# AML\_HW4\_Questions\_3

April 14, 2024

0.0.1 Name: Apurva Patel

0.0.2 UNI: amp2365

## 0.1 Setup

```
[11]: import numpy as np
  import matplotlib.pyplot as plt
  import pprint
  pp = pprint.PrettyPrinter(indent=4)
  import warnings
  warnings.filterwarnings("ignore")
```

# 1 Part 1: Neural Network from scratch

For this part, you are not allowed to use any library other than numpy.

In this part, you will implement the forward pass and backward pass (i.e. the derivates of each parameter wrt to the loss) with the network image uploaded.

- The weight matrix for the hidden layer is W1 and has bias b1.
- The weight matrix for the output layer is W2 and has bias b2.
- Activation function is sigmoid for both hidden and output layer
- Loss function is the Mean Squared Error (MSE) loss

Refer to the below dictionary for dimensions for each matrix

```
[]: np.random.seed(0) # don't change this
    weights = {
    'W1': np.random.randn(3, 2),
    'b1': np.zeros(3),
    'W2': np.random.randn(3),
    'b2': 0,
    }
    X = np.random.rand(1000,2)
    Y = np.random.randint(low=0, high=2, size=(1000,))
```

```
[]: #Sigmoid Function
def sigmoid(z):
    return 1/(1 + np.exp(-z))
```

```
[]: #Implement the forward pass - Z2 and Y
def forward_propagation(X, weights):
    # Z1 -> output of the hidden layer before applying activation
    # H -> output of the hidden layer after applying activation
    # Z2 -> output of the final layer before applying activation
    # Y -> output of the final layer after applying activation

Z1 = np.dot(X, weights['W1'].T) + weights['b1']
    H = sigmoid(Z1)
    # Your code here
    Z2 = np.dot(H, weights['W2']) + weights['b2']
    Y = sigmoid(Z2)
    return Y, Z2, H, Z1
```

```
[]: # Implement the backward pass - dLdZ1, dLdW1, dLdb1
     # Y_T are the ground truth labels
     def back_propagation(X, Y_T, weights):
         N_points = X.shape[0]
         # forward propagation
         Y, Z2, H, Z1 = forward_propagation(X, weights)
         L = (1/(2*N_points)) * np.sum(np.square(Y - Y_T))
         # back propagation
         dLdY = 1/N_points * (Y - Y_T)
         dLdZ2 = np.multiply(dLdY, (sigmoid(Z2)*(1-sigmoid(Z2))))
         dLdW2 = np.dot(H.T, dLdZ2)
         ones = np.ones((1000))
         dLdb2 = np.dot(ones.T, dLdZ2)
         dLdH = np.dot(dLdZ2.reshape(-1,1), weights['W2'].reshape(-1,1).T)
         # Your code here
         dLdZ1 = np.multiply(dLdH, (sigmoid(Z1) * (1 - sigmoid(Z1))))
         dLdW1 = np.dot(dLdZ1.T, X)
         dLdb1 = np.dot(ones, dLdZ1)
         gradients = {
             'W1': dLdW1,
             'b1': dLdb1,
             'W2': dLdW2,
             'b2': dLdb2,
         }
         return gradients, L
```

```
[]: gradients, L = back_propagation(X, Y, weights)
print(L)
```

#### 0.1332476222330792

Your answers should be close to L = 0.133 and 'b1': array([ 0.00492, -0.000581, -0.00066]).

You will be graded based on your implementation and outputs for L, W1, W2 b1, and b2

# 2 Part 2: Neural network to classify images: CIFAR-10

CIFAR-10 is a dataset of 60,000 color images (32 by 32 resolution) across 10 classes - airplane, automobile, bird, cat, deer, dog, frog, horse, ship, and truck.

The train/test split is 50k/10k.

```
[]: from tensorflow.keras.datasets import cifar10 #Code to load data, do not change (x_dev, y_dev), (x_test, y_test) = cifar10.load_data()

LABELS =

□

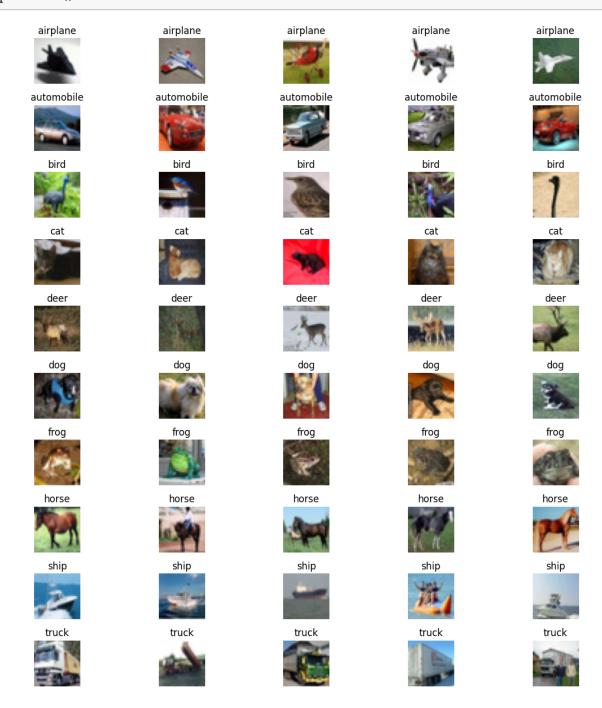
□ ('airplane', 'automobile', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
```

