

ARTIFICIAL INTELLIGENCE

UNIVERSITY OF RENNES 1

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Backpropagation Let us consider the neural network on Figure 1.

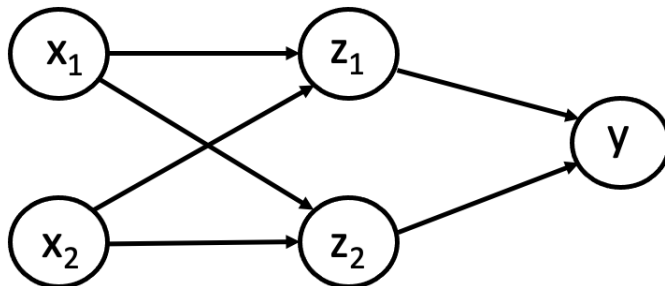


Figure 1: Neural network

In this example we try to understand using a simple numerical example, how the gradient descent algorithm works in the context of neural networks and how the network itself can compute iteratively the derivatives of the cost function.

- Let us assume that our training set contains a single example, with input $x_1 = 2$, $x_2 = 3$ and output $y = 1$. For simplicity, let us assume that the activation function is the linear function.
- Let us initialize the weights θ of the network as follows:
 $\theta_{01}^1 = 0$, $\theta_{11}^1 = 0.11$, $\theta_{21}^1 = 0.21$, $\theta_{12}^1 = 0.12$, $\theta_{22}^1 = 0.08$,
 $\theta_{01}^2 = 0$, $\theta_{11}^2 = 0.14$, $\theta_{21}^2 = 0.15$
- Compute the output of the network on the training set. Also, express the predicted value (the output of the network) as a single formula of the input and weights.
- Let us assume that we use the following loss function: $J(\theta) = \frac{1}{2}(y_{\text{predicted}} - y_{\text{traininig}})^2$
- Let us assume that the learning rate $\alpha = 0.05$ and we realize a gradient descent algorithm to learn the weights of the network. Let us now try to understand the update of the weight θ_{21}^2 , in the first iteration of the algorithm. Recall, that we compute it as

$$\theta_{21}^2 \leftarrow \theta_{21}^2 - \alpha \frac{\partial J(\theta)}{\partial \theta_{21}^2}$$

Compute the partial derivative $\frac{\partial J(\theta)}{\partial \theta_{21}^2}$ using the expression (question above)

- Let $\Delta = y_{predicted} - y_{traininig}$. Express the partial derivative $\frac{\partial J(\theta)}{\partial \theta_{21}^2}$ now using Δ and the value of z_2 (that we can remember if we do a forward calculation, with the training input)
- Compute also the partial derivative $\frac{\partial J(\theta)}{\partial \theta_{11}^2}$.
- Compute now the partial derivative $\frac{\partial J(\theta)}{\partial \theta_{11}^1}$ (that is, let us try to understand how the error function depends on a weight that is between a node in the input layer and another node in the hidden layer).
- Express the updates of θ_{11}^1 in the gradient descent, with the help of θ_{11}^2 and Δ .
- Express the updates of the other weights (between the input and hidden layer) in the same way.
- Explain how can we realize an iteration of the gradient descent through forward and backward computation in a neural network.