# **NUS-ISS**Problem Solving Using Pattern Recognition



#### Convolutional neural network

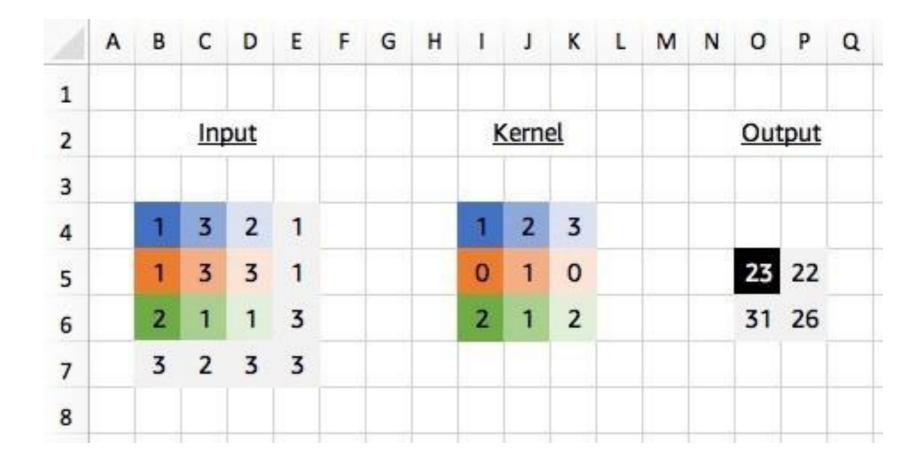
by Nicholas Ho

Recap: Convolution = filtering

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#### 2D convolution

The original



#### Note:

- Conv1D is used for input signals which are similar to the voice
- Conv2D is used for images
- Conv3D is usually used for videos where you have a frame for each time span

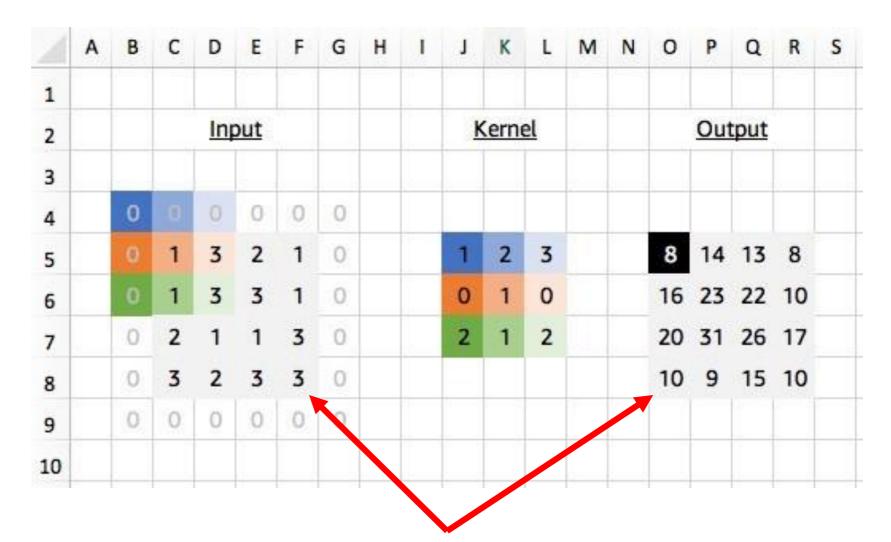
Source: https://medium.com/apache-mxnet/convolutions-explained-with-ms-excel-465d6649831c

psupr/m5.5/v1.0

#### 2D convolution

The padded

Note that the Kernel's movement is determined by the stride value, which can be adjusted (in the examples stride = 1 or [1, 1])



Padding retains the size of the output; input size = output size

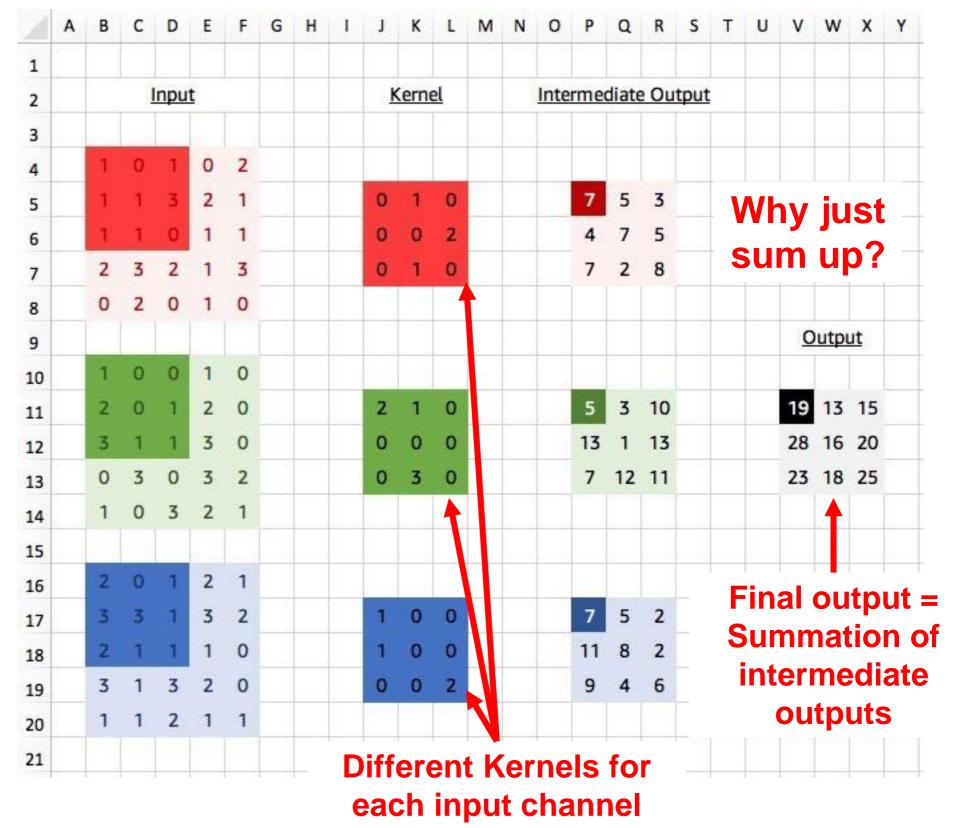
Source: https://medium.com/apache-mxnet/convolutions-explained-with-ms-excel-465d6649831c

#### 2D convolution

Multi-channel

#### Note:

- We do not decide the values of the Kernels
- The Kernel values are updated by the algorithms based on the training data
- We decide only the size of the **Kernels**



Source: https://medium.com/apache-mxnet/convolutions-explainedwith-ms-excel-465d6649831c

psupr/m5.5/v1.0



#### Max pooling

The original

#### **Convolutional vs max-pooling layers:**

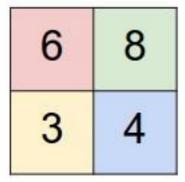
- Convolutional layers extract features
  - big Kernels extract obvious features,
  - small ones extract more detailed features
- Max Pooling layers help to downscale the feature maps so that only features with significant weights are brought over to the next layer

