

# Aragya Goyal

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## EDUCATION

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- **University of Pittsburgh (Swanson School of Engineering)** **Pittsburgh, PA**  
*B.S. - Computer Engineering (Autonomous Systems Focus); GPA: 3.99*  
*August 2022 - April 2026*

## SKILLS AND AWARDS

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- **Languages:** Python, C++, ARM Assembly
  - **Technologies:** Linux, ROS, Github, Solidworks, MATLAB, Microsoft Products, Arduino, Raspberry Pi, OpenCV
  - **Manufacturing:** Milling, Soldering, Laser Cutting, General Shop Tools
  - **General Awards:** Dean's Honor List (2021-Present), Honor List (2021-Present), Eagle Scout
  - **Engineering Awards:** FSAE Innovation Award, FIRST Chairman's, FIRST Excellence in Engineering, FIRST Industrial Design Award, VEX Judges Award

## PROFESSIONAL EXPERIENCE

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- **Carnegie Mellon University Robotics Institute (Biorobotics Lab)** **Pittsburgh, PA**  
*Undergraduate Research Intern (Part-Time)*  
*April 2023 - Present*
    - **Underwater Snake Robot:** (Link: <http://tinyurl.com/humrsCMU>)
      - \* Implemented High-Frequency Injection methods in BLDC thrusters to achieve control at low/zero speeds.
      - \* Working to implement station-keeping feature using AprilTags and IMU readings.
    - **Apple's E-Waste Recycling Project:** (Link: <https://tinyurl.com/applecmu>)
      - \* Created large datasets for Machine Learning Models to detect screws in e-waste images.
      - \* Integrated ROS and Python packages to track ArucoTags using a Realsense camera for localization of robotic arm.
      - \* Manufactured custom AprilTags using lasercutters and sheet metal manufacturing methods.

## RELATED EXPERIENCE

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- **Society of Astronautics and Rocketry** **Pittsburgh, PA**  
*Chief Engineer (Student Led Organization)*  
*August 2022 - Present*
    - Leading a group of approx. 30 students to design and fabricate a rover to participate in the University Rover Challenge. (Link: <https://tinyurl.com/roverimages>)
    - Quickly established oneself as a valuable contributor to the team's efforts, taking on a lead role in the development of the robotic hand using pneumatic technology. (Link: <https://tinyurl.com/hydraarm>)
  - **FIRST and VEX Robotics** **Royersford, PA**  
*Team Captain/Design Lead (Student Led Organization)*  
*August 2018 - June 2022*
    - Designed six robots in **Solidworks** across four years. All robots qualified for higher level of competition.
    - Taught younger students about robot design and manufacturing through workshops and general building.
    - Won the VEX Judges Award, FIRST Excellence in Engineering Award, FIRST Industrial Design Award, and the FIRST Chairman's Award.

## PROJECTS

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- **STM-32 Elevator Simulator (ARM Assembly, Project Integration):** Designed and Implemented software architecture in ARM Assembly to operate a physical elevator simulator PCB. (Link: <https://tinyurl.com/stmelevator>)
  - **Custom Cane (Human Centered Design, Solidworks, Presentation):** Designed and manufactured a Walker-Cane Fusion to make bathrooms more accessible for wheelchair users. The project won first place at the Senior Design Expo within its category. (Link: <https://tinyurl.com/CustomCane>)
  - **Formula SAE E-Brake Bias (Solidworks):** Developed an award winning e-brake bias system for a formula style racecar, utilizing Solidworks and 3D printing technology to enhance performance and usability. (Link: <https://tinyurl.com/ebrakeb>)
  - **String Art Generator and Optimizer (Research, Python):** Developed an innovative string art optimization tools and GUI using Python programming to improve upon existing string art generators. (Link: <https://tinyurl.com/goyalstring>)
  - **Silicon Prosthetic Hand (Research, Solidworks):** Designed and Manufactured prototype prosthetic hand with silicone soft actuators and tested with human participants for AP Research Project. (Link: <https://tinyurl.com/myprosthetic>)
  - **Bird Sanctuary Restoration (Eagle Scout Project, Volunteering):** Organized a project to restore parts of the Audubon Bird Sanctuary by painting fences, guardrails, and small buildings. (Link: <https://tinyurl.com/goyaleagle>)