

Score-Based Generative Modeling through Stochastic Differential Equations

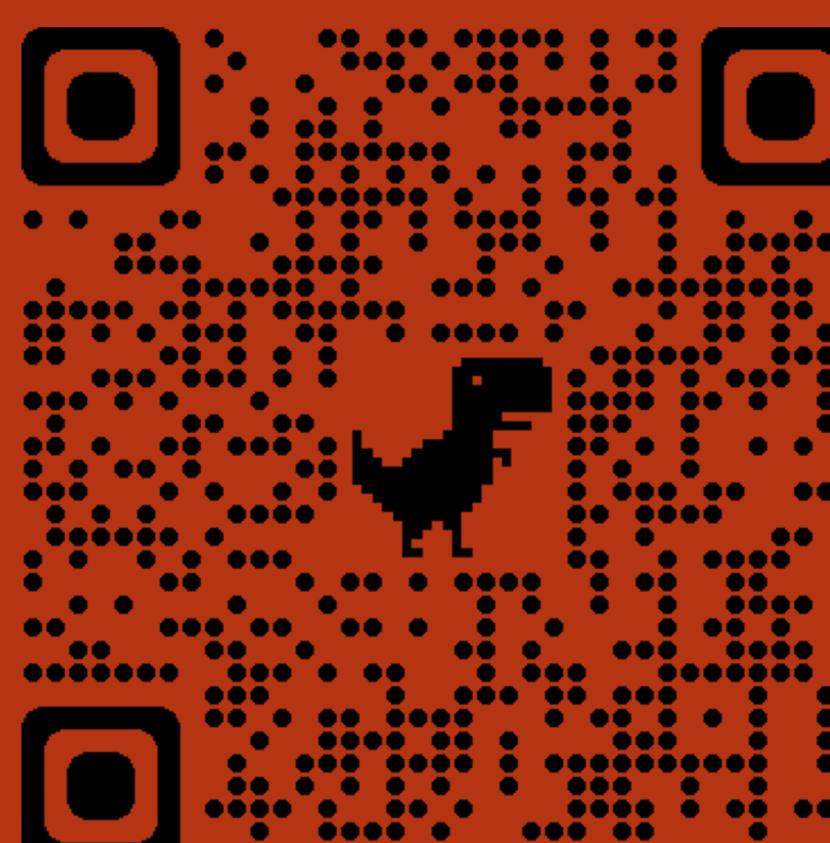
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ABSTRACT

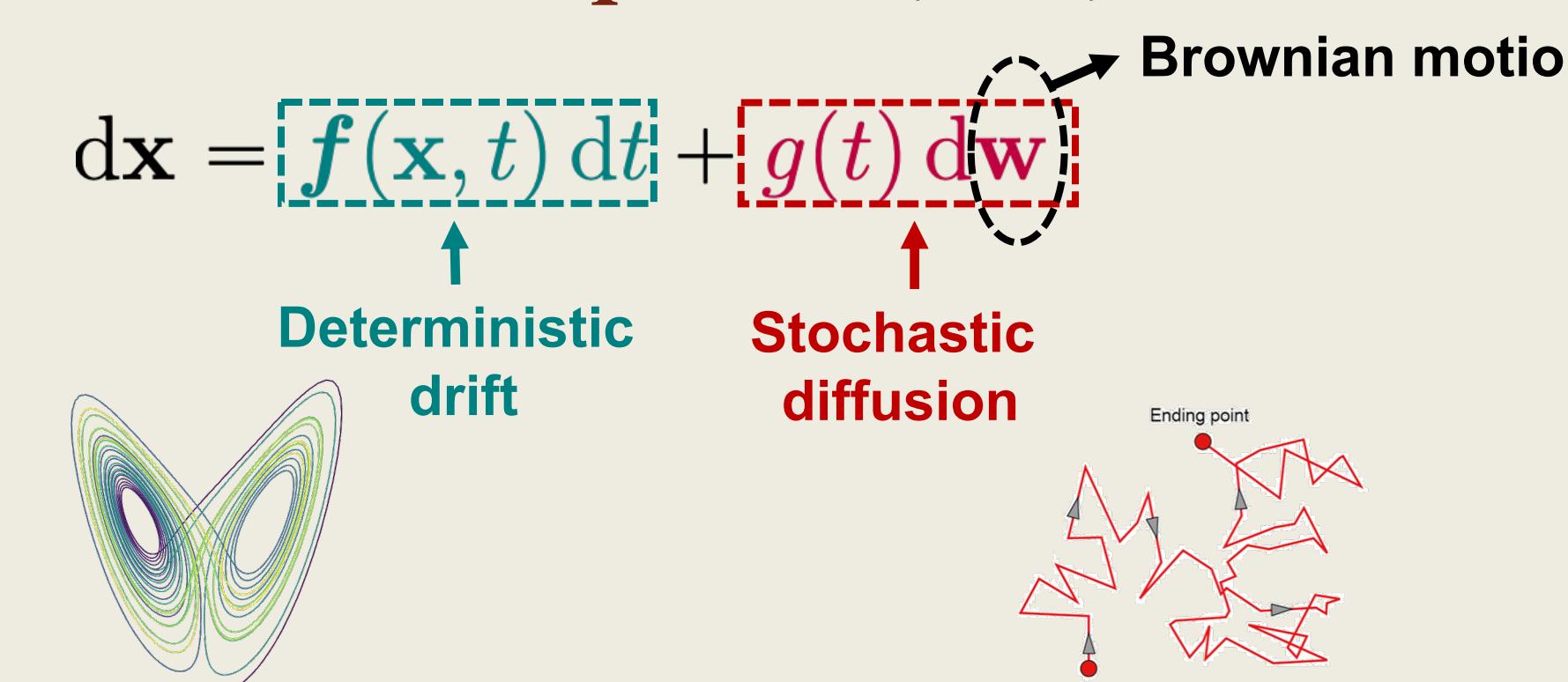
- We perturb data to noise with a fixed stochastic differential equation (SDE), and learn to reverse it for sample generation. The reverse SDE can be obtained by estimating the time-dependent gradient field (aka. score function) of the perturbed data distribution.
- We achieve outstanding sample quality: state-of-the-art FID and Inception scores on CIFAR-10, high fidelity generation of 1024x1024 images.
- The SDE framework allows exact likelihood computation. We obtain the state-of-the-art likelihood on uniformly dequantized CIFAR-10 images, without maximum likelihood training.
- We can perform controllable generation without re-training models, and demonstrate applications in class-conditional generation, image inpainting and colorization.

