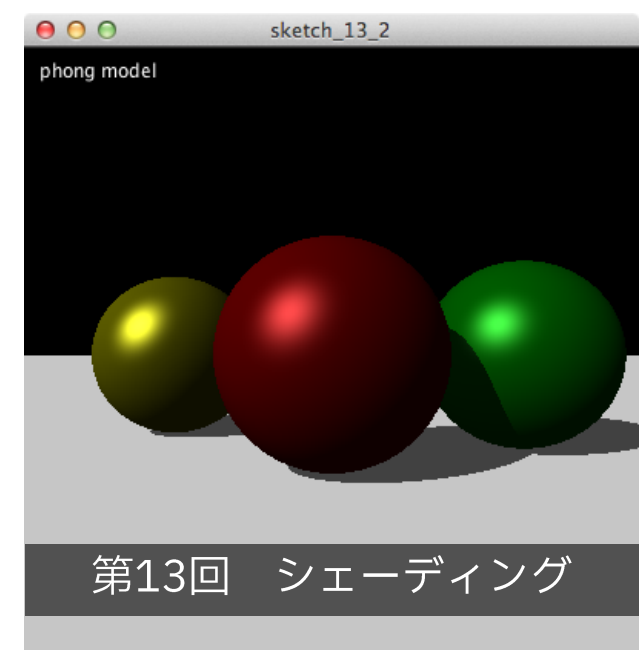
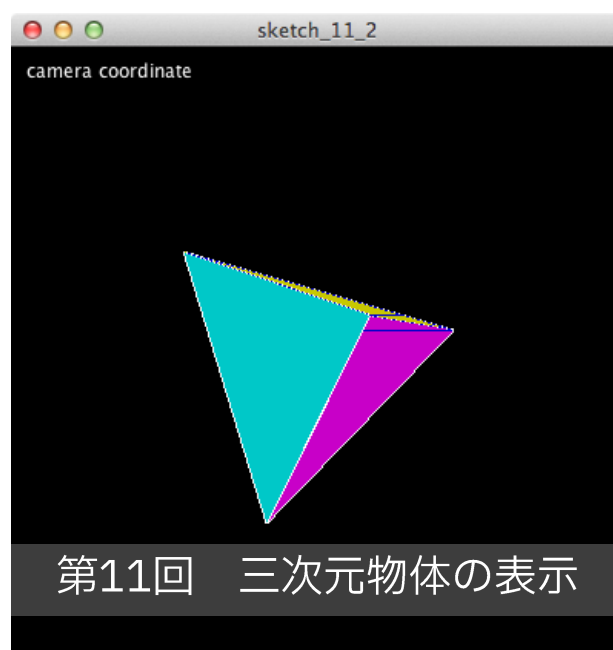
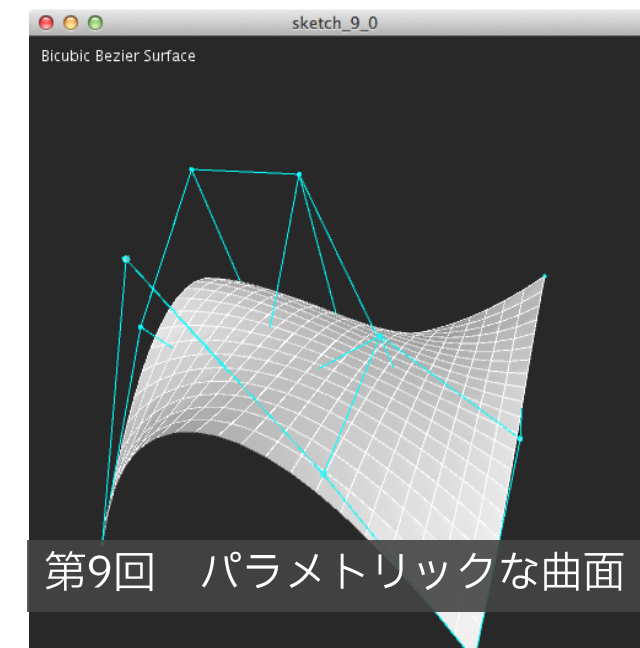
