

ELECTRICAL MACHINES AND POWER SYSTEMS

End Term Examination, 1st December 2018 (Noon to 03:00 PM)

Duration: 180 minutes

Max. Marks: 50

NOTE: You are allowed to bring one A4 size formula sheet to the Examination Hall.

1. For the delta-delta three phase power system shown in Figure 1, calculate the three line currents. [5]

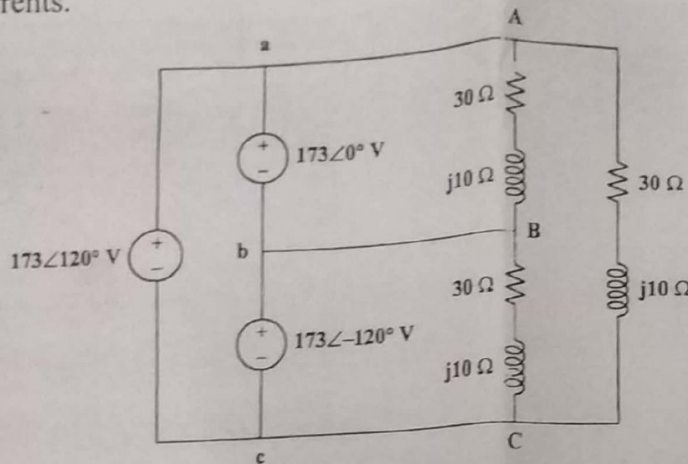


FIGURE 1

2. A. Draw an approximate equivalent circuit of a typical transformer and explain the purpose of each component in the equivalent circuit. Explain how you would calculate the efficiency of the transformer using this equivalent circuit.
 B. A single-phase transformer has 2000 turns on its primary winding and has 400 turns on its secondary winding. The maximum value of the flux-density is 1.1 Tesla (that is, 1.1 Weber/m²) when 2200 volts, 50 Hz is applied to the primary winding. Calculate the cross-sectional area of the core. [2+3]
3. A. Explain the purpose of the dot convention used in transformer equivalent circuits.
 B. An ideal lossless transformer has 100 turns on its primary winding and has 50 turns on its secondary winding. The magnetic flux in the core of the transformer is given by the equation $10\cos(314t)$ mWb where t denotes time in milliseconds. If a load resistance of $100\ \Omega$ is connected across the two terminals of the secondary winding of this transformer, how much current would flow in the secondary winding and how much input power will the transformer draw? [2+3]
4. What are the main parts used in the construction of D.C. machines? Discuss each of them in brief. Also draw the equivalent circuits for a) a shunt-wound DC generator, b) a series-wound DC generator, c) a compound-wound DC generator, and d) a self-excited DC generator. Explain the meaning and relevance of each component in these equivalent circuits. [5]
5. A. Name the three main performance characteristics of D.C. motors. Why is a series-wound D.C. motor so popular in Electric Trains?
 B. A 15 horse-power, 230 volts, 1750 RPM shunt DC motor has terminal current of

56.2 Amperes when operating at rated power and rated speed. The total armature resistance is 0.28Ω and the total field resistance is 137Ω . Compute the rated torque of the motor. Also calculate the starting current. [2+3]

6. Consider a shunt-wound DC motor, running at full rated speed, with the following parameters:
- Supply Voltage (V) = 220 volts
 - Armature Resistance (R_a) = 0.5 ohm
 - Field Resistance (R_f) = 200 ohm
 - No. of Conductors on Armature (Z) = 1000
 - No. of Parallel Paths on Armature (A) = 2
 - No. of poles (P) = 4
 - Armature Revolutions Per Minute (N) = 1000
 - Flux (ϕ) per pole = 6.45 mWb

Calculate the torque produced by the Motor. [5]

7. A. Draw the equivalent circuits for a) an Alternator, b) a Synchronous Motor, and c) a Three-Phase Induction Motor. Explain the purpose of each component in the equivalent circuits.
B. Name at least four different Prime Movers and their typical performance characteristics. [3+2]
8. A. A Gas-Turbine-Driven rotor with two poles is a part of an alternator responsible for generating a 50-Hz output voltage. At what speed should the Gas Turbine run?
B. A three-phase, wye-connected, 2500-KVA, 6.6-KV generator operates at full-load. The per-phase armature resistance is $70 \text{ m}\Omega$ and the per-phase synchronous reactance is 10.4Ω . Calculate the percentage voltage regulation at a) 0.8 power factor lagging and b) 0.8 power factor leading. [2+3]
9. A. A 1492-KW, unity power factor, three-phase, star-connected, 2300-V, 50-Hz synchronous motor has a synchronous reactance of 1.95Ω per phase. Compute the maximum torque produced by this motor if it is supplied from a constant-frequency source and if the field excitation is constant at the value which would result in unity power factor at the rated load. Neglect all losses.
B. A 208-V, 10-hp, four-pole, 60-Hz, Y-connected induction motor has a full-load slip of 5%. a) Calculate the synchronous speed of the motor. b) Calculate the rotor speed at the rated load. c) Calculate the rotor frequency at the rated load. D) Calculate the mechanical torque produced by this motor at the rated load. [3+2]
10. Name and briefly discuss the various faults encountered in modern power systems. Also discuss the various methods used to mitigate the effects of these faults. [5]