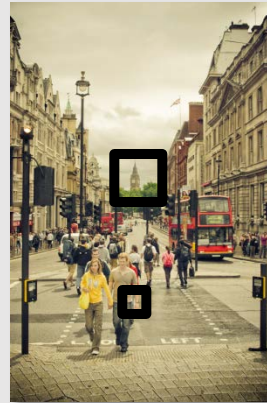


# Image Interpolation


# Today: back to images

- This photo is too small:

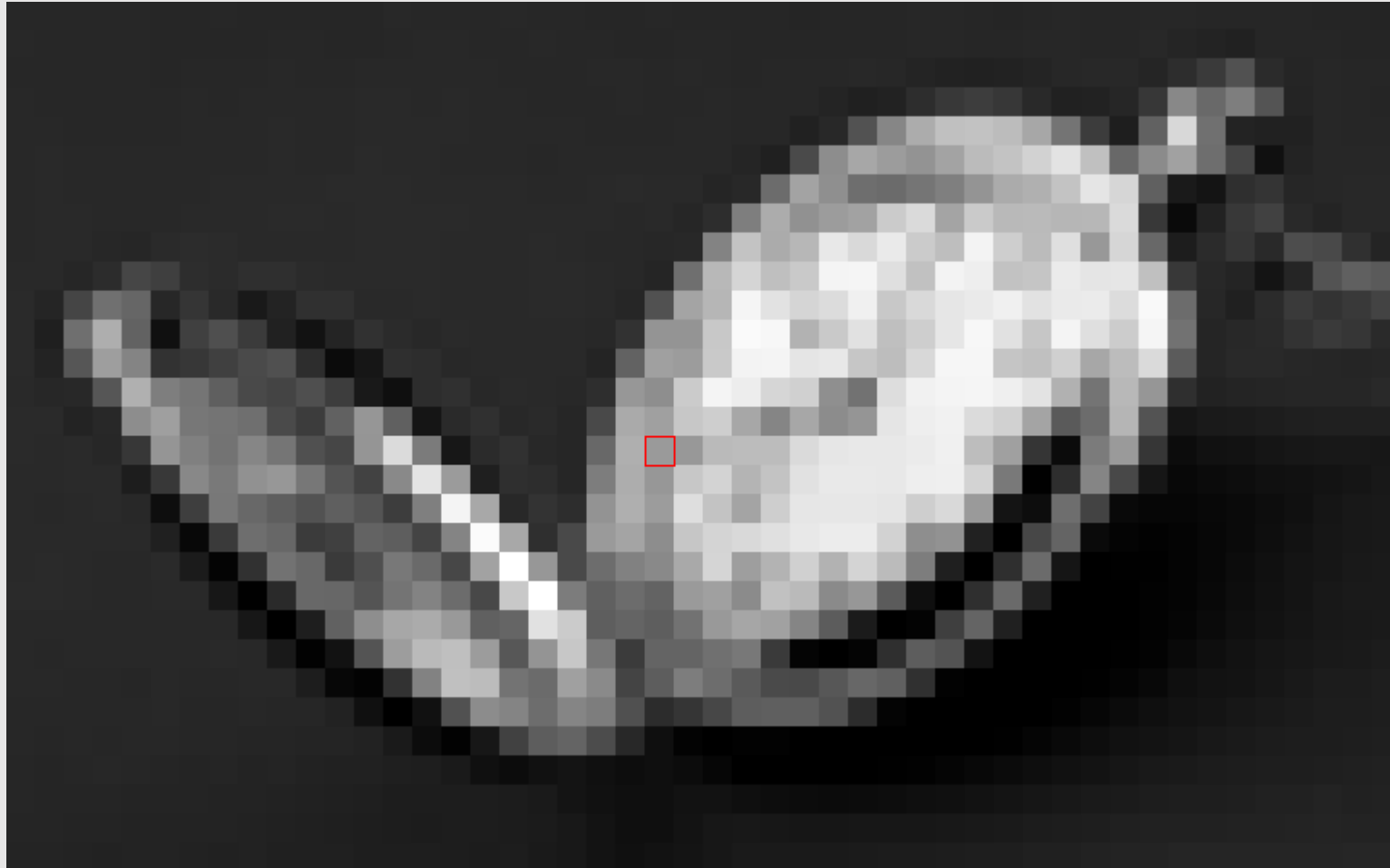
Might need this for forensics:



# Zooming

- First consider a black and white image (one intensity value per pixel) 
- We want to blow it up to poster size (say, zoom in by a factor of 16)
- First try: repeat each row 16 times, then repeat each column 16 times

# Zooming: First attempt



# Image Interpolation

**Interpolation** — Process of using known data to estimate unknown values

*e.g.*, zooming, shrinking, rotating, and geometric correction

**Interpolation** (sometimes called ***resampling***) — an imaging method to increase (or decrease) the number of pixels in a digital image.

