

Plan: Motion Capture and Co

- Introduction and past of mocap
- ...

M2R 2

The idea behind motion capture (mocap)

Modeling Motion

■ Heuristics (Procedural)

- Rules of thumb, guidelines, cheap hacks
- Keyframing, traditional cel animation

■ Simulation

- Use of physics
- Dynamics

■ Use of measured data

- Motion capture

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The idea behind motion capture (mocap)

■ You want realistic human motion?

- Simulation: uhm!! Stuff!!
- Use an actual human

■ Motion capture is the recording of human body movement (or other movement) for immediate or delayed analysis and playback

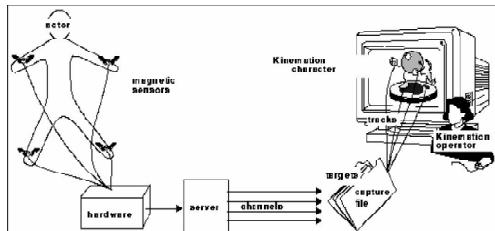
- The person moves the way the character is supposed to move

- Motion capture employs special sensors, called trackers, to record the motion of a human performer

- The recorded data is then used to generate the motion for an animation

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The idea behind motion capture (mocap)



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Uses of motion capture

■ Medicine

- biomechanics
- prosthetics
- physical therapy
- surgery

■ Sports

- motion analysis and improvement

■ Military

- targeting

■ Entertainment

- film
- games



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Two problems

motion capture + editing/retargeting



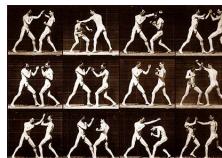
Motion capture

Editing/Retargeting, playback

?

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Eadweard Muybridge (1830-1904)



<http://www.cotar.net.com.br/photo/great/Muybridge.htm>



http://en.wikipedia.org/wiki/Image:The_Horse_in_Motion.jpg



M2R 8

Etienne-Jules Marey (1830-1904)



http://www.nrw-forum.de/img_ausst/img_press/Marey.jr



<http://www.inrp.fr/Tecne/Aceosp/Actimage/Images/Marey2.jpg>

- birds
- photographic gun



<http://www.rickwesd.com/Sht%20Marey%20COMM%20158/Images/Marey%20Photo%20Gun.jpg>

M2R 9

Harold Edgerton (1903-1990)

- high speed and stop motion photography
- exposures as small as a millionth of a second
- electronic flash
- stroboscope

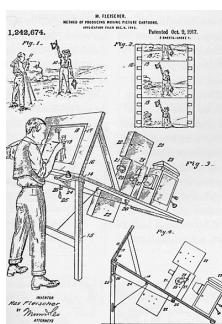


<http://www.personal.psu.edu/users/a/ark176/Assignment%204.htm>

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The rotoscope

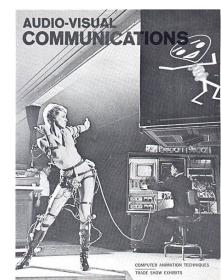
- Max Fleischer, 1915
- performer is filmed
- frame by frame playback
- "animator" traces the frame
- produces realistic motion for animated films
- Disney, Snow White, 1940's



M2R 11

Lee Harrison III, 60's and 70's

- SCANIMATE, ANIMAC, CAESER
- analog!
- prosthetic system, a motion capture harness
 - potentiometers, convert rotation or linear motion to a change in electrical resistance
 - Lincoln Logs as armatures
- TV flying logos
 - Electric Company



<http://accad.osu.edu/~waynec/history/lesson12.html>

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“Modern” era of mocap, 1970’s-present

- more players
- commercial players
- multiple uses
- 70’s: development of magnetic systems
- 80’s: development of optical systems
- 90’s: mocap is hot,
- 00’s: mocap is used more frequently for feature films

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Plan: Motion Capture and Co

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- Motion capture with markers
 - Types of mocap systems
 - ...

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Types of mocap systems (Alberto Menache)

- Outside-In
 - sources (e.g., reflective markers) on body
 - external sensors (e.g., cameras)
 - optical systems
- Inside-Out
 - sensors on body
 - external sources
 - magnetic systems
- Inside-In
 - sources and sensor on body (e.g. cyber gloves)
 - mechanical systems

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Implementation of a motion capture system

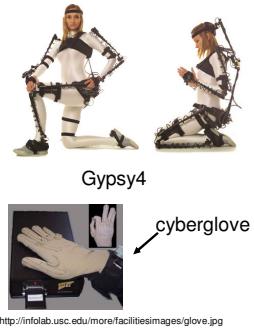
- Prosthetic
 - e.g. cyber glove
- Acoustic
 - sensor on the performer emit sound which is detected by captors
- Magnetic
 - Sensor on the performer captured signal emitted by the room structure
- Optical
 - Based on camera which tell the positions of sensor on performer

Liverman, The Animator's Motion Capture Guide

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Mechanical/prosthetic capture

- Inside-In
- **external structure** attached to **performer**
- structure detects changes
 - optic
 - mechanical



<http://infolab.usc.edu/more/facilities/images/glove.jpg>

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Mechanical/prosthetic capture

- advantages
 - computes rotations directly
 - portable, unlimited range
 - less expensive
 - can capture multiple performances simultaneously
 - no built in positional reference
- disadvantages
 - external structure unwieldy
 - cannot change the configuration, i.e., a hand capture can't be used for an arm

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Acoustic capture

- **Outside/In**
- Active Markers –
 - transmitters are attached to the performer and sequentially emit audio signal, a "click"
 - receivers measure the time to receive the signal, triangulate and compute the position of the transmitter
- advantages
 - no occlusion
- disadvantages
 - cables unwieldy
 - rate of transmission not high enough to support enough transmitters
 - size of the capture area is limited
 - sound reflections can reduce accuracy

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Magnetic capture

- **Outside/In**
- receivers are attached to the performer's body
- compute the **position and orientation** from receiver to central **magnetic transmitter**
 - AC and DC systems
- advantages
 - no occlusion
- disadvantages
 - cabling can interfere with movement (improvements?)
 - capture area can be limited by transmitter
 - metal in vicinity can interfere with system
 - capture volume can be limited

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Optical capture

- **markers** are attached to a performer
 - **passive** reflective markers
 - **active** reflective markers
- a **system of cameras** record the position of the markers



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Optical capture (active): Ascension Reactor

- **active** optical system
 - 30 infrared (IR) markers
 - each marker fires sequentially (like an acoustic system)
- 544 sensors ("cameras") along bars
 - each set of 4 parallel bars determines a particular coordinate, either x, y, or z
- capture rate 900 measurements/sec, i.e., 30 frames/sec



<http://www.ascension-tech.com/images/reactorlarge.jpg>

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Optical capture

- advantages
 - freedom of movement
 - high quality capture
 - high throughput
 - fast sampling (200 fps at a high resolution)
 - can capture fast motions
 - can have a large capture space
 - can capture many markers
 - cost \$\$\$
- disadvantages
 - **occlusion**, markers are can be hidden from the camera
 - additional performers will increase occlusion
 - may be able to add redundant cameras
 - marker **crossover**, which marker are you looking at?
 - extensive post processing (the marker's have to be located and identified)

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Major optical players

- | | |
|---|---|
| Motion Analysis | ViconPeak |
| ■ http://www.motionanalysis.com | ■ http://www.viconpeak.com/ |
| Films | Films |
| ■ Lord of the Rings | ■ Polar Express |
| ■ King Kong | ■ Harry Potter and the Prisoner of Azkaban |
| ■ Matrix | ■ The Hulk |
| ■ Final Fantasy | ■ Spider Man |
| Games | Games |
| ■ NBA Live 2004 | ■ All-Star Baseball 2002 |
| ■ Grand Theft Auto III | ■ Buffy the Vampire Slayer |
| ■ Mortal Kombat 4 (Midway) | ■ Everquest II |
| | ■ NHL 2K3 (Mocap by Red Eye Studio) |

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 - Mocap pipeline in details
 - ...

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Mocap pipeline

- planning for capture
- setup and calibrate system
- **capture performer, obtain marker positions**
- retarget to a **character**
- edit/cleanup

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Skeleton mocap

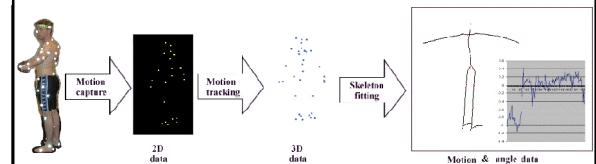
- A target skeleton is defined
- Marker at each joint of the skeleton



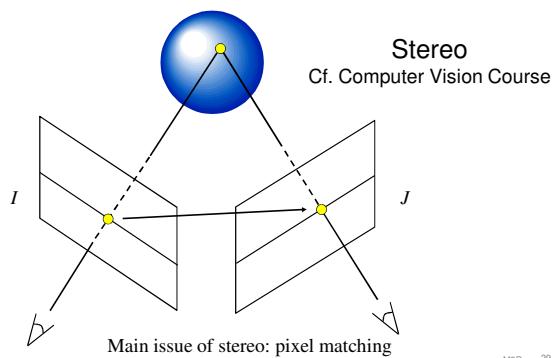
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Skeleton mocap: problems for each frame

- Motion capture/Extraction:
 - markers need to be **identified** in the image → determines 2d position
 - problem: **occlusion**, marker is not seen → use more cameras
- Motion tracking:
 - markers need to be **convert to 3D points and labeled**
 - **compute 3d position**: if a marker is seen by at least 2 cameras then its position in 3d space can be determined
 - which marker is which? (problem of skeleton fitting)



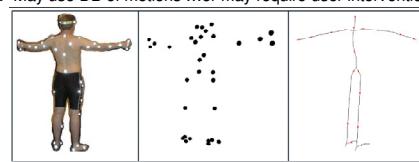
Principle 1: triangulation



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Skeleton mocap: Process of skeleton fitting

- Initial position before capture
 - identify correspondence between each marker and each joint
- During the motion, for each body joint
 - Based on previous position and speed, determine the area where the joint should be → determine the marker
- Problem: crossover, markers exchange labels
 - Skeleton tracking (Kalman filter, etc.) if few milliseconds
 - → May use DB of motions ...or may require user intervention



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Skeleton mocap example

- Mocap_skeleton_10person.wmv

M2R 31

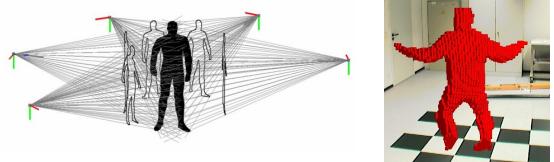
Plan: Motion Capture and Co

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 - Markerless motion capture

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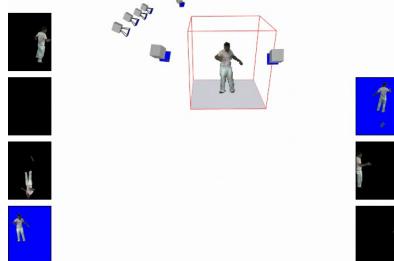
Markerless motion capture

- Less precise than marker-based mocap
- Visual hull + skeleton fitting
 - Visual hull → volumetric data (voxel)
 - Volumetric data (voxel) → skeleton



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Example of visual hull

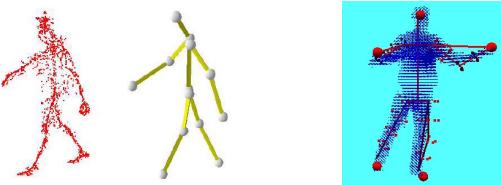


[Michoud et al 2007/10]

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Markerless motion capture

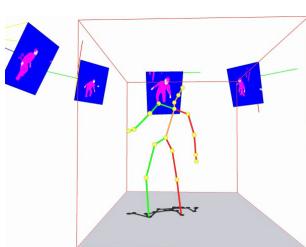
- Visual hull + skeleton fitting
 - Skeleton fitting
 - Often based on a database of skeleton positions
- Less precise than marker-based mocap



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Markerless motion capture

- Video



[Michoud et al 2007/10]

M2R 36

Kinect

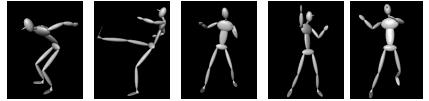
- Same idea of skeleton fitting
 - 3D volumetric data are a depth-buffer (~zbuffer)
 - Get from infra-red projector/camera
 - 20 million images with 200 distinct poses




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Skeleton mocap

- Ok we got the skeleton

and now? We would like to capture skin/face/cloth



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- Face/Skin Motion Capture
 - With markers

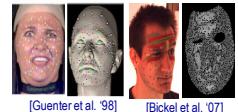
M2R 39

Motivation: Human Face Animations

- Face animations are difficult to model
- Movies and games increasingly use [performance capture](#)



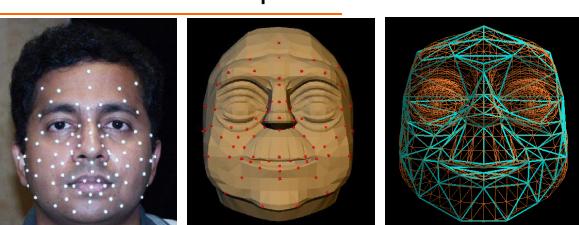
[© IGN Entertainment \(www.ign.com\), Electronic Arts](#)



[Guenther et al. '98] [Bickel et al. '07]

M2R 40

Facial motion capture

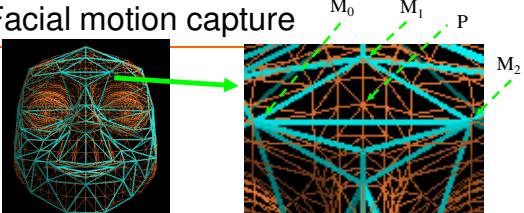


Marker based Motion Capture → applied to Gizmo

Two meshes (mesh of markers and mesh of face) need to match

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Facial motion capture

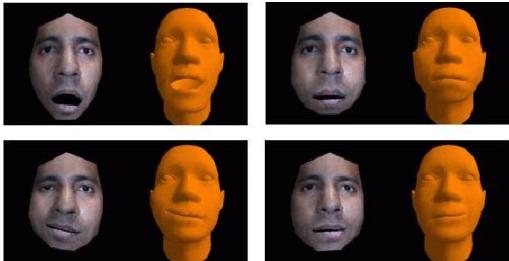


- Green: mesh of the markers; Red: mesh of the model
- P of the model → inside triangle $M_0M_1M_2$ of markers mesh
- Compute barycentric coordinates of P in the triangle

→ when M_i moves it is easy to compute the new position of P

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Facial motion capture



+ VIDEO: [facial_mocap?.avi](#)

M2R 43

Capture of the skin



Capturing and Animating Skin Deformation in Human Motion
Sang Il Park, Jessica K. Hodgins
SIGGRAPH 2006

→ [Video](#)

<http://graphics.cs.cmu.edu/projects/muscle/>

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 - With markers
 - With scanner/structured light

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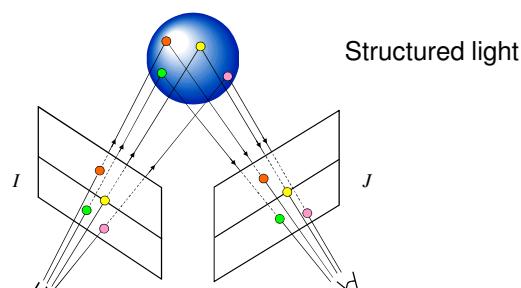
Laser scanner



+ very accurate <0.01mm
- >10sec per scan → inaccurate for motion of face

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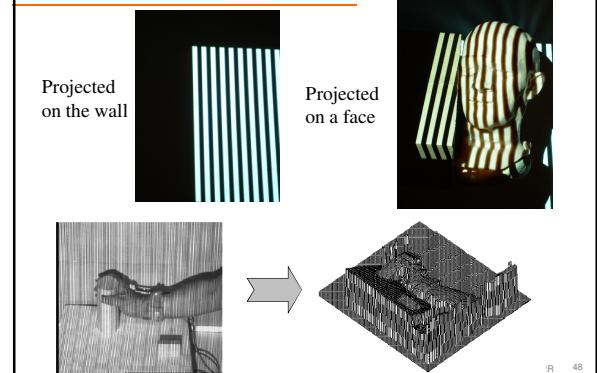
Triangulation with Structured light



Remember: main issue of stereo is pixel matching
→ solved here with color

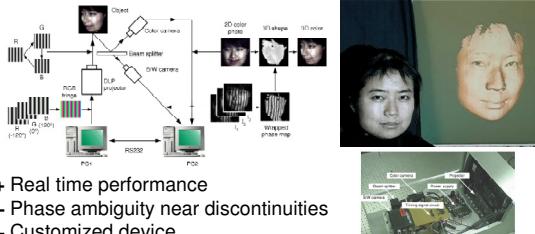
M2R 47

Structured light: Example



M2R 48

[Zhang05]: Digital fringe range sensor



S. Zhang and P. Huang, "High-resolution Real-time 3-D Shape Measurement",
Journal of Optical Engineering, 2006
Working Volume: 10-2000mm - Accuracy: 0.025%
Spatial Resolution: 532x500 - Speed: 120Hz

M2R 49

[Zhang05]: Spacetime stereo

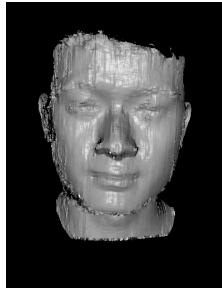
Input stereo video:



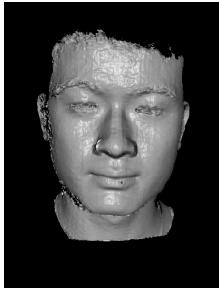
656x494x60fps videos captured by firewire cameras
Markerless Face Capture and Automatic Model Construction Using Color Structured Light
<http://grail.cs.washington.edu/projects/stfaces/>

M2R 50

Spacetime stereo, comparison

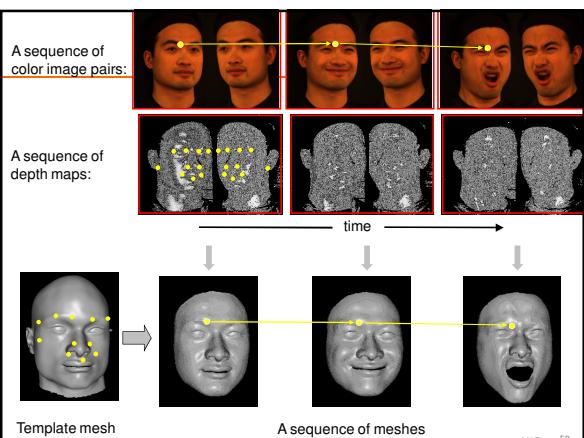


Frame-by-frame stereo
WxH=15x15 window



Spacetime stereo
WxHxT=9x5x5 window

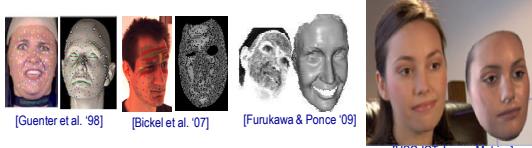
M2R 51



M2R 52

Bilan: Face Capture with Markers

- Markers and face paint (inpainting required for texture)



- Structured light (interleave regular light for texture)



M2R 53

Videos

- Video
[makerless_face_mocap_structuredlight.avi](#)

- « makeup»-based Markers → MOVA
 - Phosphor
 - <http://www.mova.com/technology.php>

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- Face/Skin Motion Capture
 - With markers
 - With scanner/structured light
 - Markerless [Bradley et al. 2010]

M2R 55

Passive Facial Performance Capture

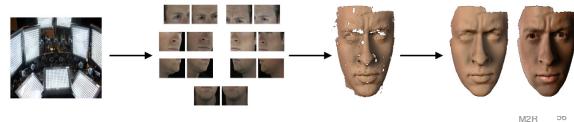
Key Observations:

(remember that stereo issue are matching)

1. Skin has high-frequency details up close (pores, freckles, etc..)
2. Details are stable over time

Idea:

- Capture skin details with optically zoomed camera setup
- Skin details allow for accurate 3D reconstruction
- Temporal stability of details allows automatic tracking



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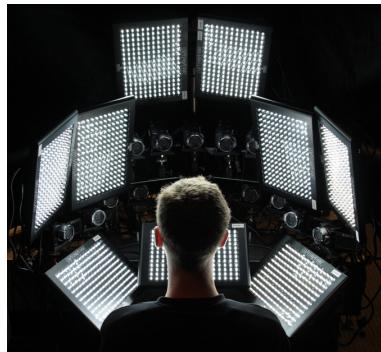
Skin Detail Acquisition



- 14 cameras – 7 binocular pairs – zoomed in
- Bright, uniform illumination – no structured lighting
→ remember that stereo issue are pixel matching, solved here skin details like pores, ...

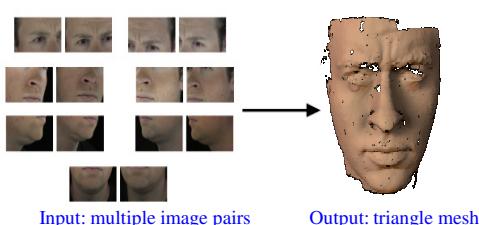
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Remark: light is very important



M2R 58

Multi-View Reconstruction

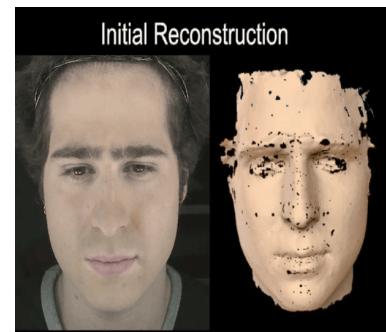


- Extended reconstruction method:
Pair-wise stereo + merging

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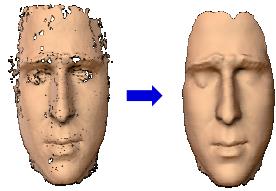
Multi-View Reconstruction

- Each frame reconstructed individually



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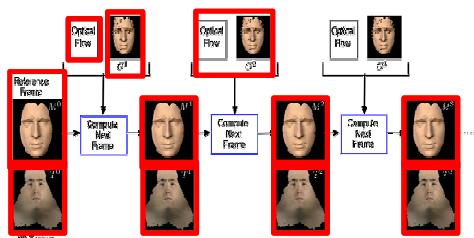
Manual Cleanup of First Frame



- Cut away hair and fill holes
- These steps performed only once per sequence

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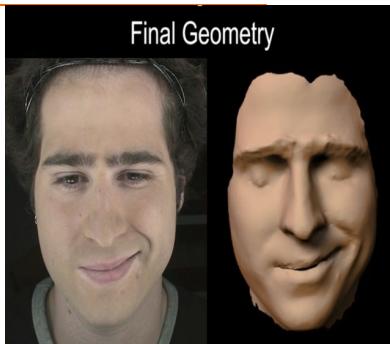
Temporal coherence



- Based on optical flow (2D motion vectors from video images)
 - Propagate first mesh forward using optical flow and initial geometry
 - Compute per-frame 2D textures

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Results + video



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Fine skin details: procedural



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 - With markers
 - With scanner/structured light
 - Markerless [Bradley et al. 2010]
 - Cloth capture

M2R 65

Markerless Cloth Capture

- Full bodies and garments



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Conclusions

- Important tool, not the entire solution
- Stylistic choice – realism
- The performance matters
- Still requires
 - artistry
 - animation
 - a lot of work
- Techniques for editing/retargeting is important

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Common errors when considering motion capture

- using motion capture makes the animator's job easier
- using motion capture will save time
- using motion capture will save money
- people underestimate the amount of planning that is needed prior to the capture session
- people are unorganized during the capture session
- people underestimate the importance of using a good motion performer
- people think that they can fix bad motion data after the capture session

The Animator's Motion Capture Guide, Liverman

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References

- Matt Liverman, *The Animator's Motion Capture Guide: Organizing, Managing and Editing*
- Alberto Menache, *Understanding Motion Capture for Computer Animation and Video Games*
- David J Sturman, "A Brief History of Motion Capture for Computer Character Animation", *Character Motion Systems, SIGGRAPH 94, Course 9*
- Many more on the web ...

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