

# MA1522: Linear Algebra for Computing

## Tutorial 4

## Revision

# Linear Span

The span of  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k \in \mathbb{R}^n$  is

$$\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} = \{ c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_k\mathbf{u}_k \mid c_1, c_2, \dots, c_k \in \mathbb{R} \}.$$

It is the set of all linear combinations of the vectors  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$ .

## Theorem

1.  $\mathbf{v} \in \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \Leftrightarrow (\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_k)\mathbf{x} = \mathbf{v}$  is consistent.  $\Leftrightarrow (\mathbf{u}_1 \ \mathbf{u}_2 \ \dots \ \mathbf{u}_k \mid \mathbf{v})$  is consistent.
2.  $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} = \mathbb{R}^n \Leftrightarrow$  the reduced row-echelon form  $\mathbf{R}$  of  $\mathbf{A}$  has no zero rows.

$$\text{Linear system: } \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{cases} \Leftrightarrow \text{Matrix Equation: } \mathbf{Ax} = \mathbf{b}$$

$$\text{Vector equation: } x_1 \begin{pmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{pmatrix} + x_2 \begin{pmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{pmatrix} + \dots + x_n \begin{pmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix} \Leftrightarrow x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n = \mathbf{b}$$

where  $\mathbf{a}_i$  is the  $i$ -th column of  $\mathbf{A}$ .

# Set relations between spans

## Theorem (Properties of Linear Spans)

Let  $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\} \subseteq \mathbb{R}^n$ . Then

- (i) (Contains the origin)  $\mathbf{0} \in \text{span}(S)$ , and
- (ii) (Closed under addition) for any  $\mathbf{u}, \mathbf{v} \in \text{span}(S)$ ,  $\mathbf{u} + \mathbf{v} \in \text{span}(S)$ .
- (iii) (Closed under scalar multiplication) for any  $\mathbf{v} \in \text{span}(S)$  and real number  $\alpha \in \mathbb{R}$ ,  $\alpha\mathbf{v} \in \text{span}(S)$ .
- (iv) For any  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m \in \text{span}(S)$  and real numbers  $c_1, c_2, \dots, c_m \in \mathbb{R}$ ,  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_m\mathbf{v}_m \in \text{span}(S)$ . That is,  $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\} \subseteq \text{span}(S)$ .

## Theorem

Let  $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  and  $T = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$ , both subsets of  $\mathbb{R}^n$ . Then  $\text{span}(T) \subseteq \text{span}(S)$  if and only if  $\mathbf{v}_i \in \text{span}(S)$  for every  $i = 1, \dots, m$ .

To check if  $\text{span}(S) = \text{span}(T)$ , we check that

- $\text{span}(S) \subseteq \text{span}(T)$ , that is,

$$\left( \begin{array}{c|c|c|c|c|c|c} \text{"T"} & \text{"S"} & & & & & \end{array} \right) = \left( \begin{array}{c|c|c|c|c|c|c} \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_m & \mathbf{u}_1 & \mathbf{u}_2 & \cdots & \mathbf{u}_k \end{array} \right) \text{ is consistent, and}$$

- $\text{span}(T) \subseteq \text{span}(S)$ , that is,

$$\left( \begin{array}{c|c|c|c|c|c|c} \text{"S"} & \text{"T"} & & & & & \end{array} \right) = \left( \begin{array}{c|c|c|c|c|c|c} \mathbf{u}_1 & \mathbf{u}_2 & \cdots & \mathbf{u}_k & \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_m \end{array} \right) \text{ is consistent.}$$

# Subspaces

A subset  $V \subseteq \mathbb{R}^n$  is a subspace if

- (i) (Contains the origin)  $\mathbf{0} \in V$ , and
- (ii) (Closed under linear combination) for any  $\mathbf{u}, \mathbf{v} \in V$  and  $\alpha, \beta \in \mathbb{R}$ ,

$$\alpha \mathbf{u} + \beta \mathbf{v} \in V.$$

## Theorem (Equivalent Definition for Subspaces)

*A subset  $V \subseteq \mathbb{R}^n$  is a subspace if and only if it is a linear span,  $V = \text{span}(S)$ , for some finite set  $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ .*

# Solution Set to Linear Systems

Solution set to a linear system can be expressed implicitly or explicitly

► Implicit form: 
$$\left\{ \mathbf{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n \mid \mathbf{Ax} = \mathbf{b} \text{ or } \begin{array}{ccccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & & & \vdots & & & & \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m \end{array} \right\}.$$

► Explicit form:

$$\{ \mathbf{u} + s_1\mathbf{v}_1 + s_2\mathbf{v}_2 + \cdots s_k\mathbf{v}_k \mid s_1, s_2, \dots, s_k \in \mathbb{R} \},$$

where  $\mathbf{u} + s_1\mathbf{v}_1 + s_2\mathbf{v}_2 + \cdots s_k\mathbf{v}_k$ ,  $s_1, s_2, \dots, s_k \in \mathbb{R}$  is the general solution to  $\mathbf{Ax} = \mathbf{b}$ .

# Solution Space of Homogeneous System

## Theorem

*The solution set  $V = \{ \mathbf{u} \mid \mathbf{A}\mathbf{u} = \mathbf{b} \}$  to a linear system  $\mathbf{A}\mathbf{x} = \mathbf{b}$  is a subspace if and only if  $\mathbf{b} = \mathbf{0}$ , that is, the system is homogeneous.*

Let

$$s_1\mathbf{u}_1 + s_2\mathbf{u}_2 + \cdots + s_k\mathbf{u}_k, \quad s_1, s_2, \dots, s_k \in \mathbb{R}$$

be the general solution to the homogeneous system  $\mathbf{A}\mathbf{x} = \mathbf{0}$ . Then the solution set of  $\mathbf{A}\mathbf{x} = \mathbf{0}$  is spanned by  $\mathbf{u}_1, \dots, \mathbf{u}_k$ ; that is,

$$\{\text{Solutions to } \mathbf{A}\mathbf{x} = \mathbf{0}\} = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$$

# Solution Set to Non-homogeneous System

## Theorem

The solution set  $W = \{ \mathbf{w} \mid \mathbf{A}\mathbf{w} = \mathbf{b} \}$  of a linear system  $\mathbf{A}\mathbf{x} = \mathbf{b}$  is given by  $\mathbf{u} + V$ , where  $V = \{ \mathbf{v} \mid \mathbf{A}\mathbf{v} = \mathbf{0} \}$  is the solution space to the associated homogeneous system and  $\mathbf{u}$  is a particular solution,  $\mathbf{A}\mathbf{u} = \mathbf{b}$ .

If

$$\mathbf{u} + s_1\mathbf{v}_1 + s_2\mathbf{v}_2 + \cdots + s_k\mathbf{v}_k, s_1, s_2, \dots, s_k \in \mathbb{R}$$

is a general solution to  $\mathbf{A}\mathbf{x} = \mathbf{b}$ ,

$$s_1\mathbf{v}_1 + s_2\mathbf{v}_2 + \cdots + s_k\mathbf{v}_k, s_1, s_2, \dots, s_k \in \mathbb{R}$$

is a general solution to  $\mathbf{A}\mathbf{x} = \mathbf{0}$ .



## Tutorial 4 Solutions

## Question 1(a)

Let  $A = \{ (1 + t, 1 + 2t, 1 + 3t) \mid t \in \mathbb{R} \}$  be a subset in  $\mathbb{R}^3$ . Describe  $A$  geometrically.

<https://www.geogebra.org/calculator/uc7pfr7a>

$A$  is a line joining the points  $(1, 1, 1)$  and  $(2, 3, 4)$ .

## Question 1(b)

Show that  $A = \{ (x, y, z) \mid x + y - z = 1 \text{ and } x - 2y + z = 0 \}$ .

<https://www.geogebra.org/calculator/uc7pfr7a>

$$\left( \begin{array}{ccc|c} 1 & 1 & -1 & 1 \\ 1 & -2 & 1 & 0 \end{array} \right) \xrightarrow{RREF} \left( \begin{array}{ccc|c} 1 & 0 & -1/3 & 2/3 \\ 0 & 1 & -2/3 & 1/3 \end{array} \right).$$

General solution:  $\begin{pmatrix} \frac{2}{3} + \frac{1}{3}s \\ \frac{1}{3} + \frac{2}{3}s \\ s \end{pmatrix}$ ,  $s \in \mathbb{R}$ . Let  $s = 1 + 3t$ , we get  $\begin{pmatrix} 1 + t \\ 1 + 2t \\ 1 + 3t \end{pmatrix}$ ,  $t \in \mathbb{R}$ , which is the set in (a).

## Question 1(c)

Write down a matrix equation  $\mathbf{M}\mathbf{x} = \mathbf{b}$  where  $\mathbf{M}$  is a  $3 \times 3$  matrix and  $\mathbf{b}$  is a  $3 \times 1$  matrix such that its solution set is  $A$ .

From (b), we obtain the first 2 rows of  $\mathbf{M}$  and  $\mathbf{b}$ . Since we have exhausted all information, the last row of  $\mathbf{M}$  and  $\mathbf{b}$  must give us no useful information. Hence, we may let it be the zero row; i.e.  $\mathbf{M} = \begin{pmatrix} 1 & 1 & -1 \\ 1 & -2 & 1 \\ 0 & 0 & 0 \end{pmatrix}$  and  $\mathbf{b} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ .

## Question 2(a)

Let  $\mathbf{u}_1 = \begin{pmatrix} 2 \\ 1 \\ 0 \\ 3 \end{pmatrix}$ ,  $\mathbf{u}_2 = \begin{pmatrix} 3 \\ -1 \\ 5 \\ 2 \end{pmatrix}$ , and  $\mathbf{u}_3 = \begin{pmatrix} -1 \\ 0 \\ 2 \\ 1 \end{pmatrix}$ . If possible, express each of the following vectors as a linear

combination of  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ . (i)  $\mathbf{v}_1 = \begin{pmatrix} 2 \\ 3 \\ -7 \\ 3 \end{pmatrix}$  (ii)  $\mathbf{v}_2 = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$  (iii)  $\mathbf{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$  (iv)  $\mathbf{v}_4 = \begin{pmatrix} -4 \\ 6 \\ -13 \\ 4 \end{pmatrix}$ .

Solve for  $(\mathbf{u}_1 \quad \mathbf{u}_2 \quad \mathbf{u}_3 \mid \mathbf{v}_1 \mid \mathbf{v}_2 \mid \mathbf{v}_3 \mid \mathbf{v}_4)$ .

$$\left( \begin{array}{ccc|ccc} 2 & 3 & -1 & 2 & 0 & 1 & -4 \\ 1 & -1 & 0 & 3 & 0 & 1 & 6 \\ 0 & 5 & 2 & -7 & 0 & 1 & -13 \\ 3 & 2 & 1 & 3 & 0 & 1 & 4 \end{array} \right) \rightarrow \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & 0 & 0 & 3 \\ 0 & 1 & 0 & -1 & 0 & 0 & -3 \\ 0 & 0 & 1 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{array} \right).$$

## Question 2(a)

Alternatively,

$$\left( \begin{array}{ccc|c} 2 & 3 & -1 & x_1 \\ 1 & -1 & 0 & x_2 \\ 0 & 5 & 2 & x_3 \\ 3 & 2 & 1 & x_4 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & -1 & 0 & x_2 \\ 0 & 5 & -1 & x_1 - 2x_2 \\ 0 & 0 & 3 & -x_1 + 2x_2 + x_3 \\ 0 & 0 & 0 & x_1 + 7x_2 + 2x_3 - 3x_4 \end{array} \right) \rightarrow \left( \begin{array}{ccc|c} 1 & 0 & 0 & \frac{2x_1 + 11x_2 + x_3}{15} \\ 0 & 1 & 0 & \frac{2x_1 - 4x_2 + x_3}{15} \\ 0 & 0 & 1 & \frac{-x_1 + 2x_2 + x_3}{3} \\ 0 & 0 & 0 & 0 \end{array} \right),$$

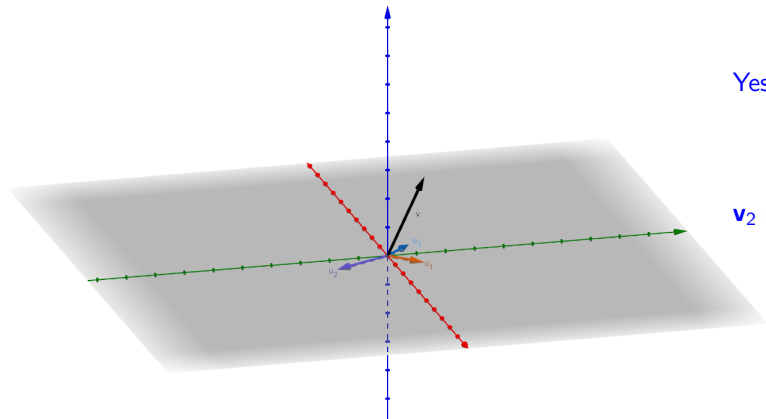
assuming  $x_1 + 7x_2 + 2x_3 - 3x_4 = 0$ . So a vector  $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$  is a linear combination of  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$  if and only if it satisfies

$x_1 + 7x_2 + 2x_3 - 3x_4 = 0$ . If that is true, then  $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = a\mathbf{u}_1 + b\mathbf{u}_2 + c\mathbf{u}_3$ , where

$$a = \frac{2x_1 + 11x_2 + x_3}{15}, \quad b = \frac{2x_1 - 4x_2 + x_3}{15}, \quad c = \frac{-x_1 + 2x_2 + x_3}{3}.$$

## Question 2(b)

Is it possible to find 2 vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$  such that they are not a multiple of each other, and both are not a linear combination of  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ ?



Yes, for example, take  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$  and

$$\mathbf{v}_2 = \mathbf{v}_1 + \mathbf{u}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 1 \\ 4 \end{pmatrix}.$$

### Question 3(a)

Let  $V = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mid x - y - z = 0 \right\}$  be a subset of  $\mathbb{R}^3$ . Let  $S = \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 5 \\ 2 \\ 3 \end{pmatrix} \right\}$ . Show that  $\text{span}(S) = V$ .

General solution to  $x - y - z = 0$  is  $x = s + t$ ,  $y = s$ ,  $z = t$  where  $s, t \in \mathbb{R}$ . Hence,  $V = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\}$ .

► Since  $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 5 \\ 2 \\ 3 \end{pmatrix}$  satisfy the equation  $x - y - z = 0$ , they are in  $V$  and hence  $\text{span}(S) \subseteq V$ .

► Check  $V = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} \subseteq \text{span}(S)$ :  $\left( \begin{array}{cc|cc} 1 & 5 & 1 & 1 \\ 1 & 2 & 1 & 0 \\ 0 & 3 & 0 & 1 \end{array} \right) \longrightarrow \left( \begin{array}{cc|cc} 1 & 0 & 1 & -2/3 \\ 0 & 1 & 0 & 1/3 \\ 0 & 0 & 0 & 0 \end{array} \right)$ .

So,  $\text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 5 \\ 2 \\ 3 \end{pmatrix} \right\} = V$ .



### Question 3(b)

Let  $T = S \cup \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ . Show that  $\text{span}(T) = \mathbb{R}^3$ .

Consider the row-echelon form of the matrix:

$$\begin{pmatrix} 1 & 5 & 0 \\ 1 & 2 & 0 \\ 0 & 3 & 1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 5 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \mathbf{R}.$$

Since there are no zero rows in  $\mathbf{R}$ , we conclude that  $T$  spans  $\mathbb{R}^3$ .

## Question 4(i)

Does  $S = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} \right\}$  spans  $\mathbb{R}^4$ ?

$$\begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$

So  $S$  spans  $\mathbb{R}^4$ .

## Question 4(ii)

Does  $S = \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$  spans  $\mathbb{R}^4$ ?

3 vectors cannot span  $\mathbb{R}^4$ .

### Question 4(iii)

Does  $S = \left\{ \begin{pmatrix} 6 \\ 4 \\ -2 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 2 \\ -1 \\ 2 \end{pmatrix}, \begin{pmatrix} 5 \\ 6 \\ -3 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 4 \\ -2 \\ -1 \end{pmatrix} \right\}$  spans  $\mathbb{R}^4$ ?

$$\begin{pmatrix} 6 & 2 & 3 & 5 & 0 \\ 4 & 0 & 2 & 6 & 4 \\ -2 & 0 & -1 & -3 & -2 \\ 4 & 1 & 2 & 2 & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} = \mathbf{R}$$

Since there is a row of zeros in  $\mathbf{R}$ ,  $S$  does not span  $\mathbb{R}^4$ .

## Question 4(iv)

Does  $S = \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} \right\}$  spans  $\mathbb{R}^4$ ?

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 0 & 2 & 1 \\ 1 & 2 & 0 & 1 & 2 \\ 0 & -1 & 1 & 2 & 3 \\ 0 & 1 & 1 & 1 & 4 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 0 & 0 & 3 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 1 & -1 \end{pmatrix} = \mathbf{R}.$$

So  $S$  spans  $\mathbb{R}^4$ .

## Question 5(a)

Determine whether  $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$  and/or  $\text{span}\{\mathbf{v}_1, \mathbf{v}_2\} \subseteq \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  if

$$\mathbf{u}_1 = \begin{pmatrix} 2 \\ -2 \\ 0 \end{pmatrix}, \mathbf{u}_2 = \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix}, \mathbf{u}_3 = \begin{pmatrix} 0 \\ 0 \\ 9 \end{pmatrix}, \mathbf{v}_1 = \begin{pmatrix} 1 \\ -1 \\ -5 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}.$$

```
>> u1=[2;-2;0];u2=[-1;1;-1];u3=[0;0;9];v1=[1;-1;-5];v2=[0;1;1];  
>> rref([u1 u2 u3 v1 v2])
```

$$\left( \begin{array}{ccc|cc} 2 & -1 & 0 & 1 & 0 \\ -2 & 1 & 0 & -1 & 1 \\ 0 & -1 & 9 & -5 & 1 \end{array} \right) \rightarrow \left( \begin{array}{ccc|cc} 1 & 0 & -\frac{9}{2} & 3 & 0 \\ 0 & 1 & -9 & 5 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right).$$

```
>> rref([v1 v2 u1 u2 u3])
```

$$\left( \begin{array}{cc|cc} 1 & 0 & 2 & -1 & 0 \\ -1 & 1 & -2 & 1 & 0 \\ -5 & 1 & 0 & -1 & 9 \end{array} \right) \rightarrow \left( \begin{array}{cc|ccc} 1 & 0 & 0 & \frac{1}{5} & -\frac{9}{5} \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -\frac{3}{5} & \frac{9}{10} \end{array} \right).$$

So  $\text{span}\{\mathbf{v}_1, \mathbf{v}_2\} \not\subseteq \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  and  $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \not\subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$ .

## Question 5(b)

Determine whether  $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$  and/or  $\text{span}\{\mathbf{v}_1, \mathbf{v}_2\} \subseteq \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  if

$$\mathbf{u}_1 = \begin{pmatrix} 1 \\ 6 \\ 4 \end{pmatrix}, \mathbf{u}_2 = \begin{pmatrix} 2 \\ 4 \\ -1 \end{pmatrix}, \mathbf{u}_3 = \begin{pmatrix} -1 \\ 2 \\ 5 \end{pmatrix}, \mathbf{v}_1 = \begin{pmatrix} 1 \\ -2 \\ -5 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 0 \\ 8 \\ 9 \end{pmatrix}.$$

```
>> u1=[1;6;4];u2=[2;4;-1];u3=[-1;2;5];v1=[1;-2;-5];v2=[0;8;9];  
>> rref([u1 u2 u3 v1 v2])  
>> rref([v1 v2 u1 u2 u3])
```

So  $\text{span}\{\mathbf{v}_1, \mathbf{v}_2\} \subseteq \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$  and  $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$ . We conclude that the two linear spans are equal.

## Question 6(a)

Determine if  $S = \left\{ \begin{pmatrix} p \\ q \\ p \\ q \end{pmatrix} \mid p, q \in \mathbb{R} \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

$$S = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} \right\}.$$



## Question 6(b)

Determine if  $S = \left\{ \begin{pmatrix} a \\ b \\ c \end{pmatrix} \mid a \geq b \text{ or } b \geq c \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

$S$  is not a linear span (thus not a subspace) since  $\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$  is in  $S$  but  $(-1) \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$  is not.

## Question 6(c)

Determine if  $S = \left\{ \begin{pmatrix} x \\ y \\ z \\ w \end{pmatrix} \mid 4x = 3y \text{ and } 2x = -3w \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

$$S = \left\{ \begin{pmatrix} x \\ \frac{4x}{3} \\ z \\ -\frac{2x}{3} \end{pmatrix} \mid x, z \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ \frac{4}{3} \\ 0 \\ -\frac{2}{3} \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right\}.$$

## Question 6(d)

Determine if  $S = \left\{ \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \mid \begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ a & b & c & d \end{vmatrix} = 0 \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

```
>> syms a b c d; det([1 0 1 0;0 1 0 0;1 0 0 1;a b c d])
```

$$\begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ a & b & c & d \end{vmatrix} = a - c - d.$$

So the set  $S$  can be rewritten as

$$S = \left\{ \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \mid a - c - d = 0 \right\} = \left\{ \begin{pmatrix} s+t \\ u \\ s \\ t \end{pmatrix} \mid s, t, u \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

## Question 6(e)

Determine if  $S = \left\{ \begin{pmatrix} w \\ x \\ y \\ z \end{pmatrix} \mid w + x = y + z \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

$S$  can be rewritten as  $S = \left\{ \begin{pmatrix} w \\ x \\ y \\ z \end{pmatrix} \mid w + x - y - z = 0 \right\}$ . Solving the equation  $w + x - y - z = 0$ , we have

$$S = \left\{ \begin{pmatrix} -s + t + u \\ s \\ t \\ u \end{pmatrix} \mid s, t, u \in \mathbb{R} \right\} = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

## Question 6(f)

Determine if  $S = \left\{ \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \mid ab = cd \right\}$  is a subspace. If it is, express the set as a linear span. If not, explain why.

$S$  is not a linear span (thus not a subspace) since  $\begin{pmatrix} 2 \\ 0 \\ 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 2 \\ 0 \\ 1 \end{pmatrix}$  are vectors in  $S$  but  $\begin{pmatrix} 2 \\ 0 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 2 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ 1 \\ 1 \end{pmatrix}$  is not.

## Question 6(g)

$S$  is the solution set of  $\mathbf{Ax} = \mathbf{0}$  where  $\mathbf{A} = \begin{pmatrix} 2 & 2 & -1 & 0 & 1 \\ -1 & -1 & 2 & -3 & 1 \\ 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & -2 & 0 & -1 \end{pmatrix}$ .

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>> rref([2 2 -1 0 1;-1 -1 2 -3 1;0 0 1 1 1;1 1 -2 0 -1]).
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$$\left( \begin{array}{ccccc|c} 2 & 2 & -1 & 0 & 1 & 0 \\ -1 & -1 & 2 & -3 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & -2 & 0 & -1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccccc|c} 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

The solution set of  $\mathbf{Ax} = \mathbf{0}$  is  $\left\{ \begin{pmatrix} -s-t \\ s \\ -t \\ 0 \\ t \end{pmatrix} \mid s, t \in \mathbb{R} \right\}$ . So,  $S = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\}$ .