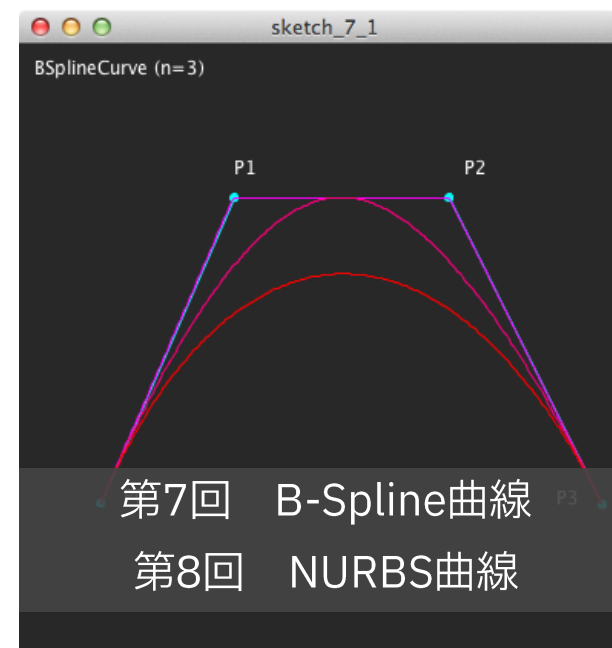
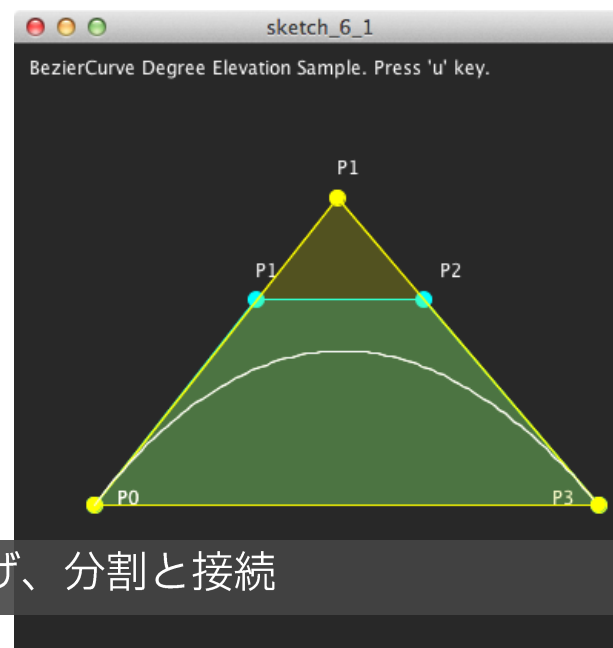
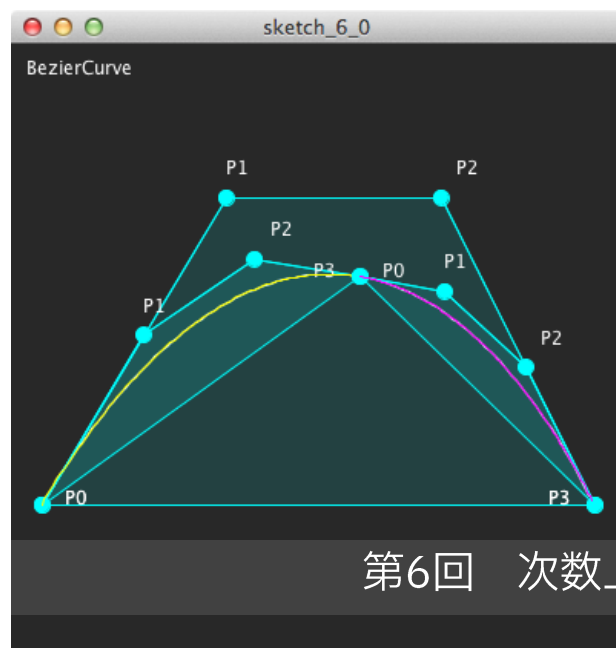
