DFR0534

1.0.4

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Chapter 1

DFR0534

An Arduino Uno/Nano, ESP32 library for a DFR0534 audio module. The library works with SoftwareSerial/HardwareSerial and is very similar to https://github.com/sleemanj/JQ8400_Serial, but is no fork.

Examples, how to use the library

- examples/playFileByName/playFileByName.ino
- examples/playFileByNumber/playFileByNumber.ino
- examples/playCombined/playCombined.ino

1.1 SoftwareSerial for Arduino Uno/Nano

To create a DFR0534 object pass the SoftwareSerial object as a parameter to the DFR0534 constructor, for example #include <SoftwareSerial.h>
#include <DFR0534.h>

#define TX_PIN A0
#define RX_PIN A1
SoftwareSerial g_serial(RX_PIN, TX_PIN);
DFR0534 g_audio(g_serial);

1.2 HardwareSerial for ESP32

To create a DFR0534 object pass the HardwareSerial object as a parameter to the DFR0534 constructor, for example

```
#include <DFR0534.h>
#define TX_PIN 19
#define RX_PIN 23
HardwareSerial g_serial(1);

DFR0534 g_audio(g_serial);

void setup() {
    g_serial.begin(9600, SERIAL_8N1, RX_PIN, TX_PIN);
```

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1.3 License and copyright

This library is licensed under the terms of

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1.4 Appendix 3

1.4 Appendix

1.4.1 DFR0534 pinout

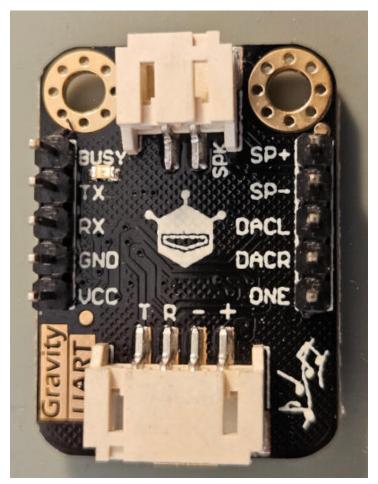


Figure 1.1 DFR0534 frontside

4 DFR0534



Figure 1.2 DFR0534 backside

Minimal schematic to use this library

Pin	Connected to
TX	SoftwareSerial/HardwareSerial RX
RX	SoftwareSerial/HardwareSerial TX*
GND	Ground
VCC	3.3-5V
SP+	Speaker + connector
SP-	Speaker - connector

^{*}If your microcontroller runs at 5V use a 1k resistor between RX and SoftwareSerial TX.

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interface	s with brief descriptions:
DFR0534	
Class for a DFR0534 audio module	

6 Class Index

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

layCombined.ino	35
layFileByName.ino	36
layFileByNumber.ino	37
FR0534.cpp	38
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Chapter 4

Class Documentation

4.1 DFR0534 Class Reference

```
Class for a DFR0534 audio module.
```

```
#include <DFR0534.h>
```

Public Types

```
    enum DFR0534CHANNELS { CHANNELMP3 , CHANNELAUX , CHANNELMP3AUX , CHANNELUNKNOWN }
    enum DFR0534DRIVE {
        DRIVEUSB , DRIVESD , DRIVEFLASH , DRIVEUNKNOWN ,
        DRIVENO = 0xff }
    enum DFR0534LOOPMODE {
        LOOPBACKALL , SINGLEAUDIOLOOP , SINGLEAUDIOSTOP , PLAYRANDOM ,
        DIRECTORYLOOP , RANDOMINDIRECTORY , SEQUENTIALINDIRECTORY , SEQUENTIAL ,
        PLAYMODEUNKNOWN }
    enum DFR0534EQ {
        NORMAL , POP , ROCK , JAZZ ,
        CLASSIC , EQUNKNOWN }
    enum DFR0534STATUS { STOPPED , PLAYING , PAUSED , STATUSUNKNOWN }
```

Public Member Functions

• DFR0534 (Stream &stream)

Constructor of a the DFR0534 audio module.

• void decreaseVolume ()

Decrease volume by one step.

void fastBackwardDuration (word seconds)

Fast backward.

void fastForwardDuration (word seconds)

Fast forward in seconds.

• byte getDrive ()

Get current drive.

byte getDrivesStates ()

Checks which drives are ready/online.

bool getDuration (byte &hour, byte &minute, byte &second)

Get duration/length of current file.

• bool getFileName (char *name)

Get name for current file.

word getFileNumber ()

Get file number of current file.

int getFirstFileNumberInCurrentDirectory ()

Get number of first file in current directory.

• bool getRuntime (byte &hour, byte &minute, byte &second)

Get elapsed runtime/duration of the current file.

• byte getStatus ()

Get module status.

• int getTotalFiles ()

Get total number of supported audio files on current drive.

int getTotalFilesInCurrentDirectory ()

Count all audio files for the current directory.

• void increaseVolume ()

Increase volume by one step.

void insertFileByNumber (word track, byte drive=DRIVEFLASH)

Pause current file and play another file by number.

· void pause ()

Pause the current file.

· void play ()

Play the current selected file.

void playCombined (char *list)

Combined/concatenated play of files.

• void playFileByName (char *path, byte drive=DRIVEFLASH)

Play audio file by file name/path.

void playFileByNumber (word track)

Play audio file by number.

void playLastInDirectory ()

Play last file in directory (in "file copy order")

· void playNext ()

Play next file (in "file copy order")

void playNextDirectory ()

Play first file in next directory (in "file copy order")

• void playPrevious ()

Play previous file (in "file copy order")

void prepareFileByNumber (word track)

Select file by number, but not start playing.

• void repeatPart (byte startMinute, byte startSecond, byte stopMinute, byte stopSecond)

Repeat part of the current file.

void setChannel (byte channel)

Set output for DAC to channel MP3, AUX or both.

void setDirectory (char *path, byte drive=DRIVEFLASH)

Should set directory, but does not work for me.

void setDrive (byte drive)

Switch to drive.

void setEqualizer (byte mode)

Set equalizer to NORMAL, POP, ROCK, JAZZ or CLASSIC.

• void setLoopMode (byte mode)

Set loop mode.

void setRepeatLoops (word loops)

Set repeat loops.

• void setVolume (byte volume)

Set volume.

• void stop ()

Stop the current file.

void stopInsertedFile ()

Stop inserted file.

• void startSendingRuntime ()

Start sending elapsed runtime every 1 second.

void stopCombined ()

Stop combined play (playlist)

void stopRepeatPart ()

Stop repeating part of the current file.

• void stopSendingRuntime ()

Stop sending runtime.

4.1.1 Detailed Description

Class for a DFR0534 audio module.

Definition at line 32 of file DFR0534.h.

4.1.2 Member Enumeration Documentation

4.1.2.1 DFR0534CHANNELS

```
enum DFR0534::DFR0534CHANNELS
```

Supported input channels

Enumerator

CHANNELMP3	Use MP3 input channel for DAC output (=default after device startup)
CHANNELAUX	Use AUX input (P26 and P27) for DAC output
CHANNELMP3AUX	Combines MP3 and AUX audio from P26 and P27 for DAC output
CHANNELUNKNOWN	Unknown

Definition at line 35 of file DFR0534.h.

```
00036 {
00037 CHANNELMP3,
00038 CHANNELAUX,
00039 CHANNELMP3AUX,
00040 CHANNELUNKNOWN
00041 };
```

4.1.2.2 DFR0534DRIVE

```
enum DFR0534::DFR0534DRIVE
```

Supported drives

Enumerator

DRIVEUSB	USB drive
DRIVESD	SD card
DRIVEFLASH	Flash memory chip
DRIVEUNKNOWN	Unknown
DRIVENO	No drive

Definition at line 43 of file DFR0534.h.

```
00044 {
00045 DRIVEUSB,
00046 DRIVESD,
00047 DRIVEFLASH,
00048 DRIVEUNKNOWN,
00049 DRIVENO = 0xff
00050 };
```

4.1.2.3 DFR0534EQ

```
enum DFR0534::DFR0534EQ
```

EQ modes

Enumerator

Definition at line 65 of file DFR0534.h.

```
00066 {
00067 NORMAL,
00068 POP,
00069 ROCK,
00070 JAZZ,
00071 CLASSIC,
00072 EQUNKNOWN
00073 };
```

4.1.2.4 DFR0534LOOPMODE

```
enum DFR0534::DFR0534LOOPMODE
```

Loop modes

Enumerator

LOOPBACKALL	Every file on drive in "file copy order" and loop afterwards
SINGLEAUDIOLOOP	Repeat current file
SINGLEAUDIOSTOP	Stops after single file (=default after device startup)
PLAYRANDOM	Random play order
DIRECTORYLOOP	Every file in current director in "file copy order" and loop afterwards
RANDOMINDIRECTORY	Random play order in current directory
SEQUENTIALINDIRECTORY	Every file in current directory in "file copy order" without loop
SEQUENTIAL	Every file on drive in "file copy order" without loop
PLAYMODEUNKNOWN	Unknown

Definition at line 52 of file DFR0534.h.

```
00054
              LOOPBACKALL,
00055
              {\tt SINGLEAUDIOLOOP},
              SINGLEAUDIOSTOP,
PLAYRANDOM,
DIRECTORYLOOP,
00056
00057
00058
00059
              RANDOMINDIRECTORY,
00060
              SEQUENTIALINDIRECTORY,
00061
              SEQUENTIAL,
             PLAYMODEUNKNOWN
00062
00063
         };
```

4.1.2.5 DFR0534STATUS

```
enum DFR0534::DFR0534STATUS
```

Modul states

Enumerator

STOPPED	Audio module is idle
PLAYING	Audio module is playing a file
PAUSED	Audio module is paused
STATUSUNKNOWN	Unkown

Definition at line 75 of file DFR0534.h.

```
00076 {
00077 STOPPED,
00078 PLAYING,
00079 PAUSED,
00080 STATUSUNKNOWN
00081 };
```

4.1.3 Constructor & Destructor Documentation

4.1.3.1 DFR0534()

Constructor of a the DFR0534 audio module.

Parameters

in	stream	Serial connection object, like SoftwareSerial
----	--------	---

Definition at line 87 of file DFR0534.h.

4.1.4 Member Function Documentation

4.1.4.1 decreaseVolume()

```
void DFR0534::decreaseVolume ()
```

Decrease volume by one step.

Definition at line 748 of file DFR0534.cpp.

```
00749 {
00750    if (m_ptrStream == NULL) return; // Should not happen
00751    sendStartingCode();
00752    sendDataByte(0x15);
00753    sendDataByte(0x00);
00754    sendCheckSum();
```

4.1.4.2 fastBackwardDuration()

Fast backward.

Fast backward in seconds

Parameters

```
in seconds Seconds to go backward
```

Definition at line 1025 of file DFR0534.cpp.

```
01026 {
01027     if (m_ptrStream == NULL) return; // Should not happen
01028     sendStartingCode();
01029     sendDataByte(0x22);
01030     sendDataByte(0x02);
01031     sendDataByte((seconds » 8) & 0xff);
01032     sendDataByte(seconds & 0xff);
01033     sendCheckSum();
01034 }
```

4.1.4.3 fastForwardDuration()

Fast forward in seconds.

Parameters

```
in seconds Seconds to go forward
```

Definition at line 1042 of file DFR0534.cpp.

```
01043 {
01044
        if (m_ptrStream == NULL) return; // Should not happen
01045
        sendStartingCode();
01046
       sendDataByte(0x23);
01047
        sendDataByte(0x02);
01048
        sendDataByte((seconds » 8) & 0xff);
01049
        sendDataByte(seconds & 0xff);
01050
       sendCheckSum();
01051 }
```

4.1.4.4 getDrive()

```
byte DFR0534::getDrive ()
```

Get current drive.

