**Duty Cycle Assignment**

* Code:
* /\* USER CODE BEGIN Header \*/
* /\*\*
* \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*
* \* @file : main.c
* \* @brief : Main program body
* \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*
* \* @attention
* \*
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* \*
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* \*
* \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*
* \*/
* /\* USER CODE END Header \*/
* /\* Includes ------------------------------------------------------------------\*/
* **#include** "main.h"
* /\* Private includes ----------------------------------------------------------\*/
* /\* USER CODE BEGIN Includes \*/
* /\* USER CODE END Includes \*/
* /\* Private typedef -----------------------------------------------------------\*/
* /\* USER CODE BEGIN PTD \*/
* /\* USER CODE END PTD \*/
* /\* Private define ------------------------------------------------------------\*/
* /\* USER CODE BEGIN PD \*/
* /\* USER CODE END PD \*/
* /\* Private macro -------------------------------------------------------------\*/
* /\* USER CODE BEGIN PM \*/
* /\* USER CODE END PM \*/
* /\* Private variables ---------------------------------------------------------\*/
* TIM\_HandleTypeDef htim2;
* /\* USER CODE BEGIN PV \*/
* /\* USER CODE END PV \*/
* /\* Private function prototypes -----------------------------------------------\*/
* **void** **SystemClock\_Config**(**void**);
* **static** **void** **MX\_GPIO\_Init**(**void**);
* **static** **void** **MX\_TIM2\_Init**(**void**);
* /\* USER CODE BEGIN PFP \*/
* /\* USER CODE END PFP \*/
* /\* Private user code ---------------------------------------------------------\*/
* /\* USER CODE BEGIN 0 \*/
* /\* USER CODE END 0 \*/
* /\*\*
* \* @brief The application entry point.
* \* @retval int
* \*/
* **int** **main**(**void**)
* {
* /\* USER CODE BEGIN 1 \*/
* /\* USER CODE END 1 \*/
* /\* MCU Configuration--------------------------------------------------------\*/
* /\* Reset of all peripherals, Initializes the Flash interface and the Systick. \*/
* HAL\_Init();
* /\* USER CODE BEGIN Init \*/
* /\* USER CODE END Init \*/
* /\* Configure the system clock \*/
* SystemClock\_Config();
* /\* USER CODE BEGIN SysInit \*/
* /\* USER CODE END SysInit \*/
* /\* Initialize all configured peripherals \*/
* MX\_GPIO\_Init();
* MX\_TIM2\_Init();
* /\* USER CODE BEGIN 2 \*/
* HAL\_TIM\_PWM\_Start(&htim2, TIM\_CHANNEL\_1);
* /\* USER CODE END 2 \*/
* /\* Infinite loop \*/
* /\* USER CODE BEGIN WHILE \*/
* **while** (1)
* {
* /\* USER CODE END WHILE \*/
* /\* USER CODE BEGIN 3 \*/
* }
* /\* USER CODE END 3 \*/
* }
* /\*\*
* \* @brief System Clock Configuration
* \* @retval None
* \*/
* **void** **SystemClock\_Config**(**void**)
* {
* RCC\_OscInitTypeDef RCC\_OscInitStruct = {0};
* RCC\_ClkInitTypeDef RCC\_ClkInitStruct = {0};
* /\*\* Configure the main internal regulator output voltage
* \*/
* **if** (HAL\_PWREx\_ControlVoltageScaling(PWR\_REGULATOR\_VOLTAGE\_SCALE1) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* /\*\* Initializes the RCC Oscillators according to the specified parameters
* \* in the RCC\_OscInitTypeDef structure.