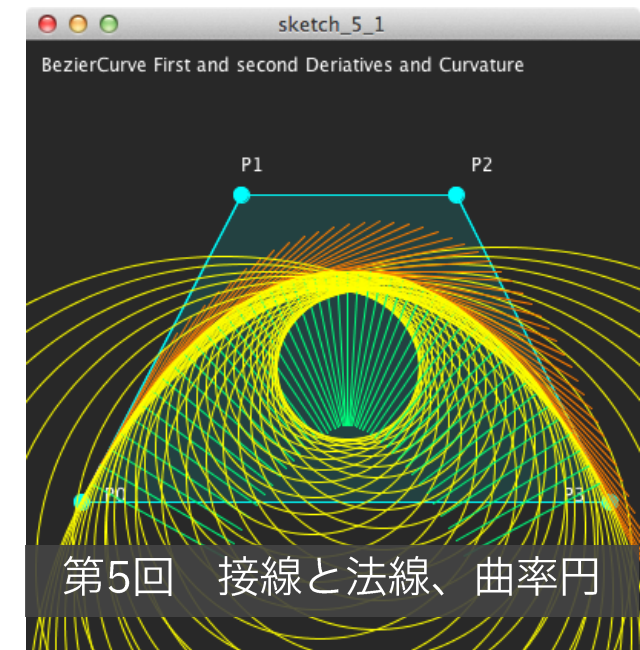
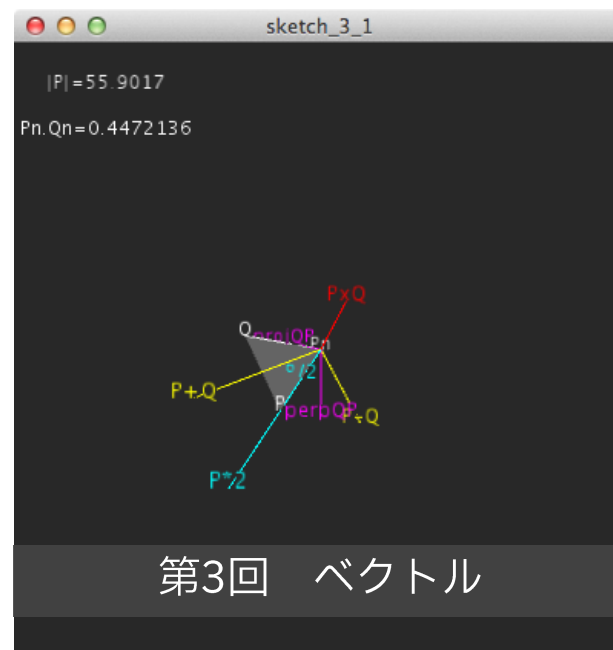
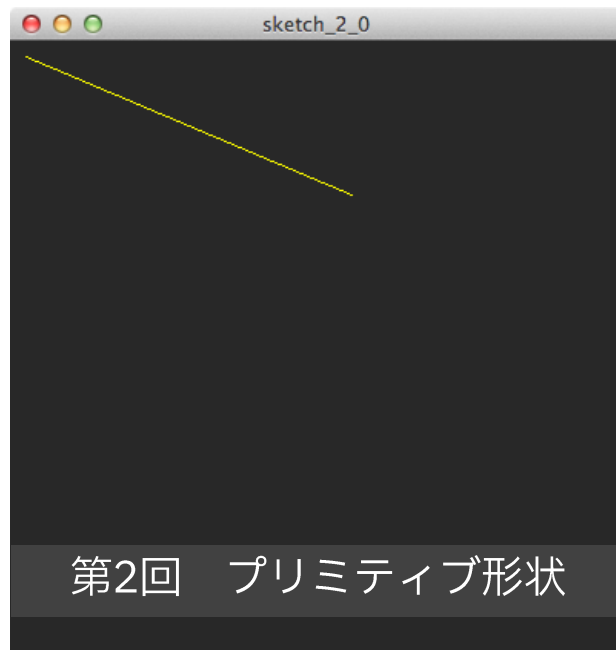