### Single depth slice

1	1	2	4
5	6	7	8
3	2	1	0
1	2	3	4

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max pool with 2x2 filters and stride 2

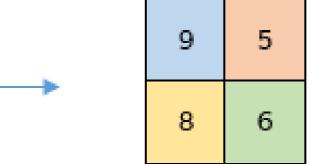


Source: <a href="http://cs231n.github.io/convolutional-networks/">http://cs231n.github.io/convolutional-networks/</a>

### Max pooling

#### With situation

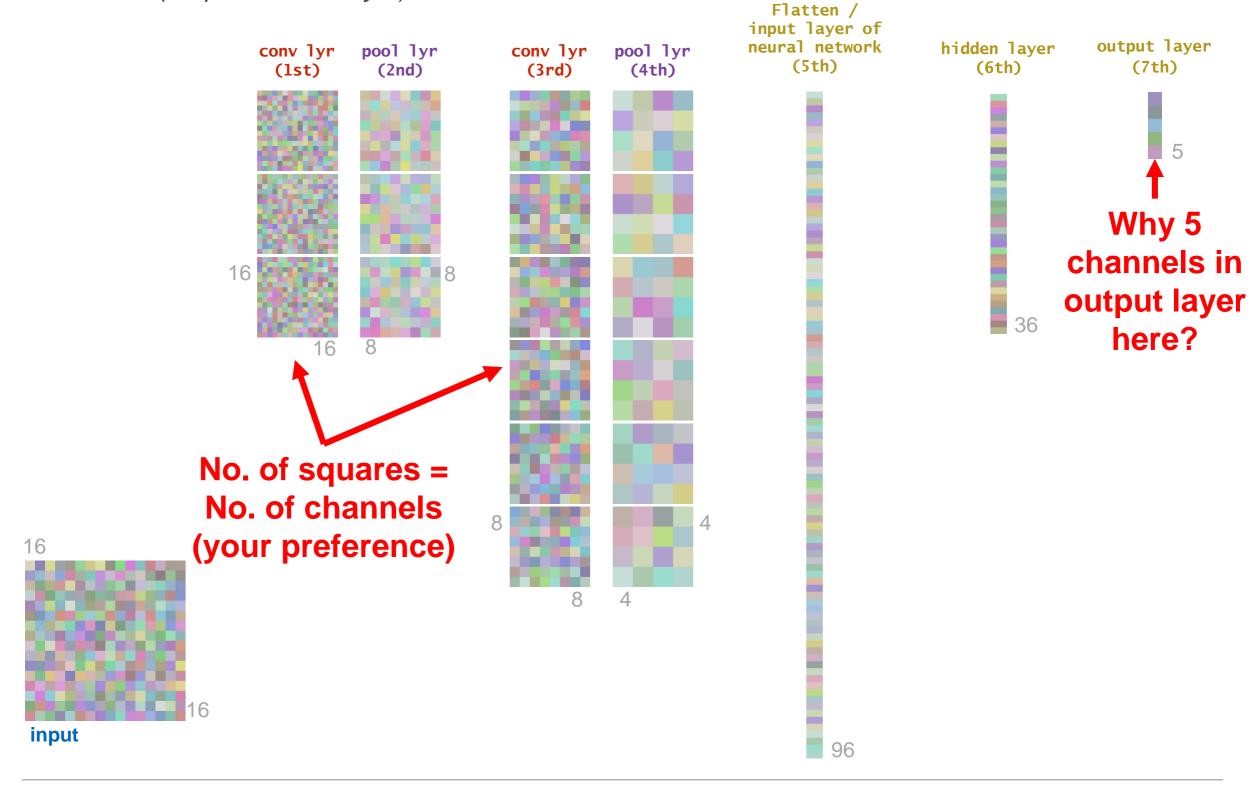
1	4	4	5	6
3	9	2	3	2
8	1	6	0	7
0	3	2	1	1



Source: https://software.intel.com/en-us/daal-programming-guide-2d-max-pooling-forward-layer

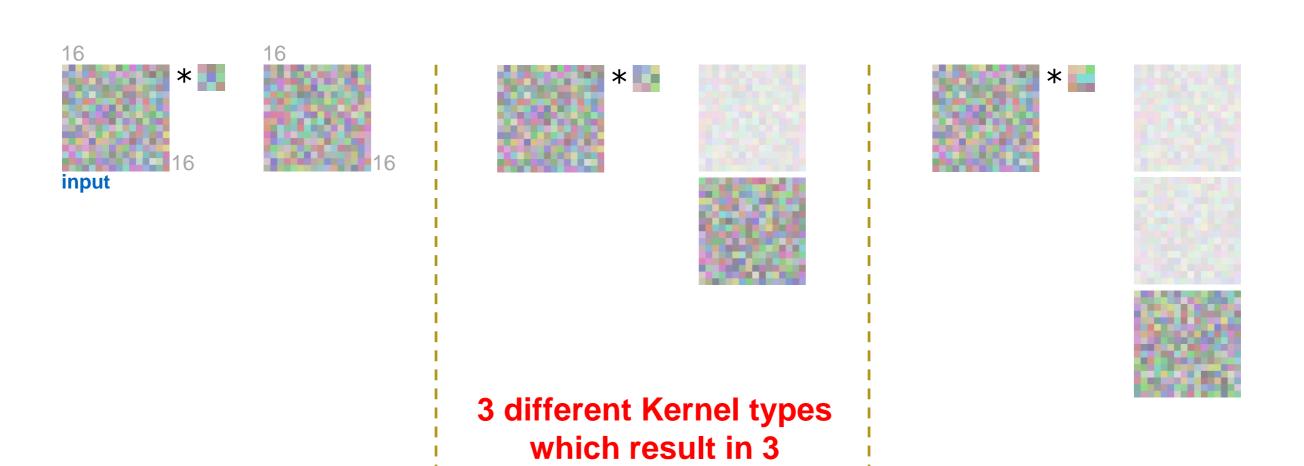
# Convolutional neural network

Overview (output of each layer)



The first convolutional layer (part 1)

 Performs 3 separate 2D convolutions (with padding) to generate 3 intermediate outputs

