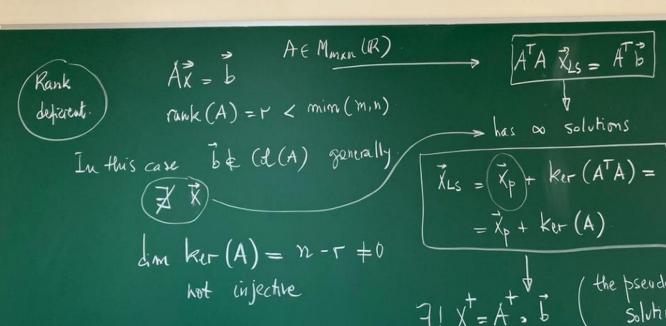
## Linear Systems 3

Rank Deficient

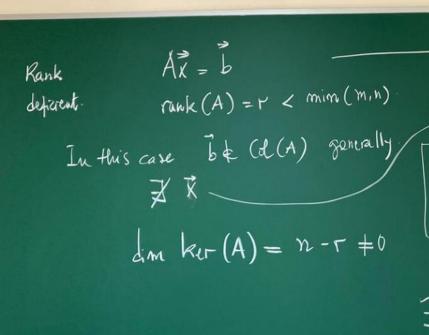


Xt is the minimum horm Solution of Kis X is orthogonal to ker(A) pin (A)\* b(:) (the pseudoinverse)

ATA ZLS = ATB

has oo solutions

= Xp + Ker (A)



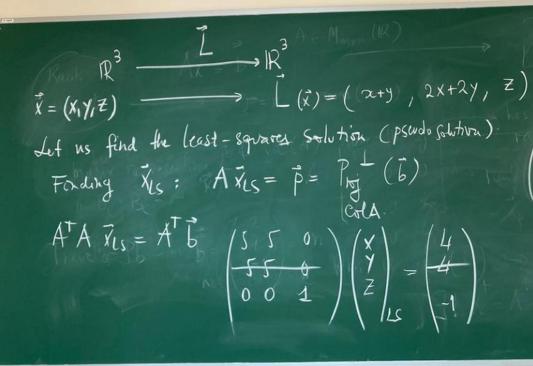
ATA 
$$\vec{X}_{LS} = AT\vec{b}$$

ATA  $\vec{X}_{LS} = AT\vec{b}$ 

The minimum norm solution of  $\vec{X}_{LS}$ 

The pseudoinverse of the pseudoinverse of

 $L(\vec{x}) = (2+y), 2x+2y, z).$  $A = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$  rank-definent LAmatrix representing L in Bc-Bc Traveller Pb  $\vec{b} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$  What is  $\vec{c} \cdot (\vec{b}) \iff \vec{x} : A\vec{x} = \vec{b}$ (Ab) = 3 16 Ge (A)





$$\begin{cases} x + y = 4/5 \\ z = -1 \end{cases}$$

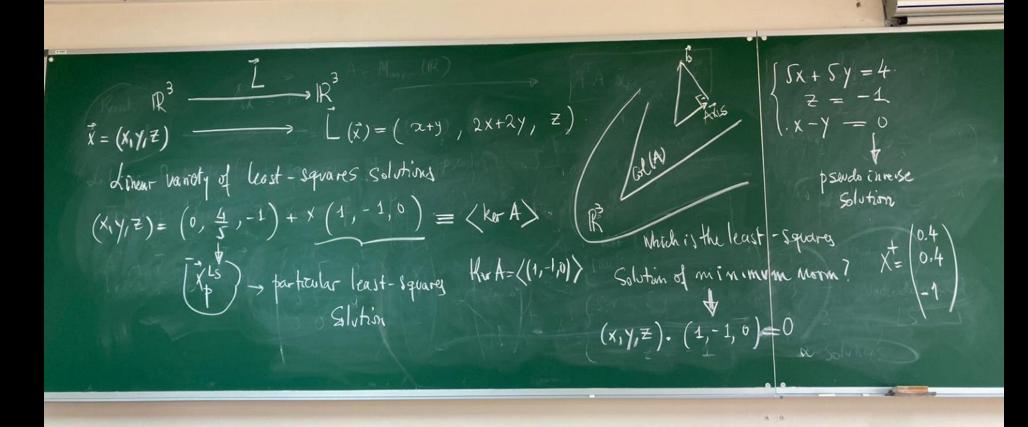
$$(x_1y_1z) = (x, \frac{4}{5} - x, -1)$$
or least - squared Sol.
$$\begin{cases} 1 \\ 1 \end{cases}$$

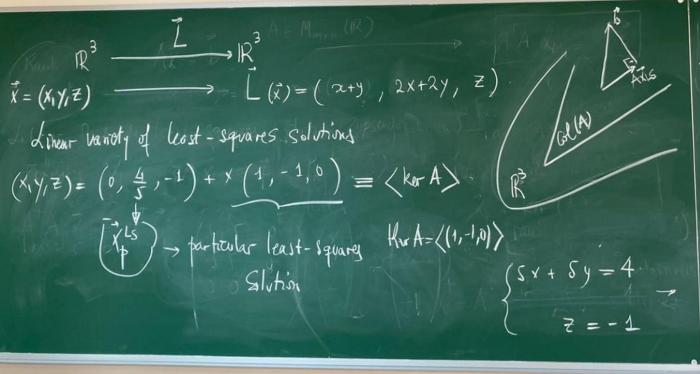
$$= 2 \qquad \text{Purely}$$

$$M = 2 \qquad \text{Under-determined}$$

$$h = 3 \qquad \text{LS}$$

$$80 \text{ Solutions}$$





$$\begin{cases} x + y = 4/5 \\ z = -1 \end{cases}$$

$$(x_1y_1z) = (x_1, \frac{4}{5} - x_1 - 1)$$
or least - squares Sol.
$$\begin{cases} 1 \\ 1 \end{cases}$$

$$= 2 \qquad \text{Purely}$$

$$m = 2 \qquad \text{Under-determed}$$

$$h = 3 \qquad \text{LS}$$
so Solutions