CGとCADの数理

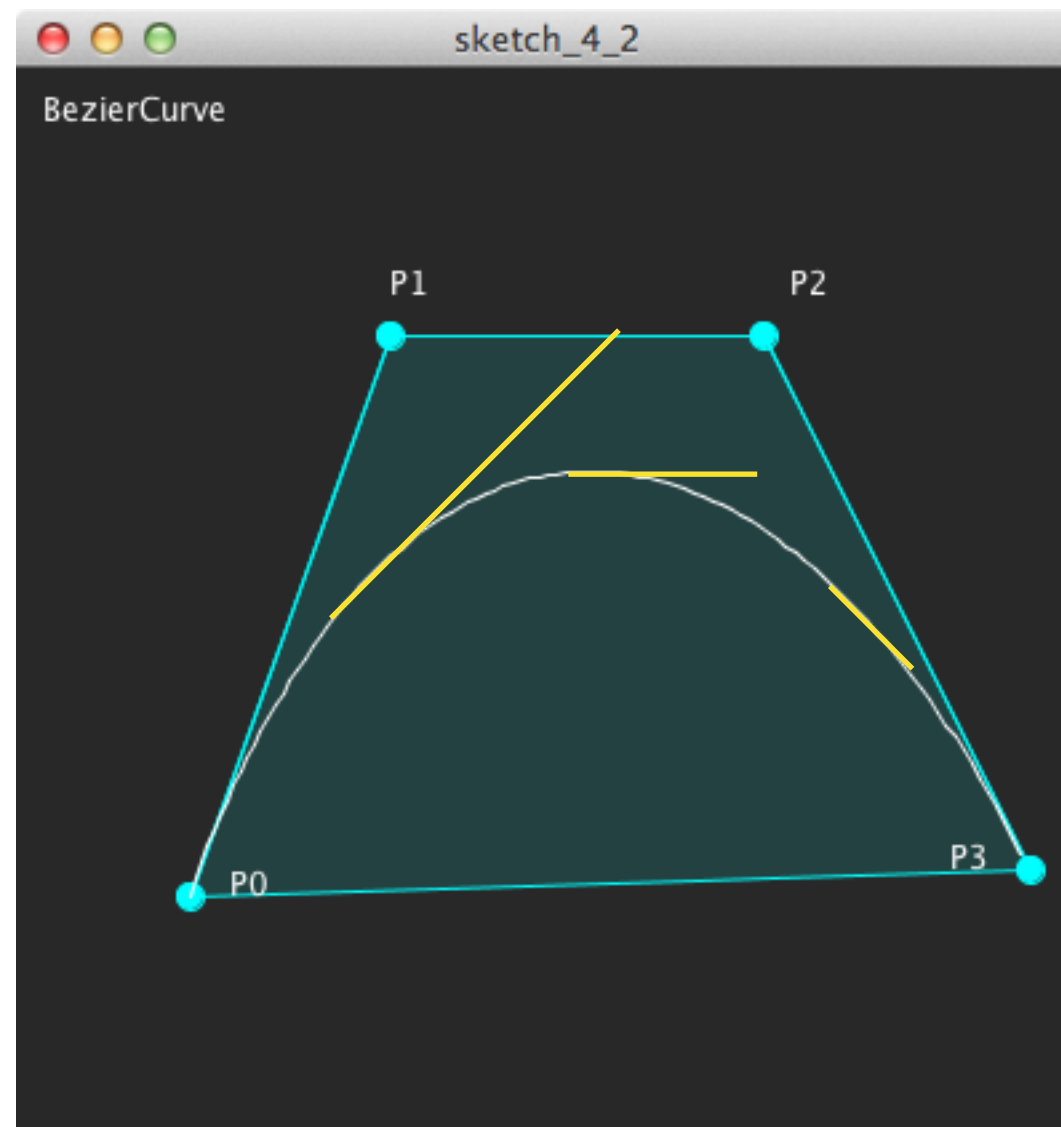
GEOMETRIC MODELING AND COMPUTER GRAPHICS

第05回 接線と法線、曲率円



ベジエ曲線

Bezier Curve



前回の講義では、ベルンシュタイン基底関数を紹介し、3次ベジエ曲線の描画に挑戦しました。本日の講義では、3次ベジエ曲線の式を1階、2階微分して接線と法線を描画し、最後に曲率の計算までを紹介致します。

$$R(t) = \boxed{(1-t)^3} P_0 + \boxed{3(1-t)^2 t} P_1 + \boxed{3(1-t) t^2} P_2 + \boxed{t^3} P_3$$

t で微分 t で微分 t で微分 t で微分

$$\begin{aligned}
 & -3(1-t)^2 & 9t^2 - 12t + 3 & 6t - 9t^2 & 3t^2
 \end{aligned}$$

$$= 3(\boxed{3t^2} - \boxed{4t} + 1)$$

$$= 3(\boxed{t^2} + \boxed{2t^2} - \boxed{2t} - \boxed{2t} + 1)$$

$$= 3(\boxed{1 - 2t + t^2} + \boxed{2t^2 - 2t})$$

$$= 3\{\boxed{(1-t)^2} - \boxed{2t(1-t)}\}$$

$$= 3(2t - \boxed{3t^2})$$

$$= 3(\boxed{2t} - \boxed{2t^2} - \boxed{t^2})$$

$$= 3\{2t(1-t) - t^2\}$$

$$\frac{dR(t)}{dt} = -3(1-t)^2 P_0 + 3\{(1-t)^2 - 2t(1-t)\} P_1 + 3\{2t(1-t) - t^2\} P_2 + 3t^2 P_3$$

$$= \boxed{-3(1-t)^2 P_0 + 3(1-t)^2 P_1} - \boxed{3 \cdot 2t(1-t) P_1} + \boxed{3 \cdot 2t(1-t) P_2} - \boxed{3t^2 P_2} + \boxed{3t^2 P_3}$$

$$= \boxed{(1-t)^2 3(P_1 - P_0)} + \boxed{2t(1-t) 3(P_2 - P_1)} + \boxed{t^2 3(P_3 - P_2)}$$

$$B_i^n = \binom{n}{i} (1-t)^{n-i} t^i$$

$$i = 0, n = 2 \text{ の場合} \quad B_0^2 = \binom{2}{0} (1-t)^{2-0} t^0 = (1-t)^2$$

$$i = 1, n = 2 \text{ の場合} \quad B_1^2 = \binom{2}{1} (1-t)^{2-1} t^1 = 2t(1-t)$$

$$i = 2, n = 2 \text{ の場合} \quad B_2^2 = \binom{2}{2} (1-t)^{2-2} t^2 = t^2$$

$$R(t) = (1-t)^3 P_0 + 3(1-t)^2 t P_1 + 3(1-t) t^2 P_2 + t^3 P_3$$

$$\begin{aligned}
 R'(t) &= (1-t)^2 \underbrace{3(P_1 - P_0)}_{=Q_0} + 2t(1-t) \underbrace{3(P_2 - P_1)}_{=Q_1} + t^2 \underbrace{3(P_3 - P_2)}_{=Q_2} \\
 &= B_0^2 Q_0 + B_1^2 Q_1 + B_2^2 Q_2
 \end{aligned}$$