#### 2.0.1 2.1 Plot 50 samples from each class/label from train set on a 10\*5 subplot

```
class_indices = {i: [] for i in range(10)}
for i, label in enumerate(y_dev):
    class_indices[label[0]].append(i)

fig, axes = plt.subplots(10, 5, figsize=(12, 12))
for i in range(10):
    for j in range(5):
        idx = class_indices[i][j]
        axes[i, j].imshow(x_dev[idx])
        axes[i, j].set_title(LABELS[i])
        axes[i, j].axis('off')
```

plt.tight\_layout()
plt.show()



# ${\bf 2.0.2} \quad {\bf 2.2} \ {\bf Preparing} \ {\bf the} \ {\bf dataset} \ {\bf for} \ {\bf NN}$

1) Print the shapes - , , ,

- 2) Flatten the images into one-dimensional vectors and again print the shapes of
- 3) Standardize the development and test sets.
- 4) One hot encode your labels
- 5) Train-test split your development set into train and validation sets (80:20 ratio).

```
[]: #Your code here
     print("Shapes before preprocessing:")
     print("x_dev shape:", x_dev.shape)
     print("y_dev shape:", y_dev.shape)
     print("x_test shape:", x_test.shape)
     print("y_test shape:", y_test.shape)
    Shapes before preprocessing:
    x_dev shape: (50000, 32, 32, 3)
    y_dev shape: (50000, 1)
    x_test shape: (10000, 32, 32, 3)
    y_test shape: (10000, 1)
[]: #Your code here
     x_dev_flat = x_dev.reshape(x_dev.shape[0], -1)
     x_test_flat = x_test.reshape(x_test.shape[0], -1)
[]: print("\nShapes after flattening:")
     print("x_dev shape (flattened):", x_dev_flat.shape)
     print("x_test shape (flattened):", x_test_flat.shape)
    Shapes after flattening:
    x_dev shape (flattened): (50000, 3072)
    x_test shape (flattened): (10000, 3072)
[]: from sklearn.model_selection import train_test_split
     from sklearn.preprocessing import StandardScaler, OneHotEncoder
[]: #Your code here
     scaler = StandardScaler()
     x_dev_scaled = scaler.fit_transform(x_dev_flat)
     x_test_scaled = scaler.transform(x_test_flat)
[]: #Your code here
     encoder = OneHotEncoder(sparse=False)
     y_dev_encoded = encoder.fit_transform(y_dev)
     y_test_encoded = encoder.transform(y_test)
[]: #Your code here
```

```
Shapes after train-test split:
x_train shape: (40000, 3072)
y_train shape: (40000, 10)
x_val shape: (10000, 3072)
y_val shape: (10000, 10)
```

## 2.0.3 2.3 Build the feed forward network with the below specifications

First layer size = 128hidden layer size = 64

last layer size = Figure this out from the data!

The last layer size is 10 as there are 10 classes in the dataset

```
[]: import tensorflow as tf
     from tensorflow.keras.models import Sequential
     from tensorflow.keras.layers import Dense, Flatten
     #Your code here
     input_size = x_train.shape[1]
     first_layer_size = 128
     hidden_layer_size = 64
     output_size = y_train.shape[1]
     # the model
     model = tf.keras.models.Sequential([
         tf.keras.layers.Dense(first layer size, activation='relu', ...
      →input_shape=(input_size,)),
         tf.keras.layers.Dense(hidden_layer_size, activation='relu'),
         tf.keras.layers.Dense(output_size, activation='softmax')
     ])
     model.compile(optimizer='adam',
                   loss='categorical_crossentropy',
                   metrics=['accuracy'])
```

# 2.0.4 Print out the model summary. Mention the number of parameters for each layer.

```
[]: #Your code here model.summary()
```

Model: "sequential"

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 128)	393344
dense_1 (Dense)	(None, 64)	8256
dense_2 (Dense)	(None, 10)	650

Total params: 402250 (1.53 MB)
Trainable params: 402250 (1.53 MB)
Non-trainable params: 0 (0.00 Byte)

