

# ODEs - General

## Picard Lindelöf

**f locally L-continuous wrt x**  $\exists$  unique soln that extends to boundary of  $\Omega$

## Gronwall

$\phi, \psi : [a, b] \rightarrow [0, \infty)$  continuous,  $\rho \geq 0$ ,  $\psi(t) \leq \rho + \int_a^b \phi(s)\psi(s)ds$   $\psi(s) \leq \rho \exp\left(\int_a^b \phi(s)ds\right)$

## consistency error

$\epsilon(t, \tau, x) = \Phi^{t+\tau, t}x - \Psi^{t+\tau, t}x$

## consistency order

$\epsilon(t, \tau, x) = O(\tau^{p+1})$

## convergence order

$x_\Delta : \Delta \rightarrow \mathbb{R}, x : I \rightarrow \mathbb{R}, \Delta_n \text{ with } \tau_n \rightarrow 0, \|\epsilon_{\Delta_n}\| = \max_{t \in \Delta_n} \|x(t) - x_{\Delta_n}(t)\| = O(\tau^p)$

## convergence theorem

$\psi$  scheme with consistency order p,  $\psi$  locally L-continuous wrt x  $\psi$  has convergence order p

## $\dot{x} = Ax$ stability

$Re\lambda \leq 0, Re\lambda = 0 \Rightarrow i(\lambda) = 1 \forall \lambda \in \sigma(A)$

$x_{k+1} = Mx_k$  **stability**

$\rho(M) \leq 1, |\lambda| = 1 \Rightarrow i(\lambda) = 1 \forall \lambda \in \sigma(M)$

## Leibnitz rule

$\frac{d}{dx} \int_{a(x)}^{b(x)} f(t, x)dt =$

$b'(x)f(b(x), x) - a'(x)f(a(x), x) + \int_{a(x)}^{b(x)} \frac{d}{dx}f(t, x)dt$

# Runge Kutta Schemes

## Form of RK schemes

$k_i = f\left(t + c_i\tau, x + \sum_{j=1}^s a_{ij}k_j\right),$

$\Psi^{t+\tau, t}x = x + \tau \sum_{i=1}^s b_i k_i$

## consistent

$\sum_{i=1}^s b_i = 1$

## invariant under autonomization

$\sum_{j=1}^s a_{ij} = c_i$

## max order

explicit  $\Rightarrow \leq s$ , implicit  $\Rightarrow \leq 2s$

## Rooted trees

$f : \mathbb{R}^d \rightarrow \mathbb{R}^d$  autonomous

$f^\beta = f^n \cdot (f^{\beta_1}, \dots, f^{\beta_n}),$

$f[] = f(x),$

$\#\beta = \#\beta_1 + \dots + \#\beta_n + 1,$

$\beta! = \#\beta \cdot \beta_1! \dots \beta_n!,$

$[]! = 1$

## Taylor expansions (!!autonomous)

$\Phi^\tau x = x + \sum_{\#\beta \leq p} \frac{\tau^{\#\beta}}{\beta!} \alpha f^\beta(x) + O(\tau^{p+1})$

$\alpha_\beta = \frac{\delta_\beta}{n!} \alpha_{\beta_1} \dots \alpha_{\beta_n}, \delta_\beta = \text{nr of orderings of } \beta$

$\Psi^\tau x = x + \sum_{\#\beta \leq p} \tau^{\#\beta} \alpha_\beta b^T A^\beta f^\beta(x) + O(\tau^{p+1})$

$\left(A^\beta\right)_i = \left(A \cdot A^{\beta_1}\right)_i \dots \left(A \cdot A^{\beta_n}\right)_i, \quad A^{[]} = \mathbf{1} \in \mathbb{R}^s$

## Butcher

RK has order p

$\forall f \in \mathcal{C}^p \Leftrightarrow b^T A^\beta = 1/\beta! \forall \#\beta \leq p$

order 1  $\Leftrightarrow$  consistent

order 2  $\Leftrightarrow \sum_{i=1}^s c_i b_i = 1/2$

order 3  $\Leftrightarrow \sum_{i=1}^s b_i c_i^2 = 1/3 \wedge Ac = 1/6$

## Adaptive Schemes

Use higher order scheme  $\hat{\Psi}$ , use max  $\tau$  with  $[\epsilon] = \Psi^\tau x - \hat{\Psi}^\tau x$  has norm  $\leq \text{TOL}$

## Embedded Schemes

Given  $\hat{\Psi} = (\hat{b}, \hat{A})$ , construct  $\Psi = (b, A)$  with order  $p < \hat{p}$  to reduce number of  $f$  evals