$\xrightarrow{n=3}$

$$R(t) = \sum_{i=0}^n B_i^3(t) P_i$$

$$R(t) = \sum_{i=0}^n B_i^n(t) P_i$$

$$R(t) = (1-t)^3 P_0 + 3(1-t)^2 t P_1 + 3(1-t) t^2 P_2 + t^3 P_3$$

$$R(t) = B_0^3(t) P_0 + B_1^3(t) P_1 + B_2^3(t) P_2 + B_3^3(t) P_3$$

----- 2の次数を n で表してみる -----

$$R'(t) = \sum_{i=0}^{n-1} B_i^2(t) Q_i$$

$$R'(t) = \sum_{i=0}^{n-1} B_i^{n-1}(t) Q_i$$

$$R'(t) = (1-t)^2 Q_0 + 2t(1-t) Q_1 + t^2 Q_2$$

$$3(P_1 - P_0)$$

$$3(P_2 - P_1)$$

$$3(P_3 - P_2)$$

$$R'(t) = B_0^2(t) Q_0 + B_1^2(t) Q_1 + B_2^2(t) Q_2$$

n 次

$$R(t) = \sum_{i=0}^3 B_i^3(t) P_i$$

$$R(t) = \sum_{i=0}^n B_i^n(t) P_i$$

$$R(t) = B_0^3(t)P_0 + B_1^3(t)P_1 + B_2^3(t)P_2 + B_3^3(t)P_3$$

$$R(t) = (1-t)^3 P_0 + 3(1-t)^2 t P_1 + 3(1-t)t^2 P_2 + t^3 P_3$$

$$R'(t) = \sum_{i=0}^2 B_i^2(t) Q_i$$

$$R'(t) = \sum_{i=0}^{n-1} B_i^{n-1}(t) Q_i$$

$$R'(t) = B_0^2(t)Q_0 + B_1^2(t)Q_1 + B_2^2(t)Q_2$$

$$R'(t) = (1-t)^2 Q_0 + 2t(1-t)Q_1 + t^2 Q_2$$

$$3(P_1 - P_0)$$

$$3(P_2 - P_1)$$

$$3(P_3 - P_2)$$

1 階微分

$$R''(t) = \sum_{i=0}^1 B_i^1(t) W_i$$

$$R''(t) = \sum_{i=0}^{n-2} B_i^{n-2}(t) W_i$$

$$R''(t) = B_0^1(t)W_0 + B_1^1(t)W_1$$

$$R''(t) = (1-t)W_0 + tW_1$$

$$2(Q_1 - Q_0)$$

$$2(Q_2 - Q_1)$$

2 階微分

[sketch_5_0.pde](#) をダウンロードして下さい

1 階微分

$$R'(t) = \sum_{i=0}^2 B_i^{(2)}(t) Q_i$$

$$R'(t) = \sum_{i=0}^{n-1} B_i^{(n-1)}(t) Q_i$$

$$R'(t) = B_0^{(2)}(t) Q_0 + B_1^{(2)}(t) Q_1 + B_2^{(2)}(t) Q_2$$

$$R'(t) = (1-t)^2 Q_0 + 2t(1-t) Q_1 + t^2 Q_2$$

$$3(P_1 - P_0)$$

$$3(P_2 - P_1)$$

$$3(P_3 - P_2)$$

$$\begin{aligned} Q0.x &= 3 * (P1.x - P0.x) ; \\ Q0.y &= 3 * (P1.y - P0.y) ; \end{aligned}$$

$$\begin{aligned} Q1.x &= 3 * (P2.x - P1.x) ; \\ Q1.y &= 3 * (P2.y - P1.y) ; \end{aligned}$$

$$\begin{aligned} Q2.x &= 3 * (P3.x - P2.x) ; \\ Q2.y &= 3 * (P3.y - P2.y) ; \end{aligned}$$

2 階微分

$$R''(t) = \sum_{i=0}^1 B_i^{(1)}(t) W_i$$

$$R''(t) = \sum_{i=0}^{n-2} B_i^{(n-2)}(t) W_i$$

$$R''(t) = B_0^{(1)}(t) W_0 + B_1^{(1)}(t) W_1$$

$$R''(t) = (1-t) W_0 + t W_1$$

$$2(Q_1 - Q_0)$$

$$2(Q_2 - Q_1)$$

$$\begin{aligned} W0.x &= 2 * (Q1.x - Q0.x) ; \\ W0.y &= 2 * (Q1.y - Q0.y) ; \end{aligned}$$

$$\begin{aligned} W1.x &= 2 * (Q2.x - Q1.x) ; \\ W1.y &= 2 * (Q2.y - Q1.y) ; \end{aligned}$$

```
PVector Q0, Q1, Q2;
```

```
Q0=new PVector();
```

```
Q0.x=3*(P1.x-P0.x); Q0.y=3*(P1.y-P0.y);
```

```
Q1=new PVector();
```

```
Q1.x=3*(P2.x-P1.x); Q1.y=3*(P2.y-P1.y);
```

```
Q2=new PVector();
```

```
Q2.x=3*(P3.x-P2.x); Q2.y=3*(P3.y-P2.y);
```

```
PVector W0, W1;
```

```
W0=new PVector();
```

```
W0.x=2*(Q1.x-Q0.x); W0.y=2*(Q1.y-Q0.y);
```

```
W1=new PVector();
```

```
W1.x=2*(Q2.x-Q1.x); W1.y=2*(Q2.y-Q1.y);
```