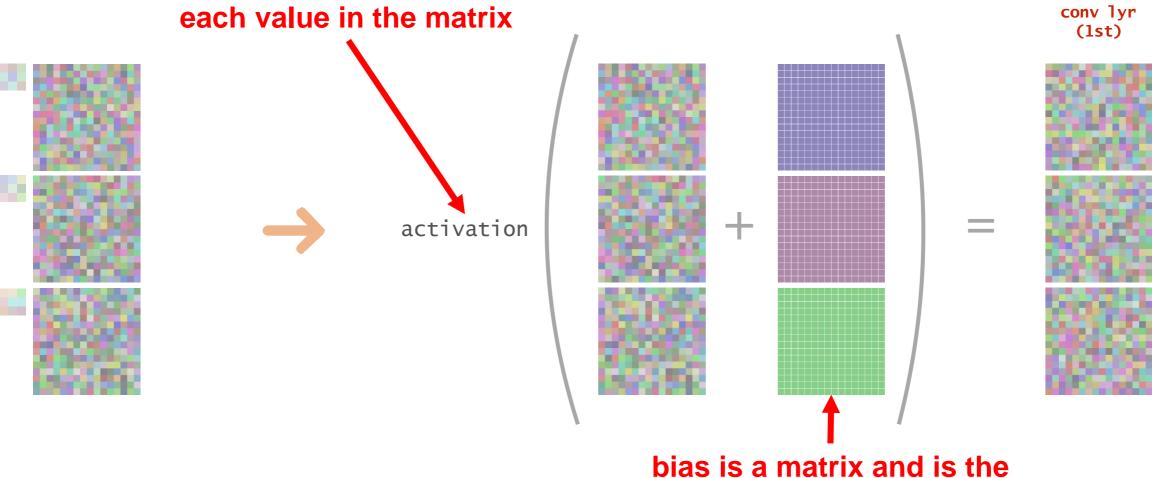


different channels

The first convolutional layer (part 2)

Can be ReLu or sigmoid function; the function is applied on each value in the matr

 Add bias to each convolution output, and apply activation function to get the final output for the convolutional layer



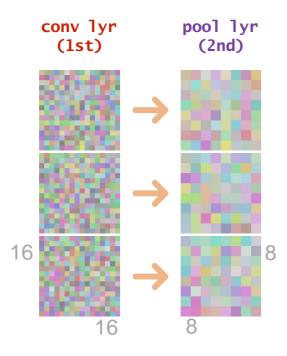
same throughout each

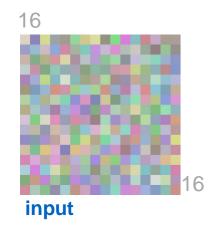
matrix but different for

various matrices

The pooling layer

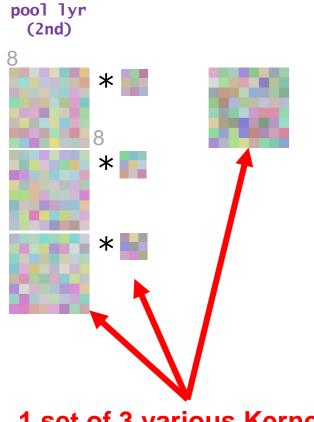
 Apply 2 x 2 max-pooling (stride 2) on the outputs from the first convolutional layer

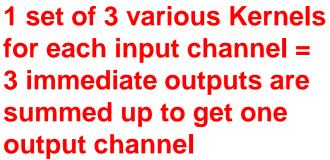




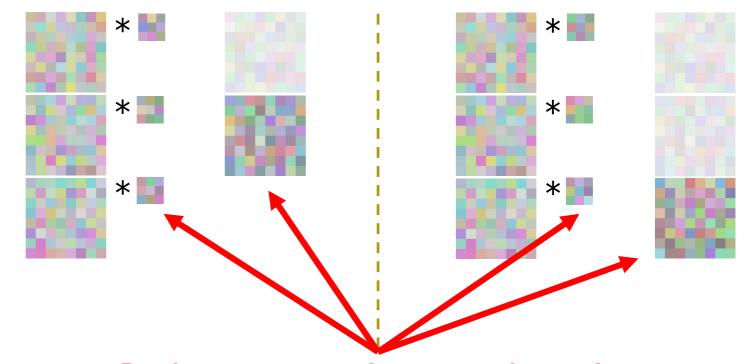
The second convolutional layer (part 1)

 Performs 6 separate multi-channel 2D convolutions (with padding) to generate 6 convolution outputs





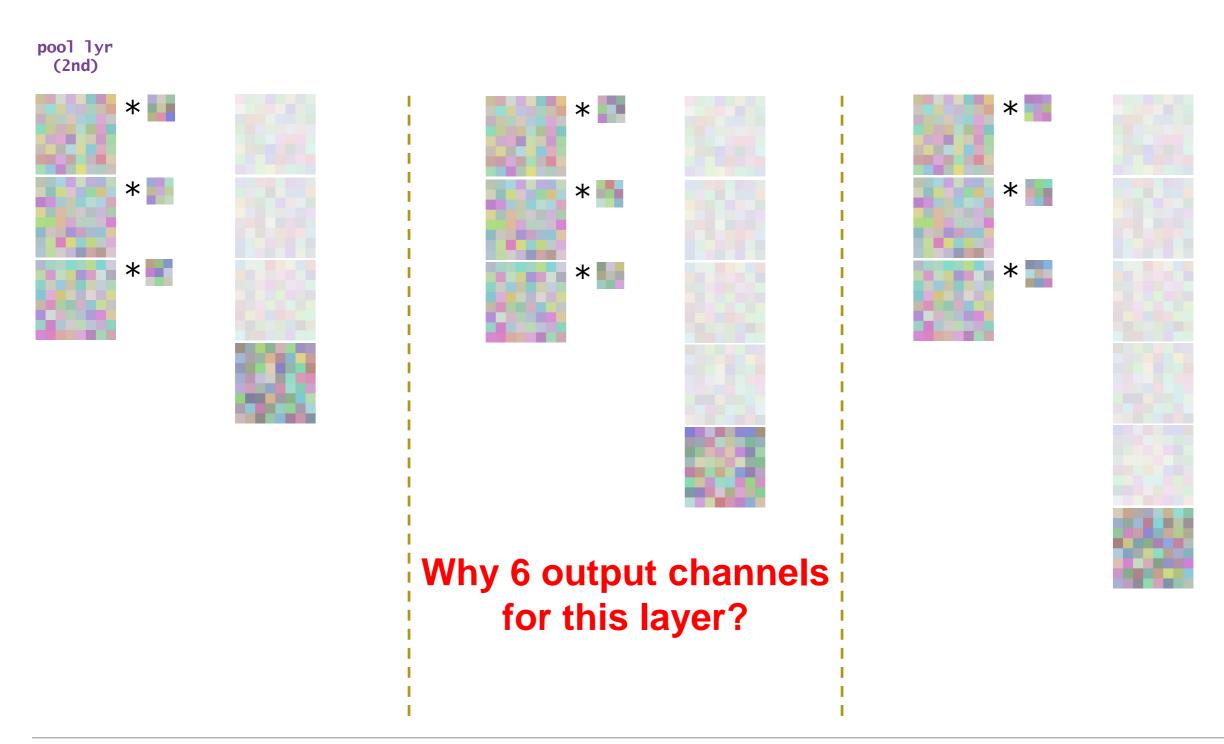
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Do the same procedure to produce other output channels with different sets of **Kernels** 

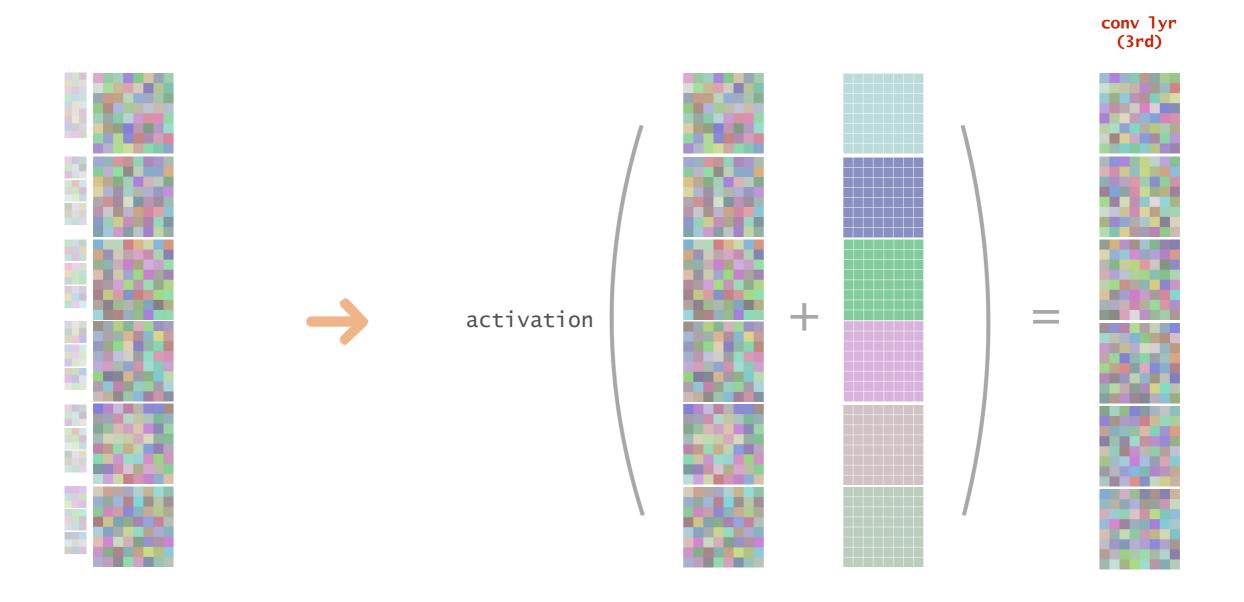
The second convolutional layer (part 2)

 Performs 6 separate multi-channel
 2D convolutions (with padding) to generate 6 convolution outputs



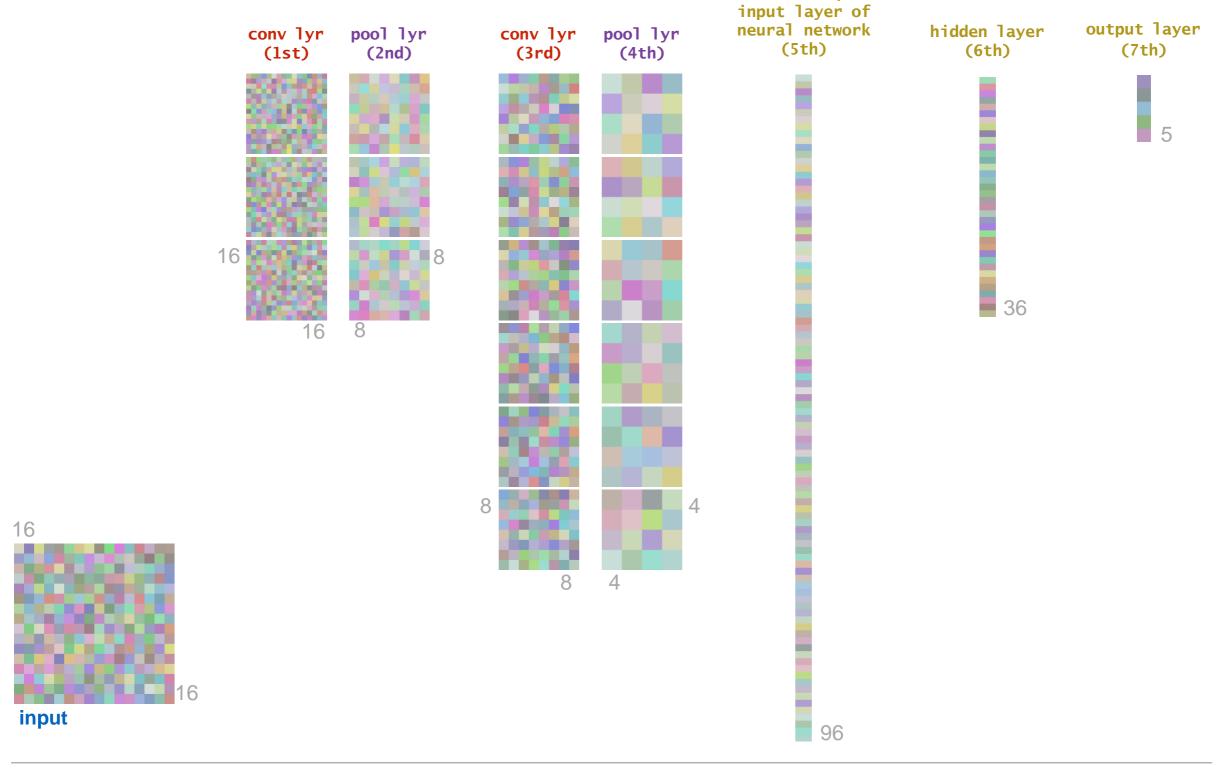
The first convolutional layer (part 3)

 Add bias to each intermediate output, and apply activation function to get the final output for the convolutional layer



# Convolutional neural network

Overview (output of each layer)

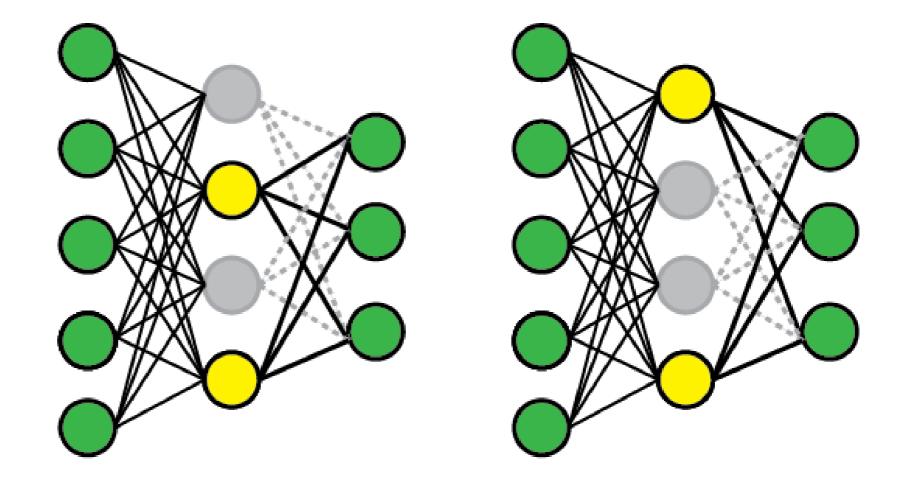


Flatten /

#### Convolutional neural network

Dropout

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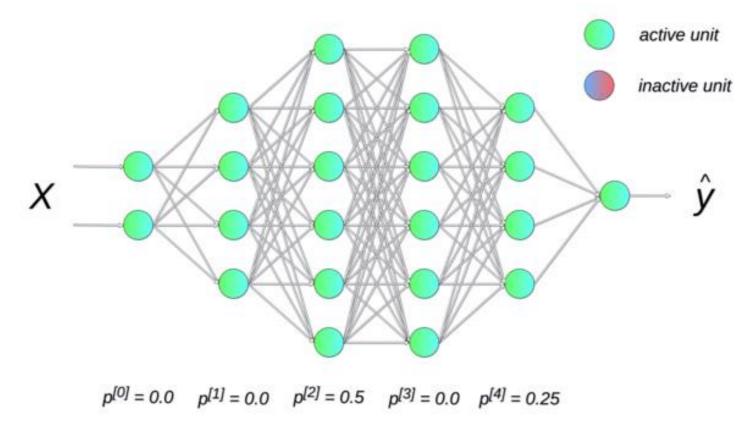
# We will apply dropout in the workshop later on

Source: https://stats.stackexchange.com/questions/201569/ difference-between-dropout-and-dropconnect



#### **Convolutional** neural network

Dropout



- Very popular method to regularize neural networks; effective in preventing overfitting
- Concept:
  - Approximates training a large number of neural networks with different architectures in parallel
  - Every unit of the neural network (except output layer) is given the probability p of being temporarily ignored/muted (i.e. "dropped out") in calculations
  - Hyper parameter p is called dropout rate and very often its default value is set to 0.5
  - In each iteration, the neurons are randomly selected according to the assigned probability. As a result, each time we work with a smaller neural network

Source: https://towardsdatascience.com/preventing-deepneural-network-from-overfitting-953458db800a

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# Any fans of Japan?

# **RECAP:**

(3 basic components in deep learning learnt)

- 1. Convolutions
- 2. Pooling
- 3. Dropout

#### **Cursive Kuzushiji**

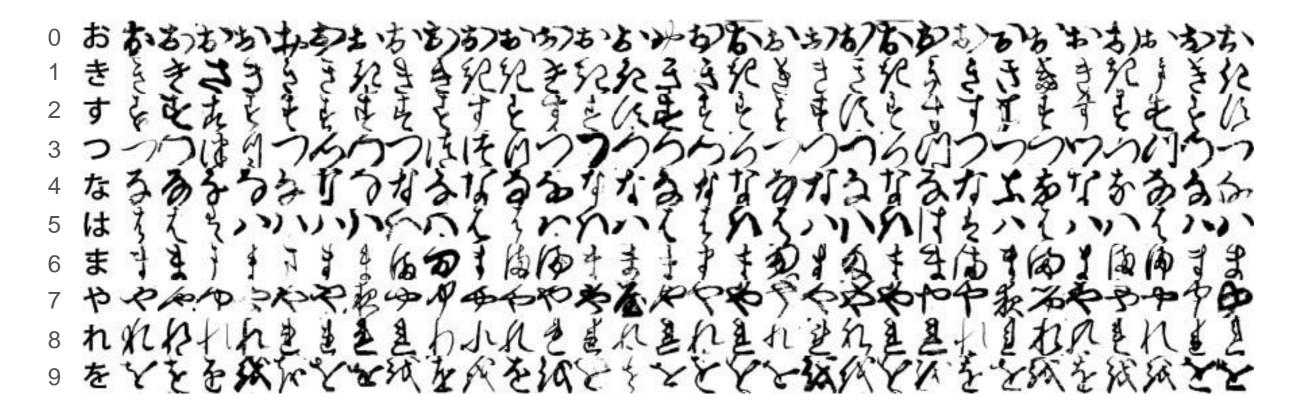
Automated solution?

# Workshop objective: To classify hand drawn Japanese characters

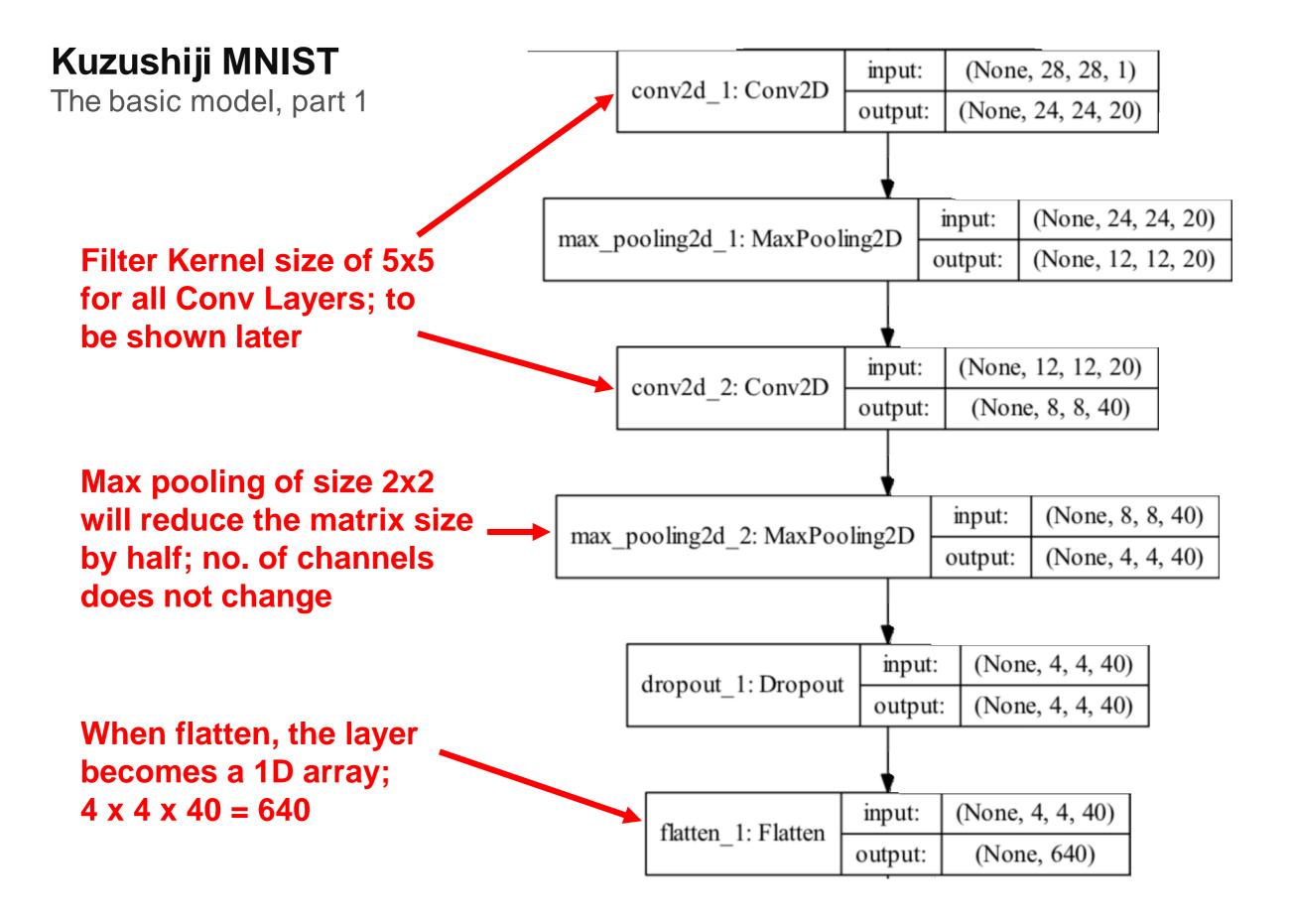


Source: https://arxiv.org/pdf/1812.01718.pdf

#### Another 'MNIST' alternative



Source: https://github.com/rois-codh/kmnist/blob/master/images/kmnist\_examples.png



#### Kuzushiji MNIST input: (None, 4, 4, 40) flatten\_1: Flatten The basic model, part 1 (None, 640) output: input: (None, 640) dense\_1: Dense (None, 128) output: **Hidden Layer** input: (None, 128) **Output Layer** dense\_2: Dense (None, 10) output:

The main layout for the code

- Import libraries
- 2. Matplotlib setup
- 3. Data preparation
- 4. Define model
- 5. Train model
- 6. Test model

1. Import libraries, part 1

- numpy for matrix manipulation;
- sklearn for measuring performance;
- matplotlib to show image and plot result;
- os for path manipulation

- > import numpy as np
- > import sklearn.metrics as metrics
- > import matplotlib.pyplot as plt
- > import os

1. Import libraries, part 2

 Import all the Keras functions that we are going to use in this problem; note that we are using Keras function under the tensorflow; not using the keras directly

To save the model

To train and test data using the model

- > from tensorflow.keras.callbacks import ModelCheckpoint,CSVLogger
- from tensorflow.keras.models import Sequential
- from tensorflow.keras.layers import Dense
- > from tensorflow.keras.layers import Dropout
- from tensorflow.keras.layers import Flatten
- > from tensorflow.keras.layers import Conv2D
- from tensorflow.keras.layers import MaxPooling2D
- > from tensorflow.keras.utils import to\_categorical

Function that allows us to convert our labels from integer into a one hot encoding type

Approach to build our model for this WS; other approaches will be covered in PRMLS course

2. Matplotlib setup, part 1

- First three lines setup the font manager, so that we can display Japanese words correctly in later usage
- Use 'ggplot' style to plot our training and testing result

2. Matplotlib setup, part 2

 Create a function that can display gray scale image correctly

Otherwise imshow will rescale our gray scale images, which is not desirable for this application

scale correctly

psupr/m5.5/v1.0

3. Data preparation, part 1

- Load train and test data; load train and test labels
- Rescale data to float, range from 0 to 1

```
Use numpy function to load the data (in npz format in numpy
```

```
> trDat = np.load('kmnist-train-imgs.npz')['arr_0']
> trLbl = np.load('kmnist-train-labels.npz')['arr_0']
> tsDat = np.load('kmnist-test-imgs.npz')['arr_0']
> tsLbl = np.load('kmnist-test-labels.npz')['arr_0']
```

Provided data is in uint8 format (unsigned 8-bit integer; range 0~255; this is too large!)

```
> trDat = trDat.astype('float32')/255
> tsDat = tsDat.astype('float32')/255
```

Hence, convert data type to float for both tr and ts data (rescale range to 0~1; optimal range)

```
> imgrows = trDat.shape[1]
> imgclms = trDat.shape[2]
```

3. Data preparation, part 2

60000 images for tr; rows & col is 28x28

10000 images for ts; rows & col is 28x28

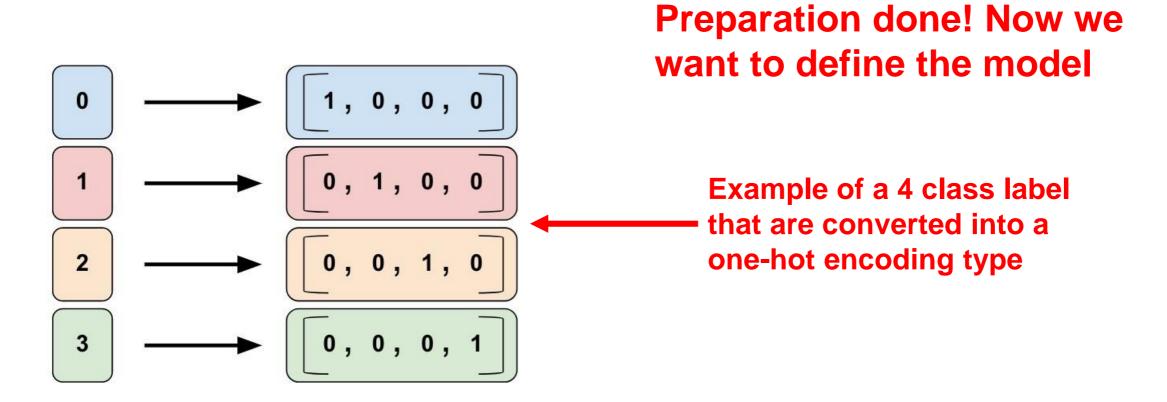
- •The current shape for trDat is (60000, 28, 28)
- •The current shape for tsDat is (10000, 28, 28)
- Need to be reshaped into the form of (samples, width, height, channel) to fit into Keras API

> tsDat

Reshaping functions to include the channel; necessary step to meet the requirements for the Keras API

3. Data preparation, part 3

 One-hot encode the train and test label information; get the number of classes in the labels



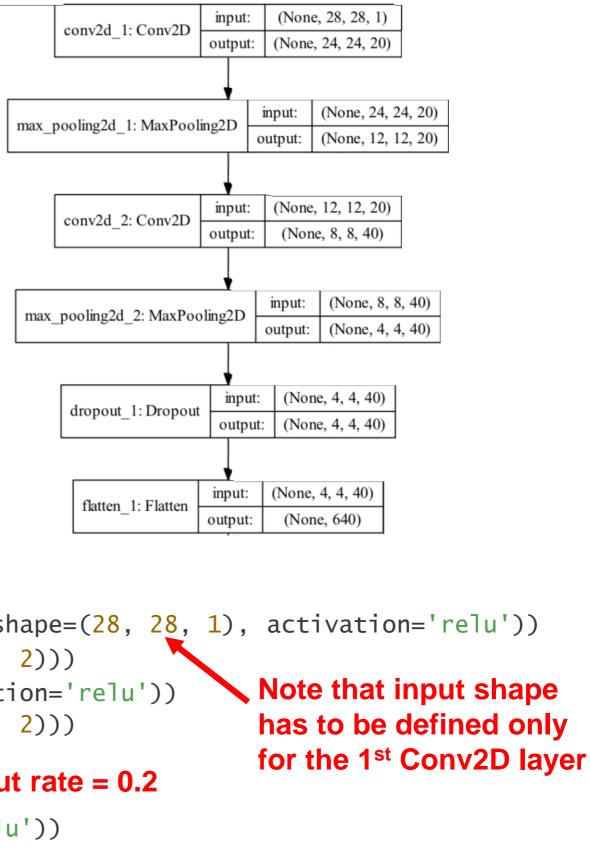
Source: https://arxiv.org/pdf/1812.01718.pdf

psupr/m5.5/v1.0

4. Define model, part 1

# Main Thing to do for today's workshop!

```
= 29
> seed
> np.random.seed(seed)
                                                 flatten 1: Flatten
> modelname
              = 'wks5 1a'
> def createModel():
      model = Sequential()
      model.add(Conv2D(20, (5, 5), input_shape=(28, 28, 1), activation='relu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
      model.add(Conv2D(40, (5, 5), activation='relu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
      model.add(Dropout(0.2))
                                   Dropout rate = 0.2
      model.add(Flatten())
      model.add(Dense(128, activation='relu'))
```



## **FAQs**

- 1. Where to put the Dropouts?
- 2. Max Pooling size strictly 2x2?
- 3. Bigger vs Smaller Kernel size?
- 4. How many channels/neurons should I put for each CNN/Dense layer?
- 5. How many CNN/Dense layers should I put?
- 6. How to enable GPU on colab?
- 7. How to put padding? (to be answered next few slides)
- 8. How do I change the stride value? (to be answered next few slides)

4. Define model, part 1

```
Padding Type
              = 29
> seed
> np.random.seed(seed)
> modelname
             = 'wks5 1a'
> def createModel():
     model = Sequential()
     model.add(Conv2D(20, (5, 5), input\_shape=(28, 28, 1), activation='relu'))
     model.add(MaxPooling2D(pool_size=(2, 2)))
     model.add(Conv2D(40, (5, 5), activation='relu', padding='same/valid'))
     model.add(MaxPooling2D(pool_size=(2, 2)))
     model.add(Dropout(0.2))
     model.add(Flatten())
     model.add(Dense(128, activation='relu'))
      . . . . .
                                                      Using
                                                                        No
                                                    padding!
                                                                    padding!
```

Changing

. . . . .

4. Define model, part 1

```
> seed = 29
> np.random.seed(seed)

> modelname = 'wks5_1a'
> def createModel():
    model = Sequential()
    model.add(Conv2D(20, (5, 5), input_shape=(28, 28, 1), activation='relu'))
    model.add(MaxPooling2D(pool_size=(2, 2), strides=(2, 2)))
    model.add(Conv2D(40, (5, 5), strides=(2, 2), activation='relu'))
    model.add(MaxPooling2D(pool_size=(2, 2)))
    model.add(Dropout(0.2))
    model.add(Flatten())
    model.add(Dense(128, activation='relu'))
```



Changing

4. Define model, part 1

```
| input: (None, 4, 4, 40) |
| output: (None, 640) |
| dense_1: Dense | input: (None, 640) |
| output: (None, 128) |
| dense_2: Dense | input: (None, 128) |
| output: (None, 128) |
| output: (None, 10) |
```

```
= 29
> seed
> np.random.seed(seed)
> modelname = 'wks5_1a'
> def createModel():
      model = Sequential()
      model.add(Conv2D(20, (5, 5), input\_shape=(28, 28, 1), activation='relu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
      model.add(Conv2D(40, (5, 5), activation='relu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
      model.add(Dropout(0.2))
                                                     Dense layers perform the
      model.add(Flatten())
                                                     main classification tasks
      model.add(Dense(128, activation='relu'))
      model.add(Dense(num_classes, activation='softmax'))
      model.compile(loss='categorical_crossentropy', optimizer='adam',
                  metrics=['accuracy'])
      return model
```

4. Define model, part 1

```
= 29
> seed
> np.random.seed(seed)
> modelname = 'wks5 1a'
> def createModel():
      model = Sequential()
      model.add(Conv2D(20, (5, 5), input\_shape=(28, 28, 1), activation='relu'))
      model.add(MaxPooling2D(pool_size=(2, 2)))
                                                          Softmax enables you to
      model.add(Conv2D(40, (5, 5), activation='relu'))
                                                          identify which output is
      model.add(MaxPooling2D(pool_size=(2, 2)))
                                                          true within the output layer
      model.add(Dropout(0.2))
      model.add(Flatten())
                                                          (in terms of probabilities)
      model.add(Dense(128, activation='relu'))
      model.add(Dense(num_classes, activation='softmax'))
      model.compile(loss='categorical_crossentropy', optimizer='adam',
                  metrics=['accuracy'])
      return model
```

4. Define model, part 1

```
= 29
> seed
> np.random.seed(seed)
> modelname
            = 'wks5 1a'
> def createModel():
      model = Sequential()
      model.add(Conv2D(20, (5, 5), input\_shape=(28, 28, 1), activation='relu'))
```

```
(None, 4, 4, 40)
                    input:
flatten 1: Flatten
                   output:
                               (None, 640)
                     input:
                              (None, 640)
  dense 1: Dense
                              (None, 128)
                    output:
                              (None, 128)
                     input:
  dense 2: Dense
                               (None, 10)
                    output:
```

```
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Conv2D(40, (5, 5), activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.2))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dense(num_classes, activation='softmax'))
model.compile(loss='categorical_crossentropy', optimizer='adam',
            metrics=['accuracy'])
return model
```

**Optimizer = an algorithm that tells the** framework how to update the weights and bias. Backbone of this is backpropagation; different optimizers have different ways to update the weights and bias

4. Define model, part 2

 'model' for training; 'modelGo' for final evaluation

Summary allows you monitor your model to check if your model construction is done correctly

Output

example

>	m	0	Ы	൧ഁ	ı
>	Ш	U	u	$\mathbf{c}$	

= createModel()

> modelGo

1290

= createModel()

model.summary()

	•		
Layer (type)	Output	Shape	Param #
conv2d_1 (Conv2D)	(None,	24, 24, 20)	520
max_pooling2d_1 (MaxPooling2	(None,	12, 12, 20)	0
conv2d_2 (Conv2D)	(None,	8, 8, 40)	20040
max_pooling2d_2 (MaxPooling2	(None,	4, 4, 40)	0
dropout_1 (Dropout)	(None,	4, 4, 40)	0
flatten_1 (Flatten)	(None,	640)	0
dense_1 (Dense)	(None,	128)	82048

Creating two models here (one for training and another for final evaluation); not necessary to do this but it is a good practice

Total params: 103,898 Trainable params: 103,898 Non-trainable params: 0

dense\_2 (Dense)

(None, 10)

4. Define model, part 3

Before training, we need to specify where/how we are saving the model

 Create checkpoints to save model during training and save training data into csv

```
> filepath
                  = modelname + ".hdf5"
                                                             Monitor model set to
> checkpoint
                  = ModelCheckpoint(filepath,
                                                             "validation accuracy"
                                     monitor='val_acc'
                                     verbose=0,
                                     save_best_only=True,
   Use ModelCheckpoint to save
                                     mode='max')
   the model in the middle of the
   training process
                                                             Save when the validation
                                                             accuracy is the max (i.e.
                  = CSVLogger(modelname + '.csv')
> csv_logger
                                                             mode = max)
                  = [checkpoint,csv_logger]
> callbacks_list
      Lastly, put the 2 objects (i.e.
                                                           Log the training and
                                                           testing information into a
      checkpoint and csv_logger) into a
```

list, named as callbacks\_list;

these 2 objects (i.e. callbacks) will

be called after each training epoch

**CSV file via CSVlogger** 

5. Train model

#### Training is only a single line

Use the model.fit function to do the training

Epochs is a hyperparameter that defines the number of times that the learning algorithm will work through the entire training dataset

Batch size is a hyperparameter that controls each time how many samples are taken at one go to train and update the weights

6. Test model, part 1

 Use a new object to load the weights, and check the best accuracy

After training, we need to do a final evaluation (no training) using a fresh model (i.e. modelGo); must be fresh to test the model with the trained weights

```
> modelGo.load_weights(filepath)
> modelGo.compile(loss='categorical crossent
```

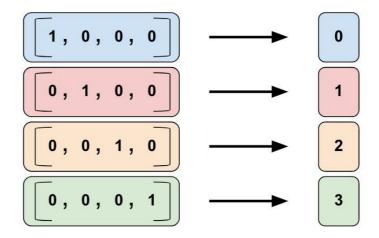
Weights loaded from the trained model and the fresh model is recompiled

6. Test model, part 2

• Test the model, calculate the accuracy and confusion matrix

Use the modelGo.predict function to test the model using the testing data set

- Use this function to convert "predicts" output from one-hot encoded to integer type; need integer format to obtain the accuracies and to report the matrix



> testout = np.argmax(tsLbl,axis=1)

Do the same conversion for the test labels

- > labelname = ['お O','き Ki','す Su','つ Tsu','な Na', 'は Ha','ま Ma','や Ya','れ Re','を Wo']
- > testScores = metrics.accuracy\_score(testout,predout)
- > confusion = metrics.confusion\_matrix(testout,predout)

Calculates the test scores in accuracy

Calculates the confusion matrix

6. Test model, part 3

- Test the model, calculate the accuracy and confusion matrix
- > print("Best accuracy (on testing dataset): %.2f%%" % (testScores\*100))
- > print(metrics.classification\_report(testout,predout,target\_names=labelname,digits=4))
- > print(confusion)

Best accuracy (on testing dataset): 96.56%							
ļ.	orecision	recall	f1-score	support			
お 0	0.9615	0.9740	0.9677	1000			
き Ki	0.9772	0.9430	0.9598	1000			
す Su	0.9562	0.9390	0.9475	1000			
つ Tsu	0.9732	0.9820	0.9776	1000			
な Na	0.9588	0.9530	0.9559	1000			
は Ha	0.9707	0.9600	0.9653	1000			
ŧ Ма	0.9245	0.9920	0.9571	1000			
や Ya	0.9877	0.9620	0.9747	1000			
n Re	0.9665	0.9800	0.9732	1000			
を WO	0.9838	0.9710	0.9774	1000			
avg / total	0.9660	0.9656	0.9656	10000			

[[9	974	2	1	1	18	1	0	1	1	1]
	5	943	6	0	5	2	24	3	7	5]
	8	3	939	9	4	7	19	4	7	0]
	0	0	8	982	0	4	5	0	1	0]
Ε	12	2	1	9	953	4	8	2	6	3]
[	1	3	13	4	1	960	13		3	2]
[	0	2	3	0	1	2	992	0	0	0]
	7	5	5		5	2	5	962	5	4]
	2	1	4	3	5	3	1	0	980	1]
	4	4	2		2	4	6	2	4	971]]

#### **Confusion Matrix**

#### **Classification Report**

6. Test model, part 4

Use pandas to read the training log in csv (i.e. modelname + '.csv') that we have saved just now

#### Loss value - 0.3 - 0.2 - 0.1 - 0.0 Accuracy -0.99- 0.97 - 0.95 - 0.93 10 20 30 40 50 60

#### Plot the result

> import pandas as pd

```
= pd.read_csv(modelname +'.csv')
 records
> plt.figure()
> plt.subplot(211)
> plt.plot(records['val_loss'])
> plt.yticks([0.00,0.10,0.20,0.30])
> plt.title('Loss value',fontsize=12)
              = plt.gca()
> ax
> ax.set_xticklabels([])
> plt.subplot(212)
> plt.plot(records['val_acc'])
> plt.yticks([0.93,0.95,0.97,0.99])
> plt.title('Accuracy',fontsize=12)
> plt.show()
```

# **Project:**

# Try the different variations in your model and observe their performances

#### Rmb to enable your GPU in your COLAB!

- The original model; given previously; this will serve as the base for the rest
- 2. Add 1x CNN and 1x MaxPooling layer; decide on the channels and sizes for these layers
- 3. Step 2 plus add 2 more Dropout layers of 20%; decide where to put them
- Steps 2 & 3 plus add an additional dense layer of activation RELU; decide on the number of neurons yourself for this layer
- 5. A model of your own configuration that gives an optimal accuracy (must be more than the original model's accuracy); this version to be submitted

# Project (Optional; only if you have time):

Try the different variations in your model and observe their performances

### Rmb to enable your GPU in your COLAB!

- 6. From the original model, add padding for all CNN layers
- 7. From the original model, add 3x additional CNN layers; decide on the channels and sizes for all CNN layers
- 8. From the original model, add 3x additional dense layers of activation RELU; decide on the number of neurons yourself for all dense layers
- 9. Steps 7 and 8 together **WITHOUT** any additional Dropout layers
- 10. Steps 7 and 8 together <u>WITH</u> additional Dropout layers of 20%; decide how many Dropout layers you need and where to put them

For those who have finished your quiz but have not finished your workshop, please do so and upload.

For those who have finished your quiz and have uploaded your workshop, please give me a while to mark your quiz and check your submission. After which, you may leave early.