## Stability function

$\dot{x} = Ax \Rightarrow \Psi^\tau x = R(\tau A)x$

$R(z) = 1 + zb^T(I - zA)^{-1}\mathbf{1}$

## Stability domain

$S_R = \{z \in \mathbb{C} : |R(z)| \leq 1\}$

$A(\alpha)$  **stable**

$\{z \in \mathbb{C} : |\arg(z)| \leq \alpha\} \subset S_R$

## L stable

$\lim_{|z| \rightarrow \infty} |R(z)| = 0$

## RK method stability

$\tau\lambda \in S_R \forall \lambda \in \sigma(A), |\tau\lambda| = 1 \Rightarrow i(\tau\lambda) = 1 \forall \lambda \in \sigma(A)$

## Collocation

Given  $0 \leq c_1 \leq \dots \leq c_s \leq 1,$

$a_{ij} = \int_0^{c_i} L_j(\theta)d\theta, \quad b_j = \int_0^1 L_j(\theta)d\theta$

$\Psi^\tau x_0 = u(\tau), \dot{u}(c_i\tau) = f(u(c_i\tau))$  with  $u$  as interpolation polynomial

$L_j(x) = \prod_{k \neq j} \frac{x - x_k}{x_j - x_k}$

Gauß schemes  $\Rightarrow$  Gauß nodes,  $p = 2s$ , A-stable

Radau schemes  $\Rightarrow$  interpolation nodes hits the grid,

$p = 2s - 1$ , L-stable

# Multistep Schemes

## MSS

$\rho(z) = \alpha_0 + \dots \alpha_k z^k, \sigma(z) =$

$\beta_0 + \dots \beta_k z^k, (Ex)(t) = x(t + \tau), Ex_j = x_{j+1}$

$\rho(E)x_\tau(t) = \tau\sigma(E)f(t, x_\tau(t))$

## MSS Consistency order

$L(x, t, \tau) = \rho(E)x(t) - \tau\sigma(E)\dot{x}(t) = O(\tau^{p+1})$

$\Leftrightarrow L(Q, 0, \tau) = 0$

$\Leftrightarrow L(\exp, 0, \tau) = O(\tau^{p+1})$

$\Leftrightarrow \sum_{j=0}^k \alpha_j j^l = l \sum_{j=0}^k \beta_j j^{l-1} \quad \forall l = 0, \dots, p$

$\rho(1) = 0, \rho'(1) = \sigma(1) \Rightarrow$  consistent

## MSS on $\dot{x} = 0$ stability

$\rho(E)x_\tau = 0$  is stable  $\Leftrightarrow |\lambda| \leq 1, |\lambda| = 1 \Rightarrow \lambda$  is a simple root of  $\rho$

## MSS Convergence order

$\forall$  IVPs with unique soln:

$\|x_\tau(t) - x(t)\| = O(\tau^p) \forall t \in \Delta_\tau \cap [t_0, T]$

$\|x_j - x_0\| = O(\tau^p) \forall j = 0, \dots, k - 1$

## MSS Convergence theorem

stability & consistency order p  $\Leftrightarrow$  convergence order p

## Stability domain

$S = \{z \in \mathbb{C} : (\rho(E) - x\sigma(E))x_\tau = 0 \text{ is stable}\}$

## Root locus curve

$S \subset \text{int}\left(\left\{\frac{\rho(e^{i\phi})}{\sigma(e^{i\phi})} : \phi \in [0, 2\pi]\right\}\right)$

## Adams Bashford Schemes

$x_{j+1} = x_{j+k-1} + \tau \sum_{i=0}^{k-1} f_{j+i}\beta_i$  (or if implicit)

$\beta_i = \int_0^1 L_{k-1-i}(\theta)d\theta$

$u(t_{j+i}) = f_\tau(t_{j+i}, x_{j+i}),$  order k+1

## BDF Schemes

$\rho(z) = \sum_{i=0}^k L'_{k-i}(0)z^i, \sigma(z) = z^k$

$u(t_{j+i}) = x_{j+i} \forall i = 0, \dots, k, \dot{u}(t_{j+k}) =$

$f_\tau(t_{j+k}, x_{j+k})$

BDF scheme is stable  $\Leftrightarrow k \leq 6$

## Max rder of MSS

explicit  $\Rightarrow \leq 2k - 1$ , implicit  $\Rightarrow \leq 2k$ ,

stable  $\leq \begin{cases} k, & \beta_k/\alpha_k = 0 \\ k + 1, & \text{k odd} \\ k + 2, & \text{k even} \end{cases}$