1階微分

$$R'(t) = \sum_{i=0}^2 B_i^2(t) Q_i$$

$$R'(t) = B_0^2(t) Q_0 + B_1^2(t) Q_1 + B_2^2(t) Q_2$$

$$R'(t) = (1-t)^2 Q_0 + 2t(1-t) Q_1 + t^2 Q_2$$

$$B_{20}t = (1-t) * (1-t);$$

$$B_{21}t = 2 * (1-t) * t;$$

$$B_{22}t = t * t;$$

2階微分

$$R''(t) = \sum_{i=0}^1 B_i^1(t) W_i$$

$$R''(t) = B_0^1(t) W_0 + B_1^1(t) W_1$$

$$R''(t) = (1-t) W_0 + t W_1$$

$$B_{10}t = 1-t;$$

$$B_{11}t = t;$$

$$R''(t) = \sum_{i=0}^{n-1} B_i^{n-1}(t) Q_i$$

$$R''(t) = \sum_{i=0}^{n-2} B_i^{n-2}(t) W_i$$

$$B_{20}t = (1-t) * (1-t) ;$$

$$B_{21}t = 2 * (1-t) * t ;$$

$$B_{22}t = t * t ;$$

$$B_{10}t = 1 - t ;$$

$$B_{11}t = t ;$$

$$R'(t) = \sum_{i=0}^2 B_i(t) Q_i$$

$$R'(t) = \sum_{i=0}^{n-1} B_i^{n-1}(t) Q_i$$

1階微分

D1 [tt]

$$R'(t) = (1-t)^2 Q_0 \rightarrow \begin{aligned} B_{20}t &= (1-t) * (1-t); \\ Q_0.x &= 3 * (P1.x - P0.x); \\ Q_0.y &= 3 * (P1.y - P0.y); \end{aligned}$$

$$+ 2t(1-t) Q_1 \rightarrow \begin{aligned} B_{21}t &= 2 * (1-t) * t; \\ Q_1.x &= 3 * (P2.x - P1.x); \\ Q_1.y &= 3 * (P2.y - P1.y); \end{aligned}$$

$$+ t^2 Q_2 \rightarrow \begin{aligned} B_{22}t &= t * t; \\ Q_2.x &= 3 * (P3.x - P2.x); \\ Q_2.y &= 3 * (P3.y - P2.y); \end{aligned}$$

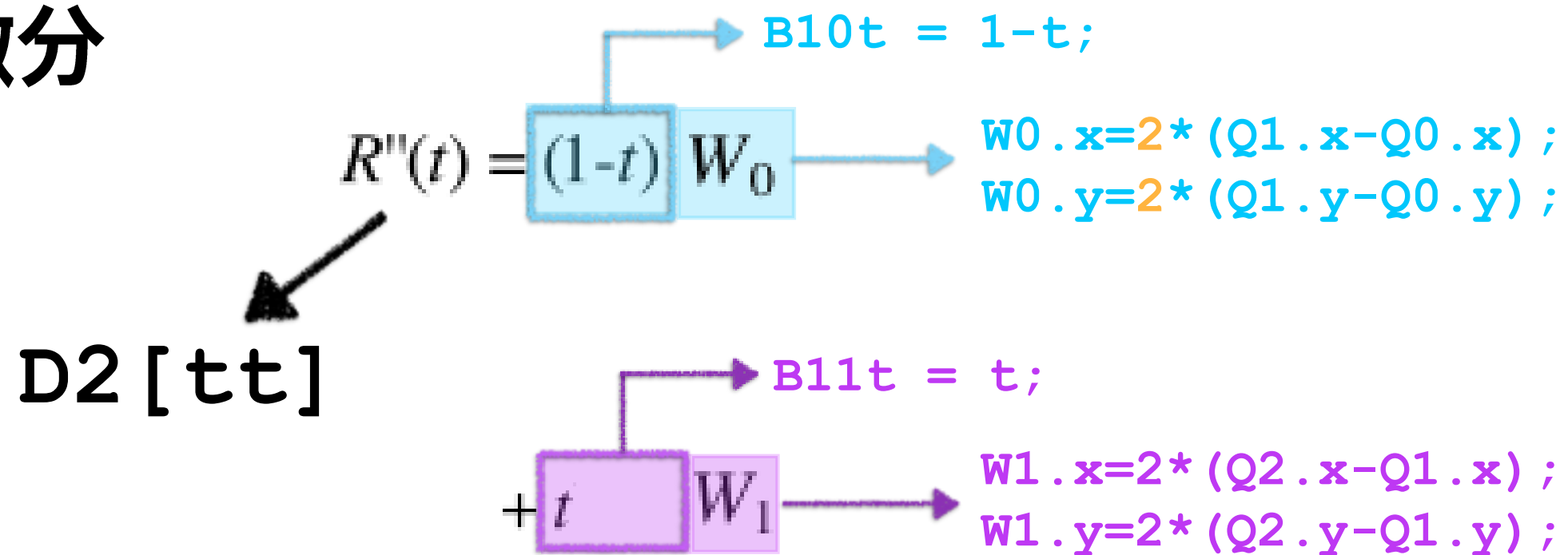
$$D1[tt].x = B_{20}t * Q_0.x + B_{21}t * Q_1.x + B_{22}t * Q_2.x;$$

$$D1[tt].y = B_{20}t * Q_0.y + B_{21}t * Q_1.y + B_{22}t * Q_2.y;$$

$$R''(t) = \sum_{i=0}^1 B_i^1(t) W_i$$

$$R''(t) = \sum_{i=0}^{n-2} B_i^{n-2}(t) W_i$$

2階微分



$$D2[t] .x = B_{10}t * W_0.x + B_{11}t * W_1.x ;$$

$$D2[t] .y = B_{10}t * W_0.y + B_{11}t * W_1.y ;$$

曲率 Curvature

正則な曲線がパラメータ t で表されている時、曲率 $K(t)$ は、以下の式で求められます。

$$K(t) = \frac{D1[tt].x * D2[tt].y - D2[tt].x * D1[tt].y}{(R'(t).x * R'(t).x + R'(t).y * R'(t).y)^{3/2}}$$

Diagram illustrating the components of the curvature formula:

- $D1[tt].x$ (Blue)
- $D2[tt].y$ (Red)
- $D2[tt].x$ (Yellow)
- $D1[tt].y$ (Green)

$$\begin{aligned} & (R'(t).x * R'(t).x + R'(t).y * R'(t).y) * (R'(t).x * R'(t).x + R'(t).y * R'(t).y)^{1/2} \\ &= (R'(t).x * R'(t).x + R'(t).y * R'(t).y) * \sqrt{R'(t).x * R'(t).x + R'(t).y * R'(t).y} \\ &= (R'(t).x * R'(t).x + R'(t).y * R'(t).y) * \text{sqrt}(R'(t).x * R'(t).x + R'(t).y * R'(t).y) \end{aligned}$$

$$D1[tt].x * D1[tt].x + D1[tt].y * D1[tt].y * \text{sqrt}(D1[tt].x * D1[tt].x + D1[tt].y * D1[tt].y);$$

```
K[tt] =  
(D1[tt].x*D2[tt].y - D2[tt].x*D1[tt].y) /  
(  
    (D1[tt].x*D1[tt].x + D1[tt].y*D1[tt].y) *  
    sqrt(D1[tt].x*D1[tt].x + D1[tt].y*D1[tt].y)  
);
```



```

Q0=new PVector(); Q0.x=3*(P1.x-P0.x); Q0.y=3*(P1.y-P0.y);
Q1=new PVector(); Q1.x=3*(P2.x-P1.x); Q1.y=3*(P2.y-P1.y);
Q2=new PVector(); Q2.x=3*(P3.x-P2.x); Q2.y=3*(P3.y-P2.y);

```

```

W0=new PVector(); W0.x=(3-1)*(Q1.x-Q0.x); W0.y=(3-1)*(Q1.y-Q0.y);
W1=new PVector(); W1.x=(3-1)*(Q2.x-Q1.x); W1.y=(3-1)*(Q2.y-Q1.y);

```

```

B20t = (1-t)*(1-t);
B21t = 2*(1-t)*t;
B22t = t*t;

```

```

B10t = 1-t;
B11t = t;

```

```

D1[tt].x=B20t*Q0.x + B21t*Q1.x + B22t*Q2.x;
D1[tt].y=B20t*Q0.y + B21t*Q1.y + B22t*Q2.y;

```

```

D2[tt].x=B10t*W0.x + B11t*W1.x;
D2[tt].y=B10t*W0.y + B11t*W1.y;

```

```

K[tt] = (D1[tt].x*D2[tt].y -
D2[tt].x*D1[tt].y)/(sqrt(D1[tt].x*D1[tt].x +
D1[tt].y*D1[tt].y)*(D1[tt].x*D1[tt].x + D1[tt].y*D1[tt].y));

```