\_\_\_\_\_\_

# 2.0.5 Do you think the number of parameters is dependent on the image height and width?

- Yes, the number of parameters in a neural network is indirectly influenced (sort opf) by the image height and width.
- In a fully connected layer, each neuron connects to every neuron in the previous layer, resulting in a large number of parameters. Therefore, larger images with more pixels will lead to more parameters in the network.
- However, the direct dependency is on the number of neurons in each layer and the connections between them, rather than the specific dimensions of the image.

```
[]: #Your comments here: Wrote in markdown above
```

Printing out your model's output on first train sample. This will confirm if your dimensions are correctly set up. The sum of this output should equal to 1.

```
[]: #modify name of X_train based on your requirement

model.compile()
output = model.predict(x_train[0].reshape(1,-1))

print("Output: {:.2f}".format(sum(output[0])))
```

```
1/1 [=====] - 1s 786ms/step
```

Output: 1.00

# 2.0.6 Using the right metric and the right loss function, with Adam as the optimizer, train your model for 20 epochs.

```
[]: #Your code here
   model.compile(optimizer='adam',
             loss='categorical_crossentropy',
             metrics=['accuracy'])
   history = model.fit(x_train, y_train, epochs=20, validation_data=(x_val, y_val))
   test_loss, test_accuracy = model.evaluate(x_test_scaled, y_test_encoded)
   print("\nTest Loss:", test_loss)
   print("Test Accuracy:", test_accuracy)
   Epoch 1/20
   accuracy: 0.3670 - val_loss: 1.6556 - val_accuracy: 0.4169
   Epoch 2/20
   accuracy: 0.4466 - val_loss: 1.5855 - val_accuracy: 0.4391
   Epoch 3/20
   accuracy: 0.4819 - val_loss: 1.5413 - val_accuracy: 0.4611
   Epoch 4/20
   accuracy: 0.5053 - val_loss: 1.4827 - val_accuracy: 0.4824
   Epoch 5/20
   accuracy: 0.5274 - val_loss: 1.4949 - val_accuracy: 0.4868
   Epoch 6/20
   1250/1250 [============ ] - 5s 4ms/step - loss: 1.2928 -
   accuracy: 0.5427 - val_loss: 1.4569 - val_accuracy: 0.4885
   Epoch 7/20
   accuracy: 0.5594 - val loss: 1.4566 - val accuracy: 0.4946
   1250/1250 [============= ] - 5s 4ms/step - loss: 1.2054 -
   accuracy: 0.5758 - val_loss: 1.5066 - val_accuracy: 0.4882
   Epoch 9/20
   1250/1250 [============== ] - 5s 4ms/step - loss: 1.1631 -
   accuracy: 0.5897 - val_loss: 1.5076 - val_accuracy: 0.4899
   Epoch 10/20
   1250/1250 [============= ] - 5s 4ms/step - loss: 1.1277 -
   accuracy: 0.6027 - val_loss: 1.4855 - val_accuracy: 0.4925
   Epoch 11/20
   1250/1250 [============ ] - 5s 4ms/step - loss: 1.0932 -
```

accuracy: 0.6122 - val\_loss: 1.5063 - val\_accuracy: 0.4946

```
Epoch 12/20
accuracy: 0.6261 - val_loss: 1.5737 - val_accuracy: 0.4999
Epoch 13/20
1250/1250 [============== ] - 5s 4ms/step - loss: 1.0274 -
accuracy: 0.6387 - val_loss: 1.5459 - val_accuracy: 0.5010
Epoch 14/20
accuracy: 0.6471 - val_loss: 1.5513 - val_accuracy: 0.5032
Epoch 15/20
1250/1250 [============== ] - 4s 4ms/step - loss: 0.9735 -
accuracy: 0.6535 - val_loss: 1.5673 - val_accuracy: 0.5007
Epoch 16/20
accuracy: 0.6658 - val_loss: 1.6597 - val_accuracy: 0.4894
Epoch 17/20
1250/1250 [============= ] - 5s 4ms/step - loss: 0.9196 -
accuracy: 0.6756 - val_loss: 1.6429 - val_accuracy: 0.4854
Epoch 18/20
accuracy: 0.6824 - val_loss: 1.6633 - val_accuracy: 0.4903
Epoch 19/20
accuracy: 0.6888 - val_loss: 1.7110 - val_accuracy: 0.4946
Epoch 20/20
accuracy: 0.6997 - val_loss: 1.7527 - val_accuracy: 0.4838
accuracy: 0.4821
Test Loss: 1.7657122611999512
Test Accuracy: 0.4821000099182129
```