Some digital cameras use interpolation to produce a larger image than the sensor captured or to create digital zoom

# Introduction

## Image interpolation

An image  $f(x,y)$  tells us the intensity values at the integral lattice locations, i.e., when  $x$  and  $y$  are both **integers**

- Image interpolation refers to the “guess” of intensity values at **missing** locations, i.e.,  $x$  and  $y$  can be arbitrary
- Note that it is just a **guess** (Note that all sensors have finite sampling distance)

# Motivations

## Why do we need image interpolation?

- We want **BIG** images
  - When we see a video clip on a PC, we like to see it in the full screen mode
- We want **GOOD** images
  - If some block of an image gets damaged during the transmission, we want to repair it
- We want **COOL** images
  - Manipulate images digitally can render fancy artistic effects as we often see in movies

# Basic Relationships Between Pixels

- Neighborhood
- Adjacency
- Connectivity
- Paths
- Regions and boundaries



# Basic Relationships Between Pixels

**Neighbors** of a pixel  $p$  at coordinates  $(x,y)$

- **4-neighbors of  $p$** , denoted by  $N_4(p)$ :  
 $(x-1, y)$ ,  $(x+1, y)$ ,  $(x, y-1)$ , and  $(x, y+1)$ .
- **4 diagonal neighbors of  $p$** , denoted by  $N_D(p)$ :  
 $(x-1, y-1)$ ,  $(x+1, y+1)$ ,  $(x+1, y-1)$ , and  $(x-1, y+1)$ .
- **8 neighbors of  $p$** , denoted  $N_8(p)$   
 $N_8(p) = N_4(p) \cup N_D(p)$

# Basic Relationships Between Pixels

## Adjacency

Let  $V$  be the set of intensity values

- **4-adjacency:** Two pixels  $p$  and  $q$  with values from  $V$  are 4-adjacent if  $q$  is in the set  $N_4(p)$ .
- **8-adjacency:** Two pixels  $p$  and  $q$  with values from  $V$  are 8-adjacent if  $q$  is in the set  $N_8(p)$ .

# Basic Relationships Between Pixels

## Adjacency

Let  $V$  be the set of intensity values

➤ **m-adjacency**: Two pixels  $p$  and  $q$  with values from  $V$  are m-adjacent if

(i)  $q$  is in the set  $N_4(p)$ , or

(ii)  $q$  is in the set  $N_D(p)$  and the set  $N_4(p) \cap N_4(q)$  has no pixels whose values are from  $V$ .

# Basic Relationships Between Pixels

## Path

- A (digital) path (or curve) from pixel  $p$  with coordinates  $(x_0, y_0)$  to pixel  $q$  with coordinates  $(x_n, y_n)$  is a sequence of distinct pixels with coordinates

$$(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$$

Where  $(x_i, y_i)$  and  $(x_{i-1}, y_{i-1})$  are adjacent for  $1 \leq i \leq n$ .

- Here  $n$  is the *length* of the path.
- If  $(x_0, y_0) = (x_n, y_n)$ , the path is **closed** path.
- We can define 4-, 8-, and m-paths based on the type of adjacency used.

## Examples: Adjacency and Path

$$\mathbf{V} = \{\mathbf{1}, \mathbf{2}\}$$

0 1 1

0 1 1

0 1 1

0 2 0

0 2 0

0 2 0

0 0 1

0 0 1

0 0 1

# Examples: Adjacency and Path

**$V = \{1, 2\}$**

0 1 1

0 1 1

0 1 1

0 2 0

0 2 0

0 2 0

0 0 1

0 0 1

0 0 1

**8-adjacent**

# Examples: Adjacency and Path

$$V = \{1, 2\}$$

0 1 1

0 1 1

0 1 1

0 2 0

0 2 0

0 2 0

0 0 1

0 0 1

0 0 1

8-adjacent

m-adjacent

# Examples: Adjacency and Path

$$V = \{1, 2\}$$

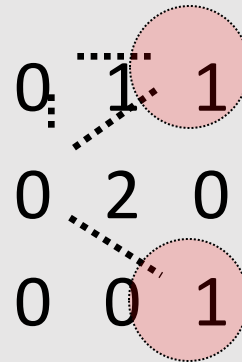
$$0_{1,1} \quad 1_{1,2} \quad 1_{1,3}$$

$$0_{2,1} \quad 2_{2,2} \quad 0_{2,3}$$

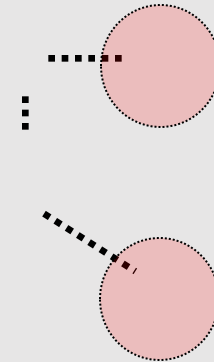
$$0_{3,1} \quad 0_{3,2} \quad 1_{3,3}$$

$$0 \quad 1 \quad 1$$

$$0 \quad 2 \quad 0$$

$$0 \quad 0 \quad 1$$


**8-adjacent**



**m-adjacent**

The 8-path from (1,3) to (3,3):

(i) (1,3), (1,2), (2,2), (3,3)

(ii) (1,3), (2,2), (3,3)

The m-path from (1,3) to (3,3):

(1,3), (1,2), (2,2), (3,3)



# Basic Relationships Between Pixels

## Connected in S

Let  $S$  represent a subset of pixels in an image. Two pixels  $p$  with coordinates  $(x_0, y_0)$  and  $q$  with coordinates  $(x_n, y_n)$  are said to be **connected in S** if there exists a path

$$(x_0, y_0), (x_1, y_1), \dots, (x_n, y_n)$$

Where  $\forall i, 0 \leq i \leq n, (x_i, y_i) \in S$

# Basic Relationships Between Pixels

Let  $S$  represent a subset of pixels in an image

- For every pixel  $p$  in  $S$ , the set of pixels in  $S$  that are connected to  $p$  is called a ***connected component*** of  $S$ .
- If  $S$  has only one connected component, then  $S$  is called ***Connected Set***.
- We call  $R$  a **region** of the image if  $R$  is a connected set
- Two regions,  $R_i$  and  $R_j$  are said to be ***adjacent*** if their union forms a connected set.
- Regions that are not to be adjacent are said to be ***disjoint***.

# Basic Relationships Between Pixels

## Boundary (or border)

- The **boundary** of the region  $R$  is the set of pixels in the region that have one or more neighbors that are not in  $R$ .
- If  $R$  happens to be an entire image, then its boundary is defined as the set of pixels in the first and last rows and columns of the image.

## Foreground and background

- An image contains  $K$  disjoint regions,  $R_k$ ,  $k = 1, 2, \dots, K$ . Let  $R_u$  denote the union of all the  $K$  regions, and let  $(R_u)^c$  denote its complement.  
All the points in  $R_u$  is called **foreground**;  
All the points in  $(R_u)^c$  is called **background**.

# Scenario I: Resolution Enhancement

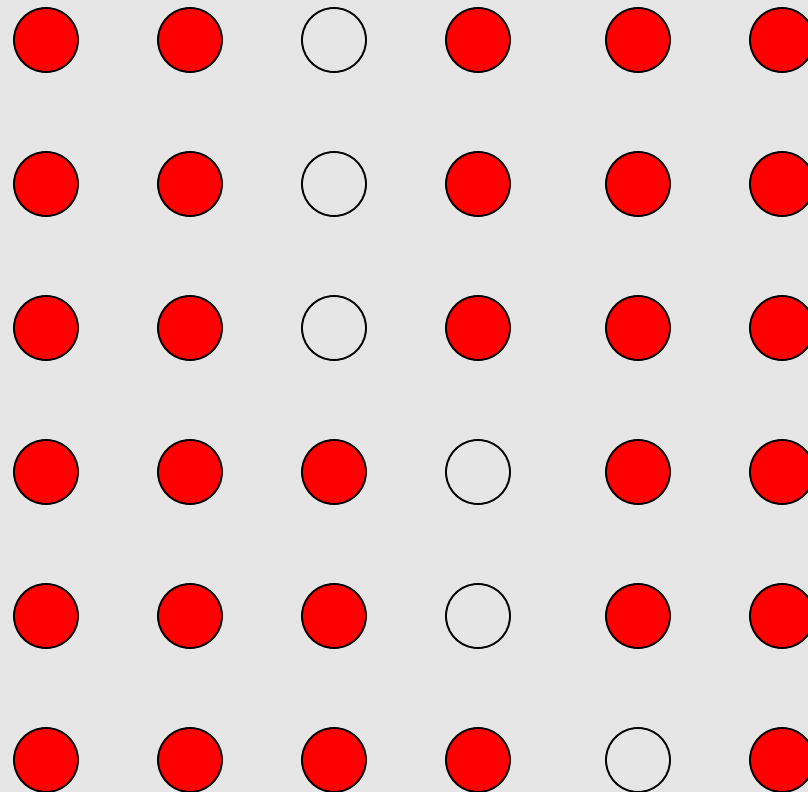


Low-Res.



High-Res.

# Scenario II: Image Inpainting

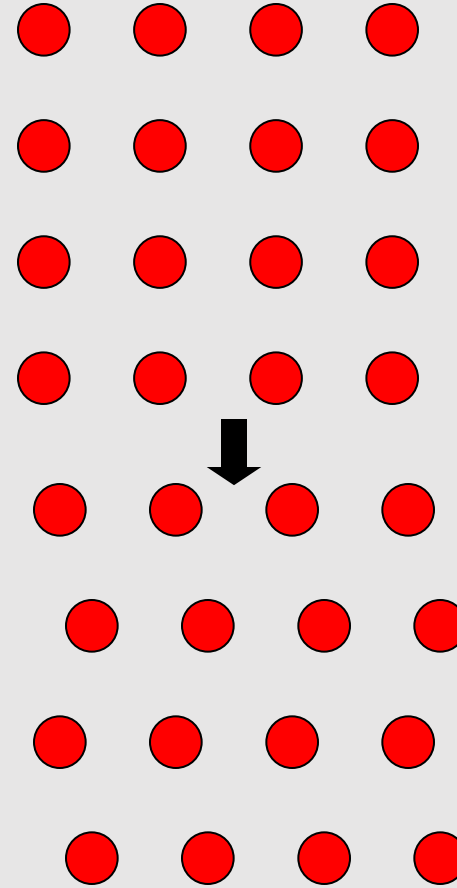


Non-damaged



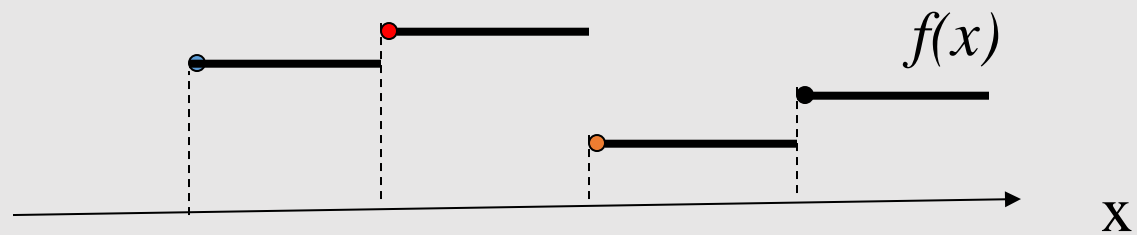
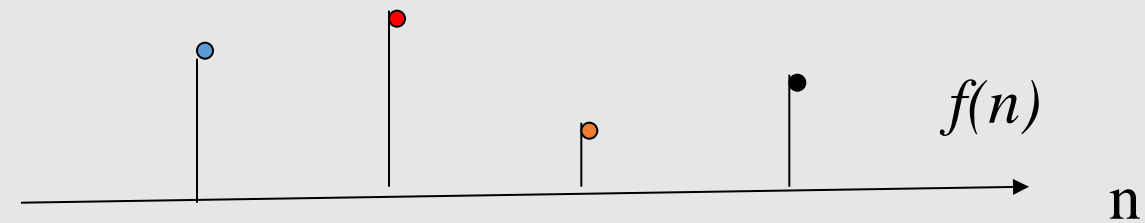
Damaged

# Scenario III: Image Warping



# Image Interpolation – Method 1

## Nearest Neighbors Interpolation



# Image Interpolation – Method 1

## Nearest Neighbors Interpolation

- Also Known as “**Pixel Replication**” and “**1D Zero-order**”

(Original image rows \* zooming factor, Original Image cols \* zooming factor)



