

Programming Abstractions – Homework II

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In this assignment, you will be using Java (make sure it is JDK 1.8 compliant) for programming. Moreover, this assignment requires you to invest quite a bit into thinking about abstraction *before* you start coding. It is based on a mathematical structure called **group**. Before we get to the code, let us define this concept:

A nonempty set of elements G forms a **group** if in G there is a defined binary operation (which we will denote by \cdot in this document), such that

1. $x, y \in G$ implies that $x \cdot y \in G$. This property is called *closure*, and the set of elements is said to be *closed under the operation*.
2. $a, b, c \in G$ implies that $a \cdot (b \cdot c) = (a \cdot b) \cdot c$. In other words, the binary operation is associative.
3. There exists an element $e \in G$ such that $a \cdot e = e \cdot a = a$ for all elements $a \in G$. This special element e is called the *identity* element of the group.
4. For every $a \in G$, there exists an element b such that $a \cdot b = b \cdot a = e$. That is, every element has an *inverse*. Often, we simply denote it by a^{-1} .

Much like programming, mathematics also relies on abstraction. Groups have become fundamentally important in modern mathematics because they distill the basic structural rules found in almost every important mathematical structure. Some are very obvious, such as the set of all integers with addition as the binary operation. Note that the same set is NOT a group with multiplication as the operation (no inverse)! However, as soon as we consider a bigger set, namely, the set of all real numbers, even with multiplication we have a valid group. These examples serve to show that you should not simply think about the set of elements, but instead, carefully consider the binary operation together with the set. It is also important to note that the binary operation may not always be commutative. That is, it is not always the case that $a \cdot b = b \cdot a$.

For a basic understanding of implementing simple groups, there is some Java code already given to you. The most important is the interface called **Group**. It is extensively documented, and students are expected to pay attention to the details provided there. Next, there is an implementation of the most obvious group we can think of: the group of all integers under addition. This is provided to you as **ZPlus**¹.

Finite groups

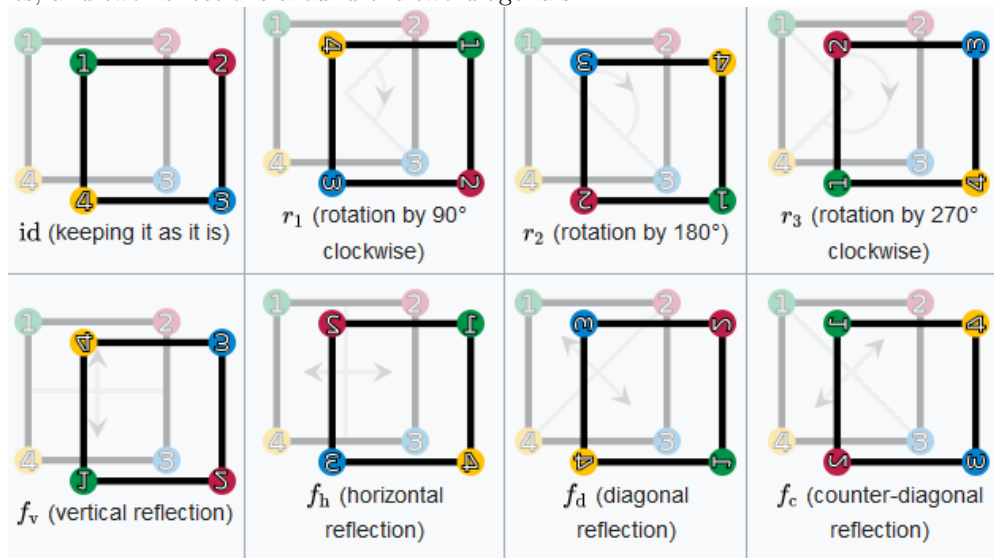
Based on everything you have seen up to this point, you may think that groups are just a fancy way of stating the basic properties of numbers. But that is not at all true! To start with, a group need not be infinite. In fact, you will now be implementing a few finite groups.

Non-commutative groups

As noted earlier, the binary operation of a group need not be commutative. That is, $a \cdot b$ is not always equal to $b \cdot a$. This may not be intuitive if you only think of numeric operations. But they make a lot of sense when we enter the world of geometry. In fact, one of the biggest applications of *group theory* is in fields like chemistry and physics, where the structural symmetry of molecules and particles is studied using this mathematical concept. So much so, that many consider the study of groups to be the “science of symmetry”. For this assignment, we will look at two very simple examples – an equilateral triangle and a square – and their symmetries.

¹The name may seem strange, but \mathbb{Z} is the standard mathematical symbol to represent the set of integers. And since addition is the binary operation for this group, I decided to call the class **ZPlus**.

Figure 1: The eight symmetries of a square: the identity operation that leaves everything as it is, three rotation operations (around its center by 90° , 180° , and 270°), two reflections around the horizontal and vertical lines, and two reflections around the two diagonals.



But first, another definition: two shapes are said to be **congruent**, if they have the same shape and size. Formally, two shapes are congruent if one can be changed into the other by using a combination of:

- (i) rotations (around a fixed point),
- (ii) reflections (around a line that serves as the axis of the reflection), and/or
- (iii) translations (a transformation that moves every point in the same direction by the same distance).

Clearly, any shape in the 2-dimensional x - y plane is congruent to itself. Some shapes, however, are congruent to themselves in more than one way! Any such “extra” congruence is called a **symmetry**. A square has eight symmetries, as shown in Fig. 1. Similarly, an equilateral triangle has six symmetries (three rotations around its center by 0° , 120° , and 240° , and three reflections around the three perpendicular bisectors).

With this background, we are now ready to dive into some actual programming.

1. Let G be the set $\{\pm 1\}$, under the standard multiplication of real numbers. Your first task is to implement this group in Java, with the name `FiniteGroupOfOrderTwo`. (20)

When thinking about implementing this, note that `Group` is a parameterized interface. In the implemented example, `ZPlus`, the parameter was obvious, because we already know the data type for “integers” (`Integer`, of course). But here, the valid data that forms the set of elements, consists of only two values. So think about what should be the data type of the generic parameter. In your implementation, this parameter class must be named `PlusOrMinusOne`. You should also ensure that the following driver method (given to you in the `ArithmeticTest` class) works with your code:

```
public static void main(String... args) {
    FiniteGroupOfOrderTwo g = new FiniteGroupOfOrderTwo();
    PlusOrMinusOne[] values = PlusOrMinusOne.values();
    System.out.printf("g.identity() = %s\n", g.identity());
    for (PlusOrMinusOne u : values) {
        for (PlusOrMinusOne v : values) {
            PlusOrMinusOne e = g.binaryOperation(u, v);
            System.out.printf("%s * %s = %s\n", u.toString(), v.toString(), e.toString());
            System.out.printf("inverseOf(%s) = %s\n", e.toString(), g.inverseOf(e).toString());
        }
    }
}
```

In the above code, `toString()` must return only the numeric value (i.e., “1” or “-1”).

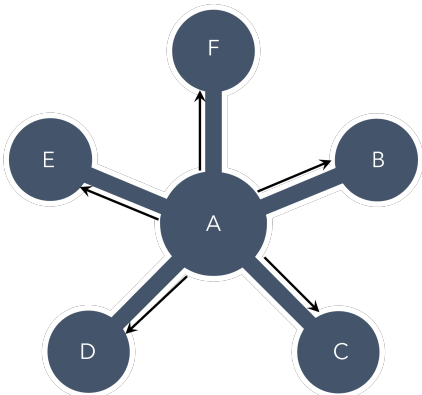


Figure 2: A radial graph, with one point as the central node. All other nodes are connected *only* to this center by a directed edge. All edges have the same length, and direct away from the center.

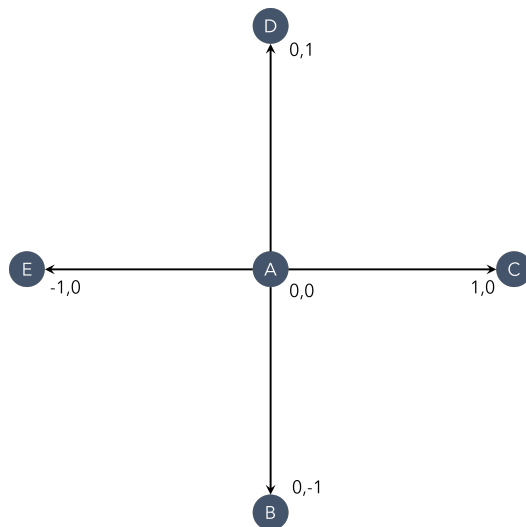


Figure 3: A geometric representation of an actual radial graph. Each point is a `Point` object, all the edges have the same length, and every edge direct away from the center.

- There is an interface called `Shape` provided in the `geometry` package. In this question, we will consider a `RadialGraph`, which is meant to represent objects of the type shown in Fig. 2 and Fig. 3. Such graphs show up all the time in social networks (*e.g.*, the central node represents an influencer with the others representing followers). Your task in this question is to complete the implementation of the `RadialGraph` class, consistent with the requirements of the `Shape` interface.

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Most of the implementation is straight-forward. Implementing rotation (in the `rotateBy(int degrees)` method), however, requires some mathematics!

Formally, rotation in the 2-dimensional Euclidean space is defined by a 2×2 matrix. To rotate all the points in the x - y plane counterclockwise by an angle θ (in radians), with respect to the positive x axis about the origin, a point (x, y) is transformed by

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x \cos \theta - y \sin \theta \\ x \sin \theta + y \cos \theta \end{bmatrix}$$

Without the matrix notation used in linear algebra, this simply means that such a rotation transforms the point (x, y) to the point $(x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta)$. Visually, this rotation is shown in Fig. 4.

To rotate a shape using this formula, you need to ensure that the center of the shape is the origin $(0, 0)$. It is a part of this assignment to figure out how to rotate a shape that has its center somewhere else.

You should ensure that the following driver method in the `RadialGraph` class works with your code (pay attention to the documentation, which explains what must be printed for the test cases used in this driver method, and what exception must be thrown):

```

public static void main(String... args) {
    Point center = new Point("center", 0, 0);
    Point east = new Point("east", 1, 0);
    Point west = new Point("west", -1, 0);
    Point north = new Point("north", 0, 1);
    Point south = new Point("south", 0, -1);
    Point toofarsouth = new Point("south", 0, -2);

    // A single node is a valid radial graph.
    RadialGraph lonely = new RadialGraph(center);

    // Must print: [(center, 0.0, 0.0)]
  }

```

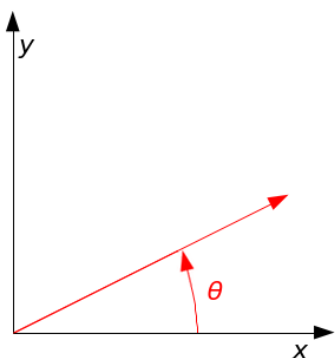


Figure 4: Counterclockwise rotation through angle θ : the vector is initially aligned with the x -axis, and after the rotation, shown by the red arrow.

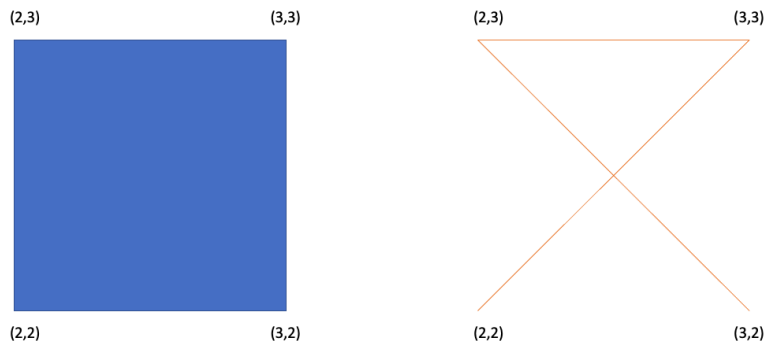


Figure 5: The square (left) initialized by passing arguments (3,3), (2,3), (2,2), and (3,2) (in this order) is, indeed, a valid square. Without such a convention being followed, we could end up with non-polygonal open curves (right). If the constructor is called with four points that do not form a valid square, your constructor must throw an `IllegalArgumentException`.

```
System.out.println(lonely);

// Must throw IllegalArgumentException, since the edges will not be of the same length
RadialGraph nope = new RadialGraph(center, Arrays.asList(north, toofarsouth, east, west));

Shape g = new RadialGraph(center, Arrays.asList(north, south, east, west));

// Must follow the documentation in the Shape abstract class, and print the following string:
// [(center, 0.0, 0.0); (east, 1.0, 0.0); (north, 0.0, 1.0); (west, -1.0, 0.0); (south, 0.0, -1.0)]
System.out.println(g);

// After this counterclockwise rotation by 90 degrees, "north" must be at (-1, 0), and
// similarly for all the other radial points. The center, however, must remain exactly
// where it was.
g = g.rotateBy(90);

// you should similarly add tests for the translateBy(x, y) method
}
```

3. Similarly, complete the implementation of the `Square` class.

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An empty constructor is already provided to you, which accepts four `Point` objects as its parameters. It is important to note that whether these points form a valid square may depend on the order in which these points are arranged. This was not a concern for radial graphs, but it does matter for a square! For example, a mistake in ordering the vertices could yield the right-side non-polygonal open curve shown in Fig. 5. For this assignment, you can assume that the order in which the input arguments are provided to the constructor, will follow the order specified in the documentation of `Shape#toString()`.

Recall that when we attempt to create a radial graph with invalid points, the constructor is required to throw an `IllegalArgumentException`. Similarly, when the `Sqaure` class' constructor is called with four points that do not follow the above convention, it must throw an `IllegalArgumentException`.

We are not providing a separate driver method for the `Square` class, because such a driver method will be nearly identical to the one we have provided for `RadialGraph`. You are highly encouraged to test your square implementation using such a method. In this method, you should test (i) the creation of squares, (ii) throwing exceptions as described above, (iii) printing a square, (iv) printing a rotated square, (v) printing a translated square, and (vi) calculating the center point.

4. Now, we will use these two shapes, `RadialGraph` and `Square`, and add the concepts of their symmetry. Take a look at the `GeometryTest` class' `main(String[])` method. This is provided to you as an outline for testing your code. Here, you will see two classes being mentioned, called `RadialGraphSymmetries`

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and `SquareSymmetries`. You will also see two methods being used: `areSymmetric`, and `symmetriesOf`. Carefully consider the `Symmetries` interface implemented by these two classes, and come up with the correct signatures for these methods in the implementations. In particular, you need to ask

If the definition in the interface (i.e., the supertype) specifies returning a type T , can the method implementation in the class (which is its subtype) return a subtype of T ? In other words, does Java allow covariant return types?

As shown in Fig. 1, a square has eight symmetries (including the identity transformation). Symmetries of radial graphs are different, though. On one hand, the number of symmetries is not fixed (depends on the number of edges and the exact location of the neighbors receiving those edges). On the other hand, if any symmetry other than the identity transformation exists, it can be expressed purely through rotation.

Your task in this question is to implement the symmetries of `Square` and `RadialGraph` in the two classes `SquareSymmetries` and `RadialGraphSymmetries`, respectively.

In this question, the total points are split equally between the implementation of radial graph symmetries and square symmetries.

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- You may have additional methods in your classes even if such methods are not required by the interface. Such additional methods, however, must not be `public`.
 - Any interface code given to you must not be changed!
 - Please keep in mind [these homework-related points mentioned in the syllabus](#).
 - **What to submit?** The complete codebase (including classes and interfaces that were already given to you) as a single `.zip` file. Your zip file, once extracted, must contain three folders: `core`, `arithmetic`, and `geometry`. Your solution to the first question is expected to be in the `arithmetic` package, while the rest of your code must be in the `geometry` package.

Deviations from the expected submission format carries varying amounts of score penalty (depending on the amount of deviation).

Submission Deadline: Oct 31 (Monday), 11:59 pm
