

## EDUCATION

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| <b>University of Pittsburgh (Swanson School of Engineering/Frederick Honors Col.)</b>                   | <b>Pittsburgh, PA</b>           |
| • <i>B.S. - Computer Engineering (Autonomous Systems Focus); GPA: 3.99/4.00</i>                         | <i>August 2022 - April 2026</i> |
| <b>Courses:</b> Data Structures and Algorithms, Embedded Processors, Microelectronics, Digital Circuits |                                 |

## PROFESSIONAL EXPERIENCE

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| <b>Carnegie Mellon University Robotics Institute</b> | <b>Pittsburgh, PA</b>       |
| • <i>Undergraduate Robotacist Intern</i>             | <i>April 2023 - Present</i> |
- **ZOË 2 Rover:** ([tinyurl.com/zoe2rover](https://tinyurl.com/zoe2rover))
    - \* Developing low-level software stack for the 2nd generation Zoë Rover set to conduct science in the Atacama Desert including CAN protocols via the ros\_canopen package for ROS2 to communicate with encoders and motors.
    - \* Developed and conducted validation of motor and motor controller datasheet specifications via physical testing.
  - **Underwater Snake Robot:** ([tinyurl.com/humrsCMU](https://tinyurl.com/humrsCMU))
    - \* Implemented High-Frequency Injection methods in Brushless DC thrusters to achieve control at low/zero speeds thus reducing minimum speed by 80% allowing for improved overall performance of the robot.
    - \* Implemented station-keeping feature using AprilTags, IMU readings, and Nested PID Controllers to perform robot state-estimation underwater.
    - \* Conducted major repairs on the robot and assisted in continual maintenance of the robot.
  - **Apple's E-Waste Recycling Project:** ([tinyurl.com/applecmu](https://tinyurl.com/applecmu))
    - \* Created large datasets for Machine Learning Models to detect screws in e-waste images.
    - \* Integrated ROS and Python packages to track AprilTags using a Realsense camera for localization of robotic arm.
    - \* Manufactured custom AprilTags using lasercutters and sheet metal manufacturing methods.

## STUDENT ORGANIZATIONS

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|---------------------------------------------|------------------------------|
| <b>Society of Astronautics and Rocketry</b> | <b>Pittsburgh, PA</b>        |
| • <i>Chief and Integration Engineer</i>     | <i>August 2022 - Present</i> |
- Engineering and integrated a rover to participate in the University Rover Challenge. ([tinyurl.com/roverimages](https://tinyurl.com/roverimages))
  - Leading a multidisciplinary team of 30 students, coordinating between mechanical, electrical, software, and science teams.
  - Securing and managing over \$7,000 in funding for team development and future growth.
  - Proposed and led the development of a prototype robotic hand using pneumatics. ([tinyurl.com/hydraarm](https://tinyurl.com/hydraarm))
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| <b>FIRST and VEX Robotics</b>         | <b>Exton &amp; Royersford, PA</b> |
| • <i>Team Captain/Design Engineer</i> | <i>August 2018 - June 2022</i>    |
- Designed six robots in Solidworks across four years. All robots qualified for higher level of competition including Worlds.
  - Mentored younger students about robot design and manufacturing through workshops and general building.
  - Won the VEX Judges Award, FIRST Excellence in Engineering Award, FIRST Industrial Design Award, and the FIRST Chairman's Award. (VEX Link: [bit.ly/3w7a6b1](https://bit.ly/3w7a6b1)) (FIRST Link: [tinyurl.com/dwbot17](https://tinyurl.com/dwbot17))

## PROJECTS

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- **STM-32 Elevator Simulator (ARM Assembly, Project Integration):** Designed and Implemented software architecture in ARM Assembly to operate a physical elevator simulator PCB. ([tinyurl.com/stmelevator](https://tinyurl.com/stmelevator))
  - **Custom Cane (Human Centered Design, Solidworks):** Designed and fabricated a Walker-Cane Fusion to increase bathrooms accessibility for wheelchair users. Won first place at the Senior Design Expo. ([tinyurl.com/CustomCane](https://tinyurl.com/CustomCane))
  - **Formula SAE E-Brake Bias (Solidworks):** Developed an e-brake bias system for a formula style racecar, utilizing Solidworks and 3D printing technology to enhance performance and usability. Won the FSAE Innovation Award for the design and implentation of the project. ([tinyurl.com/ebrakeb](https://tinyurl.com/ebrakeb))
  - **Formula SAE Low-Cost Slip Angle Sensor (OpenCV, Raspberry Pi):** Worked to design and code prototypes of sensors which would allow for validation of slip angle using mouse sensors, digital cameras, and IMU's.
  - **String Art Generator and Optimizer (Research, Python):** Developed an innovative string art optimization tools and GUI using Python programming to improve upon existing string art generators. ([tinyurl.com/goyalstring](https://tinyurl.com/goyalstring))

## SKILLS AND AWARDS

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- **Languages:** Python, C++, ARM Assembly, RISC-V Assembly
  - **Technologies:** Linux, ROS, ROS2, Docker, Github, Solidworks, MATLAB, Microsoft Products, Microcontrollers, OpenCV
  - **Manufacturing:** Milling, Soldering, Laser Cutting, General Shop Tools
  - **Awards:** Dean's Honor List (2021-Present), Honor List (2021-Present), Eagle Scout