# Image Interpolation – Method 1

## Nearest Neighbors Interpolation

Original Image

1	2
3	4

Row wise replication

1	1	2	2
3	3	4	4

Column wise replication

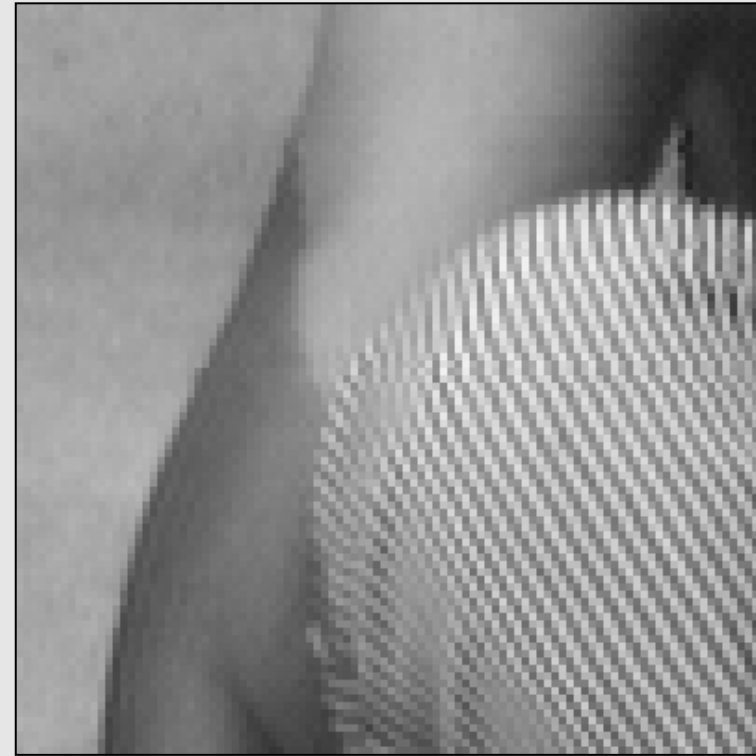
1	1	2	2
1	1	2	2
3	3	4	4
3	3	4	4

# Image Interpolation – Method 1

## Nearest Neighbors Interpolation



Original Image



Nearest Neighbors Interpolation

# Image Interpolation – Method 1

## Nearest Neighbors Interpolation

- **Advantage:**

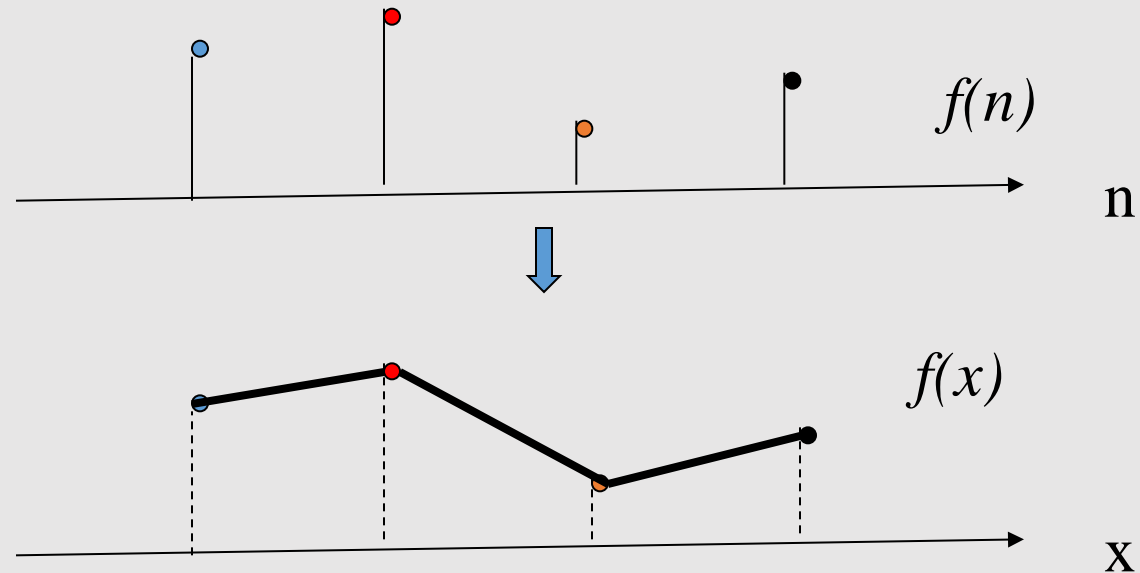
- Fast
- Simple

- **Disadvantage:**

- Jagged results
- Result in fully blurred image

# Image Interpolation – Method 2

## 1D First-order Interpolation (Linear)



Heuristic: the closer to a pixel, the higher weight is assigned

Principle: line fitting to polynomial fitting (analytical formula)

# Image Interpolation – Method 2

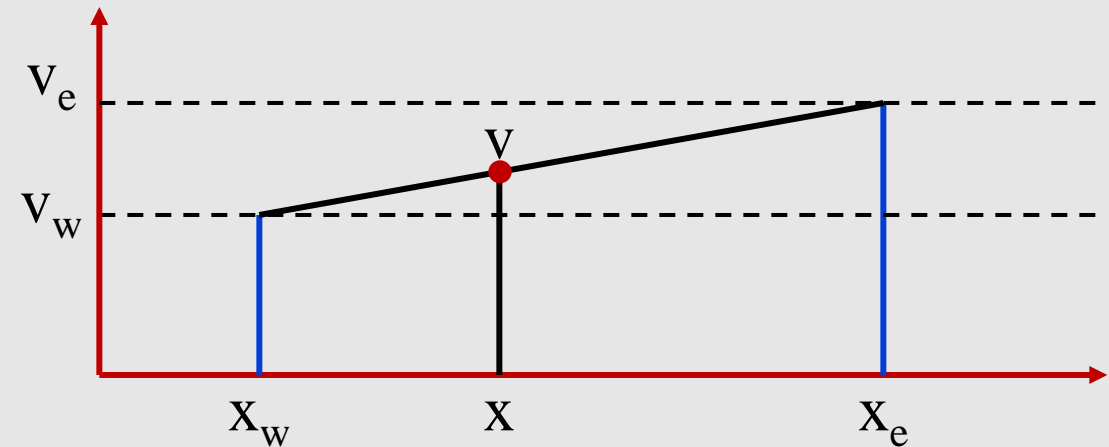
## 1D First-order Interpolation (Linear)

$$\frac{x - x_w}{x_e - x_w} = \frac{v - v_w}{v_e - v_w}$$

- Isolating  $v$  in the above equation:

$$v = \alpha v_e + (1 - \alpha) v_w$$

$$\text{where } \alpha = \frac{x - x_w}{x_e - x_w}$$



Note: when  $\alpha=0.5$ , we simply have the average of two

# Image Interpolation – Method 2

## 1D First-order Interpolation (Linear)

$$f(n) = [0, 120, 180, 120, 0]$$



Interpolate at 1/2-pixel

$$f(x) = [0, 60, 120, 150, 180, 150, 120, 60, 0], \quad x = n/2$$



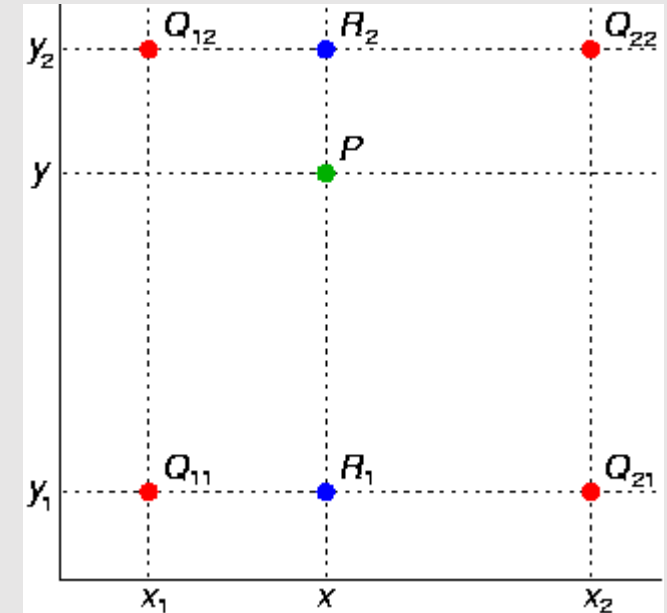
Interpolate at 1/3-pixel

$$f(x) = [0, 20, 40, 60, 80, 100, 120, 130, 140, 150, 160, 170, 180, \dots], \quad x = n/6$$