Return values

DFR0534::DRIVEUSB	USB drive
DFR0534::DRIVESD	SD card
DFR0534::DRIVEFLASH	Flash memory chip
DFR0534::DRIVENO	No drive found
DFR0534::DRIVEUNKNOWN	Error (for example request timeout)

Definition at line 345 of file DFR0534.cpp.

```
00347
        #define COMMAND 0x0A
00348
        #define RECEIVEBYTETIMEOUTMS 100
00349
        #define RECEIVEGLOBALTIMEOUTMS 500
        #define RECEIVEFAILED DRIVEUNKNOWN
00350
00351
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00352
00353
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00354
        sendStartingCode();
00355
        sendDataByte(COMMAND);
00356
        sendDataByte(0x00);
        sendCheckSum():
00357
00358
00359
        // Receive
00360
        int i=0;
00361
        byte data, firstByte = 0, sum, length=0xff, result = 0;
00362
        unsigned long receiveStartMS = millis();
00363
        do {
00364
         byte dataReady = 0;
         unsigned long lastMS = millis();
00365
00366
         // Wait for response or timeout
00367
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00368
00369
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00370
          data = m ptrStream->read();
00371
00372
          if (i==0) { // Begin of transmission
00373
            firstByte=data;
00374
            sum = 0;
00375
00376
          if ((i == 1) && (data != COMMAND)) {
00377
               Invalid signal => reset receive
00378
            i=0;
00379
            firstByte = 0;
00380
          if (i == RECEIVEHEADERLENGTH) {
00381
            length = data; // Length of receiving data if (length != 1) {
00382
00383
00384
              // Invalid length => reset receive
00385
              i=0;
00386
              firstByte = 0;
           }
00387
00388
00389
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00390
           result = data;
00391
00392
          if (firstByte == STARTINGCODE) {
00393
           if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00394
            i++;
00395
00396
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00397
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00398
00399
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00400
       return result;
00401 }
```

4.1.4.5 getDrivesStates()

```
byte DFR0534::getDrivesStates ()
```

Checks which drives are ready/online.

Returned value is a bit pattern that shows which drives are ready/online (1=online,0=offline):

- Bit 0 = DFR0534::DRIVEUSB
- Bit 1 = DFR0534::DRIVESD
- Bit 2 = DFR0534::DRIVEFLASH

Returns

Bit pattern for drives

Return values

DFR0534::DRIVEUNKNOWN | Error (for example request timeout)

Definition at line 278 of file DFR0534.cpp.

```
00279
00280
        #define COMMAND 0x09
        #define RECEIVEBYTETIMEOUTMS 100
00281
00282
        #define RECEIVEGLOBALTIMEOUTMS 500
00283
        #define RECEIVEFAILED DRIVEUNKNOWN
00284
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00285
00286
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00287
        sendStartingCode();
        sendDataByte(COMMAND);
00288
00289
        sendDataByte(0x00);
00290
        sendCheckSum();
00291
00292
        // Receive
00293
        int i=0;
        byte data, firstByte = 0, sum, length=0xff, result = 0;
00294
00295
        unsigned long receiveStartMS = millis();
00296
          byte dataReady = 0;
00297
          unsigned long lastMS = millis();
00298
          // Wait for response or timeout
00299
00300
           while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =
     m_ptrStream->available();
00301
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
data = m_ptrStream->read();
00302
00303
00304
00305
          if (i==0) { // Begin of transmission
00306
            firstByte=data;
00307
            sum = 0;
00308
          if ((i == 1) && (data != COMMAND)) {
   // Invalid signal => reset receive
00309
00310
             i=0;
00311
00312
            firstByte = 0;
00313
00314
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 1) {
00315
00316
              // Invalid length => reset receive
00317
00318
               i=0;
00319
              firstByte = 0;
00320
            }
00321
00322
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
00323
            result = data;
00324
00325
          if (firstByte == STARTINGCODE) {
00326
             if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00327
            i++;
00328
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00329
00330
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00331
00332
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00333
        return result;
00334 }
```

4.1.4.6 getDuration()

```
bool DFR0534::getDuration (
          byte & hour,
          byte & minute,
          byte & second)
```

Get duration/length of current file.

Get duration/length of current file in hours:minutes:seconds

Parameters

out	hour	Hours
out	minute	Minutes
out	second	Seconds

Return values

true	Request was successful
false	Request failed

Definition at line 1065 of file DFR0534.cpp.

```
01066 {
        #define COMMAND 0x24
01067
        #define RECEIVEFAILED false
01068
01069
        #define RECEIVEBYTETIMEOUTMS 100
01070
        #define RECEIVEGLOBALTIMEOUTMS 500
01071
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
01072
01073
        if (m_ptrStream == NULL) return false; // Should not happen
01074
        sendStartingCode();
        sendDataByte(COMMAND);
01076
        sendDataByte(0x00);
01077
        sendCheckSum();
01078
01079
        // Receive
01080
        int i=0;
01081
        byte data, firstByte = 0, sum, length=0xff;
01082
        word result = 0;
01083
        unsigned long receiveStartMS = millis();
01084
        do {
         byte dataReady = 0;
unsigned long lastMS = millis();
01085
01086
01087
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
01089
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
data = m_ptrStream->read();
01090
01091
01092
01093
          if (i==0) { // Begin of transmission
01094
           firstByte=data;
01095
            sum = 0;
01096
          if ((i == 1) && (data != COMMAND)) {
01097
01098
            // Invalid signal => reset receive
01099
01100
            firstByte = 0;
01101
          if (i == RECEIVEHEADERLENGTH) {
01102
            length = data; // Length of receiving data
if (length != 3) {
01103
01104
01105
                 Invalid length => reset receive
01106
              i=0;
01107
              firstByte = 0;
01108
01109
01110
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
01111
            switch (i-RECEIVEHEADERLENGTH-1) {
01112
              case 0:
```

```
hour=data;
01114
               break;
01115
              case 1:
               minute=data;
01116
01117
                break;
01118
              case 2:
01119
               second=data;
01120
                break;
01121
           }
01122
          if (firstBvte == STARTINGCODE) {
01123
           if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
01124
01125
            i++;
01126
01127
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
01128
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
01129
       return (data == sum); // Does checksum matches?
01130
01131 }
```

4.1.4.7 getFileName()

Get name for current file.

File name is in 8+3 format in upper case, with spaces without the dot "." between name and extension, e.g. "TEST WAV" for the file test.wav

Parameters

out name Filename. You have to allocate at least 12 chars memory for this variable.

Definition at line 913 of file DFR0534.cpp.

```
00914 {
        #define COMMAND 0x1E
00916
        #define RECEIVEBYTETIMEOUTMS 100
00917
        #define RECEIVEGLOBALTIMEOUTMS 500
00918
        #define RECEIVEFAILED false
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00919
00920
00921
        if (m_ptrStream == NULL) return false; // Should not happen
        if (name == NULL) return false;
name[0] = '\0';
00922
00923
00924
00925
        sendStartingCode();
00926
        sendDataByte(COMMAND);
00927
        sendDataByte(0x00);
00928
        sendCheckSum();
00929
00930
        // Receive
00931
        int i=0;
00932
        byte data, firstByte = 0, sum, length=0xff;
        unsigned long receiveStartMS = millis();
00933
00934
        do {
00935
        byte dataReady = 0;
00936
          unsigned long lastMS = millis();
          // Wait for response or timeout
while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00937
00938
     m ptrStream->available();
00939
00940
           if (dataReady == 0) return RECEIVEFAILED; // Timeout
00941
          data = m_ptrStream->read();
          if (i==0) { // Begin of transmission
00942
00943
            firstBvte=data:
00944
            sum = 0;
00945
00946
          if ((i == 1) && (data != COMMAND)) {
00947
            // Invalid signal => reset receive
            i.=0;
00948
00949
            firstByte = 0;
00950
00951
          if (i == RECEIVEHEADERLENGTH) length = data; // Length of receiving string
00952
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
```

```
if ((i-RECEIVEHEADERLENGTH) < 12) { // I expect no longer file names than 8+3 chars plus '\0'
              name[i-RECEIVEHEADERLENGTH-1] = data;
name[i-RECEIVEHEADERLENGTH] = '\0';
00954
00955
            }
00956
00957
00958
           if (firstByte == STARTINGCODE) {
             if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00960
            i++;
00961
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00962
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00963
00964
        return (data == sum); // Does checksum matches?
00965 }
```

4.1.4.8 getFileNumber()

```
word DFR0534::getFileNumber ()
```

Get file number of current file.

File number is in "file copy order". First audio file copied to the drive get number 1...

Returns

File number

Return values

0 | Error (for example request timeout)

Definition at line 427 of file DFR0534.cpp.

```
00428 {
00429
        #define COMMAND 0x0D
        #define RECEIVEFAILED 0
00430
        #define RECEIVEBYTETIMEOUTMS 100
00431
00432
        #define RECEIVEGLOBALTIMEOUTMS 500
00433
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00434
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00435
00436
       sendStartingCode();
00437
        sendDataByte(COMMAND);
00438
        sendDataByte(0x00);
00439
        sendCheckSum();
00440
00441
        // Receive
00442
       int i=0;
00443
        byte data, firstByte = 0, sum, length=0xff;
00444
        word result = 0;
        unsigned long receiveStartMS = millis();
00445
00446
00447
         byte dataReady = 0;
         unsigned long lastMS = millis();
00448
00449
         // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00450
     m_ptrStream->available();
00451
00452
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00453
          data = m_ptrStream->read();
00454
00455
          if (i==0) { // Begin of transmission
00456
            firstByte=data;
00457
            sum = 0;
00458
00459
          if ((i == 1) && (data != COMMAND)) {
           // Invalid signal => reset receive
00460
            i=0;
00461
00462
            firstByte = 0;
00463
00464
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 2) {
00465
00466
00467
              // Invalid length => reset receive
00468
```

```
firstByte = 0;
00470
00471
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00472
00473
            switch (i-RECEIVEHEADERLENGTH-1) {
00474
             case 0:
00475
               result=data«8;
00476
                break;
00477
              case 1:
00478
                result+=data;
00479
                break:
00480
            }
00481
00482
          if (firstByte == STARTINGCODE) {
00483
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00484
00485
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00486
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00488
00489
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00490
        return result;
00491 }
```

4.1.4.9 getFirstFileNumberInCurrentDirectory()

```
int DFR0534::getFirstFileNumberInCurrentDirectory ()
```

Get number of first file in current directory.

Returns

File number

Return values

-1 | Error (for example request timeout)

```
Definition at line 595 of file DFR0534.cpp.
```

```
00596 {
00597
        #define COMMAND 0x11
00598
        #define RECEIVEFAILED -1
00599
        #define RECEIVEBYTETIMEOUTMS 100
00600
        #define RECEIVEGLOBALTIMEOUTMS 500
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00601
00602
        if (m_ptrStream == NULL) RECEIVEFAILED; // Should not happen
00603
00604
       sendStartingCode();
00605
       sendDataByte(COMMAND);
00606
        sendDataByte(0x00);
        sendCheckSum();
00607
00608
00609
        // Receive
00610
       int i=0;
        byte data, firstByte = 0, sum, length=0xff;
00611
00612
        word result = 0;
00613
        unsigned long receiveStartMS = millis();
00614
         byte dataReady = 0;
00615
         unsigned long lastMS = millis();
00616
          // Wait for response or timeout
00617
00618
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00619
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00620
          data = m_ptrStream->read();
00621
00622
00623
          if (i==0) { // Begin of transmission
00624
            firstByte=data;
            sum = 0;
00625
00626
00627
          if ((i == 1) && (data != COMMAND)) {
00628
           // Invalid signal => reset receive
00629
            i=0;
```

```
00630
            firstByte = 0;
00631
          if (i == RECEIVEHEADERLENGTH) {
00632
            length = data; // Length of receiving data
if (length != 2) {
00633
00634
              // Invalid length => reset receive
00635
00636
00637
              firstByte = 0;
00638
00639
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00640
            switch (i-RECEIVEHEADERLENGTH-1) {
00641
00642
              case 0:
00643
               result=data«8;
00644
                break;
00645
              case 1:
00646
                result+=data;
00647
                break;
00648
            }
00649
00650
          if (firstByte == STARTINGCODE) {
00651
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
            i++;
00652
00653
00654
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00655
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00656
00657
       if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00658
       return result;
00659 }
```

4.1.4.10 getRuntime()

Get elapsed runtime/duration of the current file.

