

## ASSIGNMENT NO.-08

**Title:**

Given sequence  $k = k_1 < k_2 < \dots < k_n$  of  $n$  sorted keys, with a search probability  $p_i$  for each key  $k_i$ . Build the Binary search tree that has the least search cost given the access probability for each key?

```
#include <iostream>
```

```
#define SIZE 10
```

```
using namespace std;
```

```
class optimal
```

```
{
```

```
    public:
```

```
    int p[SIZE];
```

```
    int q[SIZE];
```

```
    int a[SIZE];
```

```
    int w[SIZE][SIZE];
```

```
    int c[SIZE][SIZE];
```

```
    int r[SIZE][SIZE];
```

```
    int n;
```

```
    int front,rear,queue[20];
```

```
    optimal() //default constructor
```

```
{
```

```
    front=rear=-1;
```

```

    }

    void getdata();

    int minvalue(int,int);

    void OBST();

    void buildtree();

};

void optimal::getdata()
{
    int i;

    cout<<"\n Optimal Binary search tree";

    cout<<"\n Enter the number of nodes :";

    cin>>n;

    cout<<"\n Enter the data : \n";

    for (i=1;i<=n;i++)
    {
        cout<<"\n a["<<i<<"]:";

        cin>>a[i];

    }

    cout<<"\n Enter probalities for successful search \n";

    for(i=1;i<=n;i++)
    {
        cout<<"p["<<i<<"]:";

```

```

    cin>>p[i];

    }

    cout<<"\n Enter probalities for unsuccessful search \n";

    for(i=1;i<=n;i++)
    {

        cout<<"q["<<i<<"]:";

        cin>>q[i];

    }

}

```

/\* This function returns a value in range  $r[i][j-1]$  to  $r[i+1][j]$  so that cost  $c[i][k-1] + c[k][j]$  is minimum \*/

```

int optimal::minvalue(int i,int j)
{
    int m,k;

    int min=32000;

    for(m=r[i][j-1];m<=r[i+1][j];m++)
    {

        if((c[i][m-1]+c[m][j])<min)
        {

            min=c[i][m-1]+c[m][j];

            k=m;

        }

    }

}

```

```
return k;
```

```
}
```

```
/* This function builds table from all given probabilities. it basically computes  
C,r,w value */
```

```
void optimal::OBST()
```

```
{
```

```
int i,j,k,m;
```

```
for(i=0;i<n;i++)
```

```
{
```

```
    //initialize
```

```
    w[i][i]=q[i];
```

```
    r[i][i]=c[i][i]=0;
```

```
    //optimal trees with one node
```

```
    w[i][i+1]=q[i]+q[i+1]+p[i+1];
```

```
    r[i][i+1]=i+1;
```

```
    c[i][i+1]=q[i]+q[i+1]+p[i+1];
```

```
}
```

```
    w[n][n]=q[n];
```

```
    r[n][n]=c[n][n]=0;
```

```
    //find optimal trees with m nodes
```

```
    for(m=2;m<=n;m++)
```

```
{
```

```
    for(i=0;i<=n-m;i++)
```

```

        {
            j=i+m;

            w[i][j]=w[i][j-1]+p[j]+q[j];

            k=minvalue(i,j);

            c[i][j]=w[i][j]+c[i][k-1]+c[k][j];

            r[i][j]=k;

        }

    }

}

```

/\* This function builds tree from table made by OBST function \*/

```
void optimal::buildtree()
```

```

{
    int i,j,k;

    cout<<"\n The optimal Binary search tree for given nodes is : \n";

    cout<<"\n The root of this OBST is : "<<r[0][n];

    cout<<"\n The cost of this OBST is: "<<c[0][n];

    cout<<"\n\n Node \t Left child \t Right child";

    cout<<"\n _____" <<endl;

    queue[++rear]=0;

    queue[++rear]=n;

    while(front!=rear)

    {

```

```

i=queue[++front];
j=queue[++front];
k=r[i][j];
cout<<"\n\t"<<k;
if(r[i][k-1]!=0)
{
    cout<<"    "<<r[i][k-1];
    queue[++rear]=i;
    queue[++rear]=k-1;
}
else
cout<<"    ";
if(r[k][j]!=0)
{
    cout<<"    "<<r[k][j];
    queue[++rear]=k;
    queue[++rear]=j;
}
else
cout<<"    ";
}
cout<<endl;
}

```

```

/* This is main function */

int main() {

    optimal obj;

    obj.getdata();

    obj.OBST();

    obj.buildtree();

    return 0;

}

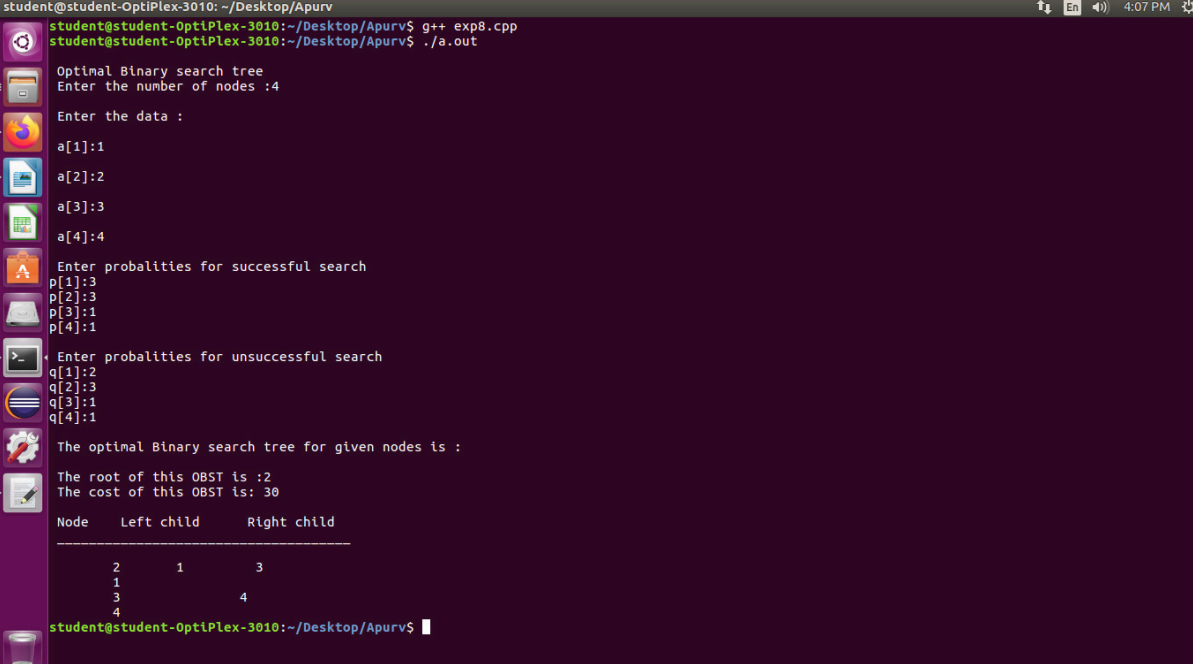
```

---



---

Output:



```

student@student-OptiPlex-3010: ~/Desktop/Apurv
student@student-OptiPlex-3010:~/Desktop/Apurv$ g++ exp8.cpp
student@student-OptiPlex-3010:~/Desktop/Apurv$ ./a.out

Optimal Binary search tree
Enter the number of nodes :4

Enter the data :
a[1]:1
a[2]:2
a[3]:3
a[4]:4

Enter probabilities for successful search
p[1]:3
p[2]:3
p[3]:1
p[4]:1

Enter probabilities for unsuccessful search
q[1]:2
q[2]:3
q[3]:1
q[4]:1

The optimal Binary search tree for given nodes is :
The root of this OBST is :2
The cost of this OBST is: 30

Node   Left child   Right child
-----
      2         1         3
      1             4
      3
      4

student@student-OptiPlex-3010:~/Desktop/Apurv$

```