

# Line Clipping II

REF:

Hearn and Baker book

#### Line basics

#### Parametric Equation of line:

$$x = x1 + u * dx$$
  

$$y = y1 + u * dy for 0 \le u \le 1$$

$$dx = x2 - x1$$
$$dy = y2 - y1$$

#### Line basics

A point on line is inside clipping window if:

$$xw_{\min} \le x_1 + u\Delta x \le xw_{\max}$$
  
 $yw_{\min} \le y_1 + u\Delta y \le yw_{\max}$ 

This can also be expressed as:

$$up_k \le q_k, \quad k = 1, 2, 3, 4$$

we will use k=1,2,3 and 4 for left, right, bottom and top edge respectively

# Liang Barsky Algo

#### Observations:

- If  $p_k = 0$  then line is parallel to corresponding edge
  - $\circ$  If for that corresponding k,  $q_k < 0$  then line is outside clipping window
  - O If for that corresponding k,  $q_k > = 0$  then line is inside the boundary
- If  $p_k < 0$ , then infinite extension of line travels from outside to inside of infinite extension of corresponding clipping boundary
- If  $p_k > 0$ , then infinite extension of line travels from inside to outside of infinite extension of corresponding clipping boundary

## Liang Barsky Algo: intro

For clipping candidate lines we can find u that defines the intersection point of line with clipping boundary

$$u = q_k/p_k$$

For each line we can find 2 parameters u1 and u2 that define the part of line that lies inside the clipping window

## Finding u1 and u2

Finding u1	Finding u2
Condition: Use only when p <sub>k</sub> <0 only (boundaries where line is coming from outside to inside)	Condition: Use only when p <sub>k</sub> >0 only (boundaries where line is going from inside to outside)
Compute $r_k = q_k/p_k$ for each edge for which $p_k < 0$ , then u1 = max $[0,r_k]$	Compute $r_k = q_k/p_k$ for each edge for which $p_k > 0$ , then u2 = min [1, $r_k$ ]

- If u1 > u2 then line segment is outside clipping window → no need to draw
- else calculate points from values of u1 and u2 and draw them

## Summary of Algo

- 1. Initialize u1=0 and u2=1
- 2. Calculate  $p_k$  and  $q_k$  for each clipping boundary ( k = 1, 2, 3, 4)
- 3. If  $p_k < 0$  then calculate  $r_k = q_k/p_k$ , and use it to update u1
- 4. If  $p_k > 0$  then calculate  $r_k = q_k / p_k$ , and use it to update u2
  - **a.** If at any point u1 > u2 reject the line
- 5. If  $p_k = 0$  and  $q_k < 0$ , reject the line
- 6. Lastly, if the line is not rejected then plot line based on points calculated from u1 and u2

#### Pseudo code

```
#include "graphics.h"
#define ROUND(a) ((int)(a+0.5))
int clipTest (float p, float q, float * u1, float * u2)
1
 float r;
 int retVal = TRUE;
  if (p < 0.0) (
   r = q / p;
   if (r > *u2)
     retVal = FALSE;
   e1se
      if (r > *ul)
      *ul = r:
  }
  else
   if (p > 0.0) (
     r = q / p;
      if (r < *u1)
       retVal = FALSE;
      else if (r < *u2)
      *u2 = r;
    }
    else
      /* p = 0, so line is parallel to this clipping edge */
      if (q < 0.0)
       /* Line is outside clipping edge * .
       retVal = FALSE:
  return (retVal);
}
```