Runtime is in hours:minutes:seconds. You have to call startSendingRuntime() before runtimes can be received.

Parameters

out	hour	Hours
out	minute	Minutes
out	second	Seconds

Return values

true	Request was successful
false	Request failed

Definition at line 1158 of file DFR0534.cpp.

```
01159 {
01160
        #define COMMAND 0x25
01161
        #define RECEIVEFAILED false
01162
       #define RECEIVEBYTETIMEOUTMS 100
       #define RECEIVEGLOBALTIMEOUTMS 500
01163
       #define RECEIVEHEADERLENGTH 2 // startingcode+command
01164
01165
01166
       if (m_ptrStream == NULL) return false; // Should not happen
01167
01168
01169
       int i=0;
       byte data, firstByte = 0, sum, length=0xff;
01170
01171
       word result = 0;
01172
       unsigned long receiveStartMS = millis();
01173
```

```
01174
          byte dataReady = 0;
01175
          unsigned long lastMS = millis();
01176
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
01177
     m_ptrStream->available();
01178
01179
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
01180
          data = m_ptrStream->read();
01181
          if (i==0) { // Begin of transmission
01182
            firstByte=data;
01183
01184
            sum = 0;
01185
01186
          if ((i == 1) && (data != COMMAND)) {
01187
            // Invalid signal => reset receive
01188
            i=0;
            firstByte = 0;
01189
01190
01191
          if (i == RECEIVEHEADERLENGTH) {
01192
            length = data; // Length of receiving data
01193
            if (length != 3) {
01194
             // Invalid length => reset receive
              i = 0:
01195
01196
              firstByte = 0;
01197
            }
01198
01199
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
01200
            switch (i-RECEIVEHEADERLENGTH-1) {
01201
             case 0:
01202
               hour=data;
01203
                break;
01204
              case 1:
01205
              minute=data;
01206
                break;
01207
              case 2:
01208
               second=data:
01209
                break;
01210
           }
01211
01212
          if (firstByte == STARTINGCODE) {
01213
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
           i++;
01214
01215
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
01216
01217
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
01218
01219
       return (data == sum); // Does checksum matches?
01220 }
```

4.1.4.11 getStatus()

byte DFR0534::getStatus ()

Get module status.

Return values

DFR0534::STOPPED	Audio module is idle
DFR0534::PLAYING	Audio module is playing a file
DFR0534::PAUSED	Audio module is paused
DFR0534::STATUSUNKNOWN	Error (for example request timeout)

Definition at line 53 of file DFR0534.cpp.

```
00054 {
        #define COMMAND 0x01
00055
        #define RECEIVEBYTETIMEOUTMS 100
00056
        #define RECEIVEGLOBALTIMEOUTMS 500
#define RECEIVEFAILED STATUSUNKNOWN
00057
00058
00059
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00060
00061
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00062
        sendStartingCode();
00063
        sendDataByte(COMMAND);;
00064
        sendDataByte(0x00);;
00065
        sendCheckSum();
```

```
00066
00067
        // Receive
00068
        int i=0;
        byte data, firstByte = 0, sum, length=0xff, result = 0;
unsigned long receiveStartMS = millis();
00069
00070
00071
        do {
          byte dataReady = 0;
unsigned long lastMS = millis();
00072
00073
00074
          // Wait for response or timeout
00075
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00076
00077
           if (dataReady == 0) return RECEIVEFAILED; // Timeout
00078
           data = m_ptrStream->read();
00079
08000
           if (i==0) { // Begin of transmission
00081
            firstByte=data;
00082
            sum = 0;
00083
00084
           if ((i == 1) && (data != COMMAND)) {
00085
               Invalid signal => reset receive
00086
            i=0;
            firstByte = 0;
00087
00088
00089
           if (i == RECEIVEHEADERLENGTH) {
00090
            length = data; // Length of receiving data
if (length != 1) {
00091
00092
              // Invalid length => reset receive
00093
               i=0;
00094
              firstByte = 0;
00095
            }
00096
00097
           if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00098
            result = data;
00099
           if (firstByte == STARTINGCODE) {
00100
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00101
00102
00103
00104
           if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00105
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00106
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00107
00108
        return result;
00109 }
```

4.1.4.12 getTotalFiles()

```
int DFR0534::getTotalFiles ()
```

Get total number of supported audio files on current drive.

Returns

Number of files

Return values

-1 | Error (for example request timeout)

Definition at line 499 of file DFR0534.cpp.

```
00500 {
00501
        #define COMMAND 0x0C
00502
        #define RECEIVEFAILED -1
       #define RECEIVEBYTETIMEOUTMS 100
00503
00504
        #define RECEIVEGLOBALTIMEOUTMS 500
00505
       #define RECEIVEHEADERLENGTH 2 // startingcode+command
00506
00507
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00508
       sendStartingCode();
00509
       sendDataByte(COMMAND);
00510
       sendDataBvte(0x00);
00511
       sendCheckSum();
00512
```

```
// Receive
00514
        int i=0;
00515
        byte data, firstByte = 0, sum, length=0xff;
00516
        word result = 0;
        unsigned long receiveStartMS = millis();
00517
00518
        do {
         byte dataReady = 0;
00519
00520
          unsigned long lastMS = millis();
00521
          // Wait for response or timeout
00522
         while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00523
00524
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00525
          data = m_ptrStream->read();
00526
00527
          if (i==0) { // Begin of transmission
00528
           firstByte=data;
00529
           sum = 0;
00530
00531
          if ((i == 1) && (data != COMMAND)) {
00532
              Invalid signal => reset receive
00533
            i=0:
            firstByte = 0;
00534
00535
00536
          if (i == RECEIVEHEADERLENGTH) {
00537
            length = data; // Length of receiving data
if (length != 2) {
00538
00539
             // Invalid length => reset receive
00540
              i=0;
             firstByte = 0;
00541
00542
            }
00543
00544
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00545
           switch (i-RECEIVEHEADERLENGTH-1) {
00546
             case 0:
              result=data«8;
00547
00548
               break;
             case 1:
00550
               result+=data;
00551
                break;
00552
           }
00553
          if (firstByte == STARTINGCODE) {
00554
           if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00555
00556
00557
00558
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00559
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00560
00561
       if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00562
       return result;
00563 }
```

4.1.4.13 getTotalFilesInCurrentDirectory()

```
int DFR0534::getTotalFilesInCurrentDirectory ()
```

Count all audio files for the current directory.

Returns

File count

Return values

```
-1 Error (for example request timeout)
```

Definition at line 667 of file DFR0534.cpp.

```
00674
00675
        if (m_ptrStream == NULL) RECEIVEFAILED; // Should not happen
00676
        sendStartingCode();
00677
        sendDataByte(COMMAND);
00678
        sendDataByte(0x00);
00679
        sendCheckSum();
00680
00681
00682
        int i=0;
00683
        byte data, firstByte = 0, sum, length=0xff;
        word result = 0;
00684
        unsigned long receiveStartMS = millis();
00685
00686
00687
         byte dataReady = 0;
00688
          unsigned long lastMS = millis();
          // Wait for response or timeout
while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00689
00690
     m_ptrStream->available();
00691
00692
           if (dataReady == 0) return RECEIVEFAILED; // Timeout
00693
          data = m_ptrStream->read();
00694
          if (i==0) { // Begin of transmission
00695
            firstByte=data;
00696
00697
            sum = 0;
00698
00699
          if ((i == 1) && (data != COMMAND)) {
00700
            // Invalid signal => reset receive
00701
            i=0;
            firstByte = 0;
00702
00703
00704
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data if (length != 2) {
00705
00706
00707
              // Invalid length => reset receive
              i=0;
00708
00709
              firstByte = 0;
00710
00711
00712
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00713
            switch (i-RECEIVEHEADERLENGTH-1) {
             case 0:
00714
00715
               result=data«8:
00716
                break;
00717
              case 1:
00718
                result+=data;
00719
                break;
00720
            }
00721
00722
          if (firstByte == STARTINGCODE) {
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00724
00725
00726
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00727
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00728
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00730
       return result;
00731 }
```

4.1.4.14 increaseVolume()

```
void DFR0534::increaseVolume ()
```

Increase volume by one step.

```
Definition at line 736 of file DFR0534.cpp.
```

```
00737 {
00738    if (m_ptrStream == NULL) return; // Should not happen
00739    sendStartingCode();
00740    sendDataByte(0x14);
00741    sendDataByte(0x00);
00742    sendCheckSum();
00743 }
```

4.1.4.15 insertFileByNumber()

Pause current file and play another file by number.

File number order is "file copy order". Continue original file when this file stops

Parameters

in	track	File number of the audio file
in	drive	Drive, where file is stored: Drive DFR0534::DRIVEUSB, DFR0534::DRIVESD or
		DFR0534::DRIVEFLASH (=default)

Definition at line 765 of file DFR0534.cpp.

```
00767
           (m_ptrStream == NULL) return; // Should not happen
00768
        if (drive >= DRIVEUNKNOWN) return;
00769
        sendStartingCode();
00770
       sendDataByte(0x16);
00771
       sendDataByte(0x03);
00772
       sendDataBvte(drive);
00773
       sendDataByte((track » 8) & 0xff);
00774
        sendDataByte(track & 0xff);
00775
        sendCheckSum();
00776 }
```

4.1.4.16 pause()

```
void DFR0534::pause ()
```

Pause the current file.

Definition at line 180 of file DFR0534.cpp.

```
00181 {
00182    if (m_ptrStream == NULL) return; // Should not happen
00183    sendStartingCode();
00184    sendDataByte(0x03);
00185    sendDataByte(0x00);
00186    sendCheckSum();
00187 }
```

4.1.4.17 play()

```
void DFR0534::play ()
```

Play the current selected file.

Definition at line 168 of file DFR0534.cpp.

```
00169 {
00170     if (m_ptrStream == NULL) return; // Should not happen
00171     sendStartingCode();
00172     sendDataByte(0x02);
00173     sendDataByte(0x00);
00174     sendCheckSum();
00175 }
```

4.1.4.18 playCombined()

Combined/concatenated play of files.

Combined is like a playlist, for example playCombined("0103") for the two files 01 and 03. The Filenames must be two chars long and the files must be in a directory called /ZH Combined playback ignores loop mode and stops after last file.

Parameters

ir	list	Concatenated list of all files to play
----	------	--

Definition at line 858 of file DFR0534.cpp.

```
00860
        if (m_ptrStream == NULL) return; // Should not happen
00861
        if (list == NULL) return;
00862
       if ((strlen(list) % 2) != 0) return;
00863
00864
       sendStartingCode();
00865
       sendDataByte(0x1B);
00866
       sendDataByte(strlen(list));
00867
       for (int i=0;i<strlen(list);i++) {</pre>
00868
         sendDataByte(list[i]);
00869
00870
       sendCheckSum();
00871 }
```

4.1.4.19 playFileByName()

Play audio file by file name/path.

