

# A higher-order adaptive DPG Method for convection-diffusion problems

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# Talk outline

- 1 The Discontinuous Petrov-Galerkin (DPG) method: discrete stability.
  - An issue for higher order methods and **singular perturbation problems**.
  - Connections to Variational Multiscale (VMS) methods
- 2 Convection-diffusion and Navier-Stokes with small diffusion.
  - Stable in pre-asymptotic regions, automatic adaptivity.
  - Avoids artificial diffusion and stabilization parameters.

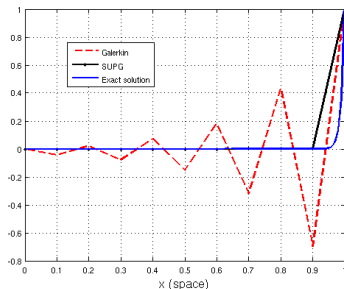


Figure: Discrete stability issues in convection-diffusion.

# DPG: a minimum residual method via optimal testing

- Given a trial space  $U$  and Hilbert test space  $V$ ,

$$b(u, v) = \ell(v) \iff Bu = \ell, \quad \begin{aligned} \langle Bu, v \rangle_V &:= b(u, v) \\ \langle \ell, v \rangle_V &:= \ell(v). \end{aligned}$$

- We seek to minimize the **dual residual** over  $U_h \subset U$

$$J(u_h) = \frac{1}{2} \|Bu_h - \ell\|_{V'}^2 \iff b(u_h, v_{\delta u}) = \ell(v_{\delta u}), \quad \forall \delta u \in U_h$$

- Computation of  $v_{\delta u} := R_V^{-1} B \delta u$  involves solving

$$(v_{\delta u}, \delta v)_V = b(\delta u, \delta v), \quad \delta u \in U_h, \quad \forall \delta v \in V.$$

This is global and infinite-dimensional. Solution: localize using **discontinuous test functions**, and approximate using an **enriched space**  $V_h \subset V$ , where  $\dim(V_h) > \dim(U_h)$  elementwise.

# Properties of DPG

- Stiffness matrices are **symmetric positive-definite**. For trial/test bases  $\{\phi_j\}_{j=1}^m$  and  $\{v_i\}_{i=1}^n$ , with  $B_{ji} = b(\phi_j, v_i)$  and  $l_i = \ell(v_i)$ . DPG solves

$$\left(B^T R_V^{-1} B\right) u = \left(B^T R_V^{-1}\right) l,$$

For localizable norms and discontinuous testing,  $R_V$  is block diagonal.

- DPG provides the best approximation in the **energy norm**

$$\|u\|_E = \|Bu\|_{V'} = \sup_{v \in V \setminus \{0\}} \frac{|b(u, v)|}{\|v\|_V}.$$

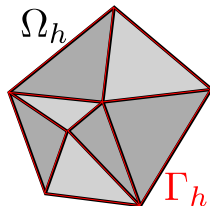
- The energy error is computable through the **error representation function**  $e$  defined through  $(e, \delta v)_V = \ell(v) - b(u_h, \delta v)$  for all  $\delta v \in V$ .

$$\|u - u_h\|_E = \|B(u - u_h)\|_{V'} = \|R_V^{-1}(I - Bu_h)\|_V = \|e\|_V$$

# Ultra-weak formulation for convection-diffusion

The first order convection-diffusion system:

$$A(u, \sigma) := \begin{bmatrix} \nabla \cdot (\beta u - \sigma) \\ \frac{1}{\epsilon} \sigma - \nabla u \end{bmatrix} = \begin{bmatrix} f \\ 0 \end{bmatrix}.$$



The variational formulation is

$$b\left((u, \sigma, \hat{u}, \hat{f}_n), (v, \tau)\right) = (u, \nabla_h \cdot \tau - \beta \cdot \nabla_h v)_{\Omega_h} + (\sigma, \epsilon^{-1} \tau + \nabla_h v)_{\Omega_h} \\ - \langle \llbracket \tau \cdot n \rrbracket, \hat{u} \rangle_{\Gamma_h} + \left\langle \hat{f}_n, \llbracket v \rrbracket \right\rangle_{\Gamma_h},$$

where  $\hat{f}_n := \beta_n u - \sigma_n$  and  $\left\langle \hat{f}_n, \llbracket v \rrbracket \right\rangle_{\Gamma_h}$  is defined

$$\left\langle \hat{f}_n, \llbracket v \rrbracket \right\rangle_{\Gamma_h} := \sum_K \int_{\partial K} \text{sgn}(\vec{n}) \hat{f}_n v.$$

# Construction of a test norm: adjoints and energy estimates

$$b(\mathbf{U}, \mathbf{V}) = (u, \nabla \cdot \tau - \beta \cdot \nabla v)_{\Omega_h} + (\sigma, \epsilon^{-1} \tau + \nabla v)_{\Omega_h} + \text{boundary terms}$$

Recover  $\|u, \sigma\|_{L^2(\Omega)}^2$  with conforming  $(v, \tau)$  satisfying the *adjoint equations*

$$\begin{aligned} \nabla \cdot \tau - \beta \cdot \nabla v &= u \\ \frac{1}{\epsilon} \tau + \nabla v &= \sigma \end{aligned}, \quad \text{boundary terms} = 0$$

“Necessary” conditions for **robustness** (independence from  $\epsilon$ ) —

$$\|u, \sigma\|_{L^2(\Omega)}^2 = b(\mathbf{U}, (v, \tau)) = \frac{b(\mathbf{U}, (v, \tau))}{\|(v, \tau)\|_V} \|(v, \tau)\|_V \leq \|\mathbf{U}\|_E \|(v, \tau)\|_V$$

Let  $\lesssim$  denote a robust bound - **if**  $\|(v, \tau)\|_V \lesssim \|u, \sigma\|_{L^2(\Omega)}$ , then we have

$$\|u, \sigma\|_{L^2(\Omega)} \lesssim \|\mathbf{U}\|_E$$

**Main idea: the test norm should measure adjoint solutions robustly.**

# Results for convection-diffusion

By constructing  $\|v\|_V$  carefully, we prove an  $\epsilon$ -independent bound<sup>1</sup>

$$\|u\|_{L^2(\Omega)} + \|\sigma\|_{L^2(\Omega)} + \epsilon \|\hat{u}\| + \sqrt{\epsilon} \|\hat{f}_n\| \lesssim \left\| (u, \sigma, \hat{u}, \hat{f}_n) \right\|_E.$$

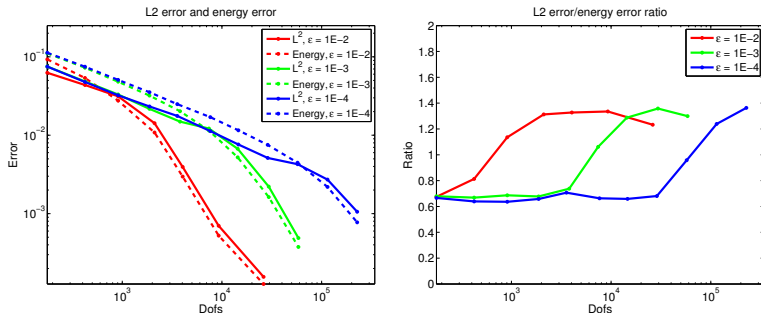


Figure:  $L^2$ /energy errors for  $\epsilon = .01, .001, .0001$  and a boundary layer solution.

<sup>1</sup>J. Chan, N. Heuer, T. Bui Thanh, and L. Demkowicz. Robust DPG method for convection-diffusion problems II: natural inflow conditions. Technical Report 12-21, ICES, June 2012. Submitted

## 2D test case: Burgers equation

$$\frac{\partial (u^2/2)}{\partial x} + \frac{\partial u}{\partial y} + \epsilon \Delta u = f$$

Burgers equation can be written  
with  $\beta(u) = (u/2, 1)$

$$\begin{aligned}\nabla \cdot (\beta(u)u - \sigma) &= f \\ \frac{1}{\epsilon} \sigma - \nabla u &= 0.\end{aligned}$$

i.e. nonlinear convection-diffusion  
on domain  $[0, 1]^2$ .

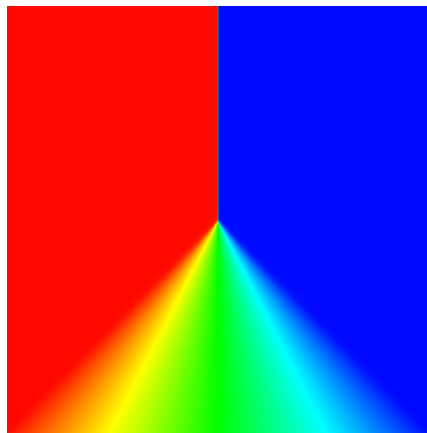


Figure: Shock solution for Burgers' equation,  $\epsilon = 1e - 4$ , using Newton-Raphson.



Adaptivity begins with a cubic  $4 \times 4$  mesh.

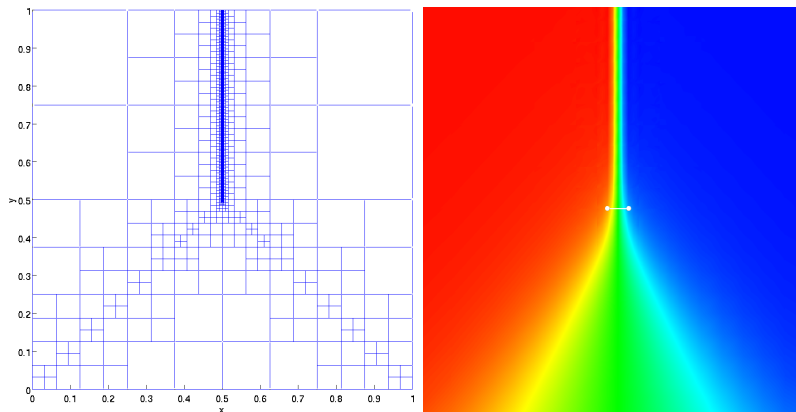


Figure: Adaptive mesh after 9 refinements, and zoom view at point  $(.5,.5)$  with shock formation and  $1e - 3$  width line for reference.

# 2D Compressible Navier-Stokes - Carter's flat plate

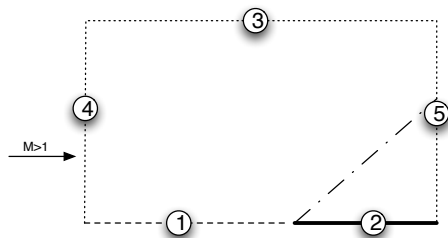
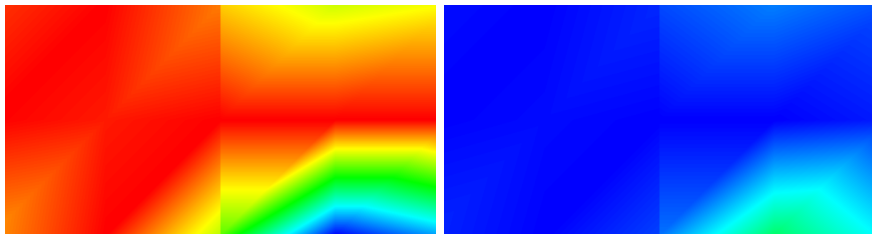
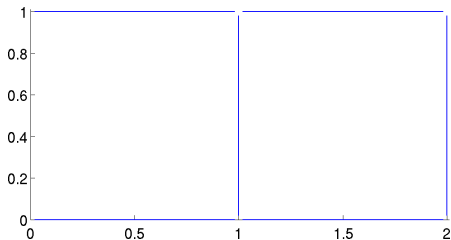


Figure: Carter flat plate problem on domain  $[0, 2] \times [0, 1]$ . Plate begins at  $x = 1$ ,  $Re = 1000$ .

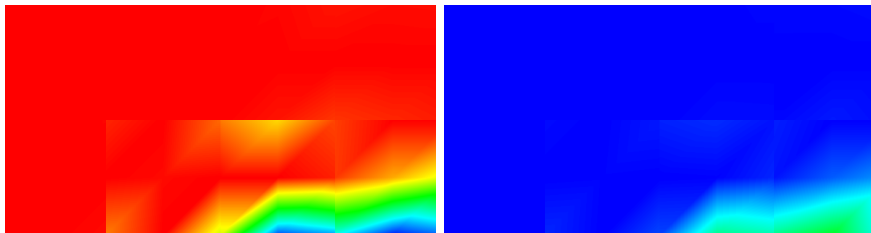
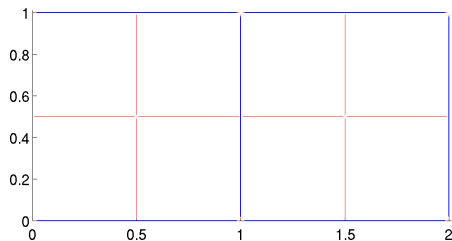
- 1 Symmetry boundary conditions.
- 2 Prescribed temperature and wall stagnation conditions.
- 3 Symmetry boundary conditions.
- 4 Inflow: conserved quantities specified using far-field values.
- 5 No outflow condition set.

Stress/heat flux boundary conditions are set in terms of the momentum and energy fluxes.

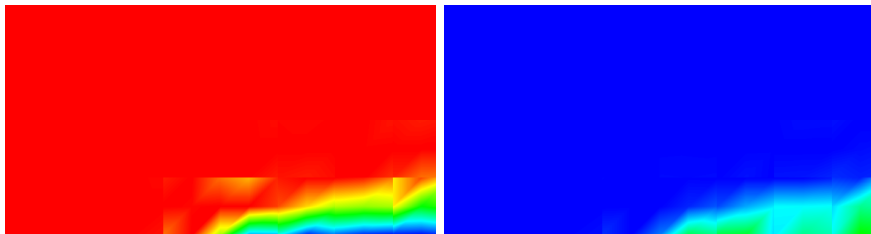
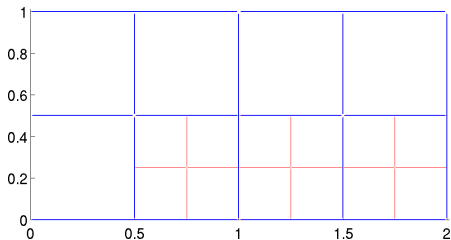
## Refinement level 0

(a)  $u_1$ (b)  $T$ 

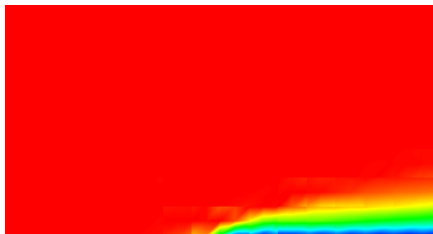
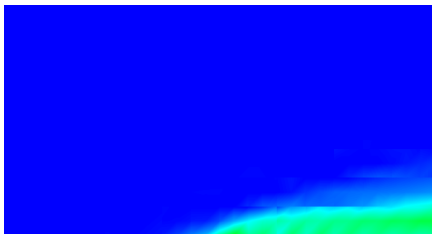
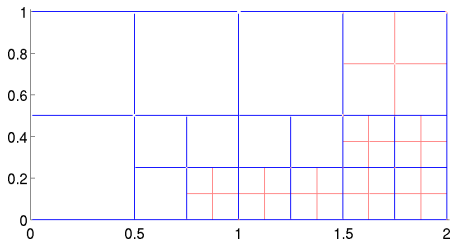
## Refinement level 1

(a)  $u_1$ (b)  $T$ 

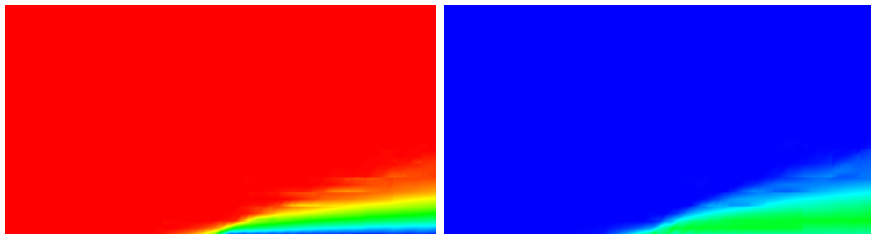
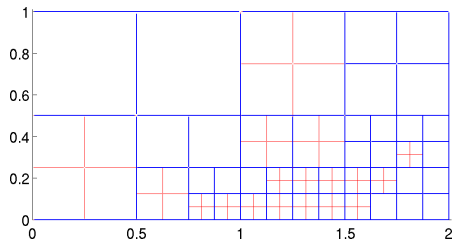
## Refinement level 2

(a)  $u_1$ (b)  $T$ 

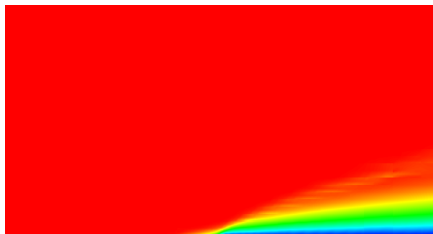
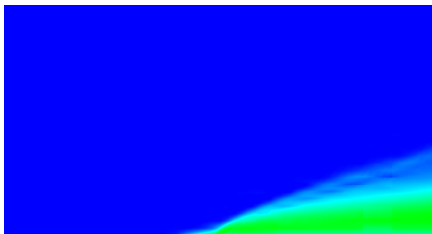
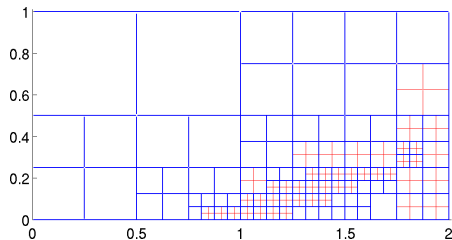
## Refinement level 3

(a)  $u_1$ (b)  $T$ 

## Refinement level 4

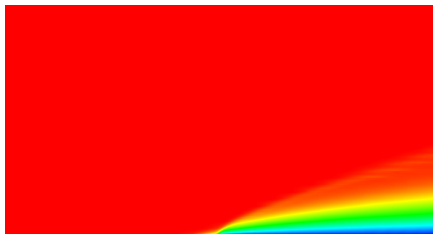
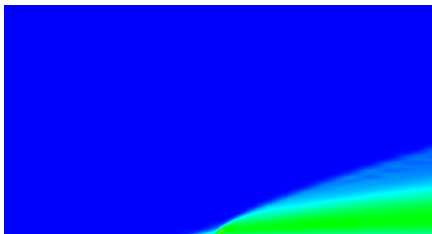
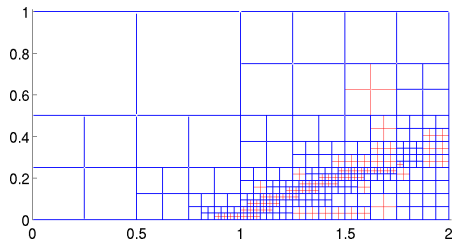
(a)  $u_1$ (b)  $T$ 

## Refinement level 5

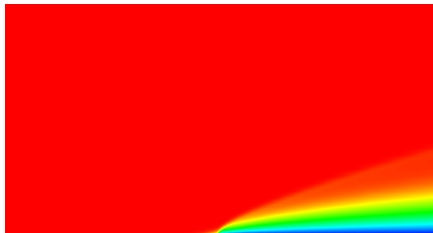
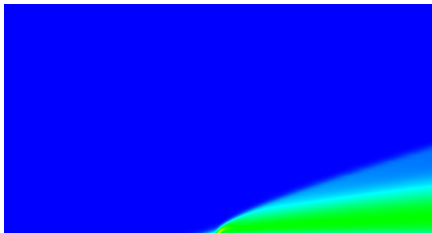
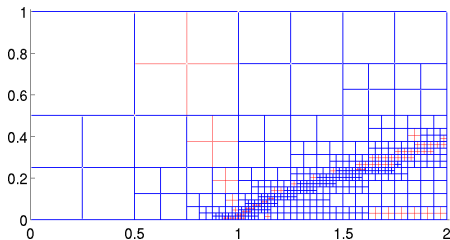
(a)  $u_1$ (b)  $T$ 



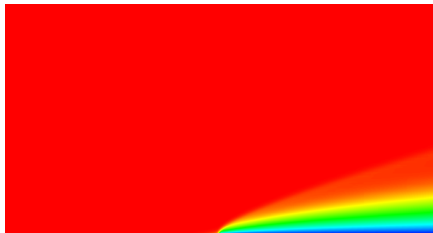
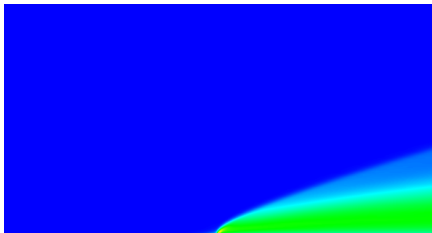
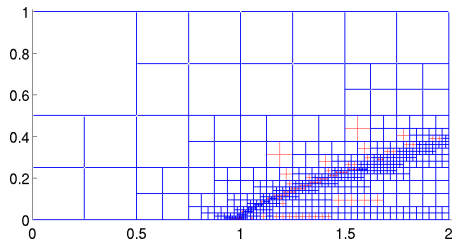
## Refinement level 6

(a)  $u_1$ (b)  $T$ 

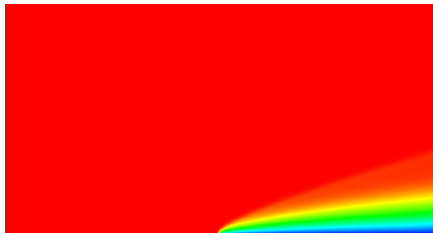
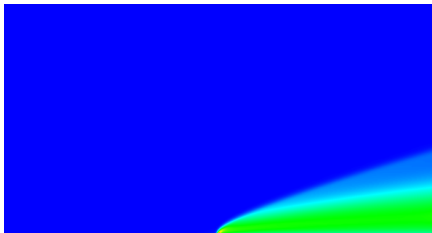
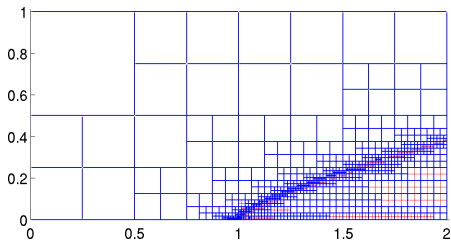
## Refinement level 7

(a)  $u_1$ (b)  $T$ 

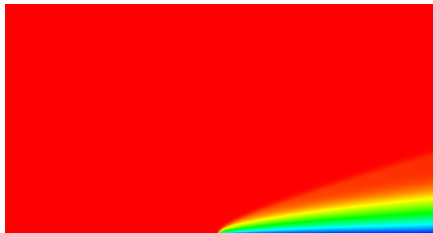
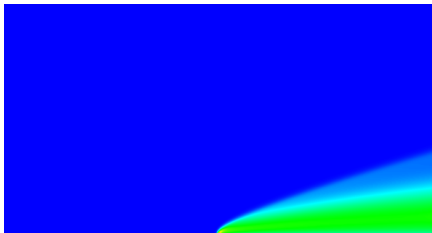
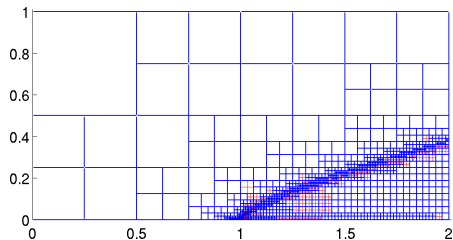
## Refinement level 8

(a)  $u_1$ (b)  $T$ 

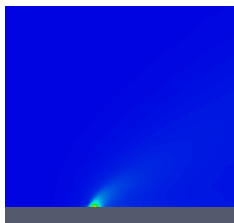
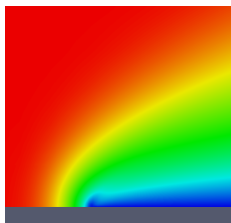
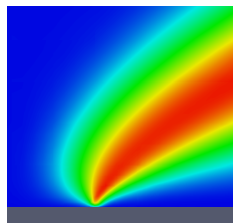
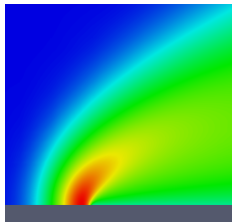
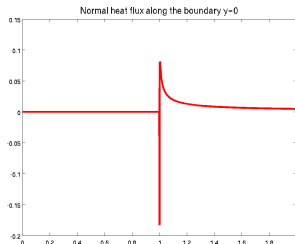
## Refinement level 9

(a)  $u_1$ (b)  $T$ 

## Refinement level 10

(a)  $u_1$ (b)  $T$ 

## Zoomed solutions at plate/stagnation point

(a)  $\rho$ (b)  $u_1$ (c)  $u_2$ (d)  $T$ (e)  $q_n$

# Automatic extension to anisotropic/ $hp$ meshes

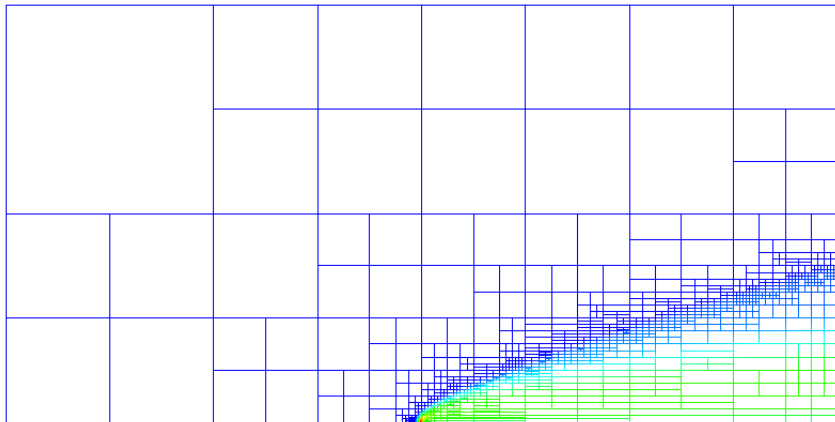


Figure: Trace  $\hat{T}$  for  $\text{Re} = 1000$  using an anisotropic refinement scheme<sup>2</sup>.

<sup>2</sup>N. Roberts, D. Ridzal, P. Bochev, and L. Demkowicz. A Toolbox for a Class of Discontinuous Petrov-Galerkin Methods Using Trilinos. Technical Report SAND2011-6678, Sandia National Laboratories, 2011

Thank you!

Questions?



# A new inflow boundary condition for a better adjoint

Non-standard choice of boundary condition:  $\hat{f}_n = \beta_n u - \sigma_n \approx \beta_n u_0$  on  $\Gamma_{\text{in}}$ , induces smoother adjoint problems and stronger energy estimates.

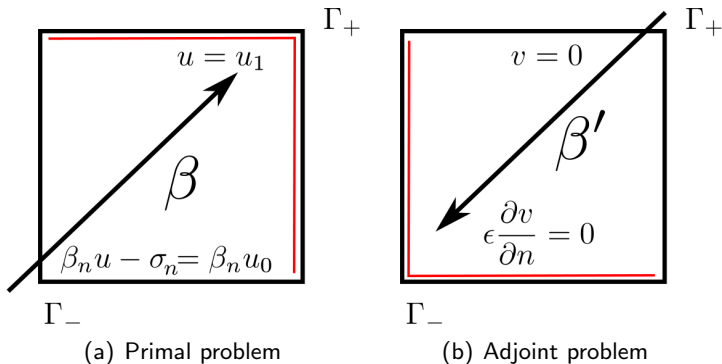


Figure: Under the new inflow condition, the wall-stop boundary condition is relaxed to a zero-stress condition at the outflow boundary of the adjoint problem.

# Convection-diffusion test norm

For solutions  $(v, \tau)$  of the adjoint equations, we derive quantities that are robustly bounded from above by  $\|u\|_{L^2(\Omega)}$ . Our test norm, as defined over a single element  $K$ , is now

$$\begin{aligned} \|(v, \tau)\|_{V,K}^2 = \min \left\{ \frac{\epsilon}{|K|}, 1 \right\} \|v\|^2 + \epsilon \|\nabla v\|^2 + \|\beta \cdot \nabla v\|^2 + \\ \|\nabla \cdot \tau\|^2 + \min \left\{ \frac{1}{\epsilon}, \frac{1}{|K|} \right\} \|\tau\|^2. \end{aligned}$$

which induces the proven *robust* bound<sup>3</sup>

$$\|u\|_{L^2(\Omega)} + \|\sigma\|_{L^2(\Omega)} + \epsilon \|\hat{u}\| + \sqrt{\epsilon} \|\hat{f}_n\| \lesssim \left\| \left( u, \sigma, \hat{u}, \hat{f}_n \right) \right\|_E.$$

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<sup>3</sup>J. Chan, N. Heuer, T. Bui Thanh, and L. Demkowicz. Robust DPG method for convection-diffusion problems II: natural inflow conditions. Technical Report 12-21, ICES, June 2012. Submitted



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