* \*/
* RCC\_OscInitStruct.OscillatorType = RCC\_OSCILLATORTYPE\_MSI;
* RCC\_OscInitStruct.MSIState = RCC\_MSI\_ON;
* RCC\_OscInitStruct.MSICalibrationValue = 0;
* RCC\_OscInitStruct.MSIClockRange = RCC\_MSIRANGE\_6;
* RCC\_OscInitStruct.PLL.PLLState = RCC\_PLL\_ON;
* RCC\_OscInitStruct.PLL.PLLSource = RCC\_PLLSOURCE\_MSI;
* RCC\_OscInitStruct.PLL.PLLM = 1;
* RCC\_OscInitStruct.PLL.PLLN = 16;
* RCC\_OscInitStruct.PLL.PLLP = RCC\_PLLP\_DIV7;
* RCC\_OscInitStruct.PLL.PLLQ = RCC\_PLLQ\_DIV2;
* RCC\_OscInitStruct.PLL.PLLR = RCC\_PLLR\_DIV2;
* **if** (HAL\_RCC\_OscConfig(&RCC\_OscInitStruct) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* /\*\* Initializes the CPU, AHB and APB buses clocks
* \*/
* RCC\_ClkInitStruct.ClockType = RCC\_CLOCKTYPE\_HCLK|RCC\_CLOCKTYPE\_SYSCLK
* |RCC\_CLOCKTYPE\_PCLK1|RCC\_CLOCKTYPE\_PCLK2;
* RCC\_ClkInitStruct.SYSCLKSource = RCC\_SYSCLKSOURCE\_PLLCLK;
* RCC\_ClkInitStruct.AHBCLKDivider = RCC\_SYSCLK\_DIV1;
* RCC\_ClkInitStruct.APB1CLKDivider = RCC\_HCLK\_DIV1;
* RCC\_ClkInitStruct.APB2CLKDivider = RCC\_HCLK\_DIV1;
* **if** (HAL\_RCC\_ClockConfig(&RCC\_ClkInitStruct, FLASH\_LATENCY\_1) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* }
* /\*\*
* \* @brief TIM2 Initialization Function
* \* @param None
* \* @retval None
* \*/
* **static** **void** **MX\_TIM2\_Init**(**void**)
* {
* /\* USER CODE BEGIN TIM2\_Init 0 \*/
* /\* USER CODE END TIM2\_Init 0 \*/
* TIM\_ClockConfigTypeDef sClockSourceConfig = {0};
* TIM\_MasterConfigTypeDef sMasterConfig = {0};
* TIM\_OC\_InitTypeDef sConfigOC = {0};
* /\* USER CODE BEGIN TIM2\_Init 1 \*/
* /\* USER CODE END TIM2\_Init 1 \*/
* htim2.Instance = TIM2;
* htim2.Init.Prescaler = 32000;
* htim2.Init.CounterMode = TIM\_COUNTERMODE\_UP;
* htim2.Init.Period = 5000;
* htim2.Init.ClockDivision = TIM\_CLOCKDIVISION\_DIV1;
* htim2.Init.AutoReloadPreload = TIM\_AUTORELOAD\_PRELOAD\_ENABLE;
* **if** (HAL\_TIM\_Base\_Init(&htim2) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* sClockSourceConfig.ClockSource = TIM\_CLOCKSOURCE\_INTERNAL;
* **if** (HAL\_TIM\_ConfigClockSource(&htim2, &sClockSourceConfig) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* **if** (HAL\_TIM\_PWM\_Init(&htim2) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* sMasterConfig.MasterOutputTrigger = TIM\_TRGO\_RESET;
* sMasterConfig.MasterSlaveMode = TIM\_MASTERSLAVEMODE\_DISABLE;
* **if** (HAL\_TIMEx\_MasterConfigSynchronization(&htim2, &sMasterConfig) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* sConfigOC.OCMode = TIM\_OCMODE\_PWM1;
* sConfigOC.Pulse = 2000;
* sConfigOC.OCPolarity = TIM\_OCPOLARITY\_HIGH;
* sConfigOC.OCFastMode = TIM\_OCFAST\_DISABLE;
* **if** (HAL\_TIM\_PWM\_ConfigChannel(&htim2, &sConfigOC, TIM\_CHANNEL\_1) != *HAL\_OK*)
* {
* Error\_Handler();
* }
* /\* USER CODE BEGIN TIM2\_Init 2 \*/
* /\* USER CODE END TIM2\_Init 2 \*/
* HAL\_TIM\_MspPostInit(&htim2);
* }
* /\*\*
* \* @brief GPIO Initialization Function
* \* @param None
* \* @retval None
* \*/
* **static** **void** **MX\_GPIO\_Init**(**void**)
* {
* GPIO\_InitTypeDef GPIO\_InitStruct = {0};
* /\* GPIO Ports Clock Enable \*/
* \_\_HAL\_RCC\_GPIOE\_CLK\_ENABLE();
* \_\_HAL\_RCC\_GPIOC\_CLK\_ENABLE();
* \_\_HAL\_RCC\_GPIOA\_CLK\_ENABLE();
* \_\_HAL\_RCC\_GPIOB\_CLK\_ENABLE();
* \_\_HAL\_RCC\_GPIOD\_CLK\_ENABLE();
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(GPIOE, M24SR64\_Y\_RF\_DISABLE\_Pin|M24SR64\_Y\_GPO\_Pin|ISM43362\_RST\_Pin, *GPIO\_PIN\_RESET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(GPIOA, ARD\_D10\_Pin|SPBTLE\_RF\_RST\_Pin|ARD\_D9\_Pin, *GPIO\_PIN\_RESET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(GPIOB, ARD\_D8\_Pin|ISM43362\_BOOT0\_Pin|ISM43362\_WAKEUP\_Pin|LED2\_Pin
* |SPSGRF\_915\_SDN\_Pin|ARD\_D5\_Pin, *GPIO\_PIN\_RESET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(GPIOD, USB\_OTG\_FS\_PWR\_EN\_Pin|PMOD\_RESET\_Pin|STSAFE\_A100\_RESET\_Pin, *GPIO\_PIN\_RESET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(SPBTLE\_RF\_SPI3\_CSN\_GPIO\_Port, SPBTLE\_RF\_SPI3\_CSN\_Pin, *GPIO\_PIN\_SET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(GPIOC, VL53L0X\_XSHUT\_Pin|LED3\_WIFI\_\_LED4\_BLE\_Pin, *GPIO\_PIN\_RESET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(SPSGRF\_915\_SPI3\_CSN\_GPIO\_Port, SPSGRF\_915\_SPI3\_CSN\_Pin, *GPIO\_PIN\_SET*);
* /\*Configure GPIO pin Output Level \*/
* HAL\_GPIO\_WritePin(ISM43362\_SPI3\_CSN\_GPIO\_Port, ISM43362\_SPI3\_CSN\_Pin, *GPIO\_PIN\_SET*);
* /\*Configure GPIO pins : M24SR64\_Y\_RF\_DISABLE\_Pin M24SR64\_Y\_GPO\_Pin ISM43362\_RST\_Pin ISM43362\_SPI3\_CSN\_Pin \*/
* GPIO\_InitStruct.Pin = M24SR64\_Y\_RF\_DISABLE\_Pin|M24SR64\_Y\_GPO\_Pin|ISM43362\_RST\_Pin|ISM43362\_SPI3\_CSN\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_OUTPUT\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* HAL\_GPIO\_Init(GPIOE, &GPIO\_InitStruct);
* /\*Configure GPIO pins : USB\_OTG\_FS\_OVRCR\_EXTI3\_Pin SPSGRF\_915\_GPIO3\_EXTI5\_Pin SPBTLE\_RF\_IRQ\_EXTI6\_Pin ISM43362\_DRDY\_EXTI1\_Pin \*/
* GPIO\_InitStruct.Pin = USB\_OTG\_FS\_OVRCR\_EXTI3\_Pin|SPSGRF\_915\_GPIO3\_EXTI5\_Pin|SPBTLE\_RF\_IRQ\_EXTI6\_Pin|ISM43362\_DRDY\_EXTI1\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_IT\_RISING;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(GPIOE, &GPIO\_InitStruct);
* /\*Configure GPIO pin : BUTTON\_EXTI13\_Pin \*/
* GPIO\_InitStruct.Pin = BUTTON\_EXTI13\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_IT\_FALLING;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(BUTTON\_EXTI13\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_A5\_Pin ARD\_A4\_Pin ARD\_A3\_Pin ARD\_A2\_Pin
* ARD\_A1\_Pin ARD\_A0\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_A5\_Pin|ARD\_A4\_Pin|ARD\_A3\_Pin|ARD\_A2\_Pin
* |ARD\_A1\_Pin|ARD\_A0\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_ANALOG\_ADC\_CONTROL;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(GPIOC, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_D1\_Pin ARD\_D0\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D1\_Pin|ARD\_D0\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF8\_UART4;
* HAL\_GPIO\_Init(GPIOA, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_D10\_Pin SPBTLE\_RF\_RST\_Pin ARD\_D9\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D10\_Pin|SPBTLE\_RF\_RST\_Pin|ARD\_D9\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_OUTPUT\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* HAL\_GPIO\_Init(GPIOA, &GPIO\_InitStruct);
* /\*Configure GPIO pin : ARD\_D7\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D7\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_ANALOG\_ADC\_CONTROL;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(ARD\_D7\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_D12\_Pin ARD\_D11\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D12\_Pin|ARD\_D11\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF5\_SPI1;
* HAL\_GPIO\_Init(GPIOA, &GPIO\_InitStruct);
* /\*Configure GPIO pin : ARD\_D3\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D3\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_IT\_RISING;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(ARD\_D3\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pin : ARD\_D6\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D6\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_ANALOG\_ADC\_CONTROL;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(ARD\_D6\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_D8\_Pin ISM43362\_BOOT0\_Pin ISM43362\_WAKEUP\_Pin LED2\_Pin
* SPSGRF\_915\_SDN\_Pin ARD\_D5\_Pin SPSGRF\_915\_SPI3\_CSN\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D8\_Pin|ISM43362\_BOOT0\_Pin|ISM43362\_WAKEUP\_Pin|LED2\_Pin
* |SPSGRF\_915\_SDN\_Pin|ARD\_D5\_Pin|SPSGRF\_915\_SPI3\_CSN\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_OUTPUT\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* HAL\_GPIO\_Init(GPIOB, &GPIO\_InitStruct);
* /\*Configure GPIO pins : DFSDM1\_DATIN2\_Pin DFSDM1\_CKOUT\_Pin \*/
* GPIO\_InitStruct.Pin = DFSDM1\_DATIN2\_Pin|DFSDM1\_CKOUT\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* GPIO\_InitStruct.Alternate = GPIO\_AF6\_DFSDM1;
* HAL\_GPIO\_Init(GPIOE, &GPIO\_InitStruct);
* /\*Configure GPIO pins : QUADSPI\_CLK\_Pin QUADSPI\_NCS\_Pin OQUADSPI\_BK1\_IO0\_Pin QUADSPI\_BK1\_IO1\_Pin
* QUAD\_SPI\_BK1\_IO2\_Pin QUAD\_SPI\_BK1\_IO3\_Pin \*/
* GPIO\_InitStruct.Pin = QUADSPI\_CLK\_Pin|QUADSPI\_NCS\_Pin|OQUADSPI\_BK1\_IO0\_Pin|QUADSPI\_BK1\_IO1\_Pin
* |QUAD\_SPI\_BK1\_IO2\_Pin|QUAD\_SPI\_BK1\_IO3\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF10\_QUADSPI;
* HAL\_GPIO\_Init(GPIOE, &GPIO\_InitStruct);
* /\*Configure GPIO pins : INTERNAL\_I2C2\_SCL\_Pin INTERNAL\_I2C2\_SDA\_Pin \*/
* GPIO\_InitStruct.Pin = INTERNAL\_I2C2\_SCL\_Pin|INTERNAL\_I2C2\_SDA\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_OD;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF4\_I2C2;
* HAL\_GPIO\_Init(GPIOB, &GPIO\_InitStruct);
* /\*Configure GPIO pins : INTERNAL\_UART3\_TX\_Pin INTERNAL\_UART3\_RX\_Pin \*/
* GPIO\_InitStruct.Pin = INTERNAL\_UART3\_TX\_Pin|INTERNAL\_UART3\_RX\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF7\_USART3;
* HAL\_GPIO\_Init(GPIOD, &GPIO\_InitStruct);
* /\*Configure GPIO pins : LPS22HB\_INT\_DRDY\_EXTI0\_Pin LSM6DSL\_INT1\_EXTI11\_Pin ARD\_D2\_Pin HTS221\_DRDY\_EXTI15\_Pin
* PMOD\_IRQ\_EXTI12\_Pin \*/
* GPIO\_InitStruct.Pin = LPS22HB\_INT\_DRDY\_EXTI0\_Pin|LSM6DSL\_INT1\_EXTI11\_Pin|ARD\_D2\_Pin|HTS221\_DRDY\_EXTI15\_Pin
* |PMOD\_IRQ\_EXTI12\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_IT\_RISING;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(GPIOD, &GPIO\_InitStruct);
* /\*Configure GPIO pins : USB\_OTG\_FS\_PWR\_EN\_Pin SPBTLE\_RF\_SPI3\_CSN\_Pin PMOD\_RESET\_Pin STSAFE\_A100\_RESET\_Pin \*/
* GPIO\_InitStruct.Pin = USB\_OTG\_FS\_PWR\_EN\_Pin|SPBTLE\_RF\_SPI3\_CSN\_Pin|PMOD\_RESET\_Pin|STSAFE\_A100\_RESET\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_OUTPUT\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* HAL\_GPIO\_Init(GPIOD, &GPIO\_InitStruct);
* /\*Configure GPIO pins : VL53L0X\_XSHUT\_Pin LED3\_WIFI\_\_LED4\_BLE\_Pin \*/
* GPIO\_InitStruct.Pin = VL53L0X\_XSHUT\_Pin|LED3\_WIFI\_\_LED4\_BLE\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_OUTPUT\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_LOW;
* HAL\_GPIO\_Init(GPIOC, &GPIO\_InitStruct);
* /\*Configure GPIO pins : VL53L0X\_GPIO1\_EXTI7\_Pin LSM3MDL\_DRDY\_EXTI8\_Pin \*/
* GPIO\_InitStruct.Pin = VL53L0X\_GPIO1\_EXTI7\_Pin|LSM3MDL\_DRDY\_EXTI8\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_IT\_RISING;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(GPIOC, &GPIO\_InitStruct);
* /\*Configure GPIO pin : USB\_OTG\_FS\_VBUS\_Pin \*/
* GPIO\_InitStruct.Pin = USB\_OTG\_FS\_VBUS\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_INPUT;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* HAL\_GPIO\_Init(USB\_OTG\_FS\_VBUS\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pins : USB\_OTG\_FS\_ID\_Pin USB\_OTG\_FS\_DM\_Pin USB\_OTG\_FS\_DP\_Pin \*/
* GPIO\_InitStruct.Pin = USB\_OTG\_FS\_ID\_Pin|USB\_OTG\_FS\_DM\_Pin|USB\_OTG\_FS\_DP\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF10\_OTG\_FS;
* HAL\_GPIO\_Init(GPIOA, &GPIO\_InitStruct);
* /\*Configure GPIO pins : INTERNAL\_SPI3\_SCK\_Pin INTERNAL\_SPI3\_MISO\_Pin INTERNAL\_SPI3\_MOSI\_Pin \*/
