21 March 2018 End of last lecture described a procedure for deciding it on n-bit number is composite, not for factoring it. Search problems (finding a solution) can in general be to refler than decision problems (does a solution exist?). CIRCUIT SAT (in its decision vusion) can be used to solve search problems because CIRCUIT SAT is "self-reducible": deciding whether there exists a satisfying with certain variables having "hard-whed" truth values reduces to another CIRCUIT SAT problem with a smaller # of variables. Satisfiable? Yes Satisfiable with X=0? $\begin{array}{c|c} \hline Sort, & with \\ \hline x_1 = 0 & 0.8 & x_2 = 0.7 \end{array}$ By following a single root-to-leaf path, we pose a sequence of n CIRCUIT-SAT questions and use their answers to find a satisfying assignment. Focus on decision problems from now on. Decision problem II is a mapping from input strings X To yes, no. The fallowing notations are equivalent: $TT(x) = yes = x \in TT = x is a yes' instance of TT$

An algorithm for TT is a procedure A such that A(x) = TT(x)A verifier for TT is a procedure V that takes two inputs: x,y. V XETT Jy V(x,y) = yes V X & TT Jy V(x,y) = yes Think of y as "evidence" that x is a 'yes' hostance of TI.

Verifi'er checks the evidence, and can't be fooled by a Wrong piece of evidence.

E.g. In a vertier for CNF-SAT, y is a truth assignment of the variables. V is an algorithm that plugs the truth assignment it of every clause and outputs 'yes'.

I always satisfied. Notation. IXI means # of Lits in the string X. Definition. A decision problem TT belongs to O If
there exists an algorithm A for TT that has
worst-case running time poly (IX) IT belongs to MP if there exists a verifier V for IT such that ly | \le poly (|x|) and running time of V is also poly (|x|). Clearly P = NP. Is P = NP? Not known. Definition. A poly-time Karp reduction from To to TT, is a poly-time only R transforming an input of TT, X, into an imput of TT, R(X), such that $\forall \times \pi_{s}(x) = \pi_{s}(R(x)),$ R is a way of solving To be rewriting the problem as an instance of T, and then solving T,.

If a poly-time reduction from To to T, exists, we write Tho Sp Th