# Image Interpolation – Method 2

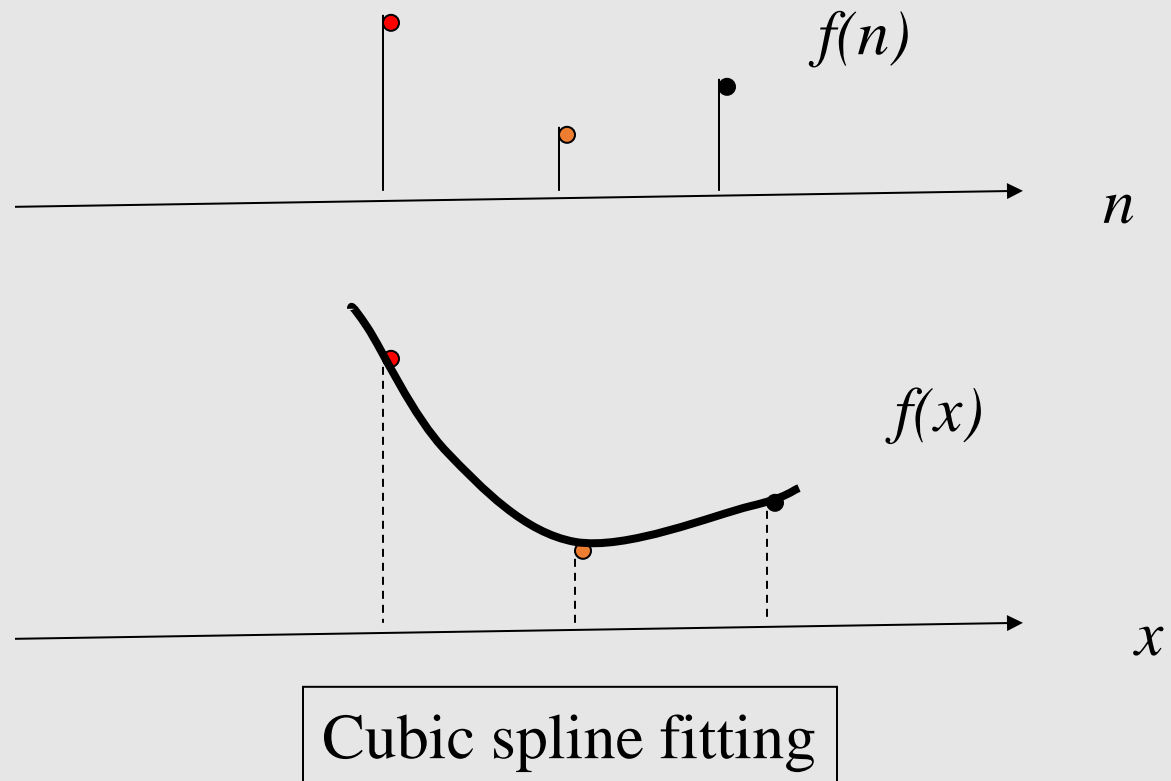
## Bilinear interpolation

- What about in 2D?
  - Interpolate in x, then in y
- Example
  - We know the red values
  - Linear interpolation in x between red values gives us the blue values
  - Linear interpolation in y between the blue values gives us the green value



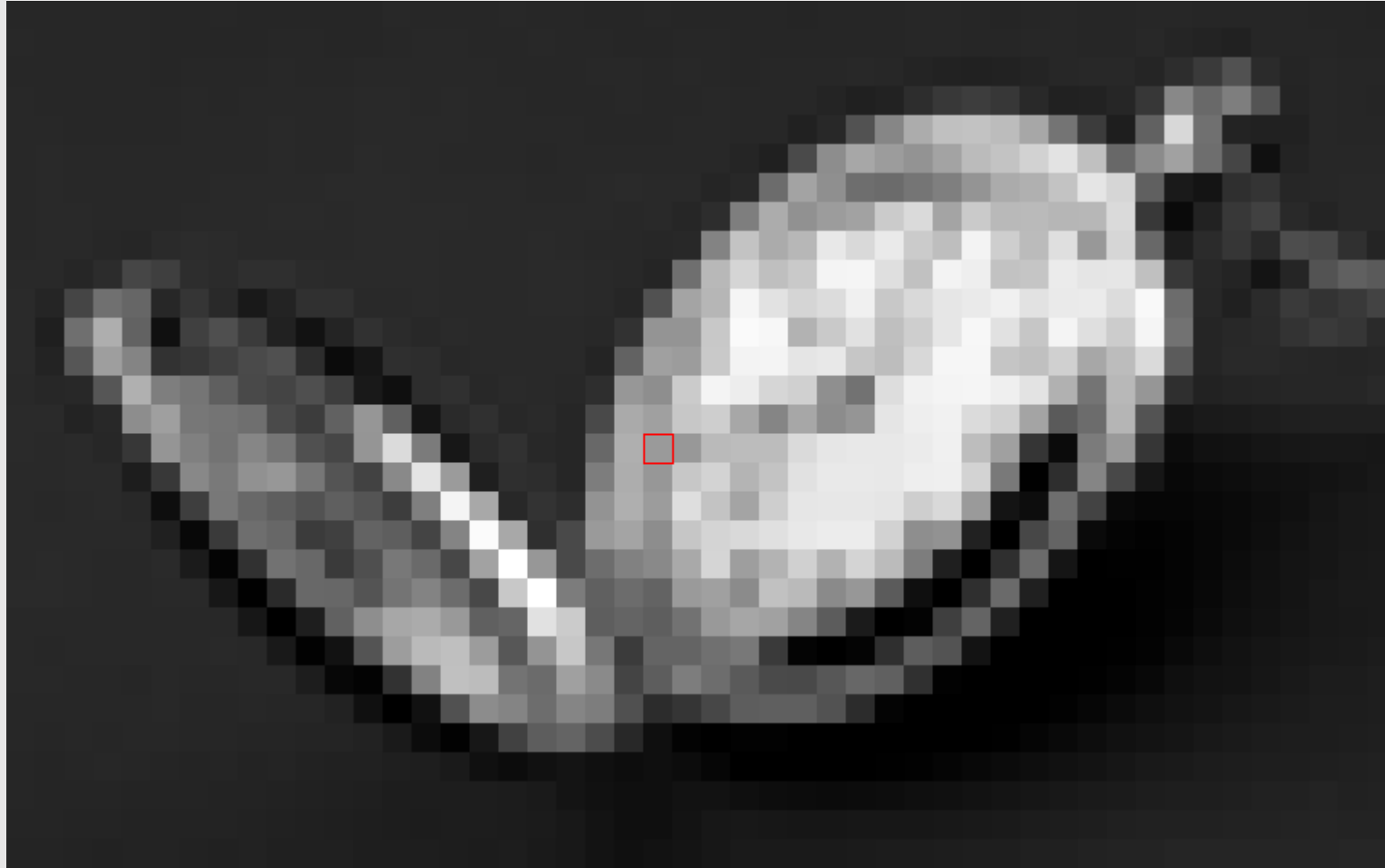
# Image Interpolation – Method 3

## 1D Third order Interpolation (Cubic)





# Nearest Neighbor Interpolation



# Bilinear Interpolation



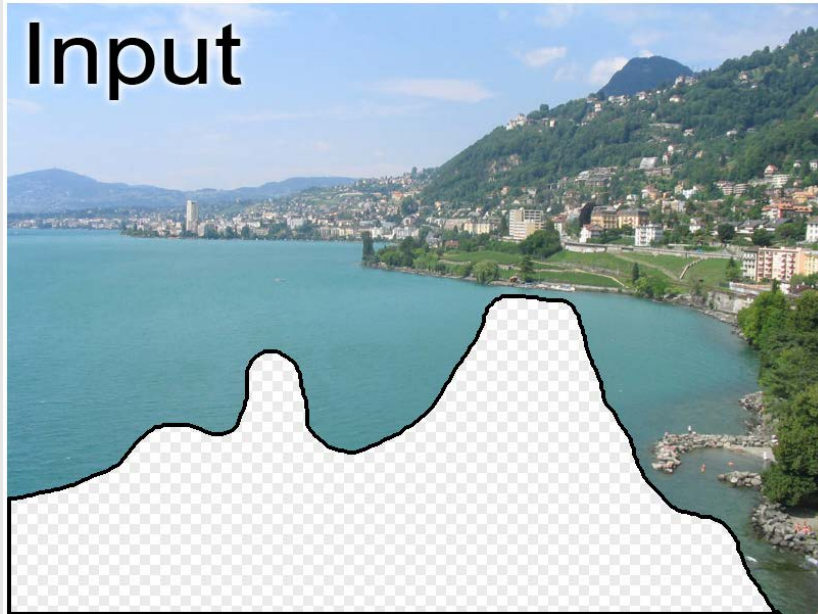
# Bicubic Interpolation



# Extrapolation

- Suppose you only know the values  $f(1)$ ,  $f(2)$ ,  $f(3)$ ,  $f(4)$  of a function
  - What is  $f(5)$ ?
- This problem is called extrapolation
  - Much harder than interpolation: what is outside the image?

# Image Extrapolation



Computed using a database of millions of photos