

# Deep Generative Models

## Lecture 3

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# Recap of Previous Lecture

## Jacobian Matrix

Let  $\mathbf{f} : \mathbb{R}^m \rightarrow \mathbb{R}^m$  be a differentiable function.

$$\mathbf{z} = \mathbf{f}(\mathbf{x}), \quad \mathbf{J} = \frac{\partial \mathbf{z}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial z_1}{\partial x_1} & \cdots & \frac{\partial z_1}{\partial x_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial z_m}{\partial x_1} & \cdots & \frac{\partial z_m}{\partial x_m} \end{pmatrix} \in \mathbb{R}^{m \times m}$$

## Change of Variables Theorem (CoV)

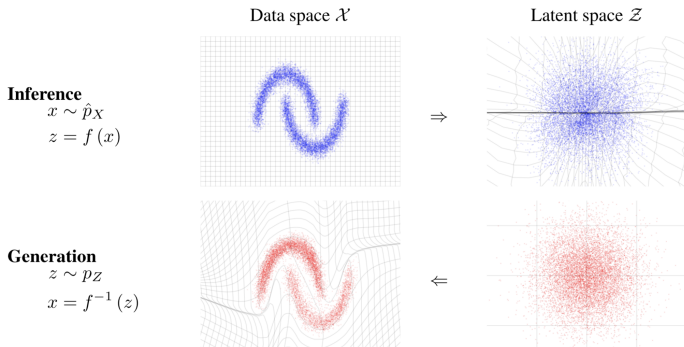
Let  $\mathbf{x} \in \mathbb{R}^m$  be a random vector with density  $p(\mathbf{x})$ , and let  $\mathbf{f} : \mathbb{R}^m \rightarrow \mathbb{R}^m$  be a  $C^1$ -diffeomorphism ( $\mathbf{f}$  and  $\mathbf{f}^{-1}$  are continuously differentiable mappings). If  $\mathbf{z} = \mathbf{f}(\mathbf{x})$ , then

$$p(\mathbf{x}) = p(\mathbf{z}) |\det(\mathbf{J}_{\mathbf{f}})| = p(\mathbf{z}) \left| \det \left( \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \right) \right| = p(\mathbf{f}(\mathbf{x})) \left| \det \left( \frac{\partial \mathbf{f}(\mathbf{x})}{\partial \mathbf{x}} \right) \right|$$
$$p(\mathbf{z}) = p(\mathbf{x}) |\det(\mathbf{J}_{\mathbf{f}^{-1}})| = p(\mathbf{x}) \left| \det \left( \frac{\partial \mathbf{x}}{\partial \mathbf{z}} \right) \right| = p(\mathbf{f}^{-1}(\mathbf{z})) \left| \det \left( \frac{\partial \mathbf{f}^{-1}(\mathbf{z})}{\partial \mathbf{z}} \right) \right|$$

# Recap of Previous Lecture

## Definition

A normalizing flow is a  $C^1$ -diffeomorphism that transforms data  $\mathbf{x}$  to noise  $\mathbf{z}$ .



## Log-Likelihood

$$\log p_{\theta}(\mathbf{x}) = \log p(\mathbf{f}_K \circ \cdots \circ \mathbf{f}_1(\mathbf{x})) + \sum_{k=1}^K \log |\det(\mathbf{J}_{\mathbf{f}_k})|$$

# Recap of Previous Lecture

## Flow Log-Likelihood

$$\log p_{\theta}(\mathbf{x}) = \log p(\mathbf{f}_{\theta}(\mathbf{x})) + \log |\det(\mathbf{J}_{\mathbf{f}})|$$

One significant challenge is efficiently computing the Jacobian determinant.

