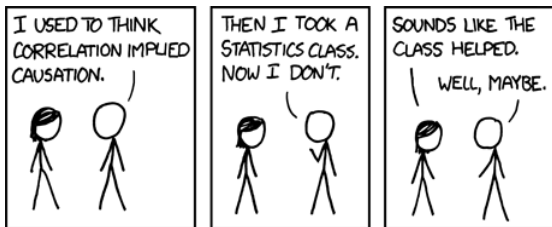


## Advanced Applied Econometrics

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## Topics covered

- 1 Review fixed effects regression models
- 2 Differences-in-differences basics: Card and Krueger (1994)
- 3 Regression differences-in-differences
- 4 Synthetic control: Abadie, Diamond and Hainmueller (2010)
- 5 Combining differences-in-differences with IV: Waldinger (2010)

## Panel Methods

- Panel data: we observe the same units (individuals, firms, countries, schools, etc.) over several time periods
- Often our outcome variable depends on unobserved factors which are also correlated with our explanatory variable of interest
- If these omitted variables are constant over time, we can use panel data estimators to consistently estimate the effect of our explanatory variable
- Main estimators for panel data:
  - Pooled OLS
  - Fixed effects estimator
  - Random effects estimator

## Panel setup

- Let  $y$  and  $x \equiv (x_1, x_2, \dots, x_k)$  be observable random variables and  $c$  be an unobservable random variable
- We are interested in the partial effects of variable  $x_j$  in the population regression function

$$E[y|x_1, x_2, \dots, x_k, c]$$

- We observe a sample of  $i = 1, 2, \dots, N$  cross-sectional units for  $t = 1, 2, \dots, T$  time periods (a balanced panel)
  - For each unit  $i$ , we denote the observable variables for all time periods as  $\{(y_{it}, x_{it}) : t = 1, 2, \dots, T\}$
  - $x_{it} \equiv (x_{it1}, x_{it2}, \dots, x_{itk})$  is a  $1 \times K$  vector
- Typically assume that cross-sectional units are i.i.d. draws from the population:  $\{y_i, x_i, c_i\}_{i=1}^N \sim i.i.d.$  (cross-sectional independence)
  - $y_i \equiv (y_{i1}, y_{i2}, \dots, y_{iT})'$  and  $x_i \equiv (x_{i1}, x_{i2}, \dots, x_{iT})'$
  - Consider asymptotic properties with  $T$  fixed and  $N \rightarrow \infty$

## Panel setup

Single unit:

$$y_i = \begin{pmatrix} y_{i1} \\ \vdots \\ y_{it} \\ \vdots \\ y_{iT} \end{pmatrix}_{T \times 1} \quad X_i = \begin{pmatrix} X_{i,1,1} & X_{i,1,2} & X_{i,1,j} & \dots & X_{i,1,K} \\ \vdots & \vdots & \vdots & & \vdots \\ X_{i,t,1} & X_{i,t,2} & X_{i,t,j} & \dots & X_{i,t,K} \\ \vdots & \vdots & \vdots & & \vdots \\ X_{i,T,1} & X_{i,T,2} & X_{i,T,j} & \dots & X_{i,T,K} \end{pmatrix}_{T \times K}$$

Panel with all units:

$$y = \begin{pmatrix} y_1 \\ \vdots \\ y_i \\ \vdots \\ y_N \end{pmatrix}_{NT \times 1} \quad X = \begin{pmatrix} X_1 \\ \vdots \\ X_i \\ \vdots \\ X_N \end{pmatrix}_{NT \times K}$$

## Unobserved effects model: Farm output

- For a randomly drawn cross-sectional unit  $i$ , the model is given by

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- $y_{it}$ : output of farm  $i$  in year  $t$
- $x_{it}$ :  $1 \times K$  vector of variable inputs for farm  $i$  in year  $t$ , such as labor, fertilizer, etc. plus an intercept
- $\beta$ :  $K \times 1$  vector of marginal effects of variable inputs
- $c_i$ : sum of all time-invariant inputs known to farmer  $i$  (but unobserved for the researcher), e.g., soil quality, managerial ability, etc.
  - often called the unobserved effect, unobserved heterogeneity, etc
- $\varepsilon_{it}$ : time-varying unobserved inputs, such as rainfall, unknown to the farmer at the time the decision on the variable inputs  $x_{it}$  is made
  - often called the idiosyncratic error
- What happens when we regress  $y_{it}$  on  $x_{it}$ ?

## Pooled OLS

- When we ignore the panel structure and regress  $y_{it}$  on  $x_{it}$  we get

$$y_{it} = x_{it}\beta + v_{it}; \quad t = 1, 2, \dots, T$$

with composite error  $v_{it} \equiv c_i + \varepsilon_{it}$

- Main assumption to obtain consistent estimates for  $\beta$  is:
  - $E[v_{it}|x_{i1}, x_{i2}, \dots, x_{iT}] = E[v_{it}|x_{it}] = 0$  for  $t = 1, 2, \dots, T$ 
    - $x_{it}$  are strictly exogenous: the composite error  $v_{it}$  in each time period is uncorrelated with the past, current and future regressors
    - But: labour input  $x_{it}$  likely depends on soil quality  $c_i$  and so we have omitted variable bias and  $\hat{\beta}$  is not consistent
  - No correlation between  $x_{it}$  and  $v_{it}$  implies no correlation between unobserved effect  $c_i$  and  $x_{it}$  for all  $t$ 
    - Violations are common: whenever we omit a time-constant variable that is correlated with the regressors (heterogeneity bias)
  - Additional problem:  $v_{it}$  are serially correlated for same  $i$  since  $c_i$  is present in each  $t$  and thus pooled OLS standard errors are invalid

## Unobserved effects model: program evaluation

- Program evaluation model:

$$y_{it} = \text{prog}_{it}\beta + c_i + \varepsilon_{it}; t = 1, 2, \dots, T$$

- $y_{it}$ : log wage of individual  $i$  in year  $t$
- $\text{prog}_{it}$ : indicator coded 1 if individual  $i$  participants in training program at  $t$  and 0 otherwise
- $\beta$ : effect of program
- $c_i$ : sum of all time-invariant unobserved characteristics that affect wages, such as ability, etc.
- What happens when we regress  $y_{it}$  on  $\text{prog}_{it}$ ?  $\hat{\beta}$  not consistent since  $\text{prog}_{it}$  is likely correlated with  $c_i$  (e.g., ability)
- Always ask: is there a time-constant unobserved variable ( $c_i$ ) that is correlated with the regressors? If yes, then pooled OLS is problematic



## Fixed effect regression

- Our unobserved effects model is:

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; t = 1, 2, \dots, T$$

- If we have data on multiple time periods, we can think of  $c_i$  as **fixed effects** or “nuisance parameters” to be estimated
- OLS estimation with fixed effects yields

$$(\hat{\beta}, \hat{c}_1, \dots, \hat{c}_N) = \underset{b, m_1, \dots, m_N}{\operatorname{argmin}} \sum_{i=1}^N \sum_{t=1}^T (y_{it} - x_{it}b - m_i)^2$$

this amounts to including  $N$  farm dummies in regression of  $y_{it}$  on  $x_{it}$

## Derivation: fixed effects regression

$$(\hat{\beta}, \hat{c}_1, \dots, \hat{c}_N) = \underset{b, m_1, \dots, m_N}{\operatorname{argmin}} \sum_{i=1}^N \sum_{t=1}^T (y_{it} - x_{it}b - m_i)^2$$

The first-order conditions (FOC) for this minimization problem are:

$$\sum_{i=1}^N \sum_{t=1}^T x'_{it} (y_{it} - x_{it}\hat{\beta} - \hat{c}_i) = 0$$

and

$$\sum_{t=1}^T (y_{it} - x_{it}\hat{\beta} - \hat{c}_i) = 0$$

for  $i = 1, \dots, N$ .

## Derivation: fixed effects regression

Therefore, for  $i = 1, \dots, N$ ,

$$\hat{c}_i = \frac{1}{T} \sum_{t=1}^T (y_{it} - x_{it}\hat{\beta}) = \bar{y}_i - \bar{x}_i\hat{\beta},$$

where

$$\bar{x}_i \equiv \frac{1}{T} \sum_{t=1}^T x_{it}; \bar{y}_i \equiv \frac{1}{T} \sum_{t=1}^T y_{it}$$

Plug this result into the first FOC to obtain:

$$\begin{aligned}\hat{\beta} &= \left( \sum_{i=1}^N \sum_{t=1}^T (x_{it} - \bar{x}_i)'(x_{it} - \bar{x}_i) \right)^{-1} \left( \sum_{i=1}^N \sum_{t=1}^T (x_{it} - \bar{x}_i)'(y_{it} - \bar{y}_i) \right) \\ \hat{\beta} &= \left( \sum_{i=1}^N \sum_{t=1}^T \ddot{x}_{it}'\ddot{x}_{it} \right)^{-1} \left( \sum_{i=1}^N \sum_{t=1}^T \ddot{x}_{it}'\ddot{y}_{it} \right)\end{aligned}$$

with time-demeaned variables  $\ddot{x}_{it} \equiv x_{it} - \bar{x}_i$ ,  $\ddot{y}_{it} \equiv y_{it} - \bar{y}_i$

## Fixed effects regression

Running a regression with the time-demeaned variables  $\ddot{y}_{it} \equiv y_{it} - \bar{y}_i$  and  $\ddot{x}_{it} \equiv x_{it} - \bar{x}$  is numerically equivalent to a regression of  $y_{it}$  on  $x_{it}$  and unit specific dummy variables.

Even better, the regression with the time demeaned variables is consistent for  $\beta$  even when  $\text{Cov}[x_{it}, c_i] \neq 0$  because time-demeaning eliminates the unobserved effects

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}$$

$$\bar{y}_i = \bar{x}_i\beta + c_i + \bar{\varepsilon}_i$$

---

$$(y_{it} - \bar{y}_i) = (x_{it} - \bar{x})\beta + (c_i - c_i) + (\varepsilon_{it} - \bar{\varepsilon}_i)$$

$$\ddot{y}_{it} = \ddot{x}_{it}\beta + \ddot{\varepsilon}_{it}$$

## Fixed effects regression: main results

- Identification assumptions:

- ①  $E[\varepsilon_{it} | x_{i1}, x_{i2}, \dots, x_{iT}, c_i] = 0; t = 1, 2, \dots, T$ 
  - regressors are strictly exogenous conditional on the unobserved effect
  - allows  $x_{it}$  to be arbitrarily related to  $c_i$
- ②  $\text{rank}\left(\sum_{t=1}^T E[\ddot{x}_{it}' \ddot{x}_{it}]\right) = K$ 
  - regressors vary over time for at least some  $i$  and not collinear

- Fixed effects estimator

- ① Demean and regress  $\ddot{y}_{it}$  on  $\ddot{x}_{it}$  (need to correct degrees of freedom)
- ② Regress  $y_{it}$  on  $x_{it}$  and unit dummies (dummy variable regression)
- ③ Regress  $y_{it}$  on  $x_{it}$  with canned fixed effects routine
  - STATA: `xtreg y x, fe i(PanelID)`

- Properties (under assumptions 1-2):

- $\hat{\beta}_{FE}$  is consistent:  $\text{plim}_{N \rightarrow \infty} \hat{\beta}_{FE,N} = \beta$
- $\hat{\beta}_{FE}$  is unbiased conditional on  $\mathbf{X}$

## Fixed effects regression: main issues

- Inference:
  - Standard errors have to be “clustered” by panel unit (e.g., farm) to allow correlation in the  $\varepsilon_{it}$ 's for the same  $i$ .
    - STATA: `xtreg , fe i(PanelID) cluster( PanelID )`
  - Yields valid inference as long as number of clusters is reasonably large
- Typically we care about  $\beta$ , but unit fixed effects  $c_i$  could be of interest
  - $\hat{c}_i$  from dummy variable regression is unbiased but not consistent for  $c_i$  (based on fixed  $T$  and  $N \rightarrow \infty$ )
  - `xtreg , fe` routine demeans the data before running the regression and therefore does not estimate  $\hat{c}_i$ 
    - intercept shows average  $\hat{c}_i$  across units
    - we can recover  $\hat{c}_i$  using  $\hat{c}_i = \bar{y}_i - \bar{x}_i \hat{\beta}$
    - `predict c_i, u`

## Example: Direct Democracy and Naturalizations

- Do minorities fare worse under direct democracy than under representative democracy?
- Hainmueller and Hangartner (2012) examine data on naturalization requests of immigrants in Switzerland, where municipalities vote on naturalization applications in:
  - referendums (direct democracy)
  - elected municipality councils (representative democracy)
- Annual panel data from 1,400 municipalities for the 1991-2009 period
  - $y_{it}$  : naturalization rate =  $\frac{\text{no. naturalizations}_{it}}{\text{eligible foreign population}_{i,t-1}}$
  - $x_{it}$  : 1 if municipality used representative democracy, 0 if municipality used direct democracy in year  $t$

## Naturalization Panel Data

```
. des muniID muni_name year nat_rate repdem
```

variable name	storage type	display format	value label	variable label
muniID	float	%8.0g		municipality code
muni_name	str43	%43s		municipality name
year	float	%ty		year
nat_rate	float	%9.0g		naturalization rate (percent)
repdem	float	%9.0g		1 representative democracy, 0 direct



## Panel Data Long Format

```
. list muniID muni_name year nat_rate repdem in 31/40
```

	muniID	muni_name	year	nat_rate	repdem
31.	2	Affoltern A.A.	2002	4.638365	0
32.	2	Affoltern A.A.	2003	4.844814	0
33.	2	Affoltern A.A.	2004	5.621302	0
34.	2	Affoltern A.A.	2005	4.387827	0
35.	2	Affoltern A.A.	2006	8.115358	1
36.	2	Affoltern A.A.	2007	7.067371	1
37.	2	Affoltern A.A.	2008	8.977719	1
38.	2	Affoltern A.A.	2009	6.119704	1
39.	3	Bonstetten	1991	.8333334	0
40.	3	Bonstetten	1992	.8403362	0

## Pooled OLS

```
. reg nat_rate repdem , cl(muniID)
```

Linear regression

Number of obs = 4655  
F( 1, 244) = 130.04  
Prob > F = 0.0000  
R-squared = 0.0748  
Root MSE = 3.98

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust		t	P> t	[95% Conf. Interval]	
	Coef.	Std. Err.				
repdem	2.503318	.2195202	11.40	0.000	2.070921	2.935714
_cons	2.222683	.10088	22.03	0.000	2.023976	2.421389

## Decompose within and between variation

```
. tsset muniID year , yearly
      panel variable: muniID (strongly balanced)
      time variable: year, 1991 to 2009
              delta: 1 year

. xtsum nat_rate
```

Variable	Mean	Std. Dev.	Min	Max	Observations
nat_rate overall	2.938992	4.137305	0	24.13793	N = 4655
between		1.622939	0	7.567746	n = 245
within		3.807039	-3.711323	24.80134	T = 19

## Time-demeaning for fixed effects: $y_{it} \rightarrow \ddot{y}_{it}$

```
. * get municipality means
. egen means_nat_rate = mean(nat_rate) , by(muniID)

. * compute deviations from means
. gen dm_nat_rate = nat_rate - means_nat_rate

. list muniID muni_name year nat_rate means_nat_rate dm_nat_rate in 20/40 ,ab(20)
```

	muniID	muni_name	year	nat_rate	means_nat_rate	dm_nat_rate
20.	2	Affoltern A.A.	1991	.2173913	3.595932	-3.37854
21.	2	Affoltern A.A.	1992	.9473684	3.595932	-2.648563
22.	2	Affoltern A.A.	1993	1.04712	3.595932	-2.548811
23.	2	Affoltern A.A.	1994	.8342023	3.595932	-2.761729
24.	2	Affoltern A.A.	1995	2.002002	3.595932	-1.59393
25.	2	Affoltern A.A.	1996	1.7769	3.595932	-1.819031
26.	2	Affoltern A.A.	1997	1.862745	3.595932	-1.733186
27.	2	Affoltern A.A.	1998	2.054155	3.595932	-1.541776
28.	2	Affoltern A.A.	1999	2.402135	3.595932	-1.193796

# Fixed effects regression with demeaned data

```
. egen means_repdem = mean(repdem) , by(muniID)

. gen dm_repdem = repdem - means_repdem

.
. * regression with demeaned data
. reg dm_nat_rate dm_repdem , cl(muniID)
```

Linear regression

Number of obs = 4655  
F( 1, 244) = 265.18  
Prob > F = 0.0000  
R-squared = 0.1052  
Root MSE = 3.6017

(Std. Err. adjusted for 245 clusters in muniID)

dm_nat_rate	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
dm_repdem	3.0228	.1856244	16.28	0.000	2.657169	3.388431
_cons	6.65e-10	5.81e-09	0.11	0.909	-1.08e-08	1.21e-08

# Fixed effects regression with canned routine

```
. xtreg nat_rate repdem , fe cl(muniID) i(muniID)
```

```
Fixed-effects (within) regression              Number of obs   =       4655
Group variable: muniID                       Number of groups =        245

R-sq:  within = 0.1052                      Obs per group: min =         19
        between = 0.0005                      avg           =        19.0
        overall = 0.0748                      max           =         19

                                           F(1,244)        =       265.18
corr(u_i, Xb)  = -0.1373                     Prob > F         =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
repdem	3.0228	.1856244	16.28	0.000	2.657169	3.388431
_cons	2.074036	.0531153	39.05	0.000	1.969413	2.178659
sigma_u	1.7129711					
sigma_e	3.69998					
rho	.17650677	(fraction of variance due to u_i)				

## Fixed effects regression with dummies

```
. reg nat_rate repdem i.muniID, cl(muniID)
```

Linear regression

Number of obs = 4655  
 F( 0, 244) = .  
 Prob > F = .  
 R-squared = 0.2423  
 Root MSE = 3.7

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
repdem	3.0228	.1906916	15.85	0.000	2.647188	3.398412
muniID						
2	1.367365	5.17e-14	2.6e+13	0.000	1.367365	1.367365
3	1.292252	5.17e-14	2.5e+13	0.000	1.292252	1.292252
9	1.284652	5.17e-14	2.5e+13	0.000	1.284652	1.284652
10	1.271783	5.17e-14	2.5e+13	0.000	1.271783	1.271783
13	.3265469	5.17e-14	6.3e+12	0.000	.3265469	.3265469

## Applying fixed effects

- We can use fixed effects for other data structures to restrict comparisons to within unit variation
  - Matched pairs
    - Twin fixed effects to control for unobserved effects of family background
  - Cluster fixed effects in hierarchical data
    - School fixed effects to control for unobserved effects of school



## Problems that even fixed effects do not solve

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; \quad t = 1, 2, \dots, T$$

- Where  $y_{it}$  is murder rate and  $x_{it}$  is police spending per capita
- What happens when we regress  $y$  on  $x$  and city fixed effects?
  - $\hat{\beta}_{FE}$  inconsistent unless strict exogeneity conditional on  $c_i$  holds
    - $E[\varepsilon_{it} | x_{i1}, x_{i2}, \dots, x_{iT}, c_i] = 0; t = 1, 2, \dots, T$
    - implies  $\varepsilon_{it}$  uncorrelated with past, current and future regressors
- Most common violations
  - ① Time-varying omitted variables
    - Economic boom leads to more police spending and less murders
    - Can include time-varying controls, but avoid post-treatment bias (i.e., collider)
  - ② Simultaneity
    - if city adjusts police based on past murder rate, then  $\text{spending}_{t+1}$  is correlated with  $\varepsilon_t$  (since higher  $\varepsilon_t$  leads to higher murder rate at  $t$ )
    - strictly exogenous  $x$  cannot react to what happens to  $y$  in the past or the future!
- Fixed effects do not obviate need for good research design!

## Random Effects

- Reconsider our unobserved effects model:

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Cannot use the fixed effects regression to estimate effects of time-constant regressors in  $x_{it}$  (eg., soil quality, farm location, etc.)
  - Since fixed effect estimator allows  $c_i$  to be correlated with  $x_{it}$ , we cannot distinguish the effects of time-invariant regressors from the time-invariant unobserved effect  $c_i$
- Need orthogonality assumption:  $\text{Cov}[x_{it}, c_i] = 0; \quad t = 1, \dots, T$ 
  - Strong assumption: Unobserved effects  $c_i$  are uncorrelated with each explanatory variable in  $x_{it}$  in each time period
  - For example if we include soil quality in  $x_{it}$  we have to assume it is uncorrelated with all other time-invariant inputs

## Random effects assumptions

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; \quad t = 1, \dots, T$$

- ①  $E[\varepsilon_{it}|x_i, c_i] = 0$ ;  $t = 1, 2, \dots, T$ : explanatory variables are strictly exogenous conditional on the unobserved effect
- ②  $E[c_i|x_i] = E[c_i] = 0$ : unobserved effects  $c_i$  are uncorrelated with regressors
- ③  $\text{rank } E[X_i' \Omega X_i] = K$ : no collinearity among regressors
  - $\Omega = E[v_i v_i']$ : the variance matrix of the composite error  $v_{it} = c_i + \varepsilon_{it}$
- ④ We typically also assume that  $\Omega$  takes a special form:
  - $E[\varepsilon_i \varepsilon_i' | x_i] = \sigma_\varepsilon^2 \mathbf{I}_T$ : idiosyncratic errors are homoskedastic for all  $t$  and serially uncorrelated
  - $E[c_i^2 | x_i] = \sigma_c^2$ : unobserved effect  $c_i$  is homoscedastic

## Random effects assumptions

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; \quad t = 1, \dots, T$$

- ❶  $E[\varepsilon_{it}|x_i, c_i] = 0$ ;  $t = 1, 2, \dots, T$ : explanatory variables are strictly exogenous conditional on the unobserved effect
- ❷  $E[c_i|x_i] = E[c_i] = 0$ : unobserved effects  $c_i$  are uncorrelated with regressors
- ❸ rank  $E[X_i' \Omega X_i] = K$ : no collinearity among regressors
  - $\Omega = E[v_i v_i']$ : the variance matrix of the composite error  $v_{it} = c_i + \varepsilon_{it}$
- ❹ We typically also assume that  $\Omega$  takes a special form:
  - $E[\varepsilon_i \varepsilon_i' | x_i] = \sigma_\varepsilon^2 \mathbf{I}_T$ : idiosyncratic errors are homoskedastic for all  $t$  and serially uncorrelated
  - $E[c_i^2 | x_i] = \sigma_c^2$ : unobserved effect  $c_i$  is homoscedastic

Assumption 4 implies  $\Omega = E[v_i v_i' | x_i] = \begin{pmatrix} \sigma_c^2 + \sigma_\varepsilon^2 & \sigma_c^2 & \dots & \sigma_c^2 \\ \sigma_c^2 & \sigma_c^2 + \sigma_\varepsilon^2 & \dots & \vdots \\ \vdots & \vdots & \ddots & \sigma_c^2 \\ \sigma_c^2 & \dots & \dots & \sigma_c^2 + \sigma_\varepsilon^2 \end{pmatrix}_{T \times T}$

## Random effects assumptions

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; \quad t = 1, \dots, T$$

- ❶  $E[\varepsilon_{it}|x_i, c_i] = 0$ ;  $t = 1, 2, \dots, T$ : explanatory variables are strictly exogenous conditional on the unobserved effect
- ❷  $E[c_i|x_i] = E[c_i] = 0$ : unobserved effects  $c_i$  are uncorrelated with regressors
- ❸ rank  $E[X_i' \Omega X_i] = K$ : no collinearity among regressors
  - $\Omega = E[v_i v_i']$ : the variance matrix of the composite error  $v_{it} = c_i + \varepsilon_{it}$
- ❹ We typically also assume that  $\Omega$  takes a special form:
  - $E[\varepsilon_i \varepsilon_i' | x_i] = \sigma_\varepsilon^2 \mathbf{I}_T$ : idiosyncratic errors are homoskedastic for all  $t$  and serially uncorrelated
  - $E[c_i^2 | x_i] = \sigma_c^2$ : unobserved effect  $c_i$  is homoscedastic
- Given assumptions 1-3, pooled OLS is consistent, since composite error  $v_{it}$  is uncorrelated with  $x_{it}$  for all  $t$
- However, pooled OLS ignores the serial correlation in  $v_{it}$

## Random effects assumptions

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}; \quad t = 1, \dots, T$$

- ①  $E[\varepsilon_{it}|x_i, c_i] = 0$ ;  $t = 1, 2, \dots, T$ : explanatory variables are strictly exogenous conditional on the unobserved effect
- ②  $E[c_i|x_i] = E[c_i] = 0$ : unobserved effects  $c_i$  are uncorrelated with regressors
- ③ rank  $E[X_i' \Omega X_i] = K$ : no collinearity among regressors
  - $\Omega = E[v_i v_i']$ : the variance matrix of the composite error  $v_{it} = c_i + \varepsilon_{it}$
- ④ We typically also assume that  $\Omega$  takes a special form:
  - $E[\varepsilon_i \varepsilon_i' | x_i] = \sigma_\varepsilon^2 \mathbf{I}_T$ : idiosyncratic errors are homoskedastic for all  $t$  and serially uncorrelated
  - $E[c_i^2 | x_i] = \sigma_c^2$ : unobserved effect  $c_i$  is homoscedastic
- Random effects estimator  $\hat{\beta}_{RE}$  exploits this serial correlation in a generalized least squares (GLS) framework
  - $\hat{\beta}_{RE}$  is consistent under assumption 1-3:  $\text{plim}_{N \rightarrow \infty} \hat{\beta}_{RE, N} = \beta$
  - $\hat{\beta}_{RE}$  is asymptotically efficient given assumption 4 (in the class of estimators consistent under  $E[v_i | x_i] = 0$ )

## Random effects estimator

- Consider the transformation parameter

$$\lambda = 1 - \left( \frac{\sigma_{\varepsilon}^2}{\sigma_{\varepsilon}^2 + T\sigma_c^2} \right)^{\frac{1}{2}} \text{ with } 0 \leq \lambda \leq 1$$

- $\sigma_{\varepsilon}^2 = \text{Var}[\varepsilon_{it}]$ : variance of idiosyncratic error
- $\sigma_c^2 = \text{Var}(c_i)$ : Variance of unobserved effect
- $\hat{\beta}_{RE}$  is equivalent to pooled OLS on:

$$\begin{aligned} y_{it} - \bar{y}_i &= (x_{it} - \lambda \bar{x}_i)\beta + (v_{it} - \lambda \bar{v}_i), \forall i, t \\ \tilde{y}_{it} &= \tilde{x}_{it}\beta + \tilde{v}_{it} \end{aligned}$$

- As  $\lambda \rightarrow 1$ ,  $\hat{\beta}_{RE} \rightarrow \hat{\beta}_{FE}$
- As  $\lambda \rightarrow 0$ ,  $\hat{\beta}_{RE} \rightarrow \hat{\beta}_{Pooled\ OLS}$ 
  - $\lambda \rightarrow 1$  as  $T \rightarrow \infty$  or if variance of  $c_i$  is large relative to variance of  $\varepsilon_{it}$
- $\lambda$  can be estimated from data  $\hat{\lambda} = 1 - (\hat{\sigma}_{\varepsilon}^2 / (\hat{\sigma}_{\varepsilon}^2 + T\hat{\sigma}_c^2))^{\frac{1}{2}}$
- Usually wise to cluster the standard errors since assumption 4 is strong

# Random effects regression

```
. xtreg nat_rate repdem , re cl(muniID) i(muniID)
```

```
Random-effects GLS regression                Number of obs      =       4655
Group variable: muniID                      Number of groups   =       245

R-sq:  within = 0.1052                      Obs per group: min =        19
       between = 0.0005                      avg           =       19.0
       overall = 0.0748                      max           =        19

corr(u_i, X)  = 0 (assumed)                  Wald chi2(1)       =       227.99
                                              Prob > chi2        =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Coef.	Robust Std. Err.	z	P> z	[95% Conf. Interval]	
repdem	2.859397	.1893742	15.10	0.000	2.48823	3.230564
_cons	2.120793	.0972959	21.80	0.000	1.930096	2.311489
sigma_u	1.3866768					
sigma_e	3.69998					
rho	.1231606	(fraction of variance due to u_i)				



## Summary: Fixed effects, random effects, Pooled OLS

- Main assumptions
  - ① Regressors are strictly exogenous conditional on the time-invariant unobserved effects
  - ② Regressors are uncorrelated with the time-invariant unobserved effects
- Results
  - Fixed effects estimator is consistent given assumption 1, but rules out time-invariant regressors
  - Random effects estimators and pooled OLS are consistent under assumptions 1-2, and allow for time-invariant regressors
  - Given homoskedasticity assumptions (random effects assumption 4), the random effects estimator is asymptotically efficient
- Assumption 2 is strong so fixed effects are typically more credible
  - Often the main reason for using panel data is to rule out all time-invariant unobserved confounders!

## Hausman test

	$\hat{\beta}_{RE}$	$\hat{\beta}_{FE}$
$H_0 : Cov[x_{it}, c_i] = 0$	Consistent and efficient	Consistent
$H_1 : Cov[x_{it}, c_i] \neq 0$	Inconsistent	Consistent

Then,

- Under  $H_0$ ,  $\hat{\beta}_{RE} - \hat{\beta}_{FE}$  should be close to zero
- Under  $H_1$ ,  $\hat{\beta}_{RE} - \hat{\beta}_{FE}$  should be different from zero
- It can be shown that in large samples, under  $H_0$ , the test statistic

$$(\hat{\beta}_{FE} - \hat{\beta}_{RE})' (\widehat{Var}[\hat{\beta}_{FE}] - \widehat{Var}[\hat{\beta}_{RE}])^{-1} (\hat{\beta}_{FE} - \hat{\beta}_{RE}) \xrightarrow{d} \chi_k^2$$

where  $k$  is the number of time-varying regressors.

- We may reject the null hypothesis of “random effects” and stick with the less efficient, but consistent fixed effects specification

# Random effects regression

```
. quietly: xtreg nat_rate repdem , fe i(muniID)

. estimates store FE

.
. quietly: xtreg nat_rate repdem , re i(muniID)

. estimates store RE

. hausman FE RE
```

	—— Coefficients ——			
	(b) FE	(B) RE	(b-B) Difference	$\sqrt{\text{diag}(V_b - V_B)}$ S.E.
repdem	3.0228	2.859397	.1634027	.0304517

b = consistent under  $H_0$  and  $H_a$ ; obtained from xtreg  
 B = inconsistent under  $H_a$ , efficient under  $H_0$ ; obtained from xtreg

Test:  $H_0$ : difference in coefficients not systematic

$$\begin{aligned}\chi^2(1) &= (b-B)' [(V_b - V_B)^{-1}] (b-B) \\ &= 28.79\end{aligned}$$

## Hausman test

- Hausman test does not test if the fixed effect model is correct; the test assumes that the fixed effects estimator is consistent!
- Conventional Hausman test assumes homoskedastic model and does not allow for clustering
- There are Hausman like tests that allow for clustered standard errors

```
. * hausman test with clustering
. quietly: xtreg nat_rate repdem , re i(muniID) cl(muniID)

. xtoverid

Test of overidentifying restrictions: fixed vs random effects
Cross-section time-series model: xtreg re robust cluster(muniID)
Sargan-Hansen statistic 26.560 Chi-sq(1) P-value = 0.0000
```

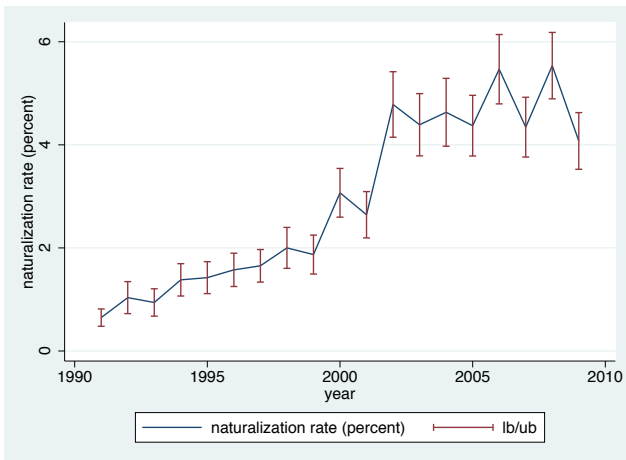
## Adding Time Effects

- Reconsider our unobserved effects model:

$$y_{it} = x_{it}\beta + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

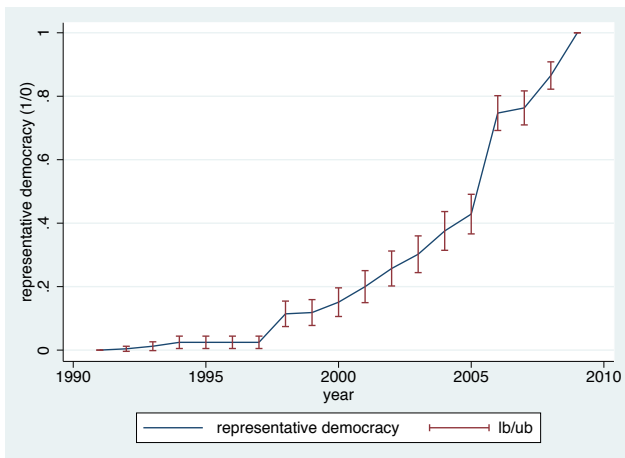
- Fixed effects assumption:  $E[\varepsilon_{it}|x_i, c_i] = 0$ ;  $t = 1, 2, \dots, T$ : regressors are strictly exogenous conditional on the unobserved effect
- Typical violation: Common shocks that affect all units in the same way and are correlated with  $x_{it}$ 
  - Trends in farming technology or climate affect productivity
  - Trends in immigration inflows affect naturalization rates
- We can allow for such common shocks by including time effects into the model

## Random effects regression



xtgraph nat\_rate

## Random effects regression



xtgraph repdem

## Fixed effects: adding time effects

- Linear time trend:

$$y_{it} = x_{it}\beta + c_i + t + \varepsilon_{it}; \quad t = 1, 2, \dots, T$$

- Linear time trend common to all units
- Time fixed effects:

$$y_{it} = x_{it}\beta + c_i + t_t + \varepsilon_{it}; \quad t = 1, 2, \dots, T$$

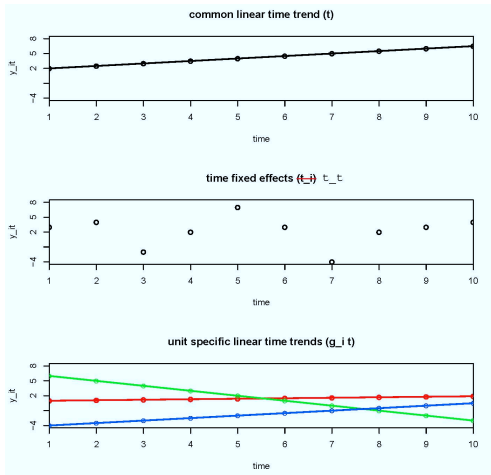
- Common shock in each time period
  - Generalized difference-in-difference model
- Unit specific linear time trends:

$$y_{it} = x_{it}\beta + c_i + g_i \cdot t + t_t + \varepsilon_{it}; \quad t = 1, 2, \dots, T$$

- Linear time trends that vary by unit



# Modeling time effects



## Fixed effects: adding time effects

```
. egen time = group(year)
```

```
. list muniID muni_name year time in 20/40 ,ab(20)
```

	muniID	muni_name	year	time
20.	2	Affoltern A.A.	1991	1
21.	2	Affoltern A.A.	1992	2
22.	2	Affoltern A.A.	1993	3
23.	2	Affoltern A.A.	1994	4
24.	2	Affoltern A.A.	1995	5
25.	2	Affoltern A.A.	1996	6
26.	2	Affoltern A.A.	1997	7
27.	2	Affoltern A.A.	1998	8
28.	2	Affoltern A.A.	1999	9
29.	2	Affoltern A.A.	2000	10
30.	2	Affoltern A.A.	2001	11

## Fixed effects: linear time trend

```
. xtreg nat_rate repdem time , fe cl(muniID) i(muniID)
```

```
Fixed-effects (within) regression           Number of obs   =       4655
Group variable: muniID                     Number of groups =       245

R-sq:  within = 0.1604                     Obs per group:  min =        19
        between = 0.0005                      avg =       19.0
        overall = 0.1350                      max =        19

                                           F(2,244)         =       247.57
corr(u_i, Xb) = -0.0079                     Prob > F          =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust		t	P> t	[95% Conf. Interval]	
	Coef.	Std. Err.				
repdem	.8247928	.2590615	3.18	0.002	.3145106	1.335075
time	.2313692	.0171752	13.47	0.000	.1975386	.2651997
_cons	.3892908	.1309232	2.97	0.003	.1314069	.6471747
sigma_u	1.6271657					
sigma_e	3.584409					
rho	.17086519	(fraction of variance due to u_i)				

## Fixed effects: year fixed effects

```
. xtreg nat_rate repdem i.time , fe cl(muniID) i(muniID)
```

```
Fixed-effects (within) regression               Number of obs   =       4655
Group variable: muniID                         Number of groups =        245

R-sq:  within = 0.1885                         Obs per group:  min =         19
          between = 0.0005                      avg =         19.0
          overall = 0.1575                      max =         19

                                         F(19,244)       =       31.48
corr(u_i, Xb)  = -0.0168                     Prob > F        =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
repdem	1.203658	.3031499	3.97	0.000	.6065335	1.800783
time						
2	.3829173	.1723225	2.22	0.027	.0434879	.7223468
3	.2789777	.1514124	1.84	0.067	-.0192644	.5772198
4	.7034078	.167466	4.20	0.000	.3735443	1.033271

## Fixed effects: unit specific time trends

```
. xtreg nat_rate repdem muniID#c.time i.time , fe cl(muniID) i(muniID)
note: 19.time omitted because of collinearity
```

```
Fixed-effects (within) regression      Number of obs      =      4655
Group variable: muniID                 Number of groups   =      245
```

```
R-sq:  within = 0.2650                Obs per group: min =      19
      between = 0.5185                  avg       =     19.0
      overall  = 0.2864                  max       =     19
```

```
corr(u_i, Xb) = -0.3963                F(18,244)           =      .
                                           Prob > F           =      .
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
repdem	.9865241	.322868	3.06	0.002	.3505601	1.622488
muniID#c.time						
1	.333343	.024298	13.72	0.000	.2854823	.3812036
2	.2914274	.024298	11.99	0.000	.2435667	.339288
3	.248985	.024298	10.25	0.000	.2011244	.2968457

## Unit specific time trends often eliminate “results”

TABLE 5.2.3  
Estimated effects of labor regulation on the performance of firms  
in Indian states

	(1)	(2)	(3)	(4)
Labor regulation (lagged)	-.186 (.064)	-.185 (.051)	-.104 (.039)	.0002 (.020)
Log development expenditure per capita		.240 (.128)	.184 (.119)	.241 (.106)
Log installed electricity capacity per capita		.089 (.061)	.082 (.054)	.023 (.033)
Log state population		.720 (.96)	0.310 (1.192)	-1.419 (2.326)
Congress majority			-.0009 (.01)	.020 (.010)
Hard left majority			-.050 (.017)	-.007 (.009)
Janata majority			.008 (.026)	-.020 (.033)
Regional majority			.006 (.009)	.026 (.023)
State-specific trends	No	No	No	Yes
Adjusted $R^2$	.93	.93	.94	.95

Notes: Adapted from Besley and Burgess (2004), table IV. The table reports regression DD estimates of the effects of labor regulation on productivity. The

## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Model recognizes the effect of change in  $x$  may occur with a late
  - effect of new tax credit for children on fertility rate
- Interpretation of coefficients:
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m+1$  at  $t$  which lasts only one period
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m+1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = m\beta_0 + (m+1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = m\beta_0 + m\beta_1 + (m+1)\beta_2 + c_i$
    - $y_{t+3} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$

## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Model recognizes the effect of change in  $x$  may occur with a late
  - effect of new tax credit for children on fertility rate
- Interpretation of coefficients:
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m + 1$  at  $t$  which lasts only one period
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m + 1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = m\beta_0 + (m + 1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = m\beta_0 + m\beta_1 + (m + 1)\beta_2 + c_i$
    - $y_{t+3} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
- $\beta_0 = y_t - y_{t-1}$  immediate change in  $y$  due to temporary one-unit increase in  $x$  (impact propensity)



## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Model recognizes the effect of change in  $x$  may occur with a late
  - effect of new tax credit for children on fertility rate
- Interpretation of coefficients:
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m+1$  at  $t$  which lasts only one period
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m+1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = m\beta_0 + (m+1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = m\beta_0 + m\beta_1 + (m+1)\beta_2 + c_i$
    - $y_{t+3} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
- $\beta_1 = y_{t+1} - y_t$  change in  $y$  one period after temporary one-unit increase in  $x$

## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Model recognizes the effect of change in  $x$  may occur with a late
  - effect of new tax credit for children on fertility rate
- Interpretation of coefficients:
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m+1$  at  $t$  which lasts only one period
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m+1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = m\beta_0 + (m+1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = m\beta_0 + m\beta_1 + (m+1)\beta_2 + c_i$
    - $y_{t+3} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
- $\beta_2 = y_{t+2} - y_{t-1}$  change in  $y$  two periods after temporary one-unit increase in  $x$

## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Model recognizes the effect of change in  $x$  may occur with a late
  - effect of new tax credit for children on fertility rate
- Interpretation of coefficients:
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m+1$  at  $t$  which lasts only one period
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m+1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = m\beta_0 + (m+1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = m\beta_0 + m\beta_1 + (m+1)\beta_2 + c_i$
    - $y_{t+3} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
- $\beta_3 = y_{t-1}$  change in  $y$  is zero three periods after temporary one-unit increase in  $x$

## Distributed Lag model

$$y_{it} = x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- Interpretation of coefficients:
  - Consider **permanent increase** in  $x_{it}$  from level  $m$  to  $m+1$  at  $t$ , i.e., ( $x_s = m, s < t$  and  $x_s = m+1, s \geq t$ )
    - $y_{t-1} = m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_t = (m+1)\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t+1} = (m+1)\beta_0 + (m+1)\beta_1 + m\beta_2 + c_i$
    - $y_{t+2} = (m+1)\beta_0 + (m+1)\beta_1 + (m+1)\beta_2 + c_i$
    - $y_{t+3} = (m+1)\beta_0 + (m+1)\beta_1 + (m+1)\beta_2 + c_i$
- After one period  $y$  has increased by  $\beta_0 + \beta_1$ , after two periods  $y$  has increased by  $\beta_0 + \beta_1 + \beta_2$  and there are no further increases after two periods
- Long-run increase in  $y$  :  $\beta_0 + \beta_1 + \beta_2$  (long-run propensity)

## Lagged effects of direct democracy

```
. xtreg nat_rate repdem L1.repdem L2.repdem L3.repdem i.year, fe cl(muniID) i(muniID)
```

```
Fixed-effects (within) regression              Number of obs   =       3920
Group variable: muniID                        Number of groups =       245

R-sq:  within  = 0.1536                      Obs per group:  min =        16
        between = 0.0012                      avg   =       16.0
        overall  = 0.1235                      max   =        16

                                           F(19,244)       =       21.63
corr(u_i, Xb)  = -0.0206                     Prob > F        =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
repdem						
--.	.6364802	.3593924	1.77	0.078	-.0714272	1.344388
L1.	1.201065	.4233731	2.84	0.005	.367133	2.034998
L2.	-.1648692	.4697434	-0.35	0.726	-1.090139	.7604003
L3.	-.5245206	.4109918	-1.28	0.203	-1.334065	.2850239

## Long-run effect of direct democracy

```
. lincom repdem + L1.repdem + L2.repdem + L3.repdem
```

```
( 1)  repdem + L.repdem + L2.repdem + L3.repdem = 0
```

nat_rate	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
(1)	1.294485	.4426322	2.92	0.004	.4226175	2.166353

## Lags and Leads model

$$y_{it} = x_{i,t+1}\beta_{-1} + x_{it}\beta_0 + x_{i,t-1}\beta_1 + x_{i,t-2}\beta_2 + c_i + \varepsilon_{it}; \quad t = 1, 2, \dots, T$$

- Can use estimate of  $\beta_{-1}$  to test for anticipation effects
  - Consider **temporary increase** in  $x_{it}$  from level  $m$  to  $m + 1$  at  $t$ 
    - $y_{t-2} = \beta_{-1}m + m\beta_0 + m\beta_1 + m\beta_2 + c_i$
    - $y_{t-1} = \beta_{-1}(m + 1) + m\beta_0 + m\beta_1 + m\beta_2 + c_i$
- Anticipation effect:  $\beta_{-1} = y_{t-1} - y_{t-2}$  change in  $y$  in period  $t - 1$ , the period before the temporary one-unit increase in  $x$
- Placebo test: if  $x$  causes  $y$ , but  $y$  does not cause  $x$ , then  $\beta_{-1}$  should be close to zero

# Leads and Lags

```
. xtreg nat_rate Fl.repdem repdem L1.repdem L2.repdem L3.repdem i.year, fe cl(muniID) i(muniID)
```

```
Fixed-effects (within) regression                Number of obs   =       3675
Group variable: muniID                          Number of groups =        245

R-sq:  within = 0.1621                          Obs per group: min =        15
        between = 0.0010                          avg           =       15.0
        overall = 0.1269                          max           =        15

                                                F(19,244)       =       20.34
corr(u_i, Xb)  = -0.0353                          Prob > F        =       0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Coef.	Robust Std. Err.	t	P> t	[95% Conf. Interval]	
repdem						
Fl.	.1707685	.3212906	0.53	0.596	-.4620886	.8036255
--.	.6975731	.4397095	1.59	0.114	-.1685376	1.563684
L1.	.8723962	.4619322	1.89	0.060	-.0374873	1.78228
L2.	.014941	.4583628	0.03	0.974	-.8879119	.9177939
L3.	-.2904252	.4108244	-0.71	0.480	-1.09964	.5187895



## The Autor Test

- Let  $D_{it}$  be a binary indicator equaling 1 if unit  $i$  **switched** from control to treatment between  $t$  and  $t - 1$ ; 0 otherwise
  - Lags:  $D_{i,t-1}$ : unit switched between  $t - 1$  and  $t - 2$
  - Leads:  $D_{i,t+1}$ : unit switches between  $t + 1$  and  $t$
- Include lags and leads into the fixed effects model:

$$y_{it} = D_{i,t+2}\beta_{-2} + D_{i,t+1}\beta_{-1} + D_{it}\beta_0 + D_{i,t-1}\beta_1 + D_{i,t-2}\beta_2 + c_i + \varepsilon_{it}$$

- Interpretation of coefficients:
  - Leads  $\beta_{-1}, \beta_{-2}$ , etc. test for anticipation effects
  - Switch  $\beta_0$  tests for immediate effect
  - Lags  $\beta_1, \beta_2$ , etc. test for long-run effects
    - highest lag dummy can be coded 1 for all post-switch years

# Lags and Leads of Switch to Representative Democracy

```
. list muni_name year repdem switch_t sw_lag1 sw_lag2 sw_lag3 ///  
>          sw_lead1 sw_lead2 sw_lead3 in 806/817
```

	muni_n~e	year	repdem	switch_t	sw_lag1	sw_lag2	sw_lag3	sw_lead1	sw_lead2	sw_lead3
806.	Stäfa	1998	0	0	0	0	0	0	0	0
807.	Stäfa	1999	0	0	0	0	0	0	0	0
808.	Stäfa	2000	0	0	0	0	0	0	0	0
809.	Stäfa	2001	0	0	0	0	0	0	0	0
810.	Stäfa	2002	0	0	0	0	0	0	0	1
811.	Stäfa	2003	0	0	0	0	0	0	1	0
812.	Stäfa	2004	0	0	0	0	0	1	0	0
813.	Stäfa	2005	1	1	0	0	0	0	0	0
814.	Stäfa	2006	1	0	1	0	0	0	0	0
815.	Stäfa	2007	1	0	0	1	0	0	0	0
816.	Stäfa	2008	1	0	0	0	1	0	0	0
817.	Stäfa	2009	1	0	0	0	1	0	0	0

# Dynamic Effect of Switching to Representative Democracy

```
. xtreg nat_rate sw_lag3 sw_lag2 sw_lag1 switch_t ///
>      sw_lead1 sw_lead2 sw_lead3 sw_lead4 sw_lead5 i.year, fe cluster(muniID) i(muniID)
```

```
Fixed-effects (within) regression                Number of obs   =       4655
Group variable: muniID                          Number of groups  =       245

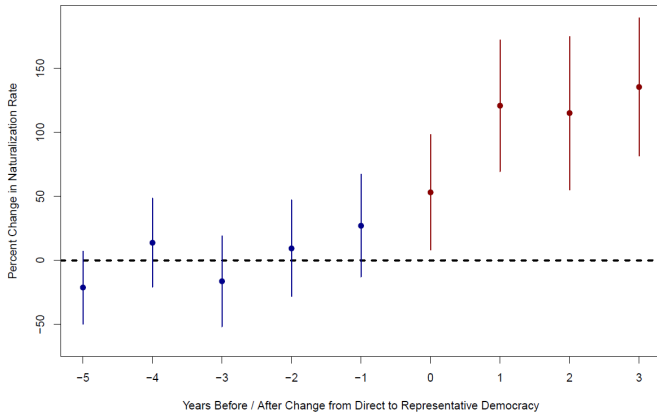
R-sq:  within = 0.1913                          Obs per group: min =        19
        between = 0.0011                          avg =       19.0
        overall = 0.1601                          max =        19

F(27,244) = 23.76
corr(u_i, Xb) = -0.0162                        Prob > F = 0.0000
```

(Std. Err. adjusted for 245 clusters in muniID)

nat_rate	Robust					
	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]	
sw_lag3	1.160345	.5080271	2.28	0.023	.1596665	2.161023
sw_lag2	1.743682	.5395212	3.23	0.001	.680969	2.806396
sw_lag1	1.881663	.4880099	3.86	0.000	.9204133	2.842913
switch_t	.7564792	.428627	1.76	0.079	-.0878019	1.60076
sw_lead1	.2138757	.3899881	0.55	0.584	-.5542971	.9820485
sw_lead2	.0843676	.3575292	0.24	0.814	-.61987	.7886051
sw_lead3	.1440446	.3194086	0.45	0.652	-.4851054	.7731945
sw_lead4	.0750194	.2990359	0.25	0.802	-.5140018	.6640405
sw_lead5	-.0942415	.2599789	-0.36	0.717	-.6063307	.4178477

# Dynamic Effect of Switching to Representative Democracy



## Lagged Dependent Variable

$$y_{it} = \alpha y_{i,t-1} + c_i + \varepsilon_{it}, \quad t = 1, 2, \dots, T$$

- $y_{it}$  could be capital stock of firm  $i$  at time  $t$  and  $\alpha$  the capital depreciation rate
- For simplicity, we assume that  $\varepsilon_{it}$  are uncorrelated in time (as well as across individuals)
- Note that

$$y_{i,t-1} = \alpha y_{i,t-2} + c_i + \varepsilon_{i,t-1}$$

- So we have  $\text{Cov}[y_{i,t-1}, c_i] \neq 0$  and therefore we need to include fixed effects  $c_i$  into the regression
- Does this work though?

## Lagged dependent variable

With  $T = 3$  we have

$$y_{i3} = \alpha y_{i2} + c_i + \varepsilon_{i3}$$

$$y_{i2} = \alpha y_{i1} + c_i + \varepsilon_{i2}$$

and we can take time differences to eliminate  $c_i$  (similar to fixed effects)

$$y_{i3} - y_{i2} = \alpha(y_{i2} - y_{i1}) + (c_i - c_i) + (\varepsilon_{i3} - \varepsilon_{i2})$$

$$\Delta y_{i3} = \alpha \Delta y_{i2} + \Delta \varepsilon_{i3}$$

Since  $\varepsilon_{i2}$  affects both  $\Delta y_{i2} = y_{i2} - y_{i1}$  and  $\Delta \varepsilon_{i3} = \varepsilon_{i3} - \varepsilon_{i2}$  we get

$\text{Cov}[\Delta y_{i2}, \Delta \varepsilon_{i3}] \neq 0$  and thus still have endogeneity

Models with fixed effects and lagged  $y$  do not produce consistent estimators  
Might use past levels  $y_{i1}$  as an instrument for  $\Delta y_{i2}$ , but this

requires strong assumptions (e.g., no serial correlation in  $\varepsilon_{it}$ )