

# Team Member Contribution Document

Aqsa:

1. Proposal, Progress Report/Presentation, Final Report/Presentation, Demo Video
2. Implementation of the environment
3. Implementation of Task Planning PDDL algorithm

Kousar:

4. Proposal, Progress Report/Presentation, Final Report/Presentation, Demo Video
5. Implementation of Task Planning PDDL algorithm
6. Compute joint configurations for accurate manipulation

Kerem:

7. Proposal, Progress Report/Presentation, Final Report/Presentation, Demo Video
8. Motion Planning Based C++ Algorithms: Bi-RRT\*, RRT\*, and PSBi-RRT
9. Python interface for C++ algorithms implemented