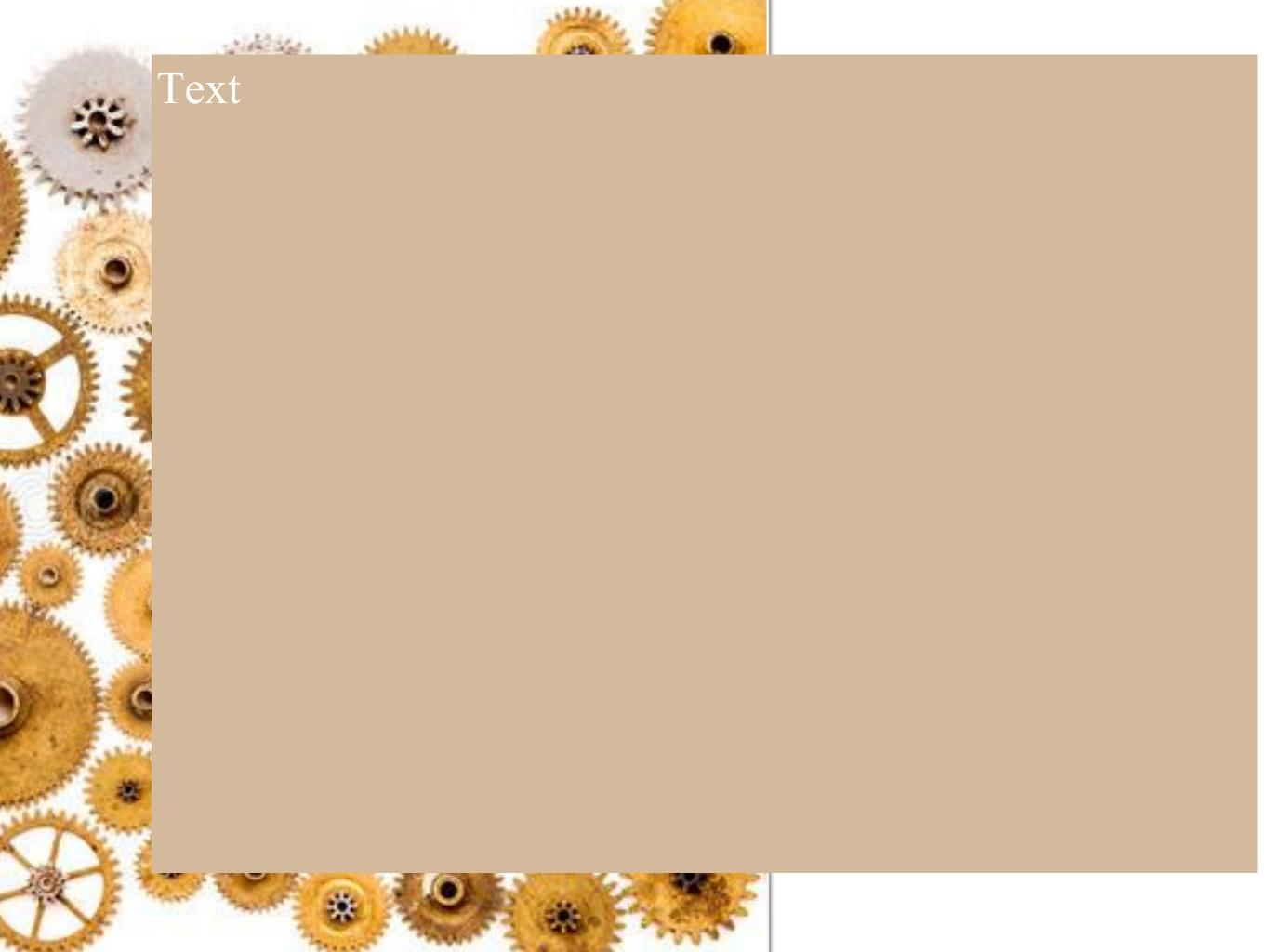
```
void clipLine (dcPt winMin, dcPt winMax, wcF:2 pl, wcPt2 p2)
 float u1 = 0 0, u2 = 1.0, dx = p2.x - p1.x dy;
  if (clipTest (-dx, pl.x - winMin.x, &ul, &u2))
    if (clipTest (dx, winMax.x - pl.x, &ul, &u2)) {
      dy = p2.y - p1.y;
      if (clipTest (-dy, pl.y - winMin.y, &ul, &u2))
        if (clipTest (dy, winMax.y - pl.y, &ul, &u2)) (
          if (u2 < 1.0) {
            p2.x = p1.x + u2 * dx;
            p2.y = p1.y + u2 * dy;
          if (u1 > 0.0) (
            pl.x += ul * dx;
            pl.y += u1 * dy;
          lineDDA (ROUND(pl.x), ROUND(pl.y) ROUND(p2.x), ROUND(p2.y)
```

Examples on board

The End

### Text

P



### Text

The End