Documentation for NAO full control using Kinect and video display.

# Overview

## Scenario

### **Go way**

Main application: Main control and switcher.

Kinect Catcher: Catch Kinect Joints and face rotation

NAO.NET get position and move NAO to the current Values

### Back way

NAO.NET back values to Controller Windows Application

Return current video position to windows

Display video to android device.

More About NAO-Kinect:

GitHub:

<http://www.GitHub.com/ArabicRobotics>

Contact us :

<http://www.ArabicRobotics.com>