* GPIO\_InitStruct.Pin = INTERNAL\_SPI3\_SCK\_Pin|INTERNAL\_SPI3\_MISO\_Pin|INTERNAL\_SPI3\_MOSI\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF6\_SPI3;
* HAL\_GPIO\_Init(GPIOC, &GPIO\_InitStruct);
* /\*Configure GPIO pin : PMOD\_SPI2\_SCK\_Pin \*/
* GPIO\_InitStruct.Pin = PMOD\_SPI2\_SCK\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF5\_SPI2;
* HAL\_GPIO\_Init(PMOD\_SPI2\_SCK\_GPIO\_Port, &GPIO\_InitStruct);
* /\*Configure GPIO pins : PMOD\_UART2\_CTS\_Pin PMOD\_UART2\_RTS\_Pin PMOD\_UART2\_TX\_Pin PMOD\_UART2\_RX\_Pin \*/
* GPIO\_InitStruct.Pin = PMOD\_UART2\_CTS\_Pin|PMOD\_UART2\_RTS\_Pin|PMOD\_UART2\_TX\_Pin|PMOD\_UART2\_RX\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF7\_USART2;
* HAL\_GPIO\_Init(GPIOD, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ST\_LINK\_UART1\_TX\_Pin ST\_LINK\_UART1\_RX\_Pin \*/
* GPIO\_InitStruct.Pin = ST\_LINK\_UART1\_TX\_Pin|ST\_LINK\_UART1\_RX\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_PP;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF7\_USART1;
* HAL\_GPIO\_Init(GPIOB, &GPIO\_InitStruct);
* /\*Configure GPIO pins : ARD\_D15\_Pin ARD\_D14\_Pin \*/
* GPIO\_InitStruct.Pin = ARD\_D15\_Pin|ARD\_D14\_Pin;
* GPIO\_InitStruct.Mode = GPIO\_MODE\_AF\_OD;
* GPIO\_InitStruct.Pull = GPIO\_NOPULL;
* GPIO\_InitStruct.Speed = GPIO\_SPEED\_FREQ\_VERY\_HIGH;
* GPIO\_InitStruct.Alternate = GPIO\_AF4\_I2C1;
* HAL\_GPIO\_Init(GPIOB, &GPIO\_InitStruct);
* /\* EXTI interrupt init\*/
* HAL\_NVIC\_SetPriority(*EXTI9\_5\_IRQn*, 0, 0);
* HAL\_NVIC\_EnableIRQ(*EXTI9\_5\_IRQn*);
* HAL\_NVIC\_SetPriority(*EXTI15\_10\_IRQn*, 0, 0);
* HAL\_NVIC\_EnableIRQ(*EXTI15\_10\_IRQn*);
* }
* /\* USER CODE BEGIN 4 \*/
* /\* USER CODE END 4 \*/
* /\*\*
* \* @brief This function is executed in case of error occurrence.
* \* @retval None
* \*/
* **void** **Error\_Handler**(**void**)
* {
* /\* USER CODE BEGIN Error\_Handler\_Debug \*/
* /\* User can add his own implementation to report the HAL error return state \*/
* \_\_disable\_irq();
* **while** (1)
* {
* }
* /\* USER CODE END Error\_Handler\_Debug \*/
* }
* **#ifdef** USE\_FULL\_ASSERT
* /\*\*
* \* @brief Reports the name of the source file and the source line number
* \* where the assert\_param error has occurred.
* \* @param file: pointer to the source file name
* \* @param line: assert\_param error line source number
* \* @retval None
* \*/
* **void** assert\_failed(uint8\_t \*file, uint32\_t line)
* {
* /\* USER CODE BEGIN 6 \*/
* /\* User can add his own implementation to report the file name and line number,
* ex: printf("Wrong parameters value: file %s on line %d\r\n", file, line) \*/
* /\* USER CODE END 6 \*/
* }
* **#endif** /\* USE\_FULL\_ASSERT \*/
* /\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\* (C) COPYRIGHT STMicroelectronics \*\*\*\*\*END OF FILE\*\*\*\*/
* Output:

<https://drive.google.com/file/d/1mc_FT0z7VZ1Fw5dkjZvOlKMlKTmd7rwd/view?usp=sharing>