Aragya Goyal

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EDUCATION

University of Pittsburgh (Swanson School of Engineering)

Pittsburgh, PA

B.S. - Computer Engineering (Autonomous Systems Focus); GPA: 3.99

August 2022 - April 2026

Skills and Awards

• Languages: Python, C++, ARM Assembly

- Technologies: Linux, ROS, Github, Solidworks, MATLAB, Microsoft Products, Arduino, Raspberry Pi, OpenCV
- Manufacturing: Milling, Soldering, Laser Cutting, General Shop Tools
- General Awards: Dean's Honor List (2021-Present), Honor List (2021-Present), Eagle Scout
- Engineering Awards: FSAE Innovation Award, FIRST Chairman's, FIRST Excellence in Engineering, FIRST Industrial Design Award, VEX Judges Award

PROFESSIONAL EXPERIENCE

Carnegie Mellon University Robotics Institute (Biorobotics Lab)

Pittsburgh, PA

Undergraduate Research Intern (Part-Time)

April 2023 - Present

- o Underwater Snake Robot: (Link: http://tinyurl.com/humrsCMU)
 - * Implemented High-Frequency Injection methods in BLDC thrusters to achieve control at low/zero speeds.
 - * Working to implement station-keeping feature using AprilTags and IMU readings.
- $\circ \ \mathbf{Apple's} \ \mathbf{E\text{-}Waste} \ \mathbf{Recycling} \ \mathbf{Project} \colon (\mathrm{Link:} \ \mathrm{https://tinyurl.com/applecmu})$
 - st Created large datasets for Machine Learning Models to detect screws in e-waste images.
 - * Integrated ROS and Python packages to track ArucoTags using a Realsense camera for localization of robotic arm.
 - * Manufactured custom AprilTags using lasercutters and sheet metal manufacturing methods.

OTHER RELATED EXPERIENCE

Society of Astronautics and Rocketry Chief Engineer (Student Led Organization)

Pittsburgh, PA

August 2022 - Present

- Leading a group of approx. 30 students to design and fabricate a rover to participate in the University Rover Challenge. (Link: https://tinyurl.com/roverimages)
- $\circ\,$ Quickly established oneself as a valuable contributor to the team's efforts, taking on a lead role in the development of the robotic hand using pneumatic technology. (Link: https://tinyurl.com/hydraarm)

FIRST Robotics Exton, PA

Team Captain/Design Lead (Student Led Organization)

January 2020 - June 2022

- Led a team of 40 students and qualified for the Worlds level of competition, the highest win percentage since 2005, and a top 5% ranking globally. (Link: https://tinyurl.com/dewbot17)
- o Utilized Solidworks to design and develop competition and award-winning robots.

VEX Robotics Royersford, PA

Team Captain (Student Led Organization)

August 2018 - June 2022

- Organized VEX robotics competition event for 60+ teams, hosted workshops to teach CAD to fellow club members, and received recognition for outstanding leadership. (Link: https://bit.ly/3w7a6b1)
- Qualified for the State's level of competition for all 4 years of high school.

PROJECTS

- STM-32 Elevator Simulator (ARM Assembly, Project Integration): Designed and Implemented software architecture in ARM Assembly to operate a physical elevator simulator PCB. (Link: https://tinyurl.com/stmelevator)
- Custom Cane (Human Centered Design, Solidworks, Presentation): Designed and manufactured a Walker-Cane Fusion to make bathrooms more accessible for wheelchair users. The project won first place at the Senior Design Expo within its category. (Link: https://tinyurl.com/CustomCane)
- Formula SAE E-Brake Bias (Solidworks): Developed an award winning e-brake bias system for a formula style racecar, utilizing Solidworks and 3D printing technology to enhance performance and usability. (Link: https://tinyurl.com/ebrakeb)
- String Art Generator and Optimizer (Research, Python): Developed an innovative string art optimization tools and GUI using Python programming to improve upon existing string art generators. (Link: https://tinyurl.com/goyalstring)
- Silicon Prosthetic Hand (Research, Solidworks): Designed and Manufactured prototype prosthetic hand with silicone soft actuators and tested with human participants for AP Research Project. (Link: https://tinyurl.com/myprosthetic)
- Bird Sanctuary Restoration (Eagle Scout Project, Volunteering): Organized a project to restore parts of the Audubon Bird Sanctuary by painting fences, guardrails, and small buildings. (Link: https://tinyurl.com/goyaleagle)



Figure 1: Underwater Snake Robot

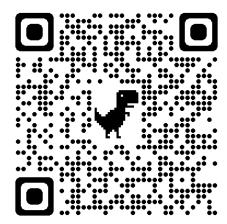


Figure 2: Apple Recycling Video



Figure 3: STM32 Elevator Simulator



Figure 4: Custom Cane



Figure 5: Dewbot XVII



Figure 6: VEX Robotics

CMU Research

Finished Projects