## Linear Flows

$$\mathbf{z} = \mathbf{f}_{\theta}(\mathbf{x}) = \mathbf{W}\mathbf{x}, \quad \mathbf{W} \in \mathbb{R}^{m \times m}, \quad \theta = \mathbf{W}, \quad \mathbf{J}_{\mathbf{f}} = \mathbf{W}^T$$

- ▶ LU Decomposition:

$$\mathbf{W} = \mathbf{P}\mathbf{L}\mathbf{U}.$$

- ▶ QR Decomposition:

$$\mathbf{W} = \mathbf{Q}\mathbf{R}.$$

Decomposition is performed only once during initialization. Then the decomposed matrices ( $\mathbf{P}$ ,  $\mathbf{L}$ ,  $\mathbf{U}$  or  $\mathbf{Q}$ ,  $\mathbf{R}$ ) are optimized.

## Recap of Previous Lecture

Consider an autoregressive model:

$$p_{\theta}(\mathbf{x}) = \prod_{j=1}^m p_{\theta}(x_j | \mathbf{x}_{1:j-1}), \quad p_{\theta}(x_j | \mathbf{x}_{1:j-1}) = \mathcal{N}(\mu_{j,\theta}(\mathbf{x}_{1:j-1}), \sigma_{j,\theta}^2(\mathbf{x}_{1:j-1})).$$

### Gaussian Autoregressive Normalizing Flow

$$\mathbf{x} = \mathbf{f}_{\theta}^{-1}(\mathbf{z}) \quad \Rightarrow \quad x_j = \sigma_{j,\theta}(\mathbf{x}_{1:j-1}) \cdot z_j + \mu_{j,\theta}(\mathbf{x}_{1:j-1}).$$

$$\mathbf{z} = \mathbf{f}_{\theta}(\mathbf{x}) \quad \Rightarrow \quad z_j = (x_j - \mu_{j,\theta}(\mathbf{x}_{1:j-1})) \cdot \frac{1}{\sigma_{j,\theta}(\mathbf{x}_{1:j-1})}.$$

- ▶ This transformation is both  $C^1$ -**diffeomorphism**, mapping  $p(\mathbf{z})$  to  $p_{\theta}(\mathbf{x})$ .
- ▶ The Jacobian matrix for this transformation is triangular.

The generative function  $\mathbf{f}_{\theta}^{-1}(\mathbf{z})$  is **sequential**, while the inference function  $\mathbf{f}_{\theta}(\mathbf{x})$  is **not sequential**.

# Recap of Previous Lecture

Let us partition  $\mathbf{x}$  and  $\mathbf{z}$  into two groups:

$$\mathbf{x} = [\mathbf{x}_1, \mathbf{x}_2] = [\mathbf{x}_{1:d}, \mathbf{x}_{d+1:m}]; \quad \mathbf{z} = [\mathbf{z}_1, \mathbf{z}_2] = [\mathbf{z}_{1:d}, \mathbf{z}_{d+1:m}].$$

## Coupling Layer

$$\begin{cases} \mathbf{x}_1 = \mathbf{z}_1; \\ \mathbf{x}_2 = \mathbf{z}_2 \odot \sigma_{\theta}(\mathbf{z}_1) + \mu_{\theta}(\mathbf{z}_1). \end{cases} \quad \begin{cases} \mathbf{z}_1 = \mathbf{x}_1; \\ \mathbf{z}_2 = (\mathbf{x}_2 - \mu_{\theta}(\mathbf{x}_1)) \odot \frac{1}{\sigma_{\theta}(\mathbf{x}_1)}. \end{cases}$$

Both density estimation and sampling require just a single pass!

## Jacobian

$$\det \left( \frac{\partial \mathbf{z}}{\partial \mathbf{x}} \right) = \det \begin{pmatrix} \mathbf{I}_d & \mathbf{0}_{d \times (m-d)} \\ \frac{\partial \mathbf{z}_2}{\partial \mathbf{x}_1} & \frac{\partial \mathbf{z}_2}{\partial \mathbf{x}_2} \end{pmatrix} = \prod_{j=1}^{m-d} \frac{1}{\sigma_{j,\theta}(\mathbf{x}_1)}.$$

A coupling layer is a special instance of an gaussian autoregressive normalizing flow.

# Recap of Previous Lecture

## Posterior Distribution (Bayes' Theorem)

$$p(\theta|\mathbf{x}) = \frac{p(\mathbf{x}|\theta)p(\theta)}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\theta)p(\theta)}{\int p(\mathbf{x}|\theta)p(\theta)d\theta}$$

- ▶  $\mathbf{x}$  – observed variables;
- ▶  $\theta$  – unobserved variables (latent parameters);
- ▶  $p_{\theta}(\mathbf{x}) = p(\mathbf{x}|\theta)$  – likelihood;
- ▶  $p(\mathbf{x}) = \int p(\mathbf{x}|\theta)p(\theta)d\theta$  – evidence;
- ▶  $p(\theta)$  – prior distribution;
- ▶  $p(\theta|\mathbf{x})$  – posterior distribution.

# Outline

1. Latent Variable Models (LVM) (continued)
2. Variational Evidence Lower Bound (ELBO)
3. Amortized Inference
4. ELBO Gradients, Reparametrization Trick
5. Variational Autoencoder (VAE)



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# Latent Variable Models (LVM)

## Maximum Likelihood Estimation (MLE) Problem

$$\theta^* = \arg \max_{\theta} p_{\theta}(\mathbf{X}) = \arg \max_{\theta} \prod_{i=1}^n p_{\theta}(\mathbf{x}_i) = \arg \max_{\theta} \sum_{i=1}^n \log p_{\theta}(\mathbf{x}_i).$$

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The distribution  $p_{\theta}(\mathbf{x})$  can be highly complex and often intractable (just like the true data distribution  $p_{\text{data}}(\mathbf{x})$ ).

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## Extended Probabilistic Model

Introduce a latent variable  $\mathbf{z}$  for each observed sample  $\mathbf{x}$ :

$$p_{\theta}(\mathbf{x}, \mathbf{z}) = p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z}); \quad \log p_{\theta}(\mathbf{x}, \mathbf{z}) = \log p_{\theta}(\mathbf{x}|\mathbf{z}) + \log p(\mathbf{z}).$$

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$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \int p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z}) d\mathbf{z}.$$

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$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \int p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z}) d\mathbf{z}.$$

## Motivation

Both  $p_{\theta}(\mathbf{x}|\mathbf{z})$  and  $p(\mathbf{z})$  are usually much simpler than  $p_{\theta}(\mathbf{x})$ .

# Latent Variable Models (LVM)

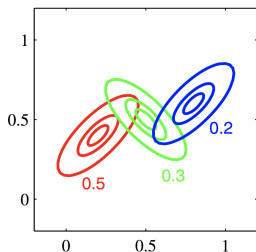
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## Examples

### *Mixture of Gaussians*



- ▶  $p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\boldsymbol{\mu}_{\mathbf{z}}, \boldsymbol{\Sigma}_{\mathbf{z}})$
- ▶  $p(\mathbf{z}) = \text{Categorical}(\boldsymbol{\pi})$

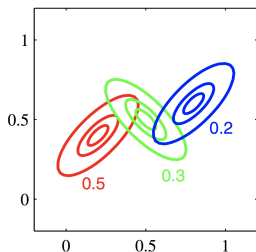


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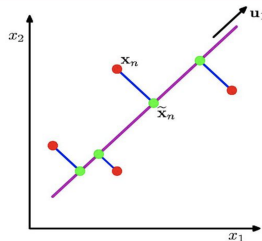
## Examples

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### PCA Model



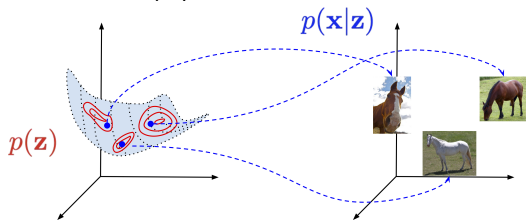
- ▶  $p_{\theta}(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2\mathbf{I})$
- ▶  $p(\mathbf{z}) = \mathcal{N}(0, \mathbf{I})$

## MLE for LVM

$$\sum_{i=1}^n \log p_{\theta}(\mathbf{x}_i) = \sum_{i=1}^n \log \int p_{\theta}(\mathbf{x}_i | \mathbf{z}_i) p(\mathbf{z}_i) d\mathbf{z}_i \rightarrow \max_{\theta}.$$

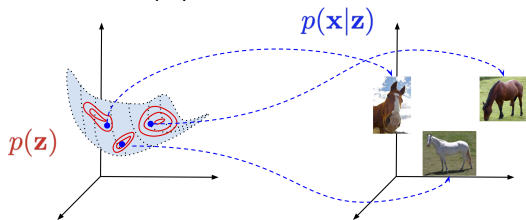
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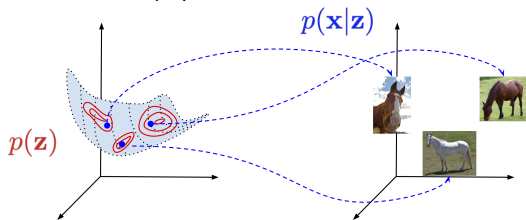
## Naive Approach

$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})} p_{\theta}(\mathbf{x}|\mathbf{z}) \approx \frac{1}{K} \sum_{k=1}^K p_{\theta}(\mathbf{x}|\mathbf{z}_k),$$

where  $\mathbf{z}_k \sim p(\mathbf{z})$ .

## MLE for LVM

$$\sum_{i=1}^n \log p_{\theta}(\mathbf{x}_i) = \sum_{i=1}^n \log \int p_{\theta}(\mathbf{x}_i | \mathbf{z}_i) p(\mathbf{z}_i) d\mathbf{z}_i \rightarrow \max_{\theta}.$$



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where  $\mathbf{z}_k \sim p(\mathbf{z})$ .

**Challenge:** As the dimensionality of  $\mathbf{z}$  increases, the number of samples needed to adequately cover the latent space grows exponentially.

image credit: [https://jmtomczak.github.io/blog/4/4\\_VAE.html](https://jmtomczak.github.io/blog/4/4_VAE.html)

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# ELBO Derivation I

## Inequality Derivation

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$$\log p_{\theta}(\mathbf{x}) = \log \int p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z} = \log \int \frac{q(\mathbf{z})}{q(\mathbf{z})} p_{\theta}(\mathbf{x}, \mathbf{z}) d\mathbf{z}$$



# ELBO Derivation I

## Inequality Derivation

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Here,  $q(\mathbf{z})$  is any distribution such that  $\int q(\mathbf{z}) d\mathbf{z} = 1$ .

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$$\mathcal{L}_{q, \theta}(\mathbf{x}) = \mathbb{E}_q \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} \leq \log p_{\theta}(\mathbf{x})$$

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This inequality holds for any choice of  $q(\mathbf{z})$ .

## ELBO Derivation II

$$p_{\theta}(\mathbf{z}|\mathbf{x}) = \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{p_{\theta}(\mathbf{x})}$$

### Equality Derivation

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z}$$

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Here,  $\text{KL}(q(\mathbf{z})\|p_{\theta}(\mathbf{z}|\mathbf{x})) \geq 0$ .

## Variational Evidence Lower Bound (ELBO)

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$$\begin{aligned}\mathcal{L}_{q,\theta}(\mathbf{x}) &= \int q(\mathbf{z}) \log \frac{p_{\theta}(\mathbf{x}, \mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \int q(\mathbf{z}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z} \\ &= \mathbb{E}_q \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \text{KL}(q(\mathbf{z})\|p(\mathbf{z}))\end{aligned}$$

### Log-Likelihood Decomposition

$$\log p_{\theta}(\mathbf{x}) = \mathcal{L}_{q,\theta}(\mathbf{x}) + \text{KL}(q(\mathbf{z})\|p_{\theta}(\mathbf{z}|\mathbf{x}))$$

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- Instead of maximizing the likelihood, maximize the ELBO:

$$\max_{\theta} p_{\theta}(\mathbf{x}) \quad \rightarrow \quad \max_{q,\theta} \mathcal{L}_{q,\theta}(\mathbf{x})$$

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- Instead of maximizing the likelihood, maximize the ELBO:

$$\max_{\theta} p_{\theta}(\mathbf{x}) \quad \rightarrow \quad \max_{q,\theta} \mathcal{L}_{q,\theta}(\mathbf{x})$$

- Maximizing the ELBO with respect to the **variational** distribution  $q$  is equivalent to minimizing the KL divergence:

$$\arg \max_q \mathcal{L}_{q,\theta}(\mathbf{x}) \equiv \arg \min_q \text{KL}(q(\mathbf{z})\|p_{\theta}(\mathbf{z}|\mathbf{x})).$$

## Variational Posterior

$$\mathcal{L}_{q,\theta}(\mathbf{x}) = \mathbb{E}_q \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \text{KL}(q(\mathbf{z})\|p(\mathbf{z})) \rightarrow \max_{q,\theta}.$$

What is the optimal distribution  $q^*(\mathbf{z})$  given fixed  $\theta^*$ ?

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Here we got the intuition about  $q(\mathbf{z})$  – it estimates the posterior  $p_{\theta^*}(\mathbf{z}|\mathbf{x})$ .

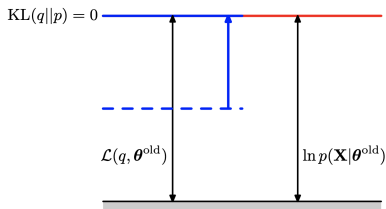
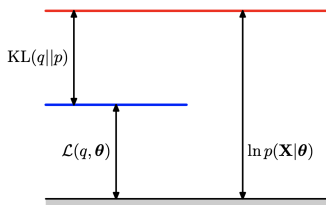
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# Outline

1. Latent Variable Models (LVM) (continued)
2. Variational Evidence Lower Bound (ELBO)
3. Amortized Inference
4. ELBO Gradients, Reparametrization Trick
5. Variational Autoencoder (VAE)

# Parametric Variable Posterior

## Variational Posterior

$$q(\mathbf{z}) = \arg \max_q \mathcal{L}_{q, \theta^*}(\mathbf{x}) = \arg \min_q \text{KL}(q \| p) = p_{\theta^*}(\mathbf{z} | \mathbf{x}).$$

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- ▶  $p_{\theta^*}(\mathbf{z} | \mathbf{x})$  may be **intractable**;
- ▶  $q(\mathbf{z})$  is individual for each data point  $\mathbf{x}$ .



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## Amortized Variational Inference

We restrict the family of possible distributions  $q(\mathbf{z})$  to a parametric class  $q_\phi(\mathbf{z} | \mathbf{x})$ , **conditioned on data  $\mathbf{x}$**  and **parameterized by  $\phi$** .

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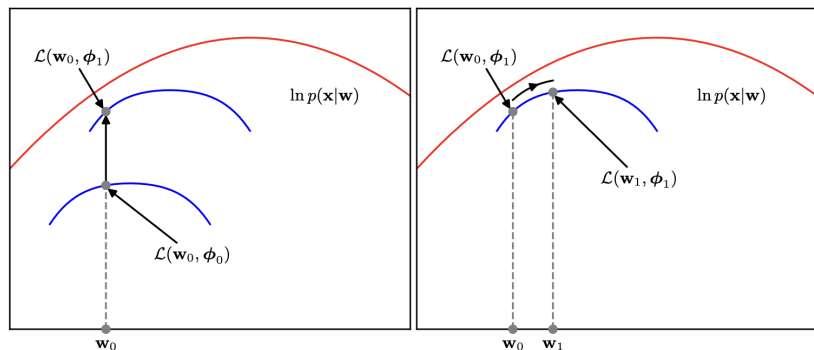
## Gradient Update

$$\begin{bmatrix} \phi_k \\ \theta_k \end{bmatrix} = \left[ \begin{bmatrix} \phi_{k-1} + \eta \cdot \nabla_\phi \mathcal{L}_{\phi, \theta}(\mathbf{x}) \\ \theta_{k-1} + \eta \cdot \nabla_\theta \mathcal{L}_{\phi, \theta}(\mathbf{x}) \end{bmatrix} \right]_{(\phi_{k-1}, \theta_{k-1})}$$

# ELBO optimization

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# ELBO optimization

## ELBO

$$\log p_{\theta}(\mathbf{x}) = \mathcal{L}_{\phi, \theta}(\mathbf{x}) + \text{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p_{\theta}(\mathbf{z}|\mathbf{x})) \geq \mathcal{L}_{\phi, \theta}(\mathbf{x}).$$

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- ▶  $\phi$  denotes the parameters of the variational posterior  $q_{\phi}(\mathbf{z}|\mathbf{x})$ .
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The remaining step is to obtain **unbiased** Monte Carlo estimates of the gradients:  $\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x})$  and  $\nabla_{\theta} \mathcal{L}_{\phi, \theta}(\mathbf{x})$ .

# Outline

1. Latent Variable Models (LVM) (continued)
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## ELBO Gradients: $\nabla_{\theta} \mathcal{L}_{\phi, \theta}(\mathbf{x})$

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### Naive Monte Carlo Estimation

$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) d\mathbf{z} \approx \frac{1}{K} \sum_{k=1}^K p_{\theta}(\mathbf{x}|\mathbf{z}_k), \quad \mathbf{z}_k \sim p(\mathbf{z}).$$

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The variational posterior  $q_{\phi}(\mathbf{z}|\mathbf{x})$  typically concentrates more probability mass in a much smaller region than the prior  $p(\mathbf{z})$ .

# ELBO Gradients: $\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x})$

## Gradient $\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x})$

Unlike the  $\theta$ -gradient, the density  $q_{\phi}(\mathbf{z}|\mathbf{x})$  now depends on  $\phi$ , so standard Monte Carlo estimation can't be applied:

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### Reparametrization Trick (LOTUS Trick)

Assume  $\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})$  is generated by a random variable  $\epsilon \sim p(\epsilon)$  via a deterministic mapping  $\mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon)$ . Then,

$$\mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z}|\mathbf{x})} \mathbf{f}(\mathbf{z}) = \mathbb{E}_{\epsilon \sim p(\epsilon)} \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon))$$



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**Note:** The LHS expectation is with respect to the parametric distribution  $q_{\phi}(\mathbf{z}|\mathbf{x})$ , while the RHS is for the non-parametric  $p(\epsilon)$ .

# ELBO Gradients: E-Step ( $\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x})$ )

Reparametrization Trick (LOTUS Trick)

$$\nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \mathbf{f}(\mathbf{z}) d\mathbf{z} = \nabla_{\phi} \int p(\epsilon) \mathbf{f}(\mathbf{g}_{\phi}(\mathbf{x}, \epsilon)) d\epsilon$$

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where  $\epsilon^* \sim p(\epsilon)$ .

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where  $\epsilon^* \sim p(\epsilon)$ .

## Variational Assumption

$$p(\epsilon) = \mathcal{N}(0, \mathbf{I}); \quad \mathbf{z} = \mathbf{g}_{\phi}(\mathbf{x}, \epsilon) = \sigma_{\phi}(\mathbf{x}) \odot \epsilon + \mu_{\phi}(\mathbf{x});$$

$$q_{\phi}(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^2(\mathbf{x})).$$

Here,  $\mu_{\phi}(\cdot)$  and  $\sigma_{\phi}(\cdot)$  are parameterized functions (outputs of a neural network).

Thus, we can write  $q_{\phi}(\mathbf{z}|\mathbf{x}) = \text{NN}_{e, \phi}(\mathbf{x})$ , the **encoder**.

## ELBO Gradient: E-Step ( $\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x})$ )

$$\nabla_{\phi} \mathcal{L}_{\phi, \theta}(\mathbf{x}) = \nabla_{\phi} \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) d\mathbf{z} - \nabla_{\phi} \text{KL}(q_{\phi}(\mathbf{z}|\mathbf{x}) \| p(\mathbf{z}))$$

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### Reconstruction Term

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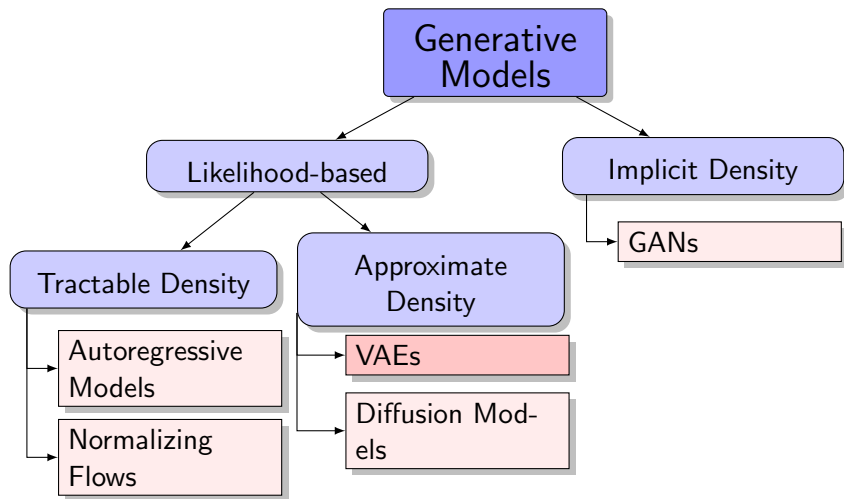
This expression admits a closed-form analytic solution.



# Outline

1. Latent Variable Models (LVM) (continued)
2. Variational Evidence Lower Bound (ELBO)
3. Amortized Inference
4. ELBO Gradients, Reparametrization Trick
5. Variational Autoencoder (VAE)

# Generative Models Zoo



# Variational Autoencoder (VAE)

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**Note:** The encoder  $q_\phi(\mathbf{z}|\mathbf{x})$  isn't needed during generation.



# Variational Autoencoder

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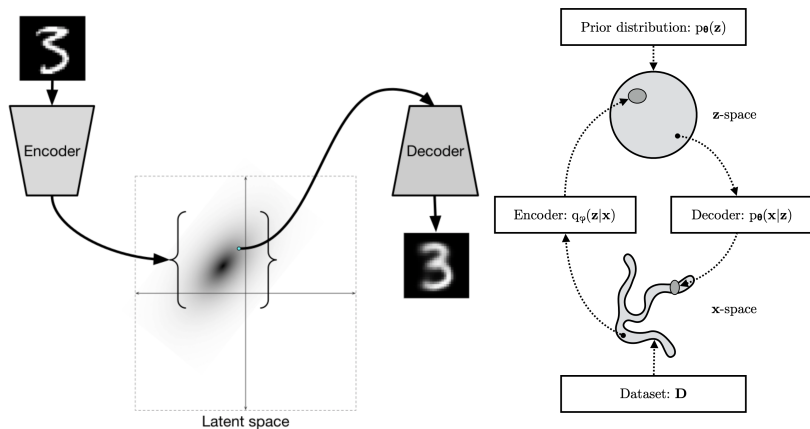
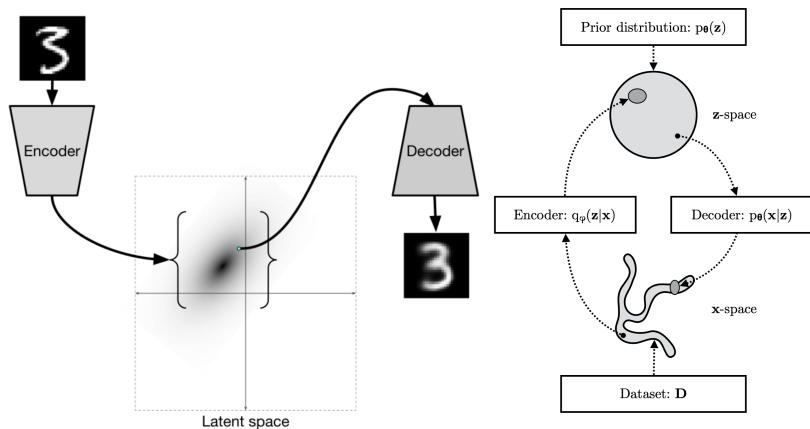


image credit: <http://ijdykeman.github.io/ml/2016/12/21/cvae.html>  
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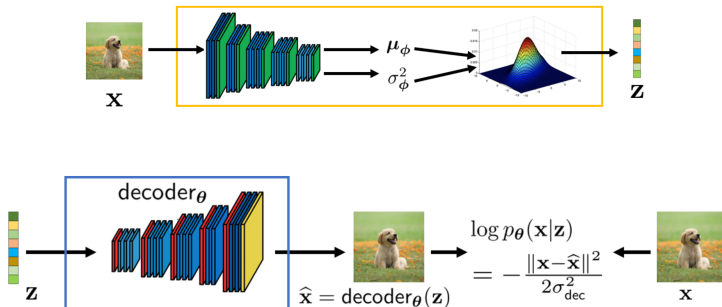


VAEs are widely used as a preliminary stage of projecting data onto low-dimensional space.

image credit: <http://ijdykeman.github.io/ml/2016/12/21/cvae.html>  
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# Variational Autoencoder

- ▶ The encoder  $q_\phi(\mathbf{z}|\mathbf{x}) = \text{NN}_{e,\phi}(\mathbf{x})$  outputs  $\mu_\phi(\mathbf{x})$  and  $\sigma_\phi(\mathbf{x})$ .
- ▶ The decoder  $p_\theta(\mathbf{x}|\mathbf{z}) = \text{NN}_{d,\theta}(\mathbf{z})$  outputs parameters of the observed data distribution.



# VAE vs Normalizing Flows

	VAE	NF
Objective	ELBO $\mathcal{L}$	Forward KL/MLE
Encoder	stochastic $\mathbf{z} \sim q_{\phi}(\mathbf{z} \mathbf{x})$	deterministic $\mathbf{z} = \mathbf{f}_{\theta}(\mathbf{x})$ $q_{\theta}(\mathbf{z} \mathbf{x}) = \delta(\mathbf{z} - \mathbf{f}_{\theta}(\mathbf{x}))$
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## Theorem

MLE for a normalizing flow is equivalent to maximizing the ELBO for a VAE where:

$$p_{\theta}(\mathbf{x}|\mathbf{z}) = \delta(\mathbf{x} - \mathbf{f}_{\theta}^{-1}(\mathbf{z})) = \delta(\mathbf{x} - \mathbf{g}_{\theta}(\mathbf{z}));$$

$$q_{\theta}(\mathbf{z}|\mathbf{x}) = \delta(\mathbf{z} - \mathbf{f}_{\theta}(\mathbf{x})).$$

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Nielsen D., et al., *SurVAE Flows: Surjections to Bridge the Gap Between VAEs and Flows*, 2020

# Summary

- ▶ LVMs introduce latent representations for observed data, enabling more interpretable models.
- ▶ LVMs maximize the variational evidence lower bound (ELBO) to obtain maximum likelihood estimates for the parameters.
- ▶ Parametric posterior distribution  $q_{\phi}(\mathbf{z}|\mathbf{x})$  makes the method scalable.
- ▶ The reparametrization trick provides unbiased gradients with respect to the variational posterior  $q_{\phi}(\mathbf{z}|\mathbf{x})$ .
- ▶ The VAE model is a latent variable model parameterized by two neural networks: a stochastic encoder  $q_{\phi}(\mathbf{z}|\mathbf{x})$  and a stochastic decoder  $p_{\theta}(\mathbf{x}|\mathbf{z})$ .
- ▶ Nowadays, the main role of VAEs is to project data into low-dimensional latent space.