## 2.0.7 Plot the training curves as described below

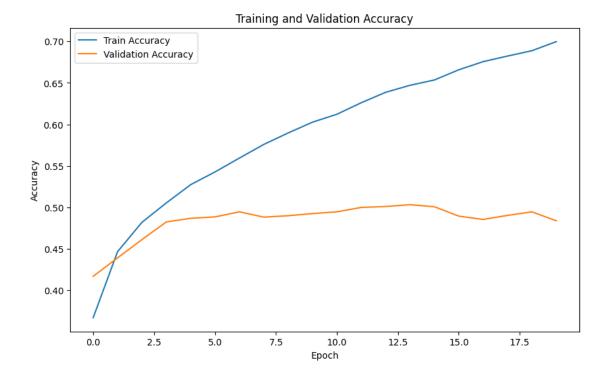
# 2.7.1 Display the train vs validation loss over each epoch

```
[]: #Your code here
plt.figure(figsize=(10, 6))
plt.plot(history.history['loss'], label='Train Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title('Training and Validation Loss')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.legend()
plt.show()
```



# 2.7.2 Display the train vs validation accuracy over each epoch

```
[]: #Your code here
plt.figure(figsize=(10, 6))
plt.plot(history.history['accuracy'], label='Train Accuracy')
plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
plt.title('Training and Validation Accuracy')
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.legend()
plt.show()
```



# 2.0.8 2.8 Finally, report the metric chosen on test set

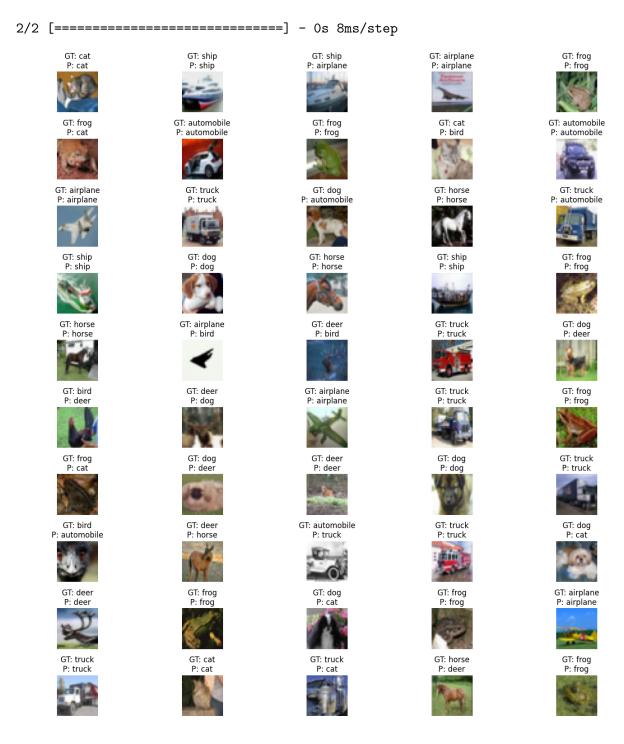
```
[]: #Your code here print("Test Accuracy:", test_accuracy)
```

Test Accuracy: 0.4821000099182129

2.0.9 2.9 Plot the first 50 samples of test dataset on a 10\*5 subplot and this time label the images with both the ground truth (GT) and predicted class (P). (Make sure you predict the class with the improved model)

```
[]: #Your code here
predictions = model.predict(x_test_scaled[:50])
predicted_classes = np.argmax(predictions, axis=1)

plt.figure(figsize=(15, 15))
for i in range(50):
    plt.subplot(10, 5, i + 1)
    plt.imshow(x_test[i])
    plt.title(f"GT: {LABELS[y_test[i][0]]}\nP: {LABELS[predicted_classes[i]]}")
    plt.axis('off')
plt.tight_layout()
plt.show()
```



# 3 Part 3 - Convolutional Neural Networks

In this part of the homework, we will build and train a classical convolutional neural network on the CIFAR Dataset

```
[1]: from tensorflow.keras.models import Sequential
    from tensorflow.keras.layers import Dense, Conv2D, MaxPool2D, Flatten
    import pandas as pd
    from tensorflow.keras.utils import to_categorical
    from tensorflow.keras.datasets import cifar10
[2]: #Code to load the dataset - Do not change
     (x_dev, y_dev), (x_test, y_test) = cifar10.load_data()
    print("x dev: {},y_dev: {},x_test: {},y_test: {}".format(x_dev.shape, y_dev.
      ⇒shape, x_test.shape, y_test.shape))
    x_dev, x_test = x_dev.astype('float32'), x_test.astype('float32')
    x dev = x dev/255.0
    x_test = x_test/255.0
    from sklearn.model selection import train test split
    X train, X val, y train, y val = train_test_split(x dev, y dev, test_size = 0.2, 
      →random_state = 42)
    Downloading data from https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz
    170498071/170498071 [============] - 7s Ous/step
    x_dev: (50000, 32, 32, 3),y_dev: (50000, 1),x_test: (10000, 32, 32, 3),y_test:
    (10000, 1)
[3]: # OHE the labels for y
    y_train = to_categorical(y_train, num_classes=10)
    y_val = to_categorical(y_val, num_classes=10)
    y_test = to_categorical(y_test, num_classes=10)
[4]: print("Shape of X_train:", X_train.shape)
    print("Shape of X_val:", X_val.shape)
    print("Shape of x_test:", x_test.shape)
    Shape of X_train: (40000, 32, 32, 3)
    Shape of X_val: (10000, 32, 32, 3)
    Shape of x_test: (10000, 32, 32, 3)
[5]: print("Shape of y_train:", y_train.shape)
    print("Shape of y_val:", y_val.shape)
    print("Shape of y_test:", y_test.shape)
    Shape of y_train: (40000, 10)
    Shape of y_val: (10000, 10)
    Shape of y_test: (10000, 10)
```

