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As opposed to the first AICC course, where we were mostly presented with tools, we will now see more applications of these tools for communication and computation. Mainly, we will see 3 applications in the first part of the semester:

- Source coding (compressing information)
- Cryptography (authentication / privacy / integrity of information)
- Channel Coding (dealing with noise and loss of information / protecting the information from natural damages)

What these three have in common is the idea of storing and communicating information. The notion of entropy, which will come up quite often, will also be important.

Basic probability review

Special case first: finite sample space Ω and uniform distribution. $\Omega = \{\omega_1, \omega_2, \dots, \omega_n\}$. Events: $E \subseteq \Omega$. Then:

$$P(E) = \frac{|E|}{|\Omega|} \qquad \text{(uniform distribution)} \tag{1}$$

Definition 1 (conditional probability). Let E, F be two events. Then, the probability that event E occurs knowing that F has occured:

$$P(E|F) = \frac{|E \cap F|}{|F|} \tag{2}$$

Intuitively, you restrict the sample space to F only, because you know that F has happened: this translates to the division by the cardinality of F instead of the cardinality of G. The intersection of F and F follows from the fact that the sample space is restricted to F: if there exists elements that are in F but not in F, they are outside of the new sample space F, which means that these elements CANNOT occur in conjunction with F. Therefore, we take the intersection of F and F to assure that these elements are not taken into account in the computation.

Theorem 2 (Law of total probability). Let E and F be two events in Ω , and let F^C denote the complement of F. Then:

$$P(E) = P(E|F)P(F) + P(E|F^{C})P(F^{C})$$
(3)

This follows quite directly from the fact that $E = (E \cap F) \cup (E \cap F^C)$, so $P(E) = P(E \cap F) + P(E \cap F^C) \dots$

Remark (divide and conquer). You can sometimes create a partition of your sample space, in a way that allows you to better apply the numbers you are given (p.27-28). This method is called *divide and conquer*.

Theorem 3 (Bayes). Bayes' theorem allows you to compute p(F|E), given that you know p(E|F), p(E) and p(F):

$$p(F|E) = \frac{p(E|F)p(F)}{p(E)} \tag{4}$$

Remark (application). This is useful, in real scenarios, when either one of p(E|F) and p(F|E) is easily observable, but the other isn't. For example, policemen may observe how many people are driving drunk knowing that they have had an accident (they just test the driver after the accident), but they cannot observe how many people are having an accident knowing that they are driving drunk (they can not really test drivers, and then let them drive drunk just to check if they have an accident or not).

Definition 4. A random variable X is a function $X : \Omega \to \mathbb{R}$. It is attached a probability distribution function $p_X(x)$, which represents the probability that X will take on the value x, that is, that the following event E occurs:

$$E = \{ \omega \in \Omega : X(\omega) = x \} \tag{5}$$

Hence,

$$p_X(x) = p(E) = \sum_{\omega \in E} p(\omega) \tag{6}$$

The set of all possible values of X is sometimes called the alphabet of X, written with more curly letters like A.

Theorem 5 (two random variables). Let $X : \Omega \to \mathbb{R}$ and $Y : \Omega \to \mathbb{R}$ be two random variables. The probability of the event $E = \{X = x\} \cap \{Y = y\} (= \{X = x \land Y = y\})$ is

$$p_{X,Y}(x,y) = \sum_{\omega \in E} p(\omega) \tag{7}$$

We can compute p_X (or p_Y , similarly) from $p_{X,Y}$:

$$p_X(x) = \sum_{y} p_{X,Y}(x,y) \tag{8}$$

In one sense, we "fix in place" the value of x and "scroll through" all possible values of y, and add their probabilities up. Here, p_X is called the **marginal distribution** of $p_{X,Y}(x,y)$ with respect to x.

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Definition 6 (expected value). The **expected value**, or **mean** of a random variable $X : \Omega \to \mathbb{R}$, can be computed as

$$E[X] = \sum_{x \in \mathcal{A}(X)} x p_X(x) \quad \text{(requires } p_X\text{)},\tag{9}$$

or as

$$E[X] = \sum_{\omega \in \Omega} X(\Omega)p(\omega). \tag{10}$$

One could say that the first way is "calculating over the codomain", and the second way is "calculating over the domain" (of X).

Remark. The expected value is a linear operation. Let X_1, X_2, \ldots, X_n be random variables from Ω to \mathbb{R} , and let $\lambda_1, \lambda_2, \ldots, \lambda_n$ be real numbers. Then

$$E\left[\sum_{i=1}^{n} X_i \lambda_i\right] = \sum_{i=1}^{n} \lambda_i E[X_i] \tag{11}$$

Extending notions from events to random variables

The notion of independent events extends to random variables. Recall that two events E and F are independent iff p(E|F) = p(E), which is equivalent to saying that $p(E \cap F) = p(E)p(F)$.

Similarly, two random variables may be independent if the value taken by one does not influence the value taken by the other.

Definition 7 (independent random variables). We say that two random variables $X, Y : \Omega \to \mathbb{R}$ are **independent** iff

$$p_{X,Y}(x,y) = p_X(x)p_Y(y) \tag{12}$$

More generally, n random variables are independent iff

$$p_{S_1,\dots,S_n} = \prod_{i=1}^n p_{S_i} \tag{13}$$

From there, we can also extend the notion of conditional probability to random variables.

Definition 8. We define the conditional probability of two random variables $X, Y: \Omega \to \mathbb{R}$ as

$$p(X = x | Y = y) = \frac{p(X = x \land Y = y)}{p(Y = y)}.$$
(14)

Remark. The following statements are equivalent:

$$p_{X,Y}(x,y) = p_X(x) \tag{15}$$

$$p_{X|Y}(x|y) = p_X(x) \tag{16}$$

$$p_{Y|X}(y|x) = p_Y(y) \tag{17}$$

Remark (useful trick). If you are asked to check the independence of X and Y, you don't have to check the equality of (16) or (17). You just have to find the expression for the left-hand side function, and see if it depends on the other variable (\implies they are NOT independent), or if it is just a function of one variable (\implies they are independent).

Theorem 9 (consequence of the independence of random variables). In all cases, $E[X + Y] \neq E[X] + E[Y]$. However, if X and Y are independent, we also have that

$$E[XY] = E[X]E[Y] \tag{18}$$

Source & Entropy

The main object that will interest us when studying source coding is the source itself. The question of the definition of a source took mathematicians and computer scientists a while to answer. We can loosely model a source as a black box that outputs *information*: we are not really interested in its inner mechanisms, but rather in what comes out of it, that is, *information*. This information could take many forms, for example sequences of symbols: since we are considering sources from a computer science point of view, we will be interested in sources that shite out sequences of numbers.

The notion of *entropy* comes into the frame when we realize that a symbol that can be *predicted* before it comes out of the source provides no new information. For example, if the sequence of numbers coming out of the source is 1, 1, 5, 5, 3, 3, 19, 19, 1, ..., we quickly realize that we do not need to store the second number of each pair, as it brings no new information to the table.

An important observation that we can make at this point (it was initially made by Hartley in 1929) is that this link between information and entropy can be modeled very elegantly by random variables! If we think about it, the core idea of a random variable is that it gives you a number that you cannot certainly predict (hence, in fact, the name of *random* variable). If we choose to use this model, a source can be viewed as outputting a sequence of random variables.

Let us now consider a source outputting a sequence of random variables, call them $S_1, S_2, S_3, \ldots, S_n$. Another fundamental question we may ask ourselves is: how much information is actually conveyed by each individual symbol? A partial answer was given by Hartley, that is, that this must depend on the alphabet of the random variable:

Definition 10. The **alphabet** of a random variable is the codomain of the random variable, that is, the set of all values that the random variable may take.

Indeed, the bigger the alphabet, the more information it can carry, as there are more possibilities for each symbol, and therefore less predictability. With basic combinatorics, we can see that there are $|\mathcal{A}|^n$ possible length-n sequences (s_1, s_2, \ldots, s_n) . Therefore, the amount of information carried by S_i is $\log |\mathcal{A}|$.

Example 11. Imagine this is the sequence of good days (1) and bad days (0) in London during a year:

$$(s_1, s_2, \dots, s_{365}) = (0, 1, 1, 0, 1, \dots, 0, 1, 1).$$

There is a lot of entropy, it is unpredictable. It would therefore be hard to optimize the storage of this information better. San Diego:

$$(\overbrace{0,0,0,\dots,0}^{24 \text{ zeros}},1,\overbrace{0,0,0,\dots,0,0}^{340 \text{ zeros}}).$$

This is a very predictