



Technische Universität München

School of Computation, Information and Technology



Master's Thesis

Residual-based Methods for Robust Spectral Analysis in Dynamical Systems

April Herwig

april.herwig@tum.de

Supervisor: Prof Oliver Junge

Submission Date:

I assure the single handed composition of this master's thesis only supported by declared resources.

Garching,

Abstract

Koopmania

Contents

1	Introduction	1
2	Background	1
2.1	Koopman and Perron-Frobenius Operators	1
2.2	Spectral Properties	3
2.2.1	The Spectrum	3
2.2.2	Spectra of Koopman and Perron-Frobenius Operators .	5
2.3	Pseudospectra	7
2.3.1	Definitions of the Pseudospectrum	7
2.3.2	Properties	10
3	Numerical Methods	13
3.1	Petrov-Galerkin Methods	13
3.2	Extended Dynamic Mode Decomposition (EDMD)	13
3.3	Residual EDMD (ResDMD)	13
3.4	kernel EDMD (kEDMD)	13
3.5	kernel ResDMD (kResDMD)	13
4	Benchmark Examples	13
5	Appendix	i
5.1	Transfer Operator for Blaschke Products	i
5.2	Some scribbles about kernels and residuals	i

1 Introduction

Dynamical systems theory has seen many revolutions. One recent such revolution is to use operator theoretic tools to analyze the global behavior of chaotic systems. Concieved in the 1930's by Koopman and Von Neumann [7], the study of global dynamics under a mapping S is conducted by studying the action of the composition $\psi \circ S$ of S with an observable ψ . Observables which act as eigenvalues for the composition operator and its dual hold information on slowly decaying structures in phase space.

Currently the most popular method by far for analyzing composition operators (named Koopman operators) is dynamic mode decomposition (DMD). The past 2 decades have seen massive growth in this topic, and DMD has recieved many evolutions [3]. One primary concern of nearly all DMD methods is *spectral pollution*. The Koopman operator often has unfavorable spectral qualities such as continuous spectrum which are unstable, and are destroyed by finite approximation. The task presented in the present paper is to identify which candidate eigenvalues (computed e.g. by DMD) are approximations of eigenvalues of the true Koopman operator (or its adjoint), and which arise due to discretization.

2 Background

We consider a discrete dynamical system generated by a map $S : \Omega \rightarrow \Omega$ defined on a measure space $(\Omega, \mathcal{A}, dx)$ which is *nonsingular*, that is $\int_{S^{-1}(A)} dx = \int_A dx$ for any $A \in \mathcal{A}$ with $\int_A dx = 0$.

2.1 Koopman and Perron-Frobenius Operators

Koopman operator theory shifts the focus from dynamics of points in state space \mathcal{X} to dynamics of observables $g : \Omega \rightarrow \mathbb{C}$. A state $x \in \Omega$ evolves by iteratively applying the map S , and similarly observables evolve under the action of the *Koopman operator*

$$\mathcal{K}g = g \circ S. \tag{2.1}$$

The primary benefit of this alternative viewpoint of dynamics is that \mathcal{K} is *linear* and can therefore be analyzed using algebraic and functional analytic tools. However, the Koopman operator acts on function spaces which are typically infinite-dimensional. Even the Krylov space $\{g, \mathcal{K}g, \mathcal{K}^2g, \dots\}$ is generically infinite-dimensional: consider e.g. an indicator function $g = \mathbb{1}_{[0,1]}$ and a translation $S(x) = x - 1$.

It should be noted that until now we have not declared a function space to act as a domain for \mathcal{K} . This is because there are many potential domains for which \mathcal{K} is not only well-defined, but has interesting properties worth studying. For the current section we consider $\mathcal{K} : L^\infty \rightarrow L^\infty$. On this space \mathcal{K} is obviously bounded, in fact it is a contraction.

The Koopman operator tracks how observables evolve with S . There is however a dual viewpoint: that of *densities* and *pushforwards*. From the duality pairing

$$\langle f, \mathcal{K}g \rangle = \langle \mathcal{L}f, g \rangle \quad (2.2)$$

for $f \in L^1$, $g \in L^\infty$ we may deduce the form of an adjoint operator, known as the *transfer operator* or *Perron-Frobenius operator*. Consider an indicator $g = \mathbb{1}_A$ for an $A \in \mathcal{A}$ and let $f \geq 0$. The left hand side of 2.2 is

$$\int f(x) \mathbb{1}_A(S(x)) \, dx = \int f(x) \mathbb{1}_{S^{-1}(A)}(x) \, dx = \int_{S^{-1}(A)} f(x) \, dx, \quad (2.3)$$

and the right hand side

$$\int \mathcal{L}f(x) \mathbb{1}_A(x) \, dx = \int_A \mathcal{L}f(x) \, dx. \quad (2.4)$$

Hence $\mathcal{L}f \in L^1$ should satisfy the equation

$$\int_A \mathcal{L}f(x) \, dx = \int_{S^{-1}(A)} f(x) \, dx. \quad (2.5)$$

A short exercise in measure theory shows that

$$A \mapsto \int_{S^{-1}(A)} f(x) \, dx \quad (2.6)$$

defines a finite absolutely continuous measure, and hence by the Radon-Nikodym theorem the measure has a unique density which by 2.5 is precisely $\mathcal{L}f$. For general $f \in L^1$ decompose $f = f^+ - f^-$ with $f^+, f^- \geq 0$ and set $\mathcal{L}f = \mathcal{L}f^+ - \mathcal{L}f^-$.

2.6 shows that \mathcal{L} is precisely the action of the pushforward $S_\# \mu = \mu \circ S^{-1}$ for densities. This provides a useful intuition for the transfer operator: we move away from the viewpoint of single points $x \in \Omega$, and instead consider *distributions* of point density. If x is chosen from a random distribution with density f , then the distribution of $S(x)$ has density $\mathcal{L}f$.

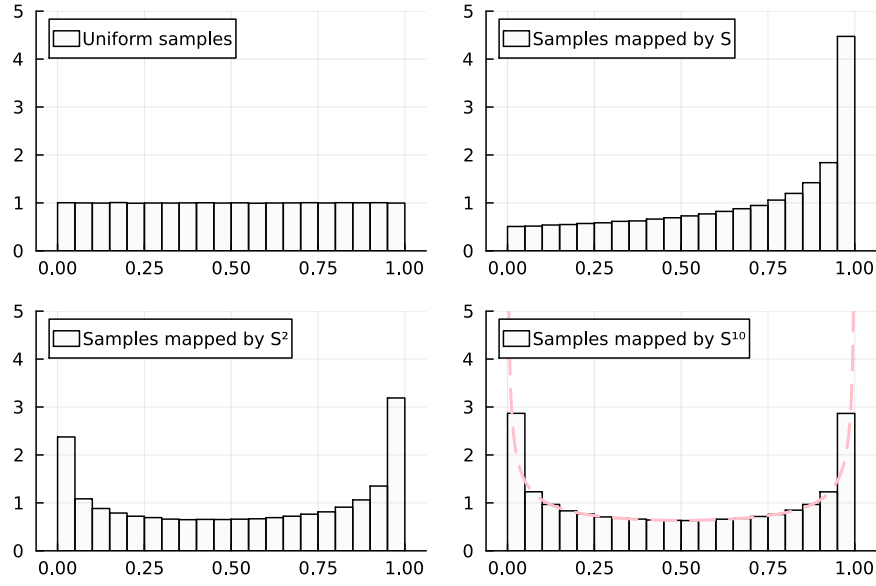


Figure 2.1: Illustration of the pushforward intuition of the Perron-Frobenius operator. Action of the \mathcal{L} associated with the quadratic map $S : [0, 1] \hookrightarrow [0, 1]$, $x \mapsto 4x(1 - x)$. One million points are sampled uniformly in $[0, 1]$ and mapped forward under S , S^2 , and S^{10} . The respective distributions are shown in histograms.

2.2 Spectral Properties

2.2.1 The Spectrum

We begin with abstract definitions for parts of the spectrum.

Definition 2.1. Let $M : D(M) \rightarrow \mathcal{X}$ be a linear operator on a Banach space $(X, \|\cdot\|)$. The domain $D(M) \subset \mathcal{X}$ of M may be a dense subset of \mathcal{X} . M is called closed if: whenever $x_k \rightarrow x$ is a convergent sequence with Mx_k convergent, then $Mx_k \rightarrow Mx$.

Closedness is weaker than continuity due to the extra assumption that Mx_k is convergent.

Definition 2.2. The spectrum $\sigma(M)$ of a closed operator M is the set of numbers $\lambda \in \mathbb{C}$ for which $M - \lambda I$ does not have a bounded inverse. The complement $\rho(M) := \mathbb{C} \setminus \sigma(M)$ is called resolvent set and $(M - \lambda I)^{-1}$ is called the resolvent.

Proposition 2.3. The spectrum admits a decomposition

$$\sigma(M) = \sigma_p(M) \oplus \sigma_c(M) \oplus \sigma_r(M) \quad (2.7)$$

into point-, continuous-, and residual-spectrum with

$$\sigma_p(M) = \{\lambda \in \mathbb{C} \mid M - \lambda I \text{ is not injective}\}, \quad (2.8)$$

$$\sigma_c(M) = \{\lambda \in \mathbb{C} \mid M - \lambda I \text{ is injective, but its range is a dense subset of } \mathcal{X}\}, \quad (2.9)$$

$$\sigma_r(M) = \{\lambda \in \mathbb{C} \mid M - \lambda I \text{ is injective, but does not have dense range}\}. \quad (2.10)$$

Remark. In some literature, 0 is never part of the spectrum. We do not take this approach.

An element $\lambda \in \sigma_p(M)$ is a *true* eigenvalue in the sense that there exists a vector $x \in \mathcal{X}$ such that $(M - \lambda I)x = 0$. The continuous spectrum has a similar characterization as the set of $\lambda \in \mathbb{C}$ for which $M_\lambda I$ is injective but *not* bounded from below, i.e. there exists a sequence $(x_k)_k$, $\|x_k\| = 1$, for which $(M - \lambda I)x_k \rightarrow 0$. Equivalently, $(M - \lambda I)^{-1}$ cannot be extended to a bounded linear operator, but is still a (densely defined) closed linear operator. (See the proof of theorem 2.15 for a proof of this characterization.)

One might ask why such detail is required in defining the spectrum. The answer lies in the subtle consequences of infinite-dimensionality. The following example from [6] shows the subtle interplay between residual spectrum and spectrum of the adjoint operator, all of which requires infinite-dimensionality.

Example 2.4 (Shift operators on $\ell^2(\mathbb{N})$). The canonical right-shift operator

$$R : (a_1, a_2, \dots) \mapsto (0, a_1, a_2, \dots) \quad (2.11)$$

is adjoint to the left shift

$$L : (a_1, a_2, \dots) \mapsto (a_2, a_3, \dots). \quad (2.12)$$

We claim:

$$\sigma_p(L) = \{\lambda \in \mathbb{C} \mid |\lambda| < 1\} \quad \sigma_p(R) = \emptyset \quad (2.13)$$

$$\sigma_c(L) = \{\lambda \in \mathbb{C} \mid |\lambda| = 1\} \quad \sigma_c(R) = \{\lambda \in \mathbb{C} \mid |\lambda| = 1\} \quad (2.14)$$

$$\sigma_r(L) = \emptyset \quad \sigma_r(R) = \{\lambda \in \mathbb{C} \mid |\lambda| < 1\}. \quad (2.15)$$

Indeed, to see 2.13 consider $|\lambda| < 1$, $a^\lambda = (\lambda, \lambda^2, \dots)$. Then clearly $La^\lambda = \lambda a^\lambda$. On the other hand, suppose $Ra = \lambda a$ for some $a \neq 0$, $\lambda \in \mathbb{C}$. Then letting n be the first index such that $a_n \neq 0$, we must have $0 = a_{n-1} = (Ra)_n = \lambda a_n$ so $\lambda = 0$. But the kernel of R is clearly $\{0\}$.

To see 2.14, take $|\lambda| = 1$ and construct *approximate* (L, λ) -eigenvectors $v^n = (\lambda, \lambda^2, \dots, \lambda^n, 0, \dots)$. Then $(L - \lambda I)v^n = (0, \dots, 0, \lambda^{n+1}, 0, \dots)$ so $\|(L - \lambda I)v^n\| = 1$ but $\|v^n\| = \sqrt{n}$. It remains to show that λ is of continuous spectrum, as opposed to residual spectrum. Indeed, for any w such that for all $v \in \ell^2$, $0 = \langle (L - \lambda I)v, w \rangle = \langle v, (R - \bar{\lambda} I)w \rangle$ so that w is an eigenvector of R which by 2.13 is a contradiction. An entirely analogous argument shows that the circle is also continuous spectrum for R .

We now reverse the discussion to see that any $|\lambda| < 1$ is in the residual spectrum of R . For $v \in \ell^2$ and w a $\bar{\lambda}$ -eigenvector of L we have $0 = \langle v, 0 \rangle = \langle v, (L - \bar{\lambda} I)w \rangle = \langle (R - \lambda I)v, w \rangle$ so that the range of $R - \lambda I$ is orthogonal to w .

Finally, $\sigma(M)$ is bounded by $\|M\|$ for any operator M , and clearly $\|L\| = 1$. But $\sigma_p(L) \cup \sigma_c(L) = \{\lambda \in \mathbb{C} \mid |\lambda| \leq 1\}$ so $\sigma_r(L) = \emptyset$. Combined with the previous paragraph, this shows 2.15.

The example already suggests some important relationships regarding the spectrum of adjoint operators.

Theorem 2.5. *Let M be a densely defined closed linear operator on a Hilbert space.*

1. $\lambda \in \sigma(M)$ iff $\bar{\lambda} \in \sigma(M^*)$.
2. If $\lambda \in \sigma_r(M)$, then $\bar{\lambda} \in \sigma_p(M^*)$.
3. Conversely, if $\lambda \in \sigma_p(M)$, then $\bar{\lambda} \in \sigma_p(M^*) \cup \sigma_r(M^*)$.
4. $\sigma_c(M) = \sigma_c(M^*)$.

Proof. 1. Suppose $M - \lambda I$ has a bounded inverse B . Then $(M - \lambda I)B = B(M - \lambda I) = I$. Equivalently $B^*(M^* - \bar{\lambda} I) = (M^* - \bar{\lambda} I)B^* = I^* = I$.

2. The range of $M - \lambda I$ is not dense in \mathcal{X} . Hence there exists a $v \perp \text{ran}(M - \lambda I)$. But this implies $v \in \ker(M^* - \bar{\lambda} I)$.

3. There exists a $v \in \ker(M - \lambda I)$ which implies $v \perp \text{ran}(M^* - \bar{\lambda} I)$.

4. This follows from 1, 2, and 3.

□

2.2.2 Spectra of Koopman and Perron-Frobenius Operators

The Koopman and Perron-Frobenius operator spectrum holds information about the long-term mixing rates of structures in phase space. We write (with some abuse of notation) $\mathcal{L}|_{\mathcal{X}}$ and $\mathcal{K}|_{\mathcal{X}}$ to denote the Perron-Frobenius / Koopman operators acting on the domain \mathcal{X} .

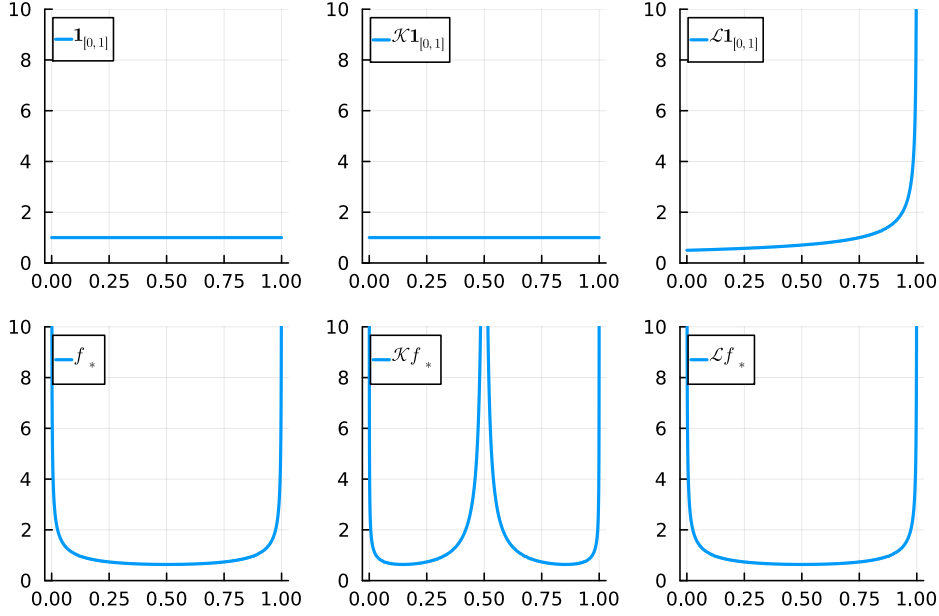


Figure 2.2: Actions of the Koopman and Perron-Frobenius operators associated with the quadratic map $S : [0, 1] \curvearrowright, x \mapsto 4x(1-x)$. The constant density $\mathbb{1}_{[0,1]}$ is fixed under \mathcal{K} and the density $f_*(x) = \frac{1}{\pi\sqrt{x(1-x)}}$ is fixed under \mathcal{L} (c.f. figure 2.1).

Definition 2.6. An eigenfunction f for $\mathcal{L}|_{L^1}$ with eigenvalue 1 is the density of a (signed) invariant measure. We say S preserves the measure $f dx$.

The following are well-known facts about the Koopman and Perron-Frobenius operator. They can be found in many sources e.g. [9].

- Theorem 2.7.**
1. If S is ergodic¹, then there is at most one invariant density. Conversely, if there is a unique invariant density which is $(dx-)$ almost everywhere positive, then S is ergodic.
 2. If S is ergodic, then every eigenvalue of $\mathcal{K}|_{L^1}$ is simple.
 3. Suppose S is invertible. Then S is weak-mixing iff 1 is the only eigenvalue of $\mathcal{K}|_{L^1}$.

The following theorem is from [5].

Definition 2.8. A set $A \subset \Omega$ in phase space is called δ -almost-invariant if

$$\int_{S^{-1}(A) \cap A} dx = (1 - \delta) \cdot \int_A dx. \quad (2.16)$$

¹Ergodicity and mixing describe how observations become decorrelated over time. S is ergodic if for all $A, B \in \mathcal{A}$ we have $\frac{1}{n} \sum_{j=0}^{n-1} \int_{S^{-j}(A) \cap B} dx \rightarrow \int_A dx \int_B dx$ as $n \rightarrow \infty$. S is weak-mixing if we have $\frac{1}{n} \sum_{j=0}^{n-1} \left| \int_{S^{-j}(A) \cap B} dx - \int_A dx \int_B dx \right| \rightarrow 0$ as $n \rightarrow \infty$.

Theorem 2.9. *Let $\mathbb{R} \ni \lambda < 1$ be an eigenvalue corresponding to a real-valued normalized eigenfunction f of $\mathcal{L}|_{L^1}$. Let further $A \subset \Omega$ be such that $\int_A f dx = \frac{1}{2}$. Then*

$$\delta + \eta = \lambda + 1 \quad (2.17)$$

if A is δ -almost-invariant and $\Omega \setminus A$ is η -almost-invariant.

These are only a few interesting properties of the spectrum of these operators, but there are many more which can be studied.

2.3 Pseudospectra

The reader will have likely noticed the sensitivity required in understanding the spectrum for infinite-dimensional operators. In particular the spectral types can be unstable w.r.t. perturbations of the operator. For example, for any self-adjoint operator M (e.g. the generator for the Koopman semigroup in a continuous-time dynamical system) there exists a compact operator E with arbitrarily small norm such that the perturbation $M + E$ has purely point spectrum.

The situation is even worse when one considers *perturbations of the dynamics* instead of perturbations of the Koopman / Perron-Frobenius operators. Consider a circle rotation $S : \mathbb{T} \rightarrow \mathbb{T}$, $e^{2\pi i \theta} \mapsto e^{2\pi i(\theta + \alpha)}$. We have $\sigma(\mathcal{L}|_{L^2}) = \sigma_p(\mathcal{L}|_{L^2}) = \alpha^{\mathbb{N}_0}$. If the rotation is rational then the spectrum is discrete, but if the rotation is irrational then the spectrum is dense in the unit circle.

In the present paper we tackle the instability problem for operator perturbations.

2.3.1 Definitions of the Pseudospectrum

Definition 2.10. *Let $M : D(M) \rightarrow \mathcal{X}$ be a closed linear operator. The ϵ -pseudospectrum of M is the smallest set in \mathbb{C} which contains the spectrum of all perturbations of M with norm less than ϵ .²*

$$\sigma_\epsilon(M) = \bigcup_{\|E\| < \epsilon} \sigma(M + E). \quad (2.18)$$

Theorem 2.11. *We have the following equivalent formulation of the pseudospectrum:*

$$\sigma_\epsilon(M) = \left\{ \lambda \in \mathbb{C} \mid \|(M - \lambda I)^{-1}\| > \frac{1}{\epsilon} \right\} \quad (2.19)$$

²Some authors will define the pseudospectrum with " \leq " instead of " $>$ ". This makes $\sigma_\epsilon(M)$ a closed set, but breaks theorem 2.11.

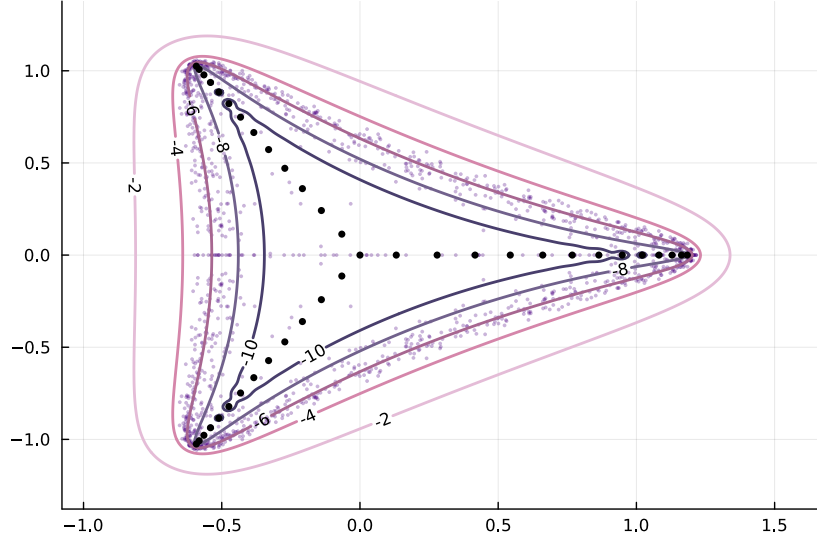


Figure 2.3: Pseudospectra for the 40×40 Toeplitz matrix T with 0 on the main diagonal, 1 on the first upper off-diagonal, and $1/4$ on the second lower off-diagonal. Contour lines show the boundary of the ϵ -pseudospectrum for $\epsilon = 10^{-2}, 10^{-4}, 10^{-6}, 10^{-8}, 10^{-10}$. Black: Spectrum of T . Purple: Spectra of $T + E$ for 40 randomly sampled perturbations E with $\|E\| < 10^{-4}$.

where we use the convention that $\|(M - \lambda I)^{-1}\| = \infty$ if $M - \lambda I$ is not invertible.

Remark. While this result is practically pseudospectrum folklore, a correct proof in the general case of closed linear operators on Banach spaces is difficult to find. Virtually all sources which cite this result, cite an unpublished technical report by Chaitin-Chatelin and Harrabi [2]. The following proof is based on [1] and extended slightly from bounded operators to closed (potentially) unbounded operators.

Proof. We prove " \subset " by contraposition: assume $\|(M - \lambda I)^{-1}\| > \frac{1}{\epsilon}$ and let $\|E\| < \epsilon$. Then $\|(M - \lambda I)^{-1}E\| < 1$ and hence $I + (M - \lambda I)^{-1}E$ is invertible. This implies

$$M - \lambda I + E = (M - \lambda I) (I + (M - \lambda I)^{-1}E) \quad (2.20)$$

is invertible.

Conversely, we prove " \supset " by showing there exists an operator E with $\|E\| < \epsilon$ such that $M - \lambda I + E$ is not invertible. Since $\|(M - \lambda I)^{-1}\| > \frac{1}{\epsilon}$ there exists a $u \in \mathcal{X}$ with $\|u\| = 1$ and $(M - \lambda I)^{-1}u = v \in D(M)$ with $\|v\| = \frac{1}{\delta} > \frac{1}{\epsilon}$.³ The Hahn-Banach theorem provides a $v^* \in \mathcal{X}^*$ with $\|v^*\| = 1$ and $v^*v = \|v\| = \frac{1}{\delta}$.

³At this point we require the strict inequality. Otherwise, the existence of such a pair u, v is not guaranteed.

Set $E = -\delta uv^*$. Then $\|E\| = \delta < \epsilon$ and

$$Ev = -\delta uv^*v = -u = -(M - \lambda I)(M - \lambda I)^{-1}u = -(M - \lambda I)v. \quad (2.21)$$

Rearranging yields $(M + E - \lambda I)v = 0$. \square

The proof of the above theorem also shows that one can consider only rank-one perturbations in 2.18:

Corollary 2.12. *We can restrict 2.18 to*

$$\sigma_\epsilon(M) = \bigcup_{\substack{\|E\| < \epsilon \\ \text{rank } E=1}} \sigma(M + E). \quad (2.22)$$

The following formulation of the pseudospectrum in the Hilbert space case will be the main tool we use in the section on numerical methods.

Definition 2.13. *The function*

$$\sigma_{\inf}(M) = \inf_{\|x\|=1} \|Mx\| \quad (2.23)$$

is known as the injection modulus.

Lemma 2.14. *Let $M : D(M) \rightarrow \mathcal{X}$ be a closed linear operator on a Hilbert space. If $\lambda \in \rho(M)$ then*

$$\sigma_{\inf}(M - \lambda I) = \sigma_{\inf}(M^* - \bar{\lambda}I), \quad (2.24)$$

but this is not necessarily true if $\lambda \in \sigma(M)$.

Proof. 2.24 for $\lambda \in \rho(M)$ follows from the fact that for bounded operators A we have $\|A\| = \|A^*\|$, applied to $A = (M - \lambda I)^{-1}$. To see that 2.24 does not hold for $\lambda \in \sigma(M)$, consider again the right shift from example 2.4. Clearly $\|Rx\| = \|x\|$ so R is bounded from below but 0 is part of the spectrum. \square

Theorem 2.15. *For a Hilbert space operator M ,*

$$\frac{1}{\|(M - \lambda I)^{-1}\|} = \min \{ \sigma_{\inf}(M - \lambda I), \sigma_{\inf}(M^* - \bar{\lambda}I) \}. \quad (2.25)$$

where we use the convention that $1/\|(M - \lambda I)^{-1}\| = 0$ when $\lambda \in \sigma(M)$.

Proof. When $\lambda \in \sigma_p(M)$, then obviously $\sigma_{\inf}(M - \lambda I) = 0$. Due to theorem 2.5 part 2, $\lambda \in \sigma_r(M)$ has $\sigma_{\inf}(M^* - \bar{\lambda}I) = 0$. Finally, let $\lambda \in \sigma_c(M)$ so $M - \lambda I$ is injective. Assume $\sigma_{\inf}(M - \lambda I) > 0$. Then $(M - \lambda I)^{-1} : \text{ran}(M - \lambda I) \rightarrow D(M)$ is bounded. But since $\text{ran}(M - \lambda I) \subset \mathcal{X}$ is dense, $(M - \lambda I)^{-1}$ has a unique bounded extension to \mathcal{X} , a contradiction. \square

Corollary 2.16. *In the Hilbert space setting, the pseudospectrum can be formulated as:*

$$\sigma_\epsilon(M) = \{\lambda \in \mathbb{C} \mid \exists u \in \mathcal{X} : \|u\| = 1 \text{ and either } \|(M - \lambda I)u\| < \epsilon \text{ or } \|(M^* - \bar{\lambda}I)u\| < \epsilon\}. \quad (2.26)$$

In the general Banach space setting,

$$\sigma_\epsilon(M) = \sigma(M) \cup \{\lambda \in \mathbb{C} \mid \exists u \in \mathcal{X} : \|u\| = 1, \|(M - \lambda I)u\| < \epsilon\}. \quad (2.27)$$

One sees from the proofs of lemma 2.14 and theorem 2.15 that $\sigma(M)$ in equation 2.27 can be replaced with $\sigma_r(M)$. The residual spectrum causes many common and unintuitive issues in spectral theory. In the study of pseudospectra, this issue is alleviated in one of three ways: (1): consider only classes of operators which have no residual spectrum (e.g. finite-dimensional or compact operators), (2): compute a slightly different object known as the *approximate-point spectrum* (see below), (3): ignore the problem entirely and write proofs which are all slightly incorrect.

Definition 2.17. *The approximate-point pseudospectrum is the set of points for which there exists an ϵ -approximate pseudoeigenvector*

$$\sigma_{ap,\epsilon}(M) = \{\lambda \in \mathbb{C} \mid \exists u \in \mathcal{X} : \|u\| = 1, \|(M - \lambda I)u\| < \epsilon\}. \quad (2.28)$$

The $\epsilon \rightarrow 0$ limit of such sets is the approximate-point spectrum

$$\sigma_{ap}(M) = \bigcap_{\epsilon > 0} \sigma_{ap,\epsilon}(M) \quad (2.29)$$

$$= \left\{ \lambda \in \mathbb{C} \mid \exists (u_k)_k : \|u_k\| = 1 \ \forall k, \lim_{k \rightarrow \infty} \|(M - \lambda I)u_k\| = 0 \right\}. \quad (2.30)$$

2.3.2 Properties

To gain some intuition for the pseudospectrum, we derive some properties for specific types of operators.

Definition 2.18. *An operator M on a Hilbert space is called normal if $M^*M = MM^*$. Special classes of normal operator include unitary operators ($M^* = M^{-1}$) and self-adjoint operators ($M^* = M$).*

Proposition 2.19. *For a normal operator M , $\sigma_r(M) = \emptyset$.*

Proof. Let $\lambda \in \sigma(M)$, $A = M - \lambda I$. If λ is not an eigenvalue then $\ker A = \{0\}$ and

$$\{0\} = \ker A = \ker A^* = (\text{ran} A)^\perp \quad (2.31)$$

where for the second equality we used the normality. Hence $\text{ran} A$ is dense. \square

Lemma 2.20. *For a closed linear operator M we have*

$$\text{dist}(\lambda, \sigma(M)) \geq \frac{1}{\|(M - \lambda I)^{-1}\|}. \quad (2.32)$$

Moreover, if M is a normal operator on a Hilbert space, then we have equality.

Proof. Let $\eta \in \sigma(M)$. Denote $A = M - \lambda I$, $B = M - \eta I$. Then A is invertible and

$$B = A - (A - B) = A(I - A^{-1}(A - B)). \quad (2.33)$$

Now $\|A^{-1}(A - B)\| \leq \|A^{-1}\| |\lambda - \eta|$ so if $|\lambda - \eta| < \frac{1}{\|A^{-1}\|}$ then the right hand side of 2.33 is invertible, a contradiction to $\eta \in \sigma(M)$.

To prove equality in the case of normal operators requires some heavy machinery from operator theory, namely:

1. Every normal operator is unitarily similar to a multiplication operator on some semi-finite measure space (i.e. there exists a unitary U such that $M = U^{-1}M_a U$ where $(M_a f)(x) = a(x)f(x)$ is a multiplication operator).
2. For multiplication operators, equation 2.32 holds with equality.

These results can be found in many sources e.g. [10]. □

Theorem 2.21. *We have*

1. $\sigma_\delta(M) \subset \sigma_\epsilon(M)$ whenever $\delta \leq \epsilon$,
2. $\bigcap_{\epsilon > 0} \sigma_\epsilon(M) = \sigma(M)$,
3. $\sigma(M) + B_\epsilon \subset \sigma_\epsilon(M)$, where B_ϵ is the ball with radius ϵ centered at 0 and $+$ refers to pointwise summation $C + D = \{x + y \mid x \in C, y \in D\}$.
4. When M is normal, $\sigma(M) + B_\epsilon = \sigma_\epsilon(M)$.

Remark. Theorem 2.21 effectively says that the Pseudospectra are nested sets which grow at least as quickly as ϵ -balls around the spectrum.

Proof. 1 and 2 are consequences of the representation 2.18 of the pseudospectrum. 3 and 4 are consequences of lemma 2.20. □

Theorem 2.22. *The function which maps $(\epsilon, M) \mapsto \sigma_\epsilon(M)$ which sends an $\epsilon > 0$ and a bounded M acting on a Hilbert space \mathcal{X} to the set $\sigma_\epsilon(M)$ is continuous using the metric*

$$d((\epsilon_1, M_1), (\epsilon_2, M_2)) = |\epsilon_1 - \epsilon_2| + \|M_1 - M_2\| \quad (2.34)$$

in the domain and the Hausdorff metric in the codomain.

Remark. 1. The idea for the proof is taken from [4], though it originally included two errors: it does not take into account residual spectrum, and makes a bound which is unfortunately not correct. These issues can be lifted in the Hilbert space setting, so that the theorem is still correct as it is stated in [4].

2. If one replaces $\sigma_\epsilon(M)$ with $\sigma_{ap,\epsilon}(M)$ in theorem 2.22, then the proof in [4] is correct and even works for general Banach spaces. To the best of this author's knowledge, there is no published proof for the Banach space setting, despite it being considered common knowledge in the study of pseudospectra.

Proof. Let (M, ϵ) and (M', ϵ') be such that $d((M, \epsilon), (M', \epsilon')) < \delta$ for some $0 < \delta < \epsilon/2$. Without loss of generality let $\epsilon \leq \epsilon'$.

Let $\lambda \in \sigma_{\epsilon'}(M')$. By 2.26 there exists a normalized $v \in \mathcal{X}$ such that either $\|(M' - \lambda I)v\| < \epsilon'$ or $\|(M'^* - \bar{\lambda}I)v\| < \epsilon'$. Assume the former is true. It follows

$$\|(M - \lambda I)v\| \leq \|(M - M')v\| + \|(M' - \lambda I)v\| < \delta - |\epsilon - \epsilon'| + \epsilon' \leq \delta + \epsilon \quad (2.35)$$

where for the last inequality we used that $\epsilon \geq \epsilon' - |\epsilon' - \epsilon|$. By 2.26, $\lambda \in \sigma_{\epsilon+\delta}(M)$ and hence $\sigma_{\epsilon'}(M') \subset \sigma_{\epsilon+\delta}(M)$.

For the case that $\|(M'^* - \bar{\lambda}I)v\| < \epsilon'$, equation 2.35 can be done exactly the same with $\|(M^* - \bar{\lambda}I)v\|$ on the left hand side.

Now let $\lambda \in \sigma_{\epsilon-\delta}(M)$. Again this implies there exists a normalized $v \in \mathcal{X}$ such that either $\|(M - \lambda I)v\| < \epsilon - \delta$ or $\|(M^* - \bar{\lambda}I)v\| < \epsilon - \delta$. Assume again the former is true. Then

$$\|(M' - \lambda I)v\| \leq \|(M' - M)v\| + \|(M - \lambda I)v\| < \delta + \epsilon - \delta \leq \epsilon' \quad (2.36)$$

and hence $\lambda \in \sigma_{\epsilon'}(M')$ so that $\sigma_{\epsilon-\delta}(M) \subset \sigma_{\epsilon'}(M')$ (again the adjoint case can be done exactly the same with adjoints on the left hand side of the equation).

We now have $\sigma_{\epsilon-\delta}(M) \subset \sigma_{\epsilon'}(M') \subset \sigma_{\epsilon+\delta}(M)$ which implies for the Hausdorff distance between $\sigma_\epsilon(M)$ and $\sigma_{\epsilon'}(M')$,

$$\mathcal{H}(\sigma_\epsilon(M), \sigma_{\epsilon'}(M')) \quad (2.37)$$

$$\leq \max\{\mathcal{H}(\sigma_\epsilon(M), \sigma_{\epsilon-\delta}(M)), \mathcal{H}(\sigma_\epsilon(M), \sigma_{\epsilon+\delta}(M))\} \quad (2.38)$$

$$\leq \mathcal{H}(\sigma_{\epsilon-\delta}(M), \sigma_{\epsilon+\delta}(M)) \quad (2.39)$$

so we must investigate the difference between $\sigma_{\epsilon-\delta}(M)$ and $\sigma_{\epsilon+\delta}(M)$. But

$$\sigma_{\epsilon+\delta}(M) \setminus \sigma_{\epsilon-\delta}(M) = \left\{ \lambda \in \mathbb{C} \mid \frac{1}{\epsilon + \delta} < \|(M - \lambda I)^{-1}\| < \frac{1}{\epsilon - \delta} \right\} \quad (2.40)$$

which is just a difference of sublevel sets for the continuous function $\lambda \mapsto \|(M - \lambda I)^{-1}\|$. Hence 2.40 collapses continuously to \emptyset as $\delta \rightarrow 0$, which implies 2.39 converges to 0 as $\delta \rightarrow 0$. \square

3 Numerical Methods

3.1 Petrov-Galerkin Methods

3.2 Extended Dynamic Mode Decomposition (EDMD)

3.3 Residual EDMD (ResDMD)

3.4 kernel EDMD (kEDMD)

3.5 kernel ResDMD (kResDMD)

4 Benchmark Examples

References

- [1] A. Boettcher and S.M. Grudsky. *Spectral Properties of Banded Toeplitz Matrices*. Society for Industrial and Applied Mathematics, 2005. ISBN: 9780898717853.
- [2] F. Chaitin-chatelin. “About Definitions of Pseudospectra of Closed Operators in Banach Spaces”. In: (May 2000).
- [3] Matthew J. Colbrook. “Chapter 4 - The multiverse of dynamic mode decomposition algorithms”. In: *Numerical Analysis Meets Machine Learning*. Ed. by Siddhartha Mishra and Alex Townsend. Vol. 25. Handbook of Numerical Analysis. Elsevier, 2024, pp. 127–230. DOI: <https://doi.org/10.1016/bs.hna.2024.05.004>.
- [4] Jianlian Cui, Chi-Kwong Li, and Yiu-Tung Poon. “Pseudospectra of special operators and pseudospectrum preservers”. In: *Journal of Mathematical Analysis and Applications* 419.2 (2014), pp. 1261–1273. ISSN: 0022-247X. DOI: <https://doi.org/10.1016/j.jmaa.2014.05.041>.
- [5] Michael Dellnitz and Oliver Junge. “On the Approximation of Complicated Dynamical Behavior”. In: *SIAM Journal on Numerical Analysis* 2.36 (1999).
- [6] Paul Garrett. *Exmaples of Operators and Spectra*. Online. 2020. URL: http://www.math.umn.edu/~CB%9Cgarrett/m/fun/notes_2012-13/06b_examples_spectra.pdf.
- [7] B. O. Koopman and J. V. Neumann. “Dynamical Systems of Continuous Spectra”. In: *Proceedings of the National Academy of Sciences of the United States of America* 18.3 (1932), pp. 255–263. ISSN: 00278424, 10916490. URL: <http://www.jstor.org/stable/86259> (visited on 11/13/2024).
- [8] Christian Kühn. “Lecture Notes on Dynamical Systems”. 2023.

- [9] Andrzej Lasota and Michael Mackey. *Chaos, Fractals, and Noise*. Springer New York, NY, 1993. DOI: <https://doi.org/10.1007/978-1-4612-4286-4>.
- [10] B. Simon. *Operator Theory*. American Mathematical Society, 2015. ISBN: 9781470411039.
- [11] Lloyd N. Trefethen and Mark Embree. *Spectra and Pseudospectra*. Princeton University Press, 2005. ISBN: 9780691213101. DOI: <https://doi.org/10.1515/9780691213101>.

5 Appendix

5.1 Transfer Operator for Blaschke Products

We consider the analytic mapping on the unit circle in \mathbb{C} ,

$$\tau : \mathbb{T} \ni z \mapsto z \frac{z - \mu}{1 - \bar{\mu}z}$$

dependent on a parameter $\mu \in \mathbb{D}$ in the open unit disk.

τ is a Lebesgue-measure preserving 2-to-1 map. The spectrum $\sigma(\mathcal{K}|_{L^2(d\theta)}) = \overline{\mathbb{D}}$ is the whole unit disk, point spectrum $\sigma_p(\mathcal{K}|_{L^2(d\theta)}) = \{1\}$.

When considering instead the adjoint $\mathcal{L} = \mathcal{K}^*$, the point spectrum has the interesting property that $\{\mu^k\}_{k=0}^\infty \cup \{\bar{\mu}^k\}_{k=0}^\infty \subset \sigma_p(\mathcal{L}|_{L^2(d\theta)})$.

More specifically, let $\mathbb{T} \subset A$ be a (suitably chosen) open annulus containing the unit circle, and $H^2(A)$ be the Hardy Hilbert space of holomorphic functions on A which are square integrable on the edge ∂A . Then on this space, $\sigma(\mathcal{L}|_{H^2(A)}) = \{\mu^k\}_{k=0}^\infty \cup \{\bar{\mu}^k\}_{k=0}^\infty$.

EDMD with monomials $\{z \mapsto z^k\}_{k=-N}^N$ (Fourier basis) results in eigendecompositions which converge exponentially to $\sigma(\mathcal{L}|_{H^2(A)})$ as $N \rightarrow \infty$.

5.2 Some scribbles about kernels and residuals

EDMD: EDMD is a Petrov-Galerkin method as written in Péter's 2016 paper. Considering a dictionary $\{\psi_i\}_{i=1}^N \subset \mathcal{H}$ ($\mathcal{H} = L^2$ mostly) and snapshots $\{x_j\}_{j=1}^M \subset X$, EDMD makes the following construction:

$$\Psi(x) = [\psi_1 \dots \psi_N] \tag{5.1}$$

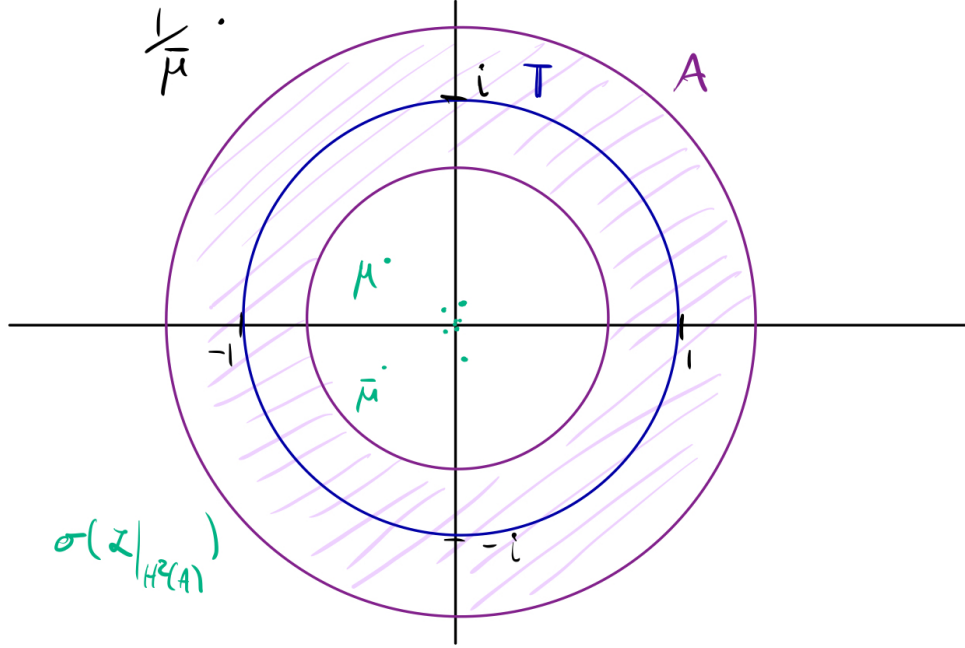
We find a matrix $K \in \mathbb{C}^{N \times N}$ that minimizes

$$\|\mathcal{K}\Psi - \Psi K\|_{\mathcal{H}(X, \mathbb{C}^{1 \times N})} \tag{5.2}$$

The \mathcal{H} norm is approximated by a quadrature:

$$\Psi_X = \Psi \begin{pmatrix} x_1 \\ \vdots \\ x_M \end{pmatrix}, \quad \Psi_Y = \Psi \circ S \begin{pmatrix} x_1 \\ \vdots \\ x_M \end{pmatrix} \tag{5.3}$$

$$\|\mathcal{K}\Psi - \Psi K\|_{\mathcal{H}(X, \mathbb{C}^{1 \times N})} \approx \|\Psi_Y - \Psi_X K\|_F. \tag{5.4}$$

Figure 5.1: Unit circle \mathbb{T} and Annulus A .

5.2 is minimized by

$$K = \Psi_X^\dagger \Psi_Y = G^\dagger A \quad (5.5)$$

where $G = \Psi_X^* \Psi_X$, $A = \Psi_X^* \Psi_Y$.

EDMD for Perron-Frobenius: Since

$$A_{ij} \stackrel{M \rightarrow \infty}{\approx} \langle \psi_i, \mathcal{K} \psi_j \rangle = \langle \mathcal{L} \psi_i, \psi_j \rangle, \quad (5.6)$$

an equivalent Galerkin approximation for $\mathcal{L} = \mathcal{K}^*$ is given by

$$P = G^\dagger A^* = \Psi_X^\dagger \Psi_X^* \Psi_Y^\dagger \Psi_Y^* \Psi_X. \quad (5.7)$$

kEDMD: Let $k : X \times X \rightarrow \mathbb{C}$ be a kernel so that

$$k(x_i, x_j) = \langle \Psi(x_i), \Psi(x_j) \rangle_{\ell^2} \quad (= \Psi(x_i) \Psi(x_j)^*). \quad (5.8)$$

(Note that $\Psi(x)$ might be infinite-dimensional, i.e. $N = \infty$, but we think of $N < \infty$ for clarity of the matrix manipulations.)

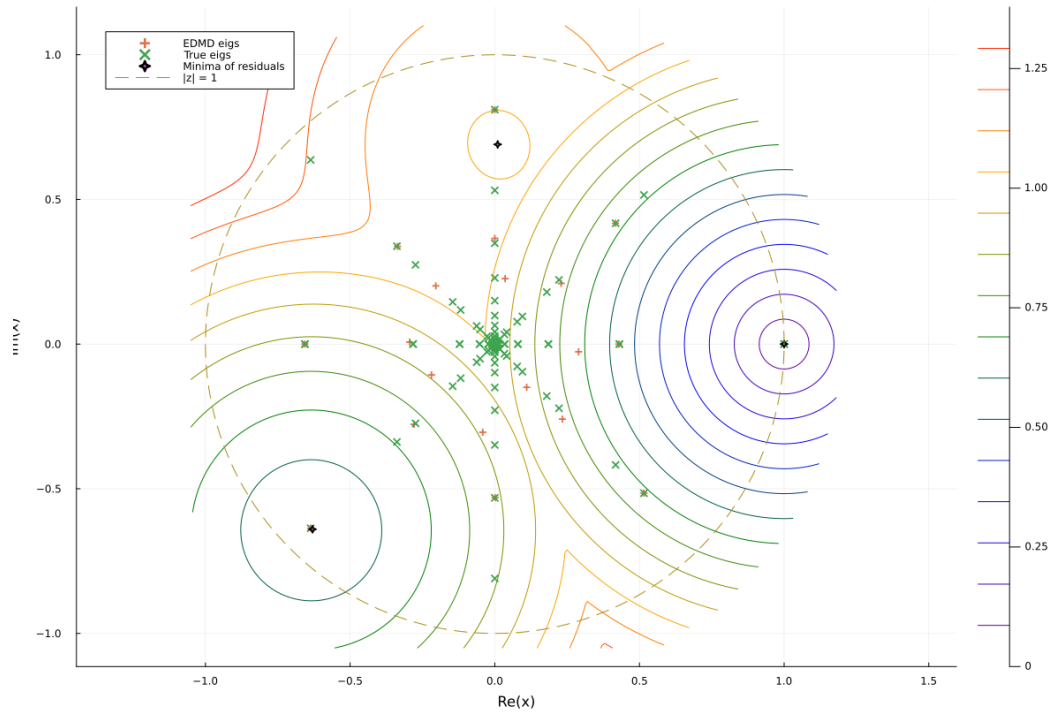


Figure 5.2: ResDMD over the space $L^2(\mathbb{T})$ for a Blaschke map $\tau(z) = z \frac{z-\mu}{1-\bar{\mu}z}$ with $\mu = 0.9e^{\pi i/4}$. True eigenvalues are known in the Hardy space $H^2(A)$ of functions holomorphic on the annulus $A = \{z \in \mathbb{C} \mid r < |z| < R\}$, $R = 11/10 - 1/32$, $r = 1/R$. ResDMD matrices G, A, L are computed w.r.t. this Hilbert space, using a dictionary of $N = 20$ monomials and $M = 200,000$ equally spaced quadrature nodes.

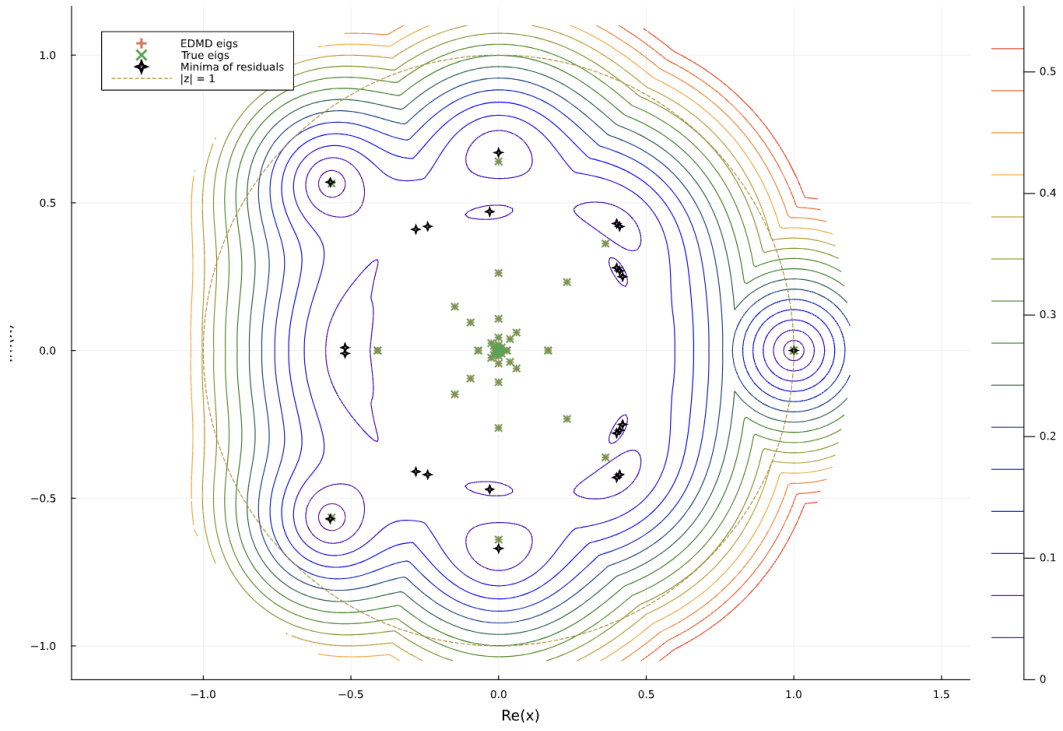


Figure 5.3: ResDMD for $\mu = 0.8e^{\pi i/4}$ over the space $H^2(A)^*$, where $H^2(A) \subset L^2$ is seen as embedded in L^2 and $(\cdot)^*$ the Banach space adjoint. This dual space is isomorphic to the space $H^2(\mathbb{D}_r) \oplus H^2(\mathbb{D}_{1/r}^\infty)$ and has a norm $\|f\|_{H^2(A)^*}^2 = \sum_{n \in \mathbb{Z}} |\hat{f}|^2 r^{|n|}$.

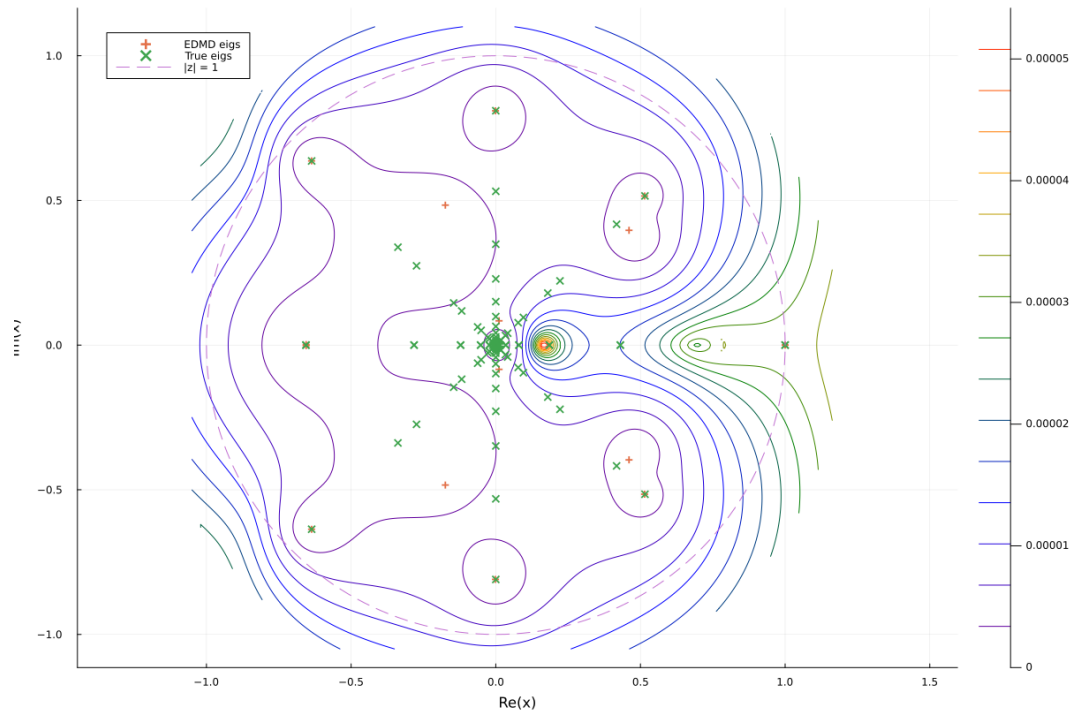


Figure 5.4: Kernelized ResDMD for the Blaschke map using a degree 20 polynomial kernel $k(x, y) = (1 + x'y)^{20}$ and $M = 2,000$ equally spaced quadrature nodes.

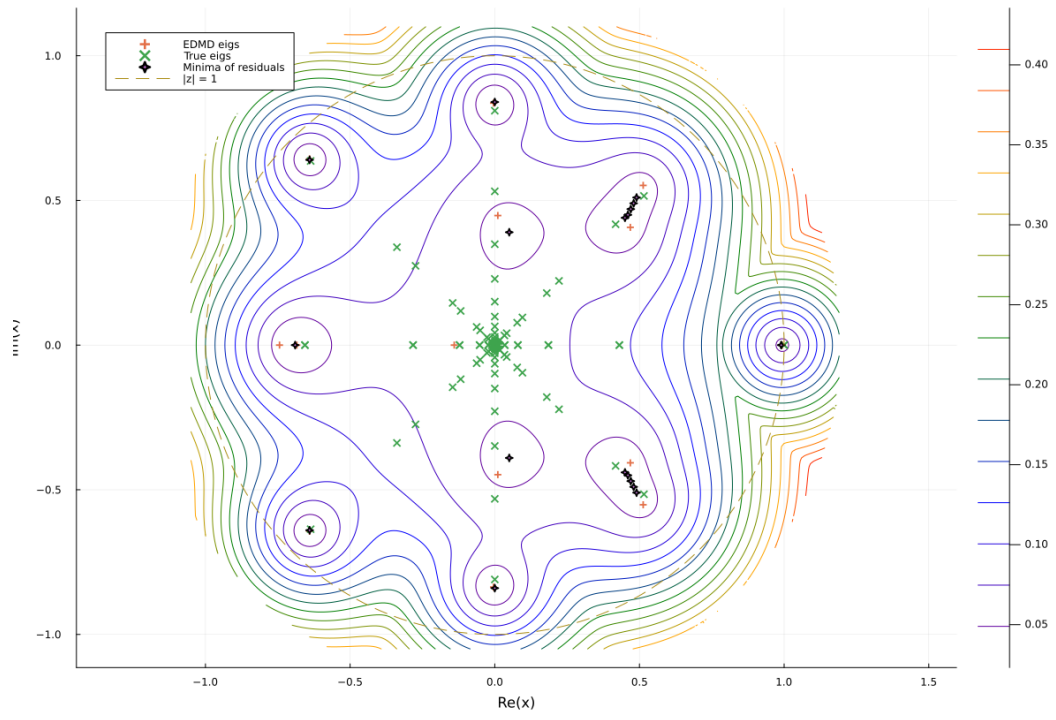


Figure 5.5: Kernelized ResDMD using an RBF kernel $k(x, y) = e^{-|x-y|^2/c}$ with $c = 0.01$ and $M = 2,000$ equally spaced quadrature nodes.

Let further $\Psi_X \stackrel{\text{SVD}}{\approx} Q\Sigma Z^*$ and

$$\hat{G} = (k(x_i, x_j))_{ij} = \Psi_X \Psi_X^* \stackrel{\text{diagonalize}}{=} Q(\Sigma^* \Sigma) Q^*, \quad (5.9)$$

$$\hat{A} = (k(y_i, x_j))_{ij} = \Psi_Y \Psi_X^* \quad (5.10)$$

Then

$$\hat{K} = (\Sigma^\dagger Q^*) \hat{A} (Q \Sigma^\dagger) \in \mathbb{C}^{M \times M} \quad (5.11)$$

has the same eigenvalues as K .

ResDMD: The key idea behind ResDMD is, for an element $z \in \mathbb{C}^N$, $g = \Psi z$:

$$\text{res}(\lambda, z) := \|(\mathcal{K} - \lambda)g\|_{\mathcal{H}(X, \mathbb{C})}^2 \quad (5.12)$$

$$\stackrel{M \rightarrow \infty}{\approx} \|(\Psi_Y - \lambda \Psi_X)z\|_{\ell^2}^2 \quad (5.13)$$

$$= z^* (\Psi_Y^* \Psi_Y - \lambda \Psi_Y^* \Psi_X - \bar{\lambda} \Psi_X^* \Psi_Y + |\lambda|^2 \Psi_X^* \Psi_X) z \quad (5.14)$$

$$= z^* (L - \lambda A^* - \bar{\lambda} A + |\lambda|^2 G) z. \quad (5.15)$$

We interpret the first equation as

$$\text{regression error} \stackrel{M \rightarrow \infty}{\approx} \text{operator residual}. \quad (5.16)$$

The function $\lambda \mapsto \text{res}(\lambda) = \min_z \text{res}(\lambda, z)$ is shown in 5.2

kResDMD: We apply idea 5.16 to \hat{K} :

$$\hat{K}^* = (\Psi_X^* Q \Sigma^\dagger)^\dagger (\Psi_Y^* Q \Sigma^\dagger) =: \hat{\Psi}_X^\dagger \hat{\Psi}_Y \quad (5.17)$$

so that \hat{K}^* solves the regression problem

$$\min_M \|\hat{\Psi}_Y - \hat{\Psi}_X M\|_F. \quad (5.18)$$

The regression error reduces to

$$\text{r\hat{e}s}(\lambda, z) := \|(\hat{\Psi}_Y - \lambda \hat{\Psi}_X)z\|_{\ell^2}^2 \quad (5.19)$$

$$= (Q\Sigma^\dagger z)^* (\Psi_Y \Psi_Y^* - \lambda \Psi_Y \Psi_X^* - \bar{\lambda} \Psi_X \Psi_Y^* + |\lambda|^2 \Psi_X \Psi_X^*) (Q\Sigma^\dagger z) \quad (5.20)$$

$$= (Q\Sigma^\dagger z)^* \left(\hat{L} - \lambda \hat{A}^* - \bar{\lambda} \hat{A} + |\lambda|^2 \hat{G} \right) (Q\Sigma^\dagger z) \quad (5.21)$$

Note at this point it is unclear whether this regression error in the case of \hat{K} has a physical meaning.

ResDMD for Perron-Frobenius: Consider $\tilde{P} = Z^* P Z$, which has the same eigenvalues as P . Then

$$\tilde{P} = (\Psi_X^* Q \Sigma)^\dagger (\Psi_Y^* Q \Sigma) =: \tilde{\Psi}_X^\dagger \tilde{\Psi}_Y \quad (5.22)$$

so that \hat{P} solves the regrestion problem

$$\min_M \|\tilde{\Psi}_Y - \tilde{\Psi}_X M\|_F. \quad (5.23)$$

The interesting thing to note is that

$$\tilde{\text{r\hat{e}s}}(\lambda, z) := \|(\tilde{\Psi}_Y - \lambda \tilde{\Psi}_X)z\|_{\ell^2}^2 \quad (5.24)$$

$$= (Q\Sigma z)^* (\Psi_Y \Psi_Y^* - \lambda \Psi_Y \Psi_X^* - \bar{\lambda} \Psi_X \Psi_Y^* + |\lambda|^2 \Psi_X \Psi_X^*) (Q\Sigma z) \quad (5.25)$$

$$= (Q\Sigma z)^* \left(\hat{L} - \lambda \hat{A}^* - \bar{\lambda} \hat{A} + |\lambda|^2 \hat{G} \right) (Q\Sigma z) \quad (5.26)$$

and hence whenever Ψ_X has the same number of zero singular values (we assume there are none i.e. $s_{\min}(\Psi_X) > 0$),

$$\text{r\hat{e}s}(\lambda) := \min_z \text{r\hat{e}s}(\lambda, z) = \min_\xi \tilde{\text{r\hat{e}s}}(\lambda, \xi) =: \tilde{\text{r\hat{e}s}}(\lambda). \quad (5.27)$$

The function $\text{r\hat{e}s}$ is shown in 5.4, 5.5.

Interpreting the regression error: Let $y = Q\Sigma z$. For convenience we conjugate λ , i.e. let $\tilde{P}z = \bar{\lambda}z$ be a candidate eigenpair for \mathcal{L} .

What follows is a rough, purely formal sketch of the idea that we want to show, from what I calculated this morning (no promises for correctness):

$$\|(\Psi_Y^* - \bar{\lambda}\Psi_X^*)y\|_{\ell^2}^2 \quad (5.28)$$

$$= \sum_{i=1}^N \left| \sum_{j=1}^M \overline{(\mathcal{K}\psi_i - \lambda\psi_i)(x_j)} y_j \right|^2 \quad (5.29)$$

$$\stackrel{M \rightarrow \infty}{\approx} \sum_{i=1}^N \left| \int \overline{(\mathcal{K}\psi_i - \lambda\psi_i)(\xi)} y(\xi) d\xi \right|^2 \quad (5.30)$$

$$= \sum_{i=1}^N |\langle (\mathcal{K} - \lambda)\psi_i, y \rangle|^2 \quad (5.31)$$

$$= \sum_{i=1}^N |\langle \psi_i, (\mathcal{L} - \bar{\lambda})y \rangle|^2 \quad (5.32)$$

$$\stackrel{N \rightarrow \infty}{\approx} \|(\mathcal{L} - \bar{\lambda})y\|_{\mathcal{H}(X, \mathbb{C})}^2. \quad (5.33)$$

where for 5.30 we say that the vector $y = (y_j)_j$ converges to a function $y : \xi \mapsto y(\xi)$, and for 5.33 we use Plancherel's theorem (hence we need to assume Ψ is an orthonormal family that in the limit has span dense in $\mathcal{H}(X, \mathbb{C})$).

It seems likely that these convergences will work, under the crucial assumption that the singular values stay bounded from above and below as $N \rightarrow \infty$, which is given if Ψ is an orthonormal family. There is some literature on kernel *QR* algorithms, which are essentially Gram-Schmidt for kernel weight matrices. However, I would much prefer if this would work without the orthonormal requirement, as most kernel functions and snapshot datasets will not make orthonormal Gram matrices.

For e.g. Gauß kernels $k(x, y) = \exp(-\|x - y\|^2/c)$, the sharpness parameter c has to be changed as M changes in order for the singular value condition to hold since if c is kept constant and M grows, the Gram matrix slowly becomes the all-ones matrix.

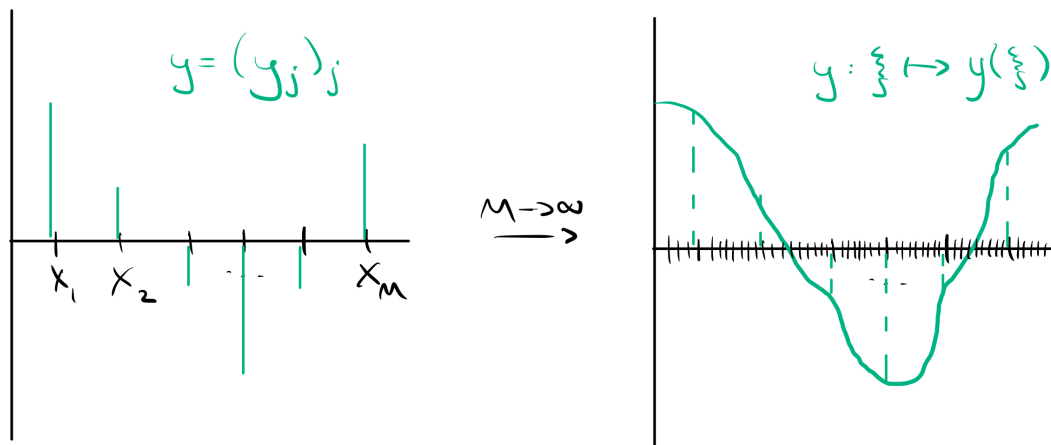


Figure 5.6: Idea behind equation 5.30