# 3.0.1 3.1 We will be implementing one of the first CNN models put forward by Yann LeCunn, which is commonly referred to as LeNet-5. The network has the following layers:

- 1) 2D convolutional layer with 6 filters, 5x5 kernel, stride of 1, 0 padding, ReLU activation
- 2) Maxpooling layer of 2x2
- 3) 2D convolutional layer with 16 filters, 5x5 kernel, stride of 1, 0 padding, ReLU activation
- 4) Maxpooling layer of 2x2
- 5) Flatten the convolution output to feed it into fully connected layers
- 6) A fully connected layer with 120 units, ReLU activation
- 7) A fully connected layer with 84 units, ReLU activation
- 8) The output layer where each unit respresents the probability of image being in that category. What activation function should you use in this layer? (You should know this)

```
[6]: #Your code here
     num_classes=10
     cnn = Sequential()
     #1
     cnn.add(Conv2D(6, kernel_size=(5, 5), strides=(1, 1), padding='valid', __
      →activation='relu', input_shape=(32, 32, 3)))
     # 2
     cnn.add(MaxPool2D(pool_size=(2, 2)))
     # 3
     cnn.add(Conv2D(16, kernel_size=(5, 5), strides=(1, 1), padding='valid', __
      ⇔activation='relu'))
     # 4
     cnn.add(MaxPool2D(pool_size=(2, 2)))
     # 5
     cnn.add(Flatten())
     # 6
     cnn.add(Dense(120, activation='relu'))
     cnn.add(Dense(84, activation='relu'))
     cnn.add(Dense(10, activation='softmax'))
```

```
cnn.compile(optimizer='adam', loss='categorical_crossentropy', u ometrics=['accuracy'])
```

# 3.0.2 3.2 Report the model summary

[7]: #Your code here cnn.summary()

Model: "sequential"

Layer (type)	1 1	Param #
conv2d (Conv2D)		456
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 14, 14, 6)	0
conv2d_1 (Conv2D)	(None, 10, 10, 16)	2416
<pre>max_pooling2d_1 (MaxPoolin g2D)</pre>	(None, 5, 5, 16)	0
flatten (Flatten)	(None, 400)	0
dense (Dense)	(None, 120)	48120
dense_1 (Dense)	(None, 84)	10164
dense_2 (Dense)	(None, 10)	850

Total params: 62006 (242.21 KB)
Trainable params: 62006 (242.21 KB)
Non-trainable params: 0 (0.00 Byte)

-----

## 3.0.3 3.3 Model Training

- 1) Train the model for 20 epochs. In each epoch, record the loss and metric (chosen in part 3) scores for both train and validation sets.
- 2) Plot separate plots for:
- displaying train vs validation loss over each epoch
- displaying train vs validation accuracy over each epoch
- 3) Report the model performance on the test set. Feel free to tune the hyperparameters such as batch size and optimizers to achieve better performance.

# [8]: #Your code here history = cnn.fit(X\_train, y\_train, epochs=20, validation\_data=(X\_val, y\_val)) Epoch 1/20 1250/1250 [============= ] - 17s 8ms/step - loss: 1.6520 accuracy: 0.3947 - val\_loss: 1.4595 - val\_accuracy: 0.4588 Epoch 2/20 accuracy: 0.5061 - val\_loss: 1.3515 - val\_accuracy: 0.5101 Epoch 3/20 1250/1250 [============= ] - 13s 11ms/step - loss: 1.2607 accuracy: 0.5462 - val\_loss: 1.2648 - val\_accuracy: 0.5535 Epoch 4/20 accuracy: 0.5770 - val\_loss: 1.2442 - val\_accuracy: 0.5554 Epoch 5/20 accuracy: 0.6039 - val\_loss: 1.2069 - val\_accuracy: 0.5725 Epoch 6/20 accuracy: 0.6223 - val\_loss: 1.2499 - val\_accuracy: 0.5701 Epoch 7/20 accuracy: 0.6383 - val\_loss: 1.1208 - val\_accuracy: 0.6090 Epoch 8/20 accuracy: 0.6552 - val\_loss: 1.1342 - val\_accuracy: 0.6030 Epoch 9/20 accuracy: 0.6714 - val\_loss: 1.1517 - val\_accuracy: 0.6099 accuracy: 0.6832 - val\_loss: 1.1419 - val\_accuracy: 0.6163 Epoch 11/20

```
1250/1250 [============== ] - 11s 9ms/step - loss: 0.8574 -
accuracy: 0.6977 - val_loss: 1.1363 - val_accuracy: 0.6141
Epoch 12/20
accuracy: 0.7082 - val_loss: 1.1504 - val_accuracy: 0.6144
Epoch 13/20
accuracy: 0.7196 - val_loss: 1.1537 - val_accuracy: 0.6196
Epoch 14/20
accuracy: 0.7306 - val_loss: 1.2035 - val_accuracy: 0.6138
Epoch 15/20
```

```
accuracy: 0.7389 - val_loss: 1.2005 - val_accuracy: 0.6164
    Epoch 16/20
    1250/1250 [============= ] - 10s 8ms/step - loss: 0.7094 -
    accuracy: 0.7494 - val_loss: 1.2299 - val_accuracy: 0.6132
    Epoch 17/20
    1250/1250 [============== ] - 10s 8ms/step - loss: 0.6804 -
    accuracy: 0.7567 - val_loss: 1.2469 - val_accuracy: 0.6104
    Epoch 18/20
    accuracy: 0.7667 - val_loss: 1.3132 - val_accuracy: 0.6078
    Epoch 19/20
    accuracy: 0.7735 - val_loss: 1.2992 - val_accuracy: 0.6099
    1250/1250 [============= ] - 8s 6ms/step - loss: 0.6151 -
    accuracy: 0.7803 - val_loss: 1.3588 - val_accuracy: 0.6026
[12]: #Your code here
    # train vs. valid loss
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.plot(history.history['loss'], label='Train Loss')
    plt.plot(history.history['val_loss'], label='Validation Loss')
    plt.title('Training and Validation Loss')
    plt.xlabel('Epoch')
    plt.ylabel('Loss')
    plt.legend()
    # train vs. valid accuracy
    plt.subplot(1, 2, 2)
    plt.plot(history.history['accuracy'], label='Train Accuracy')
    plt.plot(history.history['val_accuracy'], label='Validation Accuracy')
    plt.title('Training and Validation Accuracy')
    plt.xlabel('Epoch')
    plt.ylabel('Accuracy')
    plt.legend()
    plt.tight_layout()
    plt.show()
```



accuracy: 0.5915 Test Loss: 1.4128663539886475

Test Accuracy: 0.5914999842643738

#### **3.0.4 3.4** Overfitting

1) To overcome overfitting, we will train the network again with dropout this time. For hidden layers use dropout probability of 0.3. Train the model again for 20 epochs. Report model performance on test set.

Plot separate plots for:

- displaying train vs validation loss over each epoch
- displaying train vs validation accuracy over each epoch
- 2) This time, let's apply a batch normalization after every hidden layer, train the model for 20 epochs, report model performance on test set as above.

Plot separate plots for:

• displaying train vs validation loss over each epoch

- displaying train vs validation accuracy over each epoch
- 3) Compare batch normalization technique with the original model and with dropout, which technique do you think helps with overfitting better?

[14]: from tensorflow.keras.layers import Dropout, BatchNormalization, MaxPooling2D

## 3.4.1 Dropout

```
[15]: #Your code here
      cnn_dropout = Sequential([
          Conv2D(32, (3, 3), activation='relu', input_shape=(32, 32, 3)),
          MaxPooling2D((2, 2)),
          Conv2D(64, (3, 3), activation='relu'),
          MaxPooling2D((2, 2)),
          Conv2D(64, (3, 3), activation='relu'),
          Flatten(),
          Dropout(0.3),
          Dense(64, activation='relu'),
          Dense(10, activation='softmax')
      ])
      cnn_dropout.compile(optimizer='adam',
                            loss='categorical_crossentropy',
                            metrics=['accuracy'])
      cnn_dropout.summary()
```

Model: "sequential\_1"

Layer (type)	Output Shape	Param #
conv2d_2 (Conv2D)	(None, 30, 30, 32)	896
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 15, 15, 32)	0
conv2d_3 (Conv2D)	(None, 13, 13, 64)	18496
<pre>max_pooling2d_3 (MaxPoolin g2D)</pre>	(None, 6, 6, 64)	0
conv2d_4 (Conv2D)	(None, 4, 4, 64)	36928
flatten_1 (Flatten)	(None, 1024)	0
dropout (Dropout)	(None, 1024)	0
dense_3 (Dense)	(None, 64)	65600

\_\_\_\_\_\_

Total params: 122570 (478.79 KB)
Trainable params: 122570 (478.79 KB)
Non-trainable params: 0 (0.00 Byte)

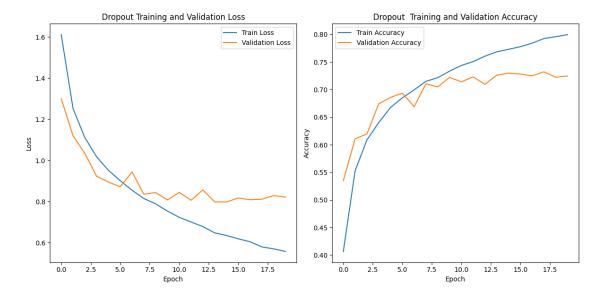
\_\_\_\_\_\_

```
Epoch 1/20
accuracy: 0.4065 - val_loss: 1.2999 - val_accuracy: 0.5349
Epoch 2/20
accuracy: 0.5529 - val_loss: 1.1198 - val_accuracy: 0.6108
Epoch 3/20
accuracy: 0.6087 - val_loss: 1.0343 - val_accuracy: 0.6196
Epoch 4/20
accuracy: 0.6402 - val_loss: 0.9230 - val_accuracy: 0.6742
Epoch 5/20
accuracy: 0.6675 - val_loss: 0.8948 - val_accuracy: 0.6859
Epoch 6/20
accuracy: 0.6851 - val_loss: 0.8718 - val_accuracy: 0.6935
Epoch 7/20
accuracy: 0.6995 - val_loss: 0.9440 - val_accuracy: 0.6690
Epoch 8/20
accuracy: 0.7149 - val_loss: 0.8357 - val_accuracy: 0.7105
Epoch 9/20
accuracy: 0.7215 - val_loss: 0.8435 - val_accuracy: 0.7049
1250/1250 [============= ] - 11s 9ms/step - loss: 0.7536 -
accuracy: 0.7335 - val_loss: 0.8077 - val_accuracy: 0.7220
Epoch 11/20
accuracy: 0.7437 - val_loss: 0.8444 - val_accuracy: 0.7141
Epoch 12/20
1250/1250 [============== ] - 9s 7ms/step - loss: 0.7007 -
accuracy: 0.7506 - val_loss: 0.8064 - val_accuracy: 0.7230
```

```
accuracy: 0.7606 - val_loss: 0.8566 - val_accuracy: 0.7096
   accuracy: 0.7684 - val_loss: 0.7984 - val_accuracy: 0.7261
   1250/1250 [=============== ] - 10s 8ms/step - loss: 0.6350 -
   accuracy: 0.7730 - val_loss: 0.7976 - val_accuracy: 0.7297
   Epoch 16/20
   accuracy: 0.7778 - val_loss: 0.8173 - val_accuracy: 0.7282
   Epoch 17/20
   accuracy: 0.7841 - val_loss: 0.8087 - val_accuracy: 0.7249
   Epoch 18/20
   1250/1250 [============= ] - 9s 7ms/step - loss: 0.5794 -
   accuracy: 0.7925 - val_loss: 0.8113 - val_accuracy: 0.7322
   Epoch 19/20
   accuracy: 0.7959 - val_loss: 0.8292 - val_accuracy: 0.7223
   Epoch 20/20
   accuracy: 0.7996 - val_loss: 0.8214 - val_accuracy: 0.7246
[17]: #Your code here
    # train vs val loss
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.plot(dropout_history.history['loss'], label='Train Loss')
    plt.plot(dropout_history.history['val_loss'], label='Validation Loss')
    plt.title('Dropout Training and Validation Loss')
    plt.xlabel('Epoch')
    plt.ylabel('Loss')
    plt.legend()
    # train vs val accuracy
    plt.subplot(1, 2, 2)
    plt.plot(dropout_history.history['accuracy'], label='Train Accuracy')
    plt.plot(dropout_history.history['val_accuracy'], label='Validation Accuracy')
    plt.title('Dropout Training and Validation Accuracy')
    plt.xlabel('Epoch')
    plt.ylabel('Accuracy')
    plt.legend()
    plt.tight_layout()
```

Epoch 13/20

# plt.show()



```
[21]: #Your code here
  test_loss, test_accuracy = cnn_dropout.evaluate(x_test, y_test)
  print("Test Loss:", test_loss)
  print("Test Accuracy:", test_accuracy)
```

accuracy: 0.7254

Test Loss: 0.823741614818573 Test Accuracy: 0.7253999710083008

## 3.4.2 Batch Normalization

Model: "sequential\_2"

Layer (type)	Output Shape	Param #
	(None, 30, 30, 32)	
<pre>batch_normalization (Batch Normalization)</pre>	(None, 30, 30, 32)	128
<pre>max_pooling2d_4 (MaxPoolin g2D)</pre>	(None, 15, 15, 32)	0
conv2d_6 (Conv2D)	(None, 13, 13, 64)	18496
<pre>batch_normalization_1 (Bat chNormalization)</pre>	(None, 13, 13, 64)	256
<pre>max_pooling2d_5 (MaxPoolin g2D)</pre>	(None, 6, 6, 64)	0
conv2d_7 (Conv2D)	(None, 4, 4, 64)	36928
<pre>batch_normalization_2 (Bat chNormalization)</pre>	(None, 4, 4, 64)	256
flatten_2 (Flatten)	(None, 1024)	0
dense_5 (Dense)	(None, 64)	65600
<pre>batch_normalization_3 (Bat chNormalization)</pre>	(None, 64)	256
dense_6 (Dense)	(None, 10)	650

Total params: 123466 (482.29 KB)
Trainable params: 123018 (480.54 KB)
Non-trainable params: 448 (1.75 KB)

\_\_\_\_\_

```
Epoch 1/20
accuracy: 0.5096 - val_loss: 1.7182 - val_accuracy: 0.4506
Epoch 2/20
accuracy: 0.6414 - val_loss: 1.1658 - val_accuracy: 0.5826
Epoch 3/20
1250/1250 [============== ] - 14s 11ms/step - loss: 0.8622 -
accuracy: 0.6986 - val_loss: 1.1748 - val_accuracy: 0.5976
Epoch 4/20
1250/1250 [============= ] - 13s 11ms/step - loss: 0.7618 -
accuracy: 0.7347 - val_loss: 0.9241 - val_accuracy: 0.6810
Epoch 5/20
accuracy: 0.7643 - val_loss: 0.9059 - val_accuracy: 0.6902
Epoch 6/20
accuracy: 0.7848 - val_loss: 1.2568 - val_accuracy: 0.6013
Epoch 7/20
accuracy: 0.8081 - val_loss: 1.0013 - val_accuracy: 0.6878
Epoch 8/20
accuracy: 0.8262 - val_loss: 0.9570 - val_accuracy: 0.7023
Epoch 9/20
accuracy: 0.8415 - val_loss: 0.9753 - val_accuracy: 0.6976
Epoch 10/20
1250/1250 [============= ] - 14s 11ms/step - loss: 0.4020 -
accuracy: 0.8575 - val_loss: 0.9361 - val_accuracy: 0.7110
Epoch 11/20
accuracy: 0.8718 - val_loss: 1.0653 - val_accuracy: 0.6949
Epoch 12/20
1250/1250 [============= ] - 15s 12ms/step - loss: 0.3351 -
accuracy: 0.8802 - val_loss: 1.1558 - val_accuracy: 0.6803
Epoch 13/20
accuracy: 0.8896 - val_loss: 1.0328 - val_accuracy: 0.7127
Epoch 14/20
accuracy: 0.9019 - val_loss: 1.2350 - val_accuracy: 0.6937
```

```
Epoch 15/20
    accuracy: 0.9081 - val_loss: 1.2298 - val_accuracy: 0.6899
    accuracy: 0.9158 - val_loss: 1.2827 - val_accuracy: 0.6875
    accuracy: 0.9190 - val_loss: 1.1549 - val_accuracy: 0.7093
    Epoch 18/20
    1250/1250 [============= ] - 13s 11ms/step - loss: 0.2141 -
    accuracy: 0.9230 - val_loss: 1.4285 - val_accuracy: 0.6658
    Epoch 19/20
    accuracy: 0.9302 - val_loss: 1.3459 - val_accuracy: 0.6849
    Epoch 20/20
    accuracy: 0.9352 - val_loss: 1.3568 - val_accuracy: 0.6940
[20]: #Your code here
    # train vs val loss
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.plot(bn_history.history['loss'], label='Train Loss')
    plt.plot(bn_history.history['val_loss'], label='Validation Loss')
    plt.title('Batch Norm Training and Validation Loss')
    plt.xlabel('Epoch')
    plt.ylabel('Loss')
    plt.legend()
    # train vs val accuracy
    plt.subplot(1, 2, 2)
    plt.plot(bn_history.history['accuracy'], label='Train Accuracy')
    plt.plot(bn_history.history['val_accuracy'], label='Validation Accuracy')
    plt.title('Batch Norm Training and Validation Accuracy')
    plt.xlabel('Epoch')
    plt.ylabel('Accuracy')
    plt.legend()
    plt.tight_layout()
    plt.show()
```



```
[22]: test_loss, test_accuracy = cnn_bn.evaluate(x_test, y_test)

print("Test Loss:", test_loss)
print("Test Accuracy:", test_accuracy)
```

accuracy: 0.6933

Test Loss: 1.358229637145996

Test Accuracy: 0.6933000087738037

**Dropout Model:** - Dropout regularization seems to be the most effective in reducing overfitting, as indicated by the higher test accuracy and lower test loss compared to the original model.

Batch Normalization Model: - While batch normalization helps to some extent, it does not perform as well as dropout in mitigating overfitting, as the test accuracy is lower compared to the dropout model.

SO for me Droput performed better than Batch Normalization.

[]: