Interfacing Data Transfer Models

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Course Title: Peripherals, Interfacing and Embedded Systems

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Lecture References:

Book:

Microprocessor Architecture, Programming and Applications with 8085 (Part-III), Author: Ramesh Gaonkor

Lecture Materials:

Ramesh Gaonkar

Peripherals (I/Os) and Interfacing

- ▶ The primary functions of the microprocessor/microcontroller are:
 - to accept data from input devices such as keyboards and A/D converters
 - read instructions from the memory
 - process data according to the instructions and
 - send the results to output devices such as LEDs, printers and monitors.
- ► The input and output devices are called either peripherals or I/O.
- Designing logic circuits (hardware) and writing instructions (software) to enable microprocessor to communicate with I/Os is called interfacing and logic circuits are called I/O ports or interfacing devices.

Transmit or receive data occurs either in

Parallel Mode:

- The entire data (i.e., 8-bit or 16-bit) is transferred at one time
- In 8085, an 8-bit data is transferred simultaneously over the 8-data lines (i.e., data bus)
- Connected via direct cable that has one wire for each bit in a character of data code being used by the terminal
- With multiple wires, all the bits of a characters can be transmitted between the terminals and computer at once
- Disadv: Very expensive & no practice over long distance
- Devices use parallel mode: Keyboards, 7-segment Display, Data Converters and Memory.

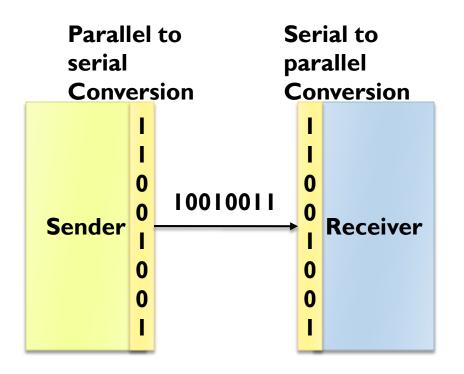
Serial Mode:

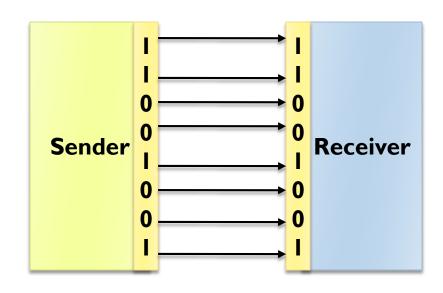
- Bits of each character are sent down to a line one by one
- Complicated process because machine needs to know how to decompose and to reconstruct of bits at each respective end
- Data are transferred one bit at a time over a single line between the MP and a peripheral.
- A data is converted to a stream of bits
- Devices use serial mode: CRT, Printers, USB, Modems, Telephone lines.

Serial Mode:

- RS232- Typical computer COM port
- SCI- Serial Communication interface, uses the universal asynchronous receiver/transmitter (USART) or UART
- SPI Serial peripheral interface

Two basic modes of data transmission





Serial Transmission

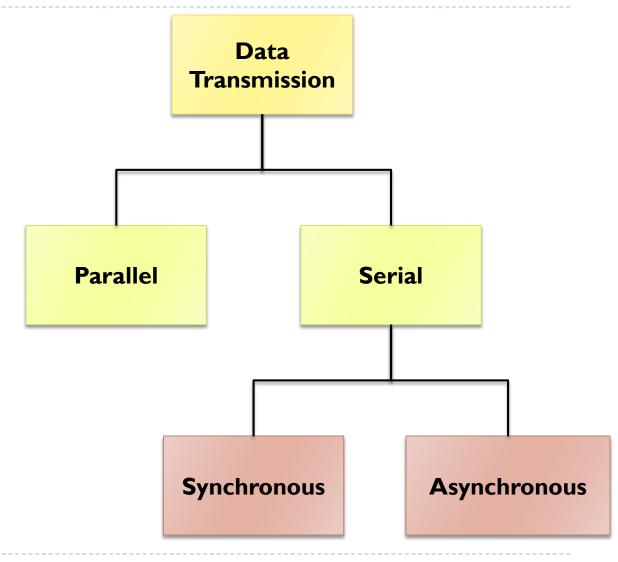
Parallel Transmission

Serial

- Cheaper
- Slower

Parallel

- Faster
- Limited to small distances
- Simultaneous transmission
- Requires separate data lines
- Bits must stay synchronized
- Expensive



Type of Serial Communication

Microprocessor/microcontroller communicates with peripherals in either of two transmission formats:

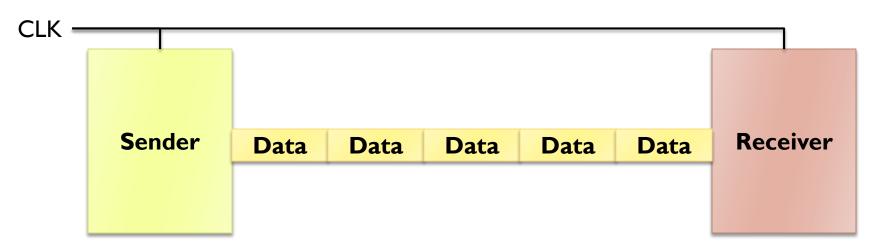
Synchronous Transmission:

- Synchronous means at the same time
- The transmit and receive are synchronized with same clock
- Block of data can be sent
- It is used for high-speed data transmission

Type of Serial Communication

Synchronous Transmission:

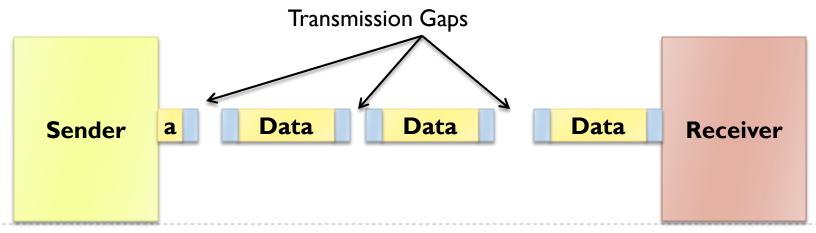
- Data rates are dependent on clock rates
- Continuously transmitting characters to remain in sync.
- More efficient: Less overhead than asynchronous transmission



Type of Serial Communication

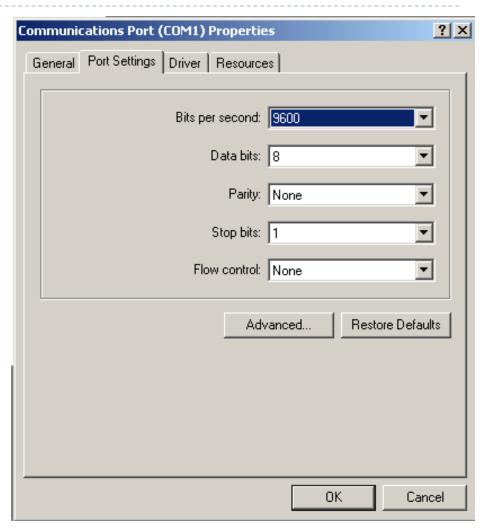
Asynchronous Transmission:

- Asynchronous means irregular intervals
- Each byte is encoded for transmission
 - Start and stop bits
- No need for sender and receiver synchronization
- It is used for low-speed data transmission
- Data transfer between microprocessor and peripherals are primarily *asynchronous*.



Asynchronous Serial Transmission

- Bits are transmitted in a specified format
- Defined by settings on transmitter and receiver:
 - Start Bit
 - Data Bits
 - Parity Bits
 - Stop Bits

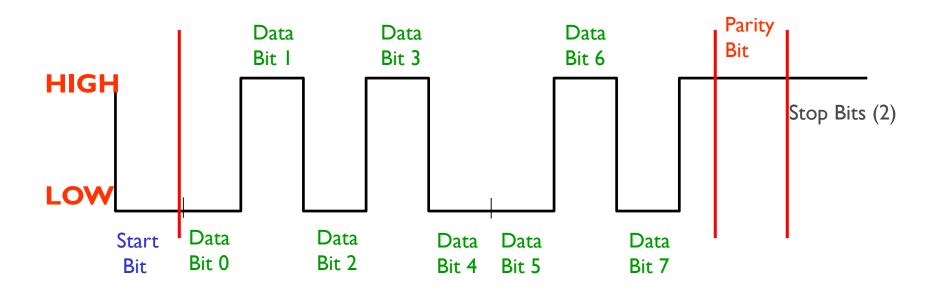


Example of Windows setting

Asynchronous Serial Transmission

One Data Package

♦ Four parts per package



Performance Comparison

- Example Scenario: Consider a character consists of 01001011
- ▶ **Asynch**: 250 char x (8 data + 2 start/stop) = 2500 bits
- Assuming I **Synch character** after each 50 Character Transmission **Synch**: (250 + 5 synch char) x 8 bits) = 2040 bits
- Thus, for the scenario Synch is approximately 20% more efficient than Aysnch
- Note: Mostly, host computers adopt Synch transmission.

Conditions for Data Transfer

Microprocessor Controlled Data Transfer

- Unconditional Data Transfer
 - ▶ MP thinks of that a peripheral is always available
- Data Transfer with Polling
 - Polling a peripheral or set of peripherals regularly
- Data Transfer with Interrupt
 - A peripheral is ready to transfer data and sends an INT signal
 - MP stops current execution and send the peripheral an INTA signal
- Data Transfer with READY Signal
 - If peripherals response time is slower than the execution time of MP then T states are extended to complete data transfer
- Data Transfer with Handshake Signals
 - Signal are exchanged between MP and peripheral prior to data transfer

Conditions for Data Transfer

Peripheral Controlled Data Transfer

- This type is applied when a peripheral is much faster than the MP
- In case of Direct Memory Access (DMA), the DMA controller sends HOLD signal to the MP and MP releases its Data and Address Bus to the DMA controller
- Thereupon, data transferred at high-speed without the intervention of MP

Thank You!!

