn.Linear(14, 29)
        # Activation function
        self.tanh = nn.Tanh()
        self.relu = nn.ReLU()
    def forward(self, x):
        # Encoder
        x = self.fc1(x)
        x = self.tanh(x)
        x = self.fc2(x)
        x = self.relu(x)
        #Decoder
        x = self.fc3(x)
        x = self.tanh(x)
        x = self.fc4(x)
        x = self.relu(x)
        return x
model = Autoencoder().to(device)
lr = 1e-4
nepochs = 100
loss = nn.MSELoss()
optimizer = torch.optim.Adam(model.parameters(), lr=lr)
```



# Compare all the 3 approaches:

Approach 1	Approach 2	Approach 3
<pre>class Autoencoder(nn.Module):     definit(self):         super(Autoencoder, self)init()      self.fc1 = nn.Linear(29, 19)     self.fc2 = nn.Linear(19, 9)     self.fc3 = nn.Linear(9, 19)     self.fc4 = nn.Linear(19,29)      self.tanh = nn.Tanh()      self.drop = nn.Dropout(0.05)  def forward(self, data):     x = self.tanh(self.fc1(data))     x = self.tanh(self.fc2(x))     x = self.tanh(self.fc3(x))     out = self.fc4(x)      return (out)</pre>	<pre>class Autoencoder(nn.Module):     definit(self):         super(Autoencoder, self)init()  # Layers in the model     self.fc1 = nn.Linear(29, 22)     self.fc2 = nn.Linear(22, 15)     self.fc3 = nn.Linear(15, 10)     self.fc4 = nn.Linear(10, 15)     self.fc5 = nn.Linear(15, 22)     self.fc6 = nn.Linear(22, 29)     # Activation function     self.tanh = nn.Tanh()     # Dropout     self.drop = nn.Dropout(0.05)  def forward(self, x):     out1 = self.tanh(self.fc1(x))     out2 = self.tanh(self.fc2(out1))     out3 = self.tanh(self.fc3(out2))     out4 = self.drop(out3)     out5 = self.tanh(self.fc4(out4))     out6 = self.tanh(self.fc5(out5))     out7 = self.fc6(out6)     return (out7)</pre>	<pre># Approach 3 class Autoencoder(nn.Module):     definit(self):         super(Autoencoder, self)init()      # Layers in the model     self.fc1 = nn.Linear(29, 14)     self.fc2 = nn.Linear(14, 7)     self.fc3 = nn.Linear(7, 14)     self.fc4 = nn.Linear(14, 29)     # Activation function     self.tanh = nn.Tanh()     self.relu = nn.ReLU()  def forward(self, x):     # Encoder     x = self.fc1(x)     x = self.fc2(x)     x = self.tanh(x)  #Decoder     x = self.fc3(x)     x = self.fc4(x)     x = self.fc4(x)     x = self.relu(x)</pre>
<ul><li>4 fc layers</li><li>Use tanh and dropout</li></ul>	<ul><li>6 fc layers</li><li>Use tanh and dropout</li></ul>	- 4 fc layers - Use tanh and relu
Total Trainable Params: 1520		Total Trainable Params: 1072