The file name/path is the full path of the audio file to be played in format which looks like a special unix 8+3 format:

- · Without a dot between file name and file extension
- · All characters in upper case
- · Maximal 8 characters for file name
- Every file and folder whose name length is shorter then 8 chars must be filled up to the 8 chars length by space chars
- · Must end with WAV or MP3
- · Only WAV and MP3 files are supported
- Wildcards * (=multiple arbitrary characters) and ? (=one single arbitrary character) are allowed and can be used to reduce the filling space chars

Valid examples:

- "/01 WAV" for a file '/01.wav'
- "/99-AFR~1MP3" for a file '/99-Africa.mp3'
- "/SUN*MP3" for first file matching '/sun*.mp3', for example '/sun.mp3'
- "/99-AFR*MP3" for first file matching '/99-Afr*.mp3'
- "/10*" for first audio file matching '/10*.*'
- "/10 /20 WAV" for the file '/10/20.wav' (first means first in "file copy order")

Parameters

in	path	Full path of the audio file	
in	drive	Drive, where file is stored: Drive DFR0534::DRIVEUSB, DFR0534::DRIVESD or	
		DFR0534::DRIVEFLASH (=default)	

Definition at line 252 of file DFR0534.cpp.

```
00253 {
00254
        if (m_ptrStream == NULL) return; // Should not happen
00255
        if (path == NULL) return;
00256
        if (drive >= DRIVEUNKNOWN) return;
00257
       sendStartingCode();
00258
        sendDataByte(0x08);
00259
       sendDataByte(strlen(path)+1);
00260
       sendDataByte(drive);
00261
       for (int i=0;i<strlen(path);i++) {</pre>
00262
         sendDataByte(path[i]);
00263
00264 sendCheckSum();
00265 }
```

4.1.4.20 playFileByNumber()

Play audio file by number.

File number order is "file copy order": First audio file copied to the drive gets number 1, second audio file copied gets number 2...)

Parameters

in	track	File number

Definition at line 135 of file DFR0534.cpp.

```
00136 {
00137
        if (m_ptrStream == NULL) return; // Should not happen
        if (track <=0) return;</pre>
00138
00139
       sendStartingCode();
00140
       sendDataByte(0x07);
00141
        sendDataByte(0x02);
       sendDataByte((track » 8) & 0xff);
00142
00143
        sendDataByte(track & 0xff);
00144
       sendCheckSum();
00145 }
```

4.1.4.21 playLastInDirectory()

```
void DFR0534::playLastInDirectory ()
```

Play last file in directory (in "file copy order")

Definition at line 568 of file DFR0534.cpp.

```
00569 {
00570     if (m_ptrStream == NULL) return; // Should not happen
00571     sendStartingCode();
00572     sendDataByte(0x0E);
00573     sendDataByte(0x00);
00574     sendCheckSum();
00575 }
```

4.1.4.22 playNext()

```
void DFR0534::playNext ()
```

Play next file (in "file copy order")

Definition at line 216 of file DFR0534.cpp.

```
00217 {
00218     if (m_ptrStream == NULL) return; // Should not happen
00219     sendStartingCode();
00220     sendDataByte(0x06);
00221     sendDataByte(0x00);
00222     sendCheckSum();
00223 }
```

4.1.4.23 playNextDirectory()

```
void DFR0534::playNextDirectory ()
```

Play first file in next directory (in "file copy order")

Definition at line 580 of file DFR0534.cpp.

```
00581 {
00582     if (m_ptrStream == NULL) return; // Should not happen
00583     sendStartingCode();
00584     sendDataByte(0x0F);
00585     sendDataByte(0x00);
00586     sendCheckSum();
00587 }
```

4.1.4.24 playPrevious()

```
void DFR0534::playPrevious ()
```

Play previous file (in "file copy order")

Definition at line 204 of file DFR0534.cpp.

```
00205 {
00206    if (m_ptrStream == NULL) return; // Should not happen
00207    sendStartingCode();
00208    sendDataByte(0x05);
00209    sendDataByte(0x00);
00210    sendCheckSum();
00211 }
```

4.1.4.25 prepareFileByNumber()

Select file by number, but not start playing.

Parameters

```
in track Number for file
```

Definition at line 972 of file DFR0534.cpp.

```
00973 {
00974     if (m_ptrStream == NULL) return; // Should not happen
00975     sendStartingCode();
00976     sendDataByte(0x1F);
00977     sendDataByte(0x02);
00978     sendDataByte((track » 8) & 0xff);
00979     sendDataByte(track & 0xff);
00980     sendCheckSum();
00981 }
```

4.1.4.26 repeatPart()

Repeat part of the current file.

Repeat between time start and stop position

Parameters

in	startMinute	Minute for start position
in	startSecond	Second for start position
in	stopMinute	Minute for stop position
in	stopSecond	Seconde for stop position

Definition at line 993 of file DFR0534.cpp.

```
if (m_ptrStream == NULL) return; // Should not happen
00995
00996
        sendStartingCode();
00997
        sendDataByte(0x20);
       sendDataByte(0x04);
00998
       sendDataByte(startMinute);
01000
       sendDataByte(startSecond);
01001
        sendDataByte(stopMinute);
01002
        sendDataByte(stopSecond);
01003
       sendCheckSum();
01004 }
```

4.1.4.27 setChannel()

Set output for DAC to channel MP3, AUX or both.

I found not P26/P27 for AUX on my DFR0534 => Only DFR0534::CHANNELMP3 makes sense (and is already set by default) Perhaps this function works on other audio modules with the same chip.

Parameters

in	channel	Output channel: DFR0534::CHANNELMP3, DFR0534::CHANNELAUX or
		DFR0534::CHANNELMP3AUX

Definition at line 893 of file DFR0534.cpp.

```
00894 {
00895    if (m_ptrStream == NULL) return; // Should not happen
00896    if (channel >= CHANNELUNKNOWN) return;
00897    sendStartingCode();
00898    sendDataByte(0x1D);
00899    sendDataByte(0x01);
00900    sendDataByte(channel);
00901    sendCheckSum();
00902 }
```

4.1.4.28 setDirectory()

Should set directory, but does not work for me.

Parameters

in	path	Directory
in	drive	Drive, where directory is stored: Drive DFR0534::DRIVEUSB, DFR0534::DRIVESD or
		DFR0534::DRIVEFLASH (=default)

Definition at line 798 of file DFR0534.cpp.

```
if (m_ptrStream == NULL) return; // Should not happen
00801
        if (path == NULL) return;
        if (drive >= DRIVEUNKNOWN) return;
00802
        sendStartingCode();
00803
        sendDataByte(0x17);
sendDataByte(strlen(path)+1);
00804
00805
00806
        sendDataByte(drive);
00807
        for (int i=0;i<strlen(path);i++) {</pre>
80800
         sendDataByte(path[i]);
00809
00810
       sendCheckSum();
00811 }
```

4.1.4.29 setDrive()

Switch to drive.

Parameters

in	drive	Drive DFR0534::DRIVEUSB, DFR0534::DRIVESD or DFR0534::DRIVEFLASH
----	-------	--

Definition at line 408 of file DFR0534.cpp.

```
00409 {
00410    if (m_ptrStream == NULL) return; // Should not happen
00411    if (drive >= DRIVEUNKNOWN) return;
00412    sendStartingCode();
00413    sendDataByte(0x0B);
00414    sendDataByte(0x01);
00415    sendDataByte(drive);
00416    sendCheckSum();
```

4.1.4.30 setEqualizer()

Set equalizer to NORMAL, POP, ROCK, JAZZ or CLASSIC.

Parameters

in	mode	EQ mode: DFR0534::NORMAL, DFR0534::POP, DFR0534::ROCK, DFR0534::JAZZ or
		DFR0534::CLASSIC

Definition at line 116 of file DFR0534.cpp.

```
00117 {
00118    if (m_ptrStream == NULL) return; // Should not happen
00119    if (mode >= EQUNKNOWN) return;
00120    sendStartingCode();
00121    sendDataByte(0x1A);
00122    sendDataByte(0x01);
00123    sendDataByte(mode);
00124    sendCheckSum();
00125 }
```

4.1.4.31 setLoopMode()

Set loop mode.

Parameters

in	mode	Loop mode: DFR0534::LOOPBACKALL, DFR0534::SINGLEAUDIOLOOP,
		DFR0534::SINGLEAUDIOSTOP, DFR0534::PLAYRANDOM, DFR0534::DIRECTORYLOOP,
		DFR0534::RANDOMINDIRECTORY, DFR0534::SEQUENTIALINDIRECTORY or
		DFR0534::SEQUENTIAL

Definition at line 818 of file DFR0534.cpp.

```
00819 {
    if (m_ptrStream == NULL) return; // Should not happen
    00821    if (mode >= PLAYMODEUNKNOWN) return;

00822    sendStartingCode();

00823    sendDataByte(0x18);

00824    sendDataByte(0x01);

00825    sendDataByte(mode);

00826    sendCheckSum();

00827 }
```

4.1.4.32 setRepeatLoops()

Set repeat loops.

Only valid for loop modes DFR0534::LOOPBACKALL, DFR0534::SINGLEAUDIOLOOP or DFR0534::DIRECTORYLOOP

Parameters

in loops Number of loops

Definition at line 836 of file DFR0534.cpp.

```
00837 {
00838    if (m_ptrStream == NULL) return; // Should not happen
00839    sendStartingCode();
00840    sendDataByte(0x19);
00841    sendDataByte(0x02);
00842    sendDataByte((loops » 8) & 0xff);
00843    sendDataByte(loops & 0xff);
00844    sendCheckSum();
00845 }
```

4.1.4.33 setVolume()

Set volume.

Volumen levels 0-30 are allowed. Audio module starts always with level 20.

Parameters

in <i>volume</i>	Volume level
------------------	--------------

Definition at line 154 of file DFR0534.cpp.

```
00155 {
00156    if (m_ptrStream == NULL) return; // Should not happen
00157    if (volume > 30) volume = 30;
00158    sendStartingCode();
00159    sendDataByte(0x13);
00160    sendDataByte(0x01);
00161    sendDataByte(volume);
00162    sendCheckSum();
00163 }
```

4.1.4.34 startSendingRuntime()

```
void DFR0534::startSendingRuntime ()
```

Start sending elapsed runtime every 1 second.

Definition at line 1136 of file DFR0534.cpp.

```
01137 {
01138     if (m_ptrStream == NULL) return; // Should not happen
01139     sendStartingCode();
01140     sendDataByte(0x25);
01141     sendDataByte(0x00);
01142     sendCheckSum();
01143 }
```

4.1.4.35 stop()

```
void DFR0534::stop ()
```

Stop the current file.

Definition at line 192 of file DFR0534.cpp.

```
00193 {
00194     if (m_ptrStream == NULL) return; // Should not happen
00195     sendStartingCode();
00196     sendDataByte(0x04);
00197     sendDataByte(0x00);
00198     sendCheckSum();
00199 }
```

4.1.4.36 stopCombined()

```
void DFR0534::stopCombined ()
```

Stop combined play (playlist)

Definition at line 876 of file DFR0534.cpp.

```
00877 {
00878    if (m_ptrStream == NULL) return; // Should not happen
00879    sendStartingCode();
00880    sendDataByte(0x1C);
00881    sendDataByte(0x00);
00882    sendCheckSum();
00883 }
```

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4.1.4.37 stopInsertedFile()

```
void DFR0534::stopInsertedFile ()
```

Stop inserted file.

Continue original file

Definition at line 783 of file DFR0534.cpp.

```
00784 {
00785     if (m_ptrStream == NULL) return; // Should not happen
00786     sendStartingCode();
00787     sendDataByte(0x10);
00788     sendDataByte(0x00);
00789     sendCheckSum();
00790 }
```

4.1.4.38 stopRepeatPart()

```
void DFR0534::stopRepeatPart ()
```

Stop repeating part of the current file.

Definition at line 1009 of file DFR0534.cpp.

```
01010 {
01011    if (m_ptrStream == NULL) return; // Should not happen
01012    sendStartingCode();
01013    sendDataByte(0x21);
01014    sendDataByte(0x00);
01015    sendCheckSum();
01016 }
```

4.1.4.39 stopSendingRuntime()

```
void DFR0534::stopSendingRuntime ()
```

Stop sending runtime.

Definition at line 1225 of file DFR0534.cpp.

```
01226 {
01227    if (m_ptrStream == NULL) return; // Should not happen
01228    sendStartingCode();
01229    sendDataByte(0x26);
01230    sendDataByte(0x00);
01231    sendCheckSum();
01232 }
```

The documentation for this class was generated from the following files:

- DFR0534.h
- DFR0534.cpp

Chapter 5

File Documentation

5.1 playCombined.ino

```
00002
      * Example for using the DFR0534 for playing combined audio files like a playlist
00003
00004 \,* This code was made for Arduino Uno/Nano. For ESP32 you have the change the code to use
     HardwareSerial
00005 * instead of SoftwareSerial (see https://github.com/codingABI/DFR0534#hardwareserial-for-esp32)
00006 */
00007
00008 #include <SoftwareSerial.h>
00009 #include <DFR0534.h>
00010
00011 #define TX PIN A0
00012 #define RX_PIN A1
00013 SoftwareSerial g_serial(RX_PIN, TX_PIN);
00014 DFR0534 g_audio(g_serial);
00015
00020 g_serial.begin(9600);
00021
00022
       // Set volume
00023
       g_audio.setVolume(18);
00024
00025
       /* The parameter string for the playCombined function is just
        * a concatenation of all files in the desired order without * path and without extension.
00026
00027
00028
        * All files have to be in the folder /ZH and the each
00029
        * file has to have a length (without extension) of two chars.
00030
00031
         * You can get example files from
     https://github.com/codingABI/DFR0534/tree/main/assets/exampleContent
00032
00033
00034
        /* Plays files the custom order, like a playlist and stops after the last file:
        * /ZH/05.wav
* /ZH/04.wav
00035
00036
        * /ZH/03.wav
00038
        * /ZH/02.wav
00039
        * /ZH/01.wav
00040
        * /ZH/OA.wav
00041
       g_audio.playCombined("05040302010A");
00042
00043 }
00044
00045 void loop() {
00046
       static unsigned long lastDisplayMS = millis();
00047
       char name[12]:
00048
        // Show information about current track every 500ms
00050
       if (millis()-lastDisplayMS > 500) {
00051
          Serial.print("number: ");
         word fileNumber = g_audio.getFileNumber();
if (fileNumber > 0) Serial.print(fileNumber); else Serial.print("--");
00052
00053
00054
00055
          Serial.print(" name: ");
          if (g_audio.getFileName(name)) Serial.print(name);
```

```
Serial.print(" status: ");
00058
00059
         switch (g_audio.getStatus()) {
00060
           case DFR0534::STOPPED:
00061
             Serial.println("Stopped");
00062
             break:
           case DFR0534::PAUSED:
00064
           Serial.println("Paused");
00065
             break;
           case DFR0534::PLAYING:
00066
00067
             Serial.println("Playing");
00068
             break:
           case DFR0534::STATUSUNKNOWN:
00069
00070
            Serial.println("Unknown");
00071
             break;
00072
         lastDisplayMS = millis();
00073
00074
       }
```

5.2 playFileByName.ino

```
00001 /*
00002 \star Example for using the DFR0534 for playing audio files by file name
00003 *
00004
      * This code was made for Arduino Uno/Nano. For ESP32 you have the change the code to use
00005 \star instead of SoftwareSerial (see https://github.com/codingABI/DFR0534#hardwareserial-for-esp32) 00006 \star/
00007
00008 #include <SoftwareSerial.h>
00009 #include <DFR0534.h>
00011 #define TX_PIN A0
00012 #define RX_PIN A1
00013 SoftwareSerial g_serial(RX_PIN, TX_PIN);
00014 DFR0534 g_audio(g_serial);
00015
00016 void setup() {
00017 // Serial for console output
       Serial.begin(9600);
00018
00019
       // Software serial for communication to DFR0534 module
00020
       q_serial.begin(9600);
00021
       // Set volume
00023
       g_audio.setVolume(18);
00024
00025
       /\star The file name/path for the function playFileByName() is the
00026
       * full path of the audio file to be played in format which looks like * a special unix 8+3 format:
00027
00028
        * - Without a dot between file name and file extension
        * - All characters in upper case
00030
        * - Maximal 8 characters for file name
00031
        \star - Every file and folder whose name length is shorter then 8 chars
        \star \, must be filled up to the 8 chars length by space chars \star - Must end with WAV or MP3
00032
00033
00034
        * - Only WAV and MP3 files are supported
00035
        * - Wildcards * (=multiple arbitrary characters) and ? (=one single arbitrary character)
00036
        * are allowed and can be used to reduce the filling space chars
00037
00038
        * Valid examples:
                      WAV" for a file '/01.wav'
00039
        * - "/01
        * - "/99-AFR~1MP3" for a file '/99-Africa.mp3'
00040
         * - "/SUN*MP3" for first file matching '/sun*.mp3', for example '/sun.mp3'
        00042
00043
        * - "/10
00044
        * (first means first in "file copy order")
00045
00046
00047
        * You can get example files from
00048
         * https://github.com/codingABI/DFR0534/tree/main/assets/exampleContent
00049
00050
        // Play the file "test.wav"
00051
       g_audio.playFileByName("/TEST
                                         WAV");
00052
00053 }
00054
00055 void loop() {
00056
       static unsigned long lastDisplayMS = millis()-500;
00057
       char name[12]:
00058
00059
       // Show information about current track once per second
       if (millis()-lastDisplayMS > 1000) {
```

```
Serial.print("number: ");
          word fileNumber = g_audio.getFileNumber();
if (fileNumber > 0) Serial.print(fileNumber); else Serial.print("--");
00062
00063
00064
          Serial.print(" name: ");
00065
          if (g_audio.getFileName(name)) Serial.print(name);
00066
00068
          Serial.print(" status: ");
00069
          switch (g_audio.getStatus()) {
00070
            case DFR0534::STOPPED:
00071
              Serial.println("Stopped");
00072
              break:
            case DFR0534::PAUSED:
00073
00074
             Serial.println("Paused");
00075
              break;
            case DFR0534::PLAYING:
00076
00077
             Serial.println("Playing");
00078
              break;
            case DFR0534::STATUSUNKNOWN:
08000
              Serial.println("Unknown");
00081
00082
          lastDisplayMS = millis();
00083
00084
00085 }
```

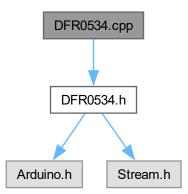
5.3 playFileByNumber.ino

```
00001 /*
00002
       \star Example for using the DFR0534 for playing audio files by file number
00003
       \star This code was made for Arduino Uno/Nano. For ESP32 you have the change the code to use
00004
     HardwareSerial
00005 * instead of SoftwareSerial (see https://github.com/codingABI/DFR0534#hardwareserial-for-esp32)
00006 */
00007
00008 #include <SoftwareSerial.h>
00009 #include <DFR0534.h>
00010
00011 #define TX_PIN A0
00012 #define RX_PIN A1
00013 SoftwareSerial g_serial(RX_PIN, TX_PIN);
00014 DFR0534 g_audio(g_serial);
00015
00016 void setup() {
00017
       // Serial for console output
00018
       Serial.begin(9600);
00019
        // Software serial for communication to DFR0534 module
00020
       g_serial.begin(9600);
00021
00022
        // Set volume
        g_audio.setVolume(18);
00024
00025
        // Show some device infos
        Serial.print("Ready drives: ");
00026
        byte drive = g_audio.getDrivesStates();
if (((drive » DFR0534::DRIVEUSB) & 1) == 1) Serial.print("USB ");
if (((drive » DFR0534::DRIVESD) & 1) == 1) Serial.print("SD ");
00027
00028
00029
00030
        if (((drive » DFR0534::DRIVEFLASH) & 1) == 1) Serial.print("FLASH ");
00031
        Serial.println();
00032
00033
        Serial.print("Current playing drive: ");
00034
        switch(g_audio.getDrive()) {
         case DFR0534::DRIVEUSB:
00036
            Serial.println("USB");
00037
            break;
00038
          case DFR0534::DRIVESD:
          Serial.println("SD");
00039
00040
            break:
00041
          case DFR0534::DRIVEFLASH:
           Serial.println("FLASH");
00043
          case DFR0534::DRIVENO:
00044
00045
            Serial.println("No drive");
00046
            break:
00047
          default:
00048
            Serial.println("Unknown");
00049
00050
00051
        Serial.print("Total files: ");
00052
00053
        Serial.println(g_audio.getTotalFiles());
        Serial.print("Total files in directory: ");
```

```
Serial.println(g_audio.getTotalFilesInCurrentDirectory());
00056
00057
        Serial.print("First file: ");
        Serial.println(g_audio.getFirstFileNumberInCurrentDirectory());
00058
00059
00060
         // Play the first audio file copied to the DFR0534
00061
        // (Second file copied to the DFR0534 would be number 2...)
00062
        g_audio.playFileByNumber(1);
00063 }
00064
00065 void loop() {
00066
        static unsigned long lastDisplayMS = millis()-500;
00067
        char name[12];
00068
00069
        \ensuremath{//} Show information about current track once per second
        if (millis()-lastDisplayMS > 1000) {
   Serial.print("number: ");
00070
00071
          if (fileNumber > 0) Serial.print(fileNumber); else Serial.print("--");
00072
00074
00075
           Serial.print(" name: ");
00076
           if (g_audio.getFileName(name)) Serial.print(name);
00077
          Serial.print(" status: ");
switch (g_audio.getStatus()) {
   case DFR0534::STOPPED:
00078
00079
08000
00081
               Serial.println("Stopped");
00082
              break;
             case DFR0534::PAUSED:
00083
             Serial.println("Paused");
00084
00085
               break:
00086
            case DFR0534::PLAYING:
00087
             Serial.println("Playing");
88000
               break;
             case DFR0534::STATUSUNKNOWN:
   Serial.println("Unknown");
00089
00090
00091
               break;
00093
           lastDisplayMS = millis();
00094
00095 }
```

5.4 DFR0534.cpp File Reference

#include "DFR0534.h"
Include dependency graph for DFR0534.cpp:



5.4.1 Detailed Description

Class: DFR0534

Description: Class for controlling a DFR0534 audio module (https://wiki.dfrobot.com/Voice_← Module_SKU__DFR0534) by SoftwareSerial

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Notes for DFR0534 audio module:

- Consumes about 20mA when idle (Vcc = 5V)
- · Creates a short "click" noise, when Vcc is powered on
- Should be used with a 1k resistor on TX when your MCU runs on 5V, because the DFR0534 uses 3.3V logic (and 5V on TX causes clicks/noise)
- Can be controlled by a RX/TX serial connection (9600 baud) or one-wire protocol
- · Can play WAV and MP3 audiofiles
- Can "insert" audiofiles while another audiofile is running. In this case to original audiofile is paused and will be resumed after the "inserted" audiofile
- Can play files in a playlist like mode called "combined" for files stored in a directory /ZH
- Can select the file to play by a file number* or file name** *File number is independent from file name. The first WAV or MP3 copied to the DFR0534 gets file number 1 and so on. To play a file by number use playFileByNumber() **File name is a little bit like a 8+3 file path and can be used with playFileByName(), but have special rules (see playFileByName() for details)
- · Can send automatically the file runtime every second (when enabled)
- · Has a NS8002 amplifier, JQ8400 Audio chip, W25Q64JVSIQ flash memory
- Has a Sleep mode 0x1B and this mode only works with one-wire protocol (https://github.
 com/arduino12/mp3_player_module_wire) and does not work for me without additional electric modifications (e.g. disconnecting speakers) => Switching off DFR0534 with a FET is a better solution

Definition in file DFR0534.cpp.

1.0.4

5.5 DFR0534.cpp

Go to the documentation of this file.

```
00001
00043 #include "DFR0534.h"
00044
00053 byte DFR0534::getStatus()
00054 {
00055
        #define COMMAND 0x01
        #define RECEIVEBYTETIMEOUTMS 100
00056
00057
        #define RECEIVEGLOBALTIMEOUTMS 500
00058
        #define RECEIVEFAILED STATUSUNKNOWN
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00060
00061
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00062
        sendStartingCode();
        sendDataByte(COMMAND);;
00063
00064
        sendDataBvte(0x00);;
00065
        sendCheckSum();
00066
00067
        // Receive
00068
        int i=0;
        byte data, firstByte = 0, sum, length=0xff, result = 0;
00069
00070
        unsigned long receiveStartMS = millis();
00071
        do {
00072
          byte dataReady = 0;
00073
          unsigned long lastMS = millis();
00074
          // Wait for response or timeout
00075
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00076
00077
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00078
          data = m_ptrStream->read();
00079
          if (i==0) { // Begin of transmission
00080
            firstByte=data;
00081
00082
            sum = 0;
00083
00084
          if ((i == 1) && (data != COMMAND)) {
00085
            // Invalid signal => reset receive
            i=0;
00086
00087
            firstByte = 0;
00088
00089
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 1) {
00090
00091
00092
              // Invalid length => reset receive
00093
              i = 0:
00094
              firstByte = 0;
00095
00096
00097
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00098
            result = data;
00099
00100
          if (firstBvte == STARTINGCODE) {
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00101
00102
            i++;
00103
00104
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00105
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00106
00107
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00108
        return result;
00109 }
00110
00116 void DFR0534::setEqualizer(byte mode)
00117 {
        if (m_ptrStream == NULL) return; // Should not happen
00118
        if (mode >= EQUNKNOWN) return;
00119
00120
        sendStartingCode();
00121
        sendDataByte(0x1A);
00122
        sendDataByte(0x01);
        sendDataByte(mode);
00123
00124
        sendCheckSum();
00125 }
00126
00135 void DFR0534::playFileByNumber(word track)
00136 {
        if (m_ptrStream == NULL) return; // Should not happen
if (track <=0) return;</pre>
00137
00138
        sendStartingCode();
00139
        sendDataByte(0x07);
00141
        sendDataByte(0x02);
00142
        sendDataByte((track » 8) & 0xff);
00143
        sendDataByte(track & 0xff);
```

```
00144
       sendCheckSum();
00145 }
00146
00154 void DFR0534::setVolume(byte volume)
00155 {
        if (m_ptrStream == NULL) return; // Should not happen
00156
        if (volume > 30) volume = 30;
00157
00158
        sendStartingCode();
00159
        sendDataByte(0x13);
00160
        sendDataByte(0x01);
00161
        sendDataByte(volume);
00162
        sendCheckSum();
00163 }
00164
00168 void DFR0534::play()
00169 {
        if (m_ptrStream == NULL) return; // Should not happen
00170
00171
        sendStartingCode();
00172
        sendDataByte(0x02);
00173
        sendDataByte(0x00);
00174
        sendCheckSum();
00175 }
00176
00180 void DFR0534::pause()
00181 {
        if (m_ptrStream == NULL) return; // Should not happen
00182
00183
        sendStartingCode();
00184
        sendDataByte(0x03);
00185
        sendDataByte(0x00);
00186
       sendCheckSum();
00187 }
00188
00192 void DFR0534::stop()
00193 {
00194
        if (m_ptrStream == NULL) return; // Should not happen
        sendStartingCode();
00195
00196
       sendDataByte(0x04);
00197
        sendDataByte(0x00);
00198
        sendCheckSum();
00199 }
00200
00204 void DFR0534::playPrevious()
00205 {
00206
        if (m_ptrStream == NULL) return; // Should not happen
00207
        sendStartingCode();
00208
        sendDataByte(0x05);
00209
        sendDataByte(0x00);
00210
       sendCheckSum();
00211 }
00212
00216 void DFR0534::playNext()
00217 {
00218
        if (m_ptrStream == NULL) return; // Should not happen
00219
        sendStartingCode();
00220
        sendDataByte(0x06);
00221
        sendDataByte(0x00);
00222
        sendCheckSum();
00223 }
00224
00252 void DFR0534::playFileByName(char *path, byte drive)
00253 {
        if (m_ptrStream == NULL) return; // Should not happen
00254
00255
        if (path == NULL) return;
00256
        if (drive >= DRIVEUNKNOWN) return;
00257
        sendStartingCode();
00258
        sendDataByte(0x08);
00259
        sendDataByte(strlen(path)+1);
00260
        sendDataByte(drive);
for (int i=0;i<strlen(path);i++) {</pre>
00261
00262
         sendDataByte(path[i]);
00263
00264
        sendCheckSum();
00265 }
00266
00278 byte DFR0534::getDrivesStates()
00279 {
00280
        #define COMMAND 0x09
00281
        #define RECEIVEBYTETIMEOUTMS 100
00282
        #define RECEIVEGLOBALTIMEOUTMS 500
        #define RECEIVEFAILED DRIVEUNKNOWN
00283
00284
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00285
00286
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00287
        sendStartingCode();
00288
        sendDataByte(COMMAND);
        sendDataByte(0x00);
00289
00290
        sendCheckSum();
```

```
00291
00292
        // Receive
00293
        int i=0:
        byte data, firstByte = 0, sum, length=0xff, result = 0;
unsigned long receiveStartMS = millis();
00294
00295
00296
        do {
00297
         byte dataReady = 0;
00298
          unsigned long lastMS = millis();
00299
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00300
     m_ptrStream->available();
00301
00302
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00303
          data = m_ptrStream->read();
00304
00305
          if (i==0) { // Begin of transmission
00306
            firstByte=data;
00307
            sum = 0;
00308
00309
          if ((i == 1) && (data != COMMAND)) {
00310
               Invalid signal => reset receive
00311
            i=0:
            firstByte = 0;
00312
00313
00314
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 1) {
00315
00316
00317
              // Invalid length => reset receive
00318
              i = 0:
              firstByte = 0;
00319
00320
            }
00321
00322
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00323
            result = data;
00324
          if (firstBvte == STARTINGCODE) {
00325
00326
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00328
00329
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00330
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00331
00332
        if (data != sum) return RECEIVEFALLED: // Does checksum matches?
00333
       return result;
00334 }
00335
00345 byte DFR0534::getDrive()
00346 {
        #define COMMAND 0x0A
00347
        #define RECEIVEBYTETIMEOUTMS 100
00348
        #define RECEIVEGLOBALTIMEOUTMS 500
00350
        #define RECEIVEFAILED DRIVEUNKNOWN
00351
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00352
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00353
00354
        sendStartingCode();
        sendDataByte(COMMAND);
00356
        sendDataByte(0x00);
00357
        sendCheckSum();
00358
00359
        // Receive
00360
        int i=0;
00361
        byte data, firstByte = 0, sum, length=0xff, result = 0;
00362
        unsigned long receiveStartMS = millis();
00363
00364
        byte dataReady = 0;
          unsigned long lastMS = millis();
00365
00366
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00367
     m_ptrStream->available();
00368
00369
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00370
          data = m_ptrStream->read();
00371
00372
          if (i==0) { // Begin of transmission
00373
            firstByte=data;
00374
            sum = 0;
00375
          if ((i == 1) && (data != COMMAND)) {
00376
00377
            // Invalid signal => reset receive
00378
            i=0;
00379
            firstByte = 0;
00380
00381
          if (i == RECEIVEHEADERLENGTH) {
00382
            length = data; // Length of receiving data
            if (length != 1) {
00383
              // Invalid length => reset receive
00384
```

```
00385
              i=0;
00386
              firstByte = 0;
00387
00388
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00389
00390
           result = data:
00392
          if (firstByte == STARTINGCODE) {
00393
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
            i++;
00394
00395
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00396
00397
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00398
00399
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00400
       return result;
00401 }
00402
00408 void DFR0534::setDrive(byte drive)
00409 {
00410
        if (m_ptrStream == NULL) return; // Should not happen
        if (drive >= DRIVEUNKNOWN) return;
00411
        sendStartingCode();
00412
00413
        sendDataByte(0x0B);
00414
        sendDataByte(0x01);
00415
        sendDataByte(drive);
00416
        sendCheckSum();
00417 }
00418
00427 word DFR0534::getFileNumber()
00428 {
00429
        #define COMMAND 0x0D
00430
       #define RECEIVEFAILED 0
00431
        #define RECEIVEBYTETIMEOUTMS 100
       #define RECEIVEGLOBALTIMEOUTMS 500
#define RECEIVEHEADERLENGTH 2 // startingcode+command
00432
00433
00434
00435
        if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00436
        sendStartingCode();
00437
        sendDataByte(COMMAND);
00438
        sendDataByte(0x00);
00439
       sendCheckSum();
00440
00441
        // Receive
00442
        int i=0;
00443
        byte data, firstByte = 0, sum, length=0xff;
00444
        word result = 0;
00445
        unsigned long receiveStartMS = millis();
00446
        do {
00447
         byte dataReady = 0;
00448
          unsigned long lastMS = millis();
00449
          // Wait for response or timeout
00450
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
00451
00452
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00453
          data = m_ptrStream->read();
00454
00455
          if (i==0) { // Begin of transmission
00456
            firstByte=data;
00457
            sum = 0:
00458
00459
          if ((i == 1) && (data != COMMAND)) {
00460
            // Invalid signal => reset receive
00461
            i=0;
00462
            firstByte = 0;
00463
          if (i == RECEIVEHEADERLENGTH) {
00464
            length = data; // Length of receiving data
if (length != 2) {
00465
00466
00467
              // Invalid length => reset receive
00468
              i=0;
00469
              firstByte = 0;
00470
            }
00471
00472
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
00473
            switch (i-RECEIVEHEADERLENGTH-1) {
00474
             case 0:
00475
               result=data«8;
00476
               break;
00477
              case 1:
00478
                result+=data;
00479
                break;
00480
            }
00481
          if (firstByte == STARTINGCODE) {
00482
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00483
```

```
00484
           i++;
00485
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00486
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00487
00488
00489
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00490
       return result;
00491 }
00492
00499 int DFR0534::getTotalFiles()
00500 {
00501
       #define COMMAND 0x0C
00502
       #define RECEIVEFAILED
00503
       #define RECEIVEBYTETIMEOUTMS 100
00504
        #define RECEIVEGLOBALTIMEOUTMS 500
00505
       #define RECEIVEHEADERLENGTH 2 // startingcode+command
00506
00507
       if (m_ptrStream == NULL) return RECEIVEFAILED; // Should not happen
00508
       sendStartingCode();
00509
       sendDataByte(COMMAND);
00510
       sendDataByte(0x00);
00511
       sendCheckSum();
00512
00513
       // Receive
00514
       int i=0;
00515
       byte data, firstByte = 0, sum, length=0xff;
00516
        word result = 0;
00517
       unsigned long receiveStartMS = millis();
00518
       do {
00519
         byte dataReady = 0;
         unsigned long lastMS = millis();
00520
00521
         // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =
00522
     m_ptrStream->available();
00523
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00524
00525
         data = m_ptrStream->read();
00527
          if (i==0) { // Begin of transmission
00528
          firstByte=data;
            sum = 0;
00529
00530
00531
          if ((i == 1) && (data != COMMAND)) {
00532
           // Invalid signal => reset receive
00533
            i=0;
00534
            firstByte = 0;
00535
          if (i == RECEIVEHEADERLENGTH) {
00536
00537
            length = data; // Length of receiving data
if (length != 2) {
00538
                Invalid length => reset receive
00540
              i=0;
00541
              firstByte = 0;
00542
           }
00543
00544
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
00545
           switch (i-RECEIVEHEADERLENGTH-1) {
00546
             case 0:
00547
              result=data«8;
00548
               break;
00549
             case 1:
00550
               result+=data;
00551
               break;
00552
           }
00553
00554
          if (firstByte == STARTINGCODE) {
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00555
            i++;
00556
00557
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00559
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00560
00561
       if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00562
       return result;
00563 }
00564
00568 void DFR0534::playLastInDirectory()
00569 {
       if (m_ptrStream == NULL) return; // Should not happen
00570
00571
       sendStartingCode():
00572
       sendDataByte(0x0E);
       sendDataByte(0x00);
00574
       sendCheckSum();
00575 }
00576
00580 void DFR0534::playNextDirectory()
00581 {
```

```
if (m_ptrStream == NULL) return; // Should not happen
00583
        sendStartingCode();
00584
        sendDataByte(0x0F);
00585
        sendDataByte(0x00);
00586
        sendCheckSum();
00587 }
00588
00595 int DFR0534::getFirstFileNumberInCurrentDirectory()
00596 {
00597
        #define COMMAND 0x11
       #define RECEIVEFAILED -1
00598
00599
        #define RECEIVEBYTETIMEOUTMS 100
        #define RECEIVEGLOBALTIMEOUTMS 500
00600
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00601
00602
00603
        if (m_ptrStream == NULL) RECEIVEFAILED; // Should not happen
00604
        sendStartingCode();
        sendDataByte(COMMAND);
00605
00606
        sendDataByte(0x00);
00607
        sendCheckSum();
00608
00609
        // Receive
00610
        int i=0;
00611
        byte data, firstByte = 0, sum, length=0xff;
00612
        word result = 0;
        unsigned long receiveStartMS = millis();
00613
00614
00615
          byte dataReady = 0;
00616
          unsigned long lastMS = millis();
00617
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00618
     m ptrStream->available();
00619
00620
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00621
          data = m_ptrStream->read();
00622
00623
          if (i==0) { // Begin of transmission
00624
            firstByte=data;
00625
            sum = 0;
00626
00627
          if ((i == 1) && (data != COMMAND)) {
            // Invalid signal => reset receive
00628
            i=0;
00629
00630
            firstByte = 0;
00631
00632
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 2) {
00633
00634
              // Invalid length => reset receive
00635
              i=0;
00636
00637
              firstByte = 0;
00638
            }
00639
00640
           \  \  \text{if ((i>RECEIVEHEADERLENGTH) \&\& (i-RECEIVEHEADERLENGTH-1<length)) } \  \  \{ \  \  \  \  \} \  \  \} 
00641
            switch (i-RECEIVEHEADERLENGTH-1) {
00642
             case 0:
00643
               result=data«8;
00644
                break;
00645
              case 1:
00646
                result+=data;
00647
                break;
00648
            }
00649
00650
          if (firstByte == STARTINGCODE) {
00651
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
00652
            i++;
00653
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00654
00655
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00657
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00658
        return result;
00659 }
00660
00667 int DFR0534::getTotalFilesInCurrentDirectory()
00668 {
00669
        #define COMMAND 0x12
00670
        #define RECEIVEFAILED -1
        #define RECEIVEBYTETIMEOUTMS 100
00671
00672
        #define RECEIVEGLOBALTIMEOUTMS 500
00673
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00674
00675
        if (m_ptrStream == NULL) RECEIVEFAILED; // Should not happen
00676
        sendStartingCode();
00677
        sendDataByte(COMMAND);
00678
        sendDataByte(0x00);
00679
        sendCheckSum();
```

```
00681
        // Receive
00682
        int i=0;
        byte data, firstByte = 0, sum, length=0xff;
00683
00684
        word result = 0;
00685
        unsigned long receiveStartMS = millis();
00686
00687
          byte dataReady = 0;
00688
          unsigned long lastMS = millis();
          // Wait for response or timeout
while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00689
00690
     m_ptrStream->available();
00691
00692
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00693
          data = m_ptrStream->read();
00694
          if (i==0) { // Begin of transmission
00695
00696
            firstByte=data;
            sum = 0;
00697
00698
00699
          if ((i == 1) && (data != COMMAND)) {
00700
            // Invalid signal => reset receive
00701
            i = 0:
00702
            firstByte = 0;
00703
00704
          if (i == RECEIVEHEADERLENGTH) {
00705
            length = data; // Length of receiving data
            if (length != 2) {
00706
00707
              // Invalid length => reset receive
00708
              i=0;
00709
              firstBvte = 0:
00710
            }
00711
00712
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00713
            switch (i-RECEIVEHEADERLENGTH-1) {
00714
             case 0:
               result=data«8;
break;
00715
00716
00717
              case 1:
00718
               result+=data;
00719
                break;
00720
            }
00721
00722
          if (firstByte == STARTINGCODE) {
00723
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00724
00725
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
00726
00727
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00728
00729
        if (data != sum) return RECEIVEFAILED; // Does checksum matches?
00730
        return result;
00731 }
00732
00736 void DFR0534::increaseVolume()
00737 {
00738
        if (m_ptrStream == NULL) return; // Should not happen
00739
        sendStartingCode();
00740
        sendDataByte(0x14);
00741
        sendDataByte(0x00);
00742
       sendCheckSum();
00743 }
00744
00748 void DFR0534::decreaseVolume()
00749 {
00750
        if (m_ptrStream == NULL) return; // Should not happen
00751
        sendStartingCode();
00752
        sendDataBvte(0x15);
00753
        sendDataByte(0x00);
00754
        sendCheckSum();
00755 }
00756
00765 void DFR0534::insertFileByNumber(word track, byte drive)
00766 {
00767
        if (m_ptrStream == NULL) return; // Should not happen
00768
        if (drive >= DRIVEUNKNOWN) return;
00769
        sendStartingCode();
00770
        sendDataByte(0x16);
00771
        sendDataByte(0x03);
00772
        sendDataByte(drive);
00773
       sendDataByte((track » 8) & 0xff);
00774
        sendDataByte(track & 0xff);
00775
        sendCheckSum();
00776 }
00777
00783 void DFR0534::stopInsertedFile()
00784 {
```

```
if (m_ptrStream == NULL) return; // Should not happen
00786
        sendStartingCode();
00787
        sendDataByte(0x10);
00788
        sendDataByte(0x00);
00789
        sendCheckSum();
00790 }
00791
00798 void DFR0534::setDirectory(char *path, byte drive)
00799 {
        if (m_ptrStream == NULL) return; // Should not happen
00800
        if (m_persoredam NoBB) return;
if (path == NULL) return;
if (drive >= DRIVEUNKNOWN) return;
00801
00802
00803
        sendStartingCode();
00804
        sendDataByte(0x17);
00805
        sendDataByte(strlen(path)+1);
00806
        sendDataByte(drive);
        for (int i=0;i<strlen(path);i++) {</pre>
00807
80800
         sendDataByte(path[i]);
00809
00810
       sendCheckSum();
00811 }
00812
00818 void DFR0534::setLoopMode(byte mode)
00819 {
00820
        if (m_ptrStream == NULL) return; // Should not happen
        if (mode >= PLAYMODEUNKNOWN) return;
00821
00822
        sendStartingCode();
00823
        sendDataByte(0x18);
00824
        sendDataByte(0x01);
00825
        sendDataByte(mode);
00826
        sendCheckSum();
00827 }
00828
00836 void DFR0534::setRepeatLoops(word loops)
00837 {
        if (m_ptrStream == NULL) return; // Should not happen
00838
00839
        sendStartingCode();
        sendDataByte(0x19);
00841
        sendDataByte(0x02);
00842
        sendDataByte((loops » 8) & 0xff);
00843
        sendDataByte(loops & 0xff);
00844
        sendCheckSum();
00845 }
00846
00858 void DFR0534::playCombined(char* list)
00859 {
00860
        if (m_ptrStream == NULL) return; // Should not happen
        if (list == NULL) return;
if ((strlen(list) % 2) != 0) return;
00861
00862
00863
00864
        sendStartingCode();
00865
        sendDataByte(0x1B);
00866
        sendDataByte(strlen(list));
00867
        for (int i=0;i<strlen(list);i++) {</pre>
00868
         sendDataByte(list[i]);
00869
00870
        sendCheckSum();
00871 }
00872
00876 void DFR0534::stopCombined()
00877 {
00878
        if (m_ptrStream == NULL) return; // Should not happen
00879
        sendStartingCode();
00880
        sendDataByte(0x1C);
00881
        sendDataByte(0x00);
00882
        sendCheckSum();
00883 }
00884
00893 void DFR0534::setChannel(byte channel)
00894 {
00895
        if (m_ptrStream == NULL) return; // Should not happen
00896
        if (channel >= CHANNELUNKNOWN) return;
        sendStartingCode();
00897
00898
        sendDataByte(0x1D);
00899
        sendDataByte(0x01);
00900
        sendDataByte(channel);
00901
        sendCheckSum();
00902 }
00903
00913 bool DFR0534::getFileName(char *name)
00914 {
00915
        #define COMMAND 0x1E
00916
        #define RECEIVEBYTETIMEOUTMS 100
00917
        #define RECEIVEGLOBALTIMEOUTMS 500
00918
        #define RECEIVEFAILED false
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
00919
00920
```

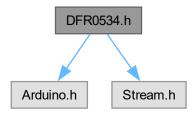
```
if (m_ptrStream == NULL) return false; // Should not happen
        if (name == NULL) return false;
name[0] = '\0';
00922
00923
00924
00925
        sendStartingCode();
00926
        sendDataByte(COMMAND);
00927
        sendDataByte(0x00);
00928
        sendCheckSum();
00929
00930
        // Receive
00931
        int i=0:
00932
        byte data, firstByte = 0, sum, length=0xff;
00933
        unsigned long receiveStartMS = millis();
00934
00935
          byte dataReady = 0;
00936
          unsigned long lastMS = millis();
00937
          // Wait for response or timeout
          while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
00938
     m_ptrStream->available();
00939
00940
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
00941
          data = m_ptrStream->read();
          if (i==0) { // Begin of transmission
00942
00943
            firstBvte=data;
00944
            sum = 0;
00945
00946
          if ((i == 1) && (data != COMMAND)) {
00947
            // Invalid signal => reset receive
00948
            i=0;
            firstByte = 0;
00949
00950
00951
          if (i == RECEIVEHEADERLENGTH) length = data; // Length of receiving string
00952
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {</pre>
00953
               ((i-RECEIVEHEADERLENGTH) < 12) { // I expect no longer file names than 8+3 chars plus '\0'
             name[i-RECEIVEHEADERLENGTH-1] = data;
name[i-RECEIVEHEADERLENGTH] = '\0';
00954
00955
00956
            }
00958
          if (firstByte == STARTINGCODE) {
00959
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum</pre>
00960
            i++;
00961
00962
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFALLED: // Timeout
00963
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
00964
        return (data == sum); // Does checksum matches?
00965 }
00966
00972 void DFR0534::prepareFileByNumber(word track)
00973 {
00974
        if (m_ptrStream == NULL) return; // Should not happen
00975
        sendStartingCode();
00976
        sendDataByte(0x1F);
00977
        sendDataByte(0x02);
00978
        sendDataByte((track » 8) & 0xff);
00979
        sendDataByte(track & 0xff);
00980
        sendCheckSum();
00981 }
00982
00993 void DFR0534::repeatPart(byte startMinute, byte startSecond, byte stopMinute, byte stopSecond)
00994 {
        if (m_ptrStream == NULL) return; // Should not happen
00995
00996
       sendStartingCode();
00997
        sendDataByte(0x20);
00998
        sendDataByte(0x04);
00999
        sendDataByte(startMinute);
01000
        sendDataByte(startSecond);
01001
        sendDataByte(stopMinute);
        sendDataByte(stopSecond);
01002
01003
        sendCheckSum();
01004 }
01005
01009 void DFR0534::stopRepeatPart()
01010 {
        if (m_ptrStream == NULL) return; // Should not happen
01011
01012
        sendStartingCode();
01013
        sendDataByte(0x21);
01014
        sendDataByte(0x00);
01015
        sendCheckSum();
01016 }
01017
01025 void DFR0534::fastBackwardDuration(word seconds)
01026 {
01027
        if (m_ptrStream == NULL) return; // Should not happen
01028
        sendStartingCode();
01029
        sendDataByte(0x22);
01030
        sendDataByte(0x02);
01031
       sendDataByte((seconds » 8) & 0xff);
```

```
sendDataByte(seconds & 0xff);
01033
        sendCheckSum();
01034 }
01035
01042 void DFR0534::fastForwardDuration(word seconds)
01043 {
        if (m_ptrStream == NULL) return; // Should not happen
01044
01045
        sendStartingCode();
01046
        sendDataByte(0x23);
01047
        sendDataByte(0x02);
        sendDataByte((seconds » 8) & 0xff);
01048
01049
        sendDataBvte(seconds & 0xff);
01050
        sendCheckSum();
01051 }
01052
01065 bool DFR0534::getDuration(byte &hour, byte &minute, byte &second)
01066 {
01067
        #define COMMAND 0x24
        #define RECEIVEFAILED false
01068
        #define RECEIVEBYTETIMEOUTMS 100
01069
01070
        #define RECEIVEGLOBALTIMEOUTMS 500
01071
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
01072
01073
        if (m_ptrStream == NULL) return false; // Should not happen
01074
        sendStartingCode();
01075
        sendDataByte(COMMAND);
01076
        sendDataByte(0x00);
01077
        sendCheckSum();
01078
01079
        // Receive
01080
       int i=0:
01081
        byte data, firstByte = 0, sum, length=0xff;
01082
        word result = 0;
01083
        unsigned long receiveStartMS = millis();
01084
         byte dataReady = 0;
01085
          unsigned long lastMS = millis();
// Wait for response or timeout
01086
01087
01088
           while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
     m_ptrStream->available();
01089
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
data = m_ptrStream->read();
01090
01091
01092
01093
          if (i==0) { // Begin of transmission
01094
            firstByte=data;
01095
            sum = 0;
01096
          if ((i == 1) && (data != COMMAND)) {
01097
            // Invalid signal => reset receive
01098
            i=0;
01099
01100
            firstByte = 0;
01101
01102
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 3) {
01103
01104
              // Invalid length => reset receive
01106
              i=0;
01107
              firstByte = 0;
01108
            }
01109
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
01110
01111
            switch (i-RECEIVEHEADERLENGTH-1) {
             case 0:
01112
01113
                hour=data;
01114
                break;
01115
              case 1:
01116
               minute=data;
01117
                break:
01118
              case 2:
01119
               second=data;
01120
                break;
01121
            }
01122
          if (firstByte == STARTINGCODE) {
01123
01124
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
01125
01126
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
01127
01128
       } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
01129
01130
        return (data == sum); // Does checksum matches?
01131 }
01132
01136 void DFR0534::startSendingRuntime()
01137 {
        if (m_ptrStream == NULL) return; // Should not happen
01138
```

```
01139
        sendStartingCode();
01140
        sendDataByte(0x25);
01141
        sendDataByte(0x00);
01142
        sendCheckSum();
01143 }
01144
01158 bool DFR0534::getRuntime(byte &hour, byte &minute, byte &second)
01159 {
01160
        #define COMMAND 0x25
01161
        #define RECEIVEFAILED false
        #define RECEIVEBYTETIMEOUTMS 100
01162
        #define RECEIVEGLOBALTIMEOUTMS 500
01163
        #define RECEIVEHEADERLENGTH 2 // startingcode+command
01164
01165
01166
        if (m_ptrStream == NULL) return false; // Should not happen
01167
        // Receive
01168
01169
        int i=0;
01170
        byte data, firstByte = 0, sum, length=0xff;
01171
        word result = 0;
01172
        unsigned long receiveStartMS = millis();
01173
        do {
01174
         byte dataReady = 0;
          unsigned long lastMS = millis();
01175
01176
          // Wait for response or timeout
           while ((millis()-lastMS < RECEIVEBYTETIMEOUTMS) && (dataReady==0)) dataReady =</pre>
01177
     m_ptrStream->available();
01178
          if (dataReady == 0) return RECEIVEFAILED; // Timeout
data = m_ptrStream->read();
01179
01180
01181
01182
          if (i==0) { // Begin of transmission
01183
           firstByte=data;
01184
            sum = 0;
01185
          if ((i == 1) && (data != COMMAND)) {
01186
            // Invalid signal => reset receive
01187
01188
01189
            firstByte = 0;
01190
01191
          if (i == RECEIVEHEADERLENGTH) {
            length = data; // Length of receiving data
if (length != 3) {
01192
01193
01194
              // Invalid length => reset receive
01195
01196
              firstByte = 0;
01197
01198
          if ((i > RECEIVEHEADERLENGTH) && (i-RECEIVEHEADERLENGTH-1<length)) {
01199
01200
            switch (i-RECEIVEHEADERLENGTH-1) {
01201
             case 0:
01202
               hour=data;
01203
                break;
01204
              case 1:
01205
               minute=data;
01206
                break;
              case 2:
01208
                second=data;
01209
                break;
01210
            }
01211
          if (firstByte == STARTINGCODE) {
01212
01213
            if (i-RECEIVEHEADERLENGTH<=length) sum+=data; // Update checksum
01214
01215
01216
          if (millis()-receiveStartMS > RECEIVEGLOBALTIMEOUTMS) return RECEIVEFAILED; // Timeout
01217
        } while (i<length+RECEIVEHEADERLENGTH+2);</pre>
01218
01219
        return (data == sum); // Does checksum matches?
01220 }
01221
01225 void DFR0534::stopSendingRuntime()
01226 {
        if (m_ptrStream == NULL) return; // Should not happen
01227
01228
        sendStartingCode();
01229
        sendDataByte(0x26);
01230
        sendDataByte(0x00);
01231
        sendCheckSum();
01232 1
```

5.6 DFR0534.h File Reference

#include <Arduino.h>
#include <Stream.h>
Include dependency graph for DFR0534.h:



This graph shows which files directly or indirectly include this file:



Classes

• class DFR0534

Class for a DFR0534 audio module.

Macros

#define DFR0534_VERSION "1.0.4"

5.6.1 Detailed Description

Class: DFR0534

Description: Class for controlling a DFR0534 audio module (https://wiki.dfrobot.com/Voice_← Module_SKU__DFR0534) by SoftwareSerial or HardwareSerial

License: 2-Clause BSD License Copyright (c) 2024 codingABI For details see: LICENSE.txt

Home: https://github.com/codingABI/DFR0534

Author

```
codingABI https://github.com/codingABI/
```

Copyright

2-Clause BSD License

Version

1.0.4

Definition in file DFR0534.h.

5.6.2 Macro Definition Documentation

5.6.2.1 DFR0534 VERSION

```
#define DFR0534_VERSION "1.0.4"
```

Library version

Definition at line 22 of file DFR0534.h.

5.7 DFR0534.h

Go to the documentation of this file.

```
00001
00019 #pragma once
00020
00022 #define DFR0534_VERSION "1.0.4"
00023
00024 #include <Arduino.h>
00025 #include <Stream.h>
00026
00027 #define STARTINGCODE 0xAA
00028
00032 class DFR0534 {
00033 public:
00035
           enum DFR0534CHANNELS
00036
             CHANNELMP3,
00037
00038
             CHANNELAUX,
00039
             CHANNELMP3AUX,
00040
             CHANNELUNKNOWN
00041
           enum DFR0534DRIVE
00043
00044
             DRIVEUSB,
00045
00046
             DRIVESD,
00047
             DRIVEFLASH,
00048
             DRIVEUNKNOWN,
00049
            DRIVENO = 0xff
00050
00052
           enum DFR0534LOOPMODE
00053
00054
             LOOPBACKALL,
00055
             SINGLEAUDIOLOOP,
00056
             SINGLEAUDIOSTOP,
00057
00058
             PLAYRANDOM,
DIRECTORYLOOP,
RANDOMINDIRECTORY,
00059
00060
             SEQUENTIALINDIRECTORY,
00061
             SEQUENTIAL,
```

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```
PLAYMODEUNKNOWN
00062
00063
00065
          enum DFR0534EQ
00066
            NORMAL,
00067
00068
            POP,
            ROCK,
00069
00070
            JAZZ
00071
            CLASSIC.
00072
            EOUNKNOWN
00073
          };
          enum DFR0534STATUS
00075
00076
00077
            STOPPED,
00078
            PLAYING,
            PAUSED,
STATUSUNKNOWN
00079
00080
00081
          DFR0534 (Stream &stream)
00087
00088
            m_ptrStream = &stream;
00089
00090
00091
          void decreaseVolume();
00092
          void fastBackwardDuration(word seconds);
00093
          void fastForwardDuration(word seconds);
00094
          byte getDrive();
00095
          byte getDrivesStates();
00096
          bool getDuration(byte &hour, byte &minute, byte &second);
00097
          bool getFileName(char *name);
00098
          word getFileNumber();
          int getFirstFileNumberInCurrentDirectory();
00099
00100
          bool getRuntime (byte &hour, byte &minute, byte &second);
00101
          byte getStatus();
00102
          int getTotalFiles();
00103
          int getTotalFilesInCurrentDirectory();
00104
          void increaseVolume();
          void insertFileByNumber(word track, byte drive=DRIVEFLASH);
00105
          void pause();
00107
          void play();
00108
          void playCombined(char* list);
00109
          void playFileByName(char *path, byte drive=DRIVEFLASH);
          void playFileByNumber(word track);
void playLastInDirectory();
00110
00111
00112
          void playNext();
00113
          void playNextDirectory();
00114
          void playPrevious();
00115
          void prepareFileByNumber(word track);
00116
          void repeatPart(byte startMinute, byte startSecond, byte stopMinute, byte stopSecond);
          void setChannel(byte channel);
00117
          void setDirectory(char *path, byte drive=DRIVEFLASH);
00118
00119
          void setDrive(byte drive);
00120
          void setEqualizer(byte mode);
00121
          void setLoopMode(byte mode);
00122
          void setRepeatLoops(word loops);
00123
          void setVolume(byte volume);
00124
          void stop();
00125
          void stopInsertedFile();
00126
          void startSendingRuntime();
00127
          void stopCombined();
00128
          void stopRepeatPart();
00129
          void stopSendingRuntime();
00130
        private:
00131
          void sendStartingCode() {
00132
           m_checksum=STARTINGCODE;
00133
            m_ptrStream->write((byte)STARTINGCODE);
00134
00135
          void sendDataByte(byte data) {
00136
           m checksum +=data:
00137
            m_ptrStream->write((byte)data);
00138
00139
          void sendCheckSum() {
00140
           m_ptrStream->write((byte)m_checksum);
00141
00142
          byte m_checksum;
          Stream *m_ptrStream = NULL;
00143
00144 };
```

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