Code:

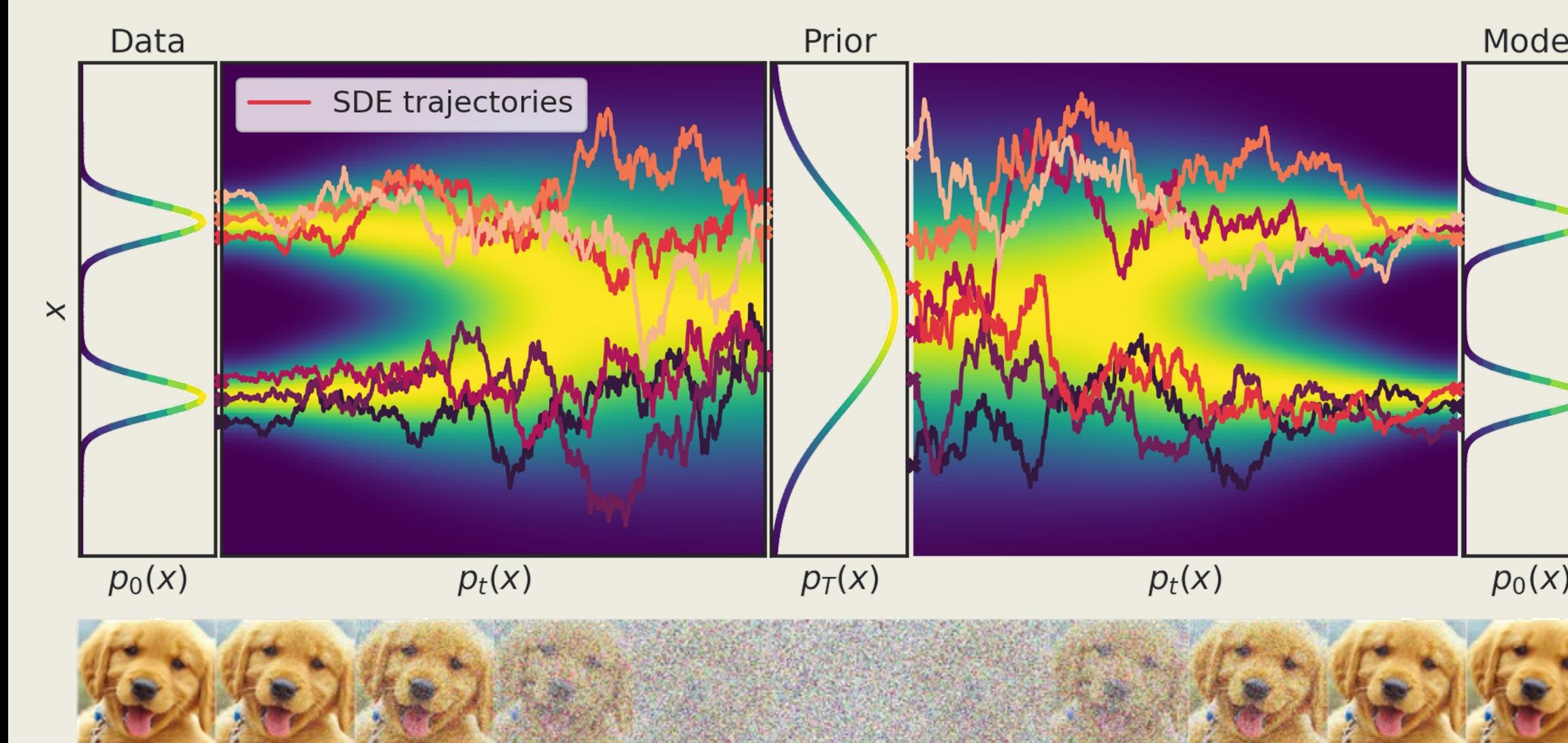


Generative Modeling with SDEs

Stochastic differential equation (SDE):



Perturbing data with a fixed SDE, and reverse it for generative modeling



The reverse-time SDE:

$$dx = [f(x, t) - g^2(t) \nabla_x \log p_t(x)] dt + g(t) dw$$

Score function of $p_t(x)$

- Must be solved in the reverse time direction
- Requires estimating score functions at all time steps.

Learning to reverse the SDE:

- Time-dependent score-based model

$$s_{\theta}(\cdot, t) : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

- Goal:

$$s_{\theta*}(x, t) \approx \nabla_x \log p_t(x)$$

- Training objective:

$$\min_{\theta} \mathbb{E}_{t \sim U(0,T)} \mathbb{E}_{x \sim p_t(x)} [\lambda(t) \| s_{\theta}(x, t) - \nabla_x \log p_t(x) \|_2^2]$$

- Score matching (Hyvärinen 2005)

- Denoising score matching (Vincent 2010)
- Sliced score matching (Song et al., 2019)

Estimated reverse-time SDE

$$dx = [f(x, t) - g^2(t) s_{\theta*}(x, t)] dt + g(t) dw$$

Solving Reverse SDEs for Sampling

Numerical SDE solvers:

- Example: Euler-Maruyama method

$$\begin{aligned} &\text{Initialize } t = T, \quad x \sim p_T(x) \\ &\text{Repeat until } t = 0 \quad \left\{ \begin{array}{l} \Delta x \leftarrow [f(x, t) - g^2(t) s_{\theta*}(x, t)] \Delta t + g(t) z \\ x \leftarrow x + \Delta x \\ t \leftarrow t + \Delta t \end{array} \right. \quad z \sim \mathcal{N}(0, |\Delta t| I) \end{aligned}$$

- Example: Reverse diffusion method (see paper)

Predictor-Corrector methods:

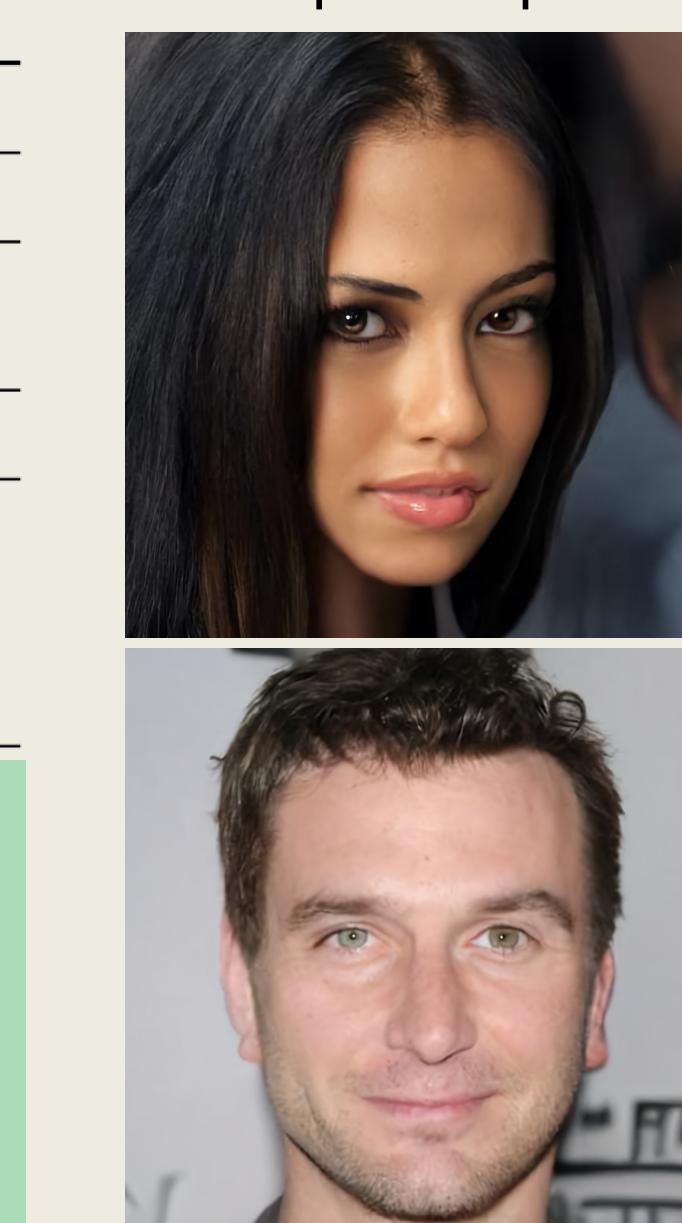
- Improves numerical SDE solvers with MCMC, at the cost of more computation and more hyperparameters.

Experimental results:

CIFAR-10 sample quality

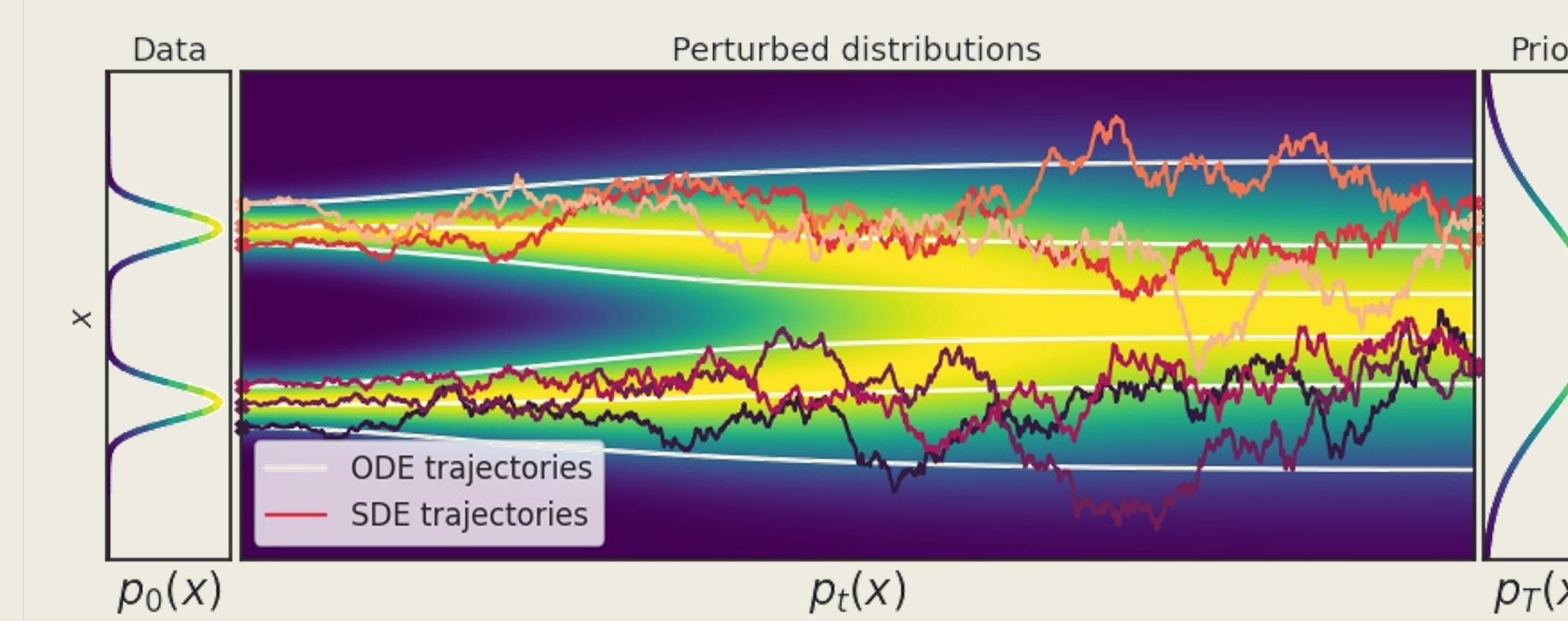
Model	FID↓	IS↑
Conditional		
BigGAN (Brock et al., 2018)	14.73	9.22
StyleGAN2-ADA (Karras et al., 2020a)	2.42	10.14
Unconditional		
StyleGAN2-ADA (Karras et al., 2020a)	2.92	9.83
NCSN (Song & Ermon, 2019)	25.32	8.87 ± .12
NCSNv2 (Song & Ermon, 2020)	10.87	8.40 ± .07
DDPM (Ho et al., 2020)	3.17	9.46 ± .11
DDPM++		
DDPM++	2.78	9.64
DDPM++ cont. (VP)	2.55	9.58
DDPM++ cont. (sub-VP)	2.61	9.56
DDPM++ cont. (deep, VP)	2.41	9.68
DDPM++ cont. (deep, sub-VP)	2.41	9.57
NCSN++	2.45	9.73
NCSN++ cont. (VE)	2.38	9.83
NCSN++ cont. (deep, VE)	2.20	9.89

CelebA-HQ
1024px samples



Probability Flow ODEs

Turning the SDE into an ODE with the same $p_t(x)$



Probability flow ODE:

$$dx = \left[f(x, t) - \frac{1}{2} g^2(t) \nabla_x \log p_t(x) \right] dt$$

Score function of $p_t(x) \approx s_{\theta*}(x, t)$

Can sample from the same distribution by solving the ODE instead of the SDE.

Exact likelihood computation:

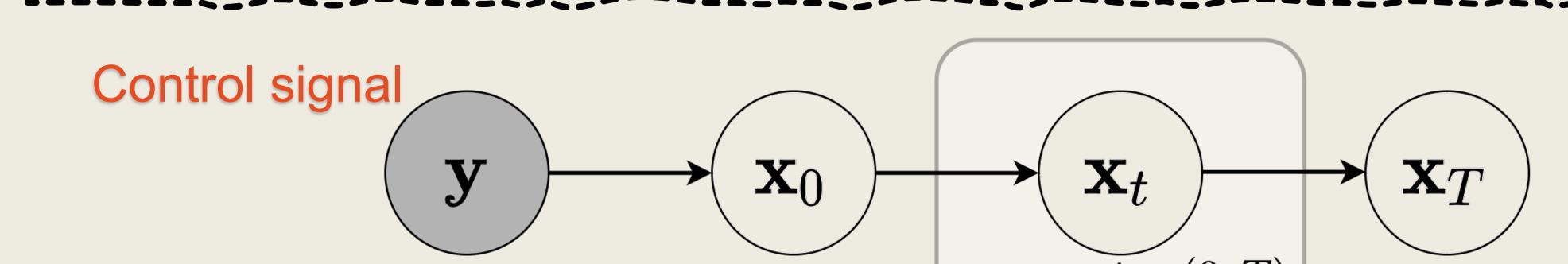
Model	NLL Test ↓	FID ↓
RealNVP (Dinh et al., 2016)	3.49	-
iResNet (Behrmann et al., 2019)	3.45	-
Glow (Kingma & Dhariwal, 2018)	3.35	-
MintNet (Song et al., 2019b)	3.32	-
Residual Flow (Chen et al., 2019)	3.28	46.37
FFJORD (Grathwohl et al., 2018)	3.40	-
Flow++ (Ho et al., 2019)	3.29	-
DDPM (L) (Ho et al., 2020)	≤ 3.70*	13.51
DDPM (L_{simple}) (Ho et al., 2020)	≤ 3.75*	3.17
DDPM	3.28	3.37
DDPM cont. (VP)	3.21	3.69
DDPM cont. (sub-VP)	3.05	3.56
DDPM++ cont. (VP)	3.16	3.93
DDPM++ cont. (sub-VP)	3.02	3.16
DDPM++ cont. (deep, VP)	3.13	3.08
DDPM++ cont. (deep, sub-VP)	2.99	2.92

Instantaneous change-of-variable formula (Chen et al. 2018)

$$\log p_T(z) \int \log p_0(x) dx$$

Controllable Generation

We can perform conditional generation with an unconditional score-based model. No need of re-training.



Reverse for controllable generation

$$\nabla_x \log p_t(x | y) = \nabla_x \log p_t(x) + \nabla_x \log p_t(y | x)$$

unconditional score, Trained w/o y
specified with domain knowledge

Image inpainting and colorization results:

