Deep Generative Models

Lecture 4

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2025, Autumn

Posterior Distribution (Bayes' Theorem)

$$p(\theta|\mathbf{x}) = \frac{p(\mathbf{x}|\theta)p(\theta)}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\theta)p(\theta)}{\int p(\mathbf{x}|\theta)p(\theta)d\theta}$$

- x observed variables;
- \bullet unobserved variables (latent parameters);
- $p(\mathbf{x}|\theta)$ likelihood;
- $p(\mathbf{x}) = \int p(\mathbf{x}|\theta)p(\theta)d\theta$ evidence;
- \triangleright $p(\theta)$ prior distribution;
- $ightharpoonup p(\theta|\mathbf{x})$ posterior distribution.

Latent Variable Models (LVM)

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z}.$$

MLE Problem for LVM

$$\begin{split} \boldsymbol{\theta}^* &= \arg\max_{\boldsymbol{\theta}} \log p(\mathbf{X}|\boldsymbol{\theta}) = \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log p(\mathbf{x}_i|\boldsymbol{\theta}) = \\ &= \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log \int p(\mathbf{x}_i|\mathbf{z}_i,\boldsymbol{\theta}) p(\mathbf{z}_i) d\mathbf{z}_i. \end{split}$$

Naive Monte Carlo Estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})} p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) \approx \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta}),$$
 where $\mathbf{z}_k \sim p(\mathbf{z}).$

ELBO Derivation 1 (Inequality)

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \log \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} \geq \mathbb{E}_q \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} = \mathcal{L}_{q, \boldsymbol{\theta}}(\mathbf{x})$$

ELBO Derivation 2 (Equality)

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \int q(\mathbf{z}) \log \frac{p(\mathbf{z}|\mathbf{x}, \theta)p(\mathbf{x}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \\ = \log p(\mathbf{x}|\theta) - \mathrm{KL}(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \theta))$$

Variational Decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}_{q,\boldsymbol{\theta}}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z}|\mathbf{x},\boldsymbol{\theta})) \geq \mathcal{L}_{q,\boldsymbol{\theta}}(\mathbf{x}).$$

Variational Evidence Lower Bound (ELBO)

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}_{q,\boldsymbol{\theta}}(\mathbf{x}) + \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z}|\mathbf{x},\boldsymbol{\theta})) \geq \mathcal{L}_{q,\boldsymbol{\theta}}(\mathbf{x}).$$

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, \theta) - \text{KL}(q(\mathbf{z})||p(\mathbf{z}))$$

Log-likelihood Decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta}) - \mathrm{KL}(q(\mathbf{z})||p(\mathbf{z})) + \mathrm{KL}(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x},\boldsymbol{\theta})).$$

Rather than maximizing likelihood, maximize the ELBO:

$$\max_{\boldsymbol{\theta}} p(\mathbf{x}|\boldsymbol{\theta}) \quad \rightarrow \quad \max_{\boldsymbol{q},\boldsymbol{\theta}} \mathcal{L}_{\boldsymbol{q},\boldsymbol{\theta}}(\mathbf{x})$$

Maximizing the ELBO with respect to the variational distribution q is equivalent to minimizing the KL divergence:

$$rg \max_{q} \mathcal{L}_{q,oldsymbol{ heta}}(\mathbf{z}) \equiv rg \min_{q} \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z} | \mathbf{x}, oldsymbol{ heta})).$$

$$egin{aligned} \mathcal{L}_{q, heta}(\mathbf{x}) &= \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) - \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z})) = \ &= \mathbb{E}_q \left[\log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) - \log rac{q(\mathbf{z})}{p(\mathbf{z})}
ight] d\mathbf{z}
ightarrow \max_{q, oldsymbol{ heta}}. \end{aligned}$$

EM Algorithm (Block-Coordinate Optimization)

- ▶ Initialize θ^* ;
- ▶ E-step: $(\mathcal{L}_{q,\theta}(\mathbf{x}) \to \mathsf{max}_q)$

$$egin{aligned} q^*(\mathbf{z}) &= rg \max_q \mathcal{L}_{q, oldsymbol{ heta}^*}(\mathbf{x}) = \ &= rg \min_q \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*)) = p(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*); \end{aligned}$$

▶ M-step: $(\mathcal{L}_{q,\theta}(\mathbf{x}) \to \mathsf{max}_{\theta})$

$$oldsymbol{ heta}^* = rg\max_{oldsymbol{ heta}} \mathcal{L}_{q^*,oldsymbol{ heta}}(\mathbf{x});$$

Repeat E-step and M-step until convergence.

EM-Algorithm

► E-Step:

$$q^*(\mathbf{z}) = rg \max_{q} \mathcal{L}_{q, \theta^*}(\mathbf{x}) = rg \min_{q} \mathrm{KL}(q(\mathbf{z}) \| p(\mathbf{z} | \mathbf{x}, \theta^*));$$

► M-Step:

$$\theta^* = \arg\max_{\boldsymbol{\theta}} \mathcal{L}_{q^*,\boldsymbol{\theta}}(\mathbf{x});$$

Amortized Variational Inference

Restrict the family of possible distributions $q(\mathbf{z})$ to a parameterized class $q(\mathbf{z}|\mathbf{x}, \phi)$, conditioned on samples \mathbf{x} and defined by ϕ .

Variational Bayes

E-Step:

$$\phi_k = \phi_{k-1} + \eta \cdot
abla_{\phi} \mathcal{L}_{\phi, heta_{k-1}}(\mathbf{x}) ig|_{\phi = \phi_{k-1}}$$

► M-Step:

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Outline

1. ELBO Gradients, Reparametrization Trick

2. Variational Autoencoder (VAE)

3. Discrete VAE Latent Representations

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$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z},\theta) - \mathrm{KL}(q(\mathbf{z}|\mathbf{x},\phi) \| p(\mathbf{z}))$$

$$\mathcal{L}_{q, heta}(\mathbf{x}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, heta) - \mathrm{KL}(q(\mathbf{z}|\mathbf{x}, \phi) \| p(\mathbf{z}))$$

M-step:
$$\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$$

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abla_{m{ heta}}}{\int} q(\mathbf{z}|\mathbf{x},m{\phi}) \log p(\mathbf{x}|\mathbf{z},m{ heta}) d\mathbf{z}$$

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abla_{m{ heta}} \log p(\mathbf{x}|\mathbf{z}^*,m{ heta}), \quad \mathbf{z}^* \sim q(\mathbf{z}|\mathbf{x},m{\phi}). \end{aligned}$$

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M-step: $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

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Naive Monte Carlo Estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z} \approx \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta}), \quad \mathbf{z}_k \sim p(\mathbf{z}).$$

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M-step: $\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x})$

$$\nabla_{\theta} \mathcal{L}_{\phi,\theta}(\mathbf{x}) = \frac{\nabla_{\theta}}{\int} q(\mathbf{z}|\mathbf{x},\phi) \log p(\mathbf{x}|\mathbf{z},\theta) d\mathbf{z}$$

$$= \int q(\mathbf{z}|\mathbf{x},\phi) \nabla_{\theta} \log p(\mathbf{x}|\mathbf{z},\theta) d\mathbf{z}$$

$$\approx \nabla_{\theta} \log p(\mathbf{x}|\mathbf{z}^*,\theta), \quad \mathbf{z}^* \sim q(\mathbf{z}|\mathbf{x},\phi).$$

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The variational posterior $q(\mathbf{z}|\mathbf{x}, \phi)$ typically concentrates more probability mass in a much smaller region than the prior $p(\mathbf{z})$.

E-step:
$$\nabla_{\phi} \mathcal{L}_{\phi,\theta}(\mathbf{x})$$

Unlike the M-step, the density $q(\mathbf{z}|\mathbf{x}, \phi)$ now depends on ϕ , so standard Monte Carlo estimation can't be applied:

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Reparametrization Trick (LOTUS Trick)

Assume $\mathbf{z} \sim q(\mathbf{z}|\mathbf{x}, \phi)$ is generated by a random variable $\epsilon \sim p(\epsilon)$ via a deterministic mapping $\mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon)$. Then,

$$\mathbb{E}_{\mathsf{z} \sim q(\mathsf{z}|\mathsf{x},\phi)} \mathsf{f}(\mathsf{z}) = \mathbb{E}_{\epsilon \sim p(\epsilon)} \mathsf{f}(\mathsf{g}_{\phi}(\mathsf{x},\epsilon))$$

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Note: The LHS expectation is with respect to the parametric distribution $q(\mathbf{z}|\mathbf{x}, \phi)$, while the RHS is for the non-parametric $p(\epsilon)$.

Reparametrization Trick (LOTUS Trick)

$$\nabla_{\phi} \int q(\mathbf{z}|\mathbf{x},\phi) \mathbf{f}(\mathbf{z}) d\mathbf{z} = \nabla_{\phi} \int p(\epsilon) \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x},\epsilon)) d\epsilon$$

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$$= \int p(\epsilon) \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon)) d\epsilon \approx \nabla_{\phi} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon^{*})),$$

where $\epsilon^* \sim p(\epsilon)$.

Reparametrization Trick (LOTUS Trick)

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abla_{\phi}\mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x},\epsilon)), \end{aligned}$$

where $\epsilon^* \sim p(\epsilon)$.

Variational Assumption

$$p(\epsilon) = \mathcal{N}(0, \mathbf{I}); \quad \mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon) = \sigma_{\phi}(\mathbf{x}) \odot \epsilon + \mu_{\phi}(\mathbf{x});$$

$$q(\mathbf{z}|\mathbf{x}, \phi) = \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^{2}(\mathbf{x})).$$

Here, $\mu_{\phi}(\cdot)$ and $\sigma_{\phi}(\cdot)$ are parameterized functions (outputs of a neural network).

Thus, we can write $q(\mathbf{z}|\mathbf{x},\phi) = \mathsf{NN}_{\mathsf{e}}(\mathbf{x},\phi)$, the **encoder**.

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q(\mathbf{z}|\mathbf{x}, \phi) || p(\mathbf{z}))$$

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Reconstruction Term

$$\begin{split} &\nabla_{\phi} \int q(\mathbf{z}|\mathbf{x},\phi) \log p(\mathbf{x}|\mathbf{z},\theta) d\mathbf{z} = \int p(\epsilon) \nabla_{\phi} \log p(\mathbf{x}|\mathbf{g}_{\phi}(\mathbf{x},\epsilon),\theta) d\epsilon \approx \\ &\approx \nabla_{\phi} \log p\left(\mathbf{x}|\sigma_{\phi}(\mathbf{x}) \odot \epsilon^* + \mu_{\phi}(\mathbf{x}),\theta\right), \quad \text{where } \epsilon^* \sim \mathcal{N}(\mathbf{0},\mathbf{I}) \end{split}$$

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The generative distribution $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$ can be implemented as a neural network.

We may write $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = NN_d(\mathbf{z}, \boldsymbol{\theta})$, called the **decoder**.

KL Term

 $p(\mathbf{z})$ is the prior over latents \mathbf{z} , typically $p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I})$.

$$\nabla_{\phi} \mathrm{KL}(q(\mathbf{z}|\mathbf{x},\phi) \| p(\mathbf{z})) = \nabla_{\phi} \mathrm{KL}\left(\mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^{2}(\mathbf{x})) \| \mathcal{N}(\mathbf{0}, \mathbf{I})\right)$$

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} - \nabla_{\phi} \mathrm{KL}(q(\mathbf{z}|\mathbf{x}, \phi) || p(\mathbf{z}))$$

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This expression admits a closed-form analytic solution.

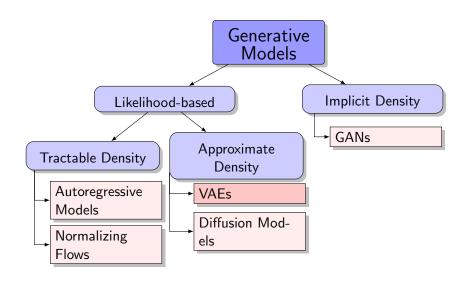
Outline

1. ELBO Gradients, Reparametrization Trick

2. Variational Autoencoder (VAE)

3. Discrete VAE Latent Representations

Generative Models Zoo



Training (EM Algorithm)

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Note: The encoder $q(\mathbf{z}|\mathbf{x}, \phi)$ isn't needed during generation.

Variational Autoencoder

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z},\theta) - \mathrm{KL}(q(\mathbf{z}|\mathbf{x},\phi) || p(\mathbf{z}))$$

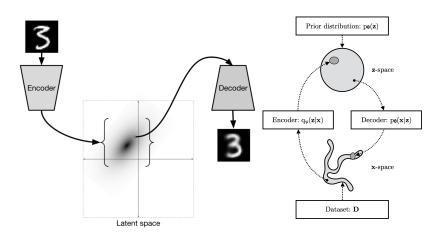
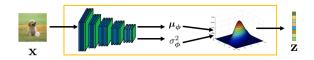
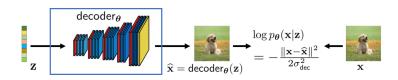


image credit: http://ijdykeman.github.io/ml/2016/12/21/cvae.html Kingma D. P., Welling M., An Introduction to Variational Autoencoders, 2019

Variational Autoencoder

- The encoder $q(\mathbf{z}|\mathbf{x}, \phi) = \mathsf{NN_e}(\mathbf{x}, \phi)$ outputs $\boldsymbol{\mu}_{\phi}(\mathbf{x})$ and $\boldsymbol{\sigma}_{\phi}(\mathbf{x})$.
- ▶ The decoder $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathsf{NN}_d(\mathbf{z}, \boldsymbol{\theta})$ outputs parameters of the observed data distribution.





VAE vs Normalizing Flows

	VAE	NF
Objective	ELBO $\mathcal L$	Forward KL/MLE
		deterministic
	stochastic	$z=f_{ heta}(x)$
Encoder	$ z \sim q(z x,\phi)$	$q(\mathbf{z} \mathbf{x}, \boldsymbol{\theta}) = \delta(\mathbf{z} - \mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}))$
		deterministic
	stochastic	$x = g_{m{ heta}}(z)$
Decoder	$ \mathbf{x} \sim p(\mathbf{x} \mathbf{z}, \boldsymbol{\theta}) $	$p(\mathbf{x} \mathbf{z}, \boldsymbol{\theta}) = \delta(\mathbf{x} - \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z}))$
Parameters	$oldsymbol{\phi},oldsymbol{ heta}$	$ heta \equiv \phi$

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Objective	ELBO $\mathcal L$	Forward KL/MLE
	stochastic	$\begin{array}{c} deterministic \\ z = f_{\theta}(x) \end{array}$
Encoder	$ z \sim q(z x,\phi)$	$q(\mathbf{z} \mathbf{x}, \boldsymbol{\theta}) = \delta(\mathbf{z} - \mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x}))$
	stochastic	$ deterministic \mathbf{x} = \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z}) $
Decoder	$\mathbf{x} \sim p(\mathbf{x} \mathbf{z}, \boldsymbol{\theta})$	$p(\mathbf{x} \mathbf{z},\boldsymbol{\theta}) = \delta(\mathbf{x} - \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z}))$
Parameters	ϕ, θ	$ heta \equiv \phi$

Theorem

MLE for a normalizing flow is equivalent to maximizing the ELBO for a VAE where:

$$p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta}) = \delta(\mathbf{x} - \mathbf{f}_{\boldsymbol{\theta}}^{-1}(\mathbf{z})) = \delta(\mathbf{x} - \mathbf{g}_{\boldsymbol{\theta}}(\mathbf{z}));$$

$$q(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}) = \delta(\mathbf{z} - \mathbf{f}_{\boldsymbol{\theta}}(\mathbf{x})).$$

Nielsen D., et al., SurVAE Flows: Surjections to Bridge the Gap Between VAEs and Flows. 2020

Outline

1. ELBO Gradients, Reparametrization Trick

2. Variational Autoencoder (VAE)

3. Discrete VAE Latent Representations

Motivation

- Previous VAE models have used continuous latent variables z.
- ► For some modalities, **discrete** representations **z** may be a more natural choice.
- Advanced autoregressive models (e.g., PixelCNN) are highly effective for distributions over discrete variables.
- Current transformer-like models process discrete tokens.

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$$\mathcal{L}_{\phi, heta}(\mathbf{x}) = \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} \log p(\mathbf{x}|\mathbf{z}, heta) - \mathrm{KL}(q(\mathbf{z}|\mathbf{x}, \phi) \| p(\mathbf{z}))
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ightarrow \max_{\phi, heta}.$$

- Apply the reparametrization trick to obtain unbiased gradients.
- ▶ Use Gaussian distributions for $q(\mathbf{z}|\mathbf{x}, \phi)$ and $p(\mathbf{z})$ to compute the KL analytically.

Assumptions

▶ Let $c \sim \text{Categorical}(\pi)$, where

$$\pi = (\pi_1, \ldots, \pi_K), \quad \pi_k = P(c = k), \quad \sum_{k=1}^K \pi_k = 1.$$

Suppose the VAE adopts a discrete latent variable c with prior $p(c) = \text{Uniform}\{1, \dots, K\}$.

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$$\mathcal{L}_{\phi, \theta}(\mathbf{x}) = \mathbb{E}_{q(c|\mathbf{x}, \phi)} \log p(\mathbf{x}|c, \theta) - \underbrace{\mathrm{KL}(q(c|\mathbf{x}, \phi) \| p(c))}_{\phi, \theta} o \max_{\phi, \theta}.$$

$$\mathrm{KL}(q(c|\mathbf{x}, \phi) || p(c)) = \sum_{k=1}^{K} q(k|\mathbf{x}, \phi) \log \frac{q(k|\mathbf{x}, \phi)}{p(k)}$$

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$$\begin{split} \mathcal{L}_{\phi,\theta}(\mathbf{x}) &= \mathbb{E}_{q(c|\mathbf{x},\phi)} \log p(\mathbf{x}|c,\theta) - \mathrm{KL}(q(c|\mathbf{x},\phi) \| p(c)) \to \max_{\phi,\theta}. \\ \mathrm{KL}(q(c|\mathbf{x},\phi) \| p(c)) &= \sum_{k=1}^K q(k|\mathbf{x},\phi) \log \frac{q(k|\mathbf{x},\phi)}{p(k)} = \\ &= \sum_{k=1}^K q(k|\mathbf{x},\phi) \log q(k|\mathbf{x},\phi) - \sum_{k=1}^K q(k|\mathbf{x},\phi) \log p(k) \end{split}$$

Assumptions

▶ Let $c \sim \text{Categorical}(\pi)$, where

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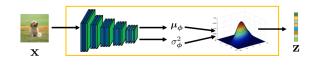
$$\mathcal{L}_{\phi, \theta}(\mathbf{x}) = \mathbb{E}_{q(c|\mathbf{x}, \phi)} \log p(\mathbf{x}|c, \theta) - \mathrm{KL}(q(c|\mathbf{x}, \phi) || p(c)) \to \max_{\phi, \theta}.$$

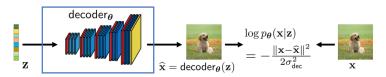
$$\begin{aligned} \operatorname{KL}(q(c|\mathbf{x}, \phi) || p(c)) &= \sum_{k=1}^{K} q(k|\mathbf{x}, \phi) \log \frac{q(k|\mathbf{x}, \phi)}{p(k)} = \\ &= \sum_{k=1}^{K} q(k|\mathbf{x}, \phi) \log q(k|\mathbf{x}, \phi) - \sum_{k=1}^{K} q(k|\mathbf{x}, \phi) \log p(k) = \\ &= -\operatorname{H}(q(c|\mathbf{x}, \phi)) + \log K. \end{aligned}$$

$$\mathcal{L}_{\phi, oldsymbol{ heta}}(\mathbf{x}) = \mathbb{E}_{q(c|\mathbf{x}, \phi)} \log p(\mathbf{x}|c, oldsymbol{ heta}) + \mathrm{H}(q(c|\mathbf{x}, \phi)) - \log K
ightarrow \max_{\phi, oldsymbol{ heta}}.$$

$$\mathcal{L}_{\phi, heta}(\mathbf{x}) = \mathbb{E}_{q(c|\mathbf{x}, \phi)} \log p(\mathbf{x}|c, heta) + \mathrm{H}(q(c|\mathbf{x}, \phi)) - \log K o \max_{\phi, heta}.$$

- ▶ The encoder should output a discrete distribution $q(c|\mathbf{x}, \phi)$.
- We need an analogue of the reparametrization trick for discrete $q(c|\mathbf{x}, \phi)$.
- The decoder $p(\mathbf{x}|c, \theta)$ must take a discrete random variable c as input.





Chan S., Tutorial on Diffusion Models for Imaging and Vision, 2024

Summary

- The reparametrization trick provides unbiased gradients with respect to the variational posterior $q(\mathbf{z}|\mathbf{x}, \phi)$.
- ▶ The VAE model is a latent variable model parameterized by two neural networks: a stochastic encoder $q(\mathbf{z}|\mathbf{x}, \phi)$ and a stochastic decoder $p(\mathbf{x}|\mathbf{z}, \theta)$.
- ▶ NF models can be interpreted as VAEs with deterministic encoder and decoder functions.
- Discrete VAE latents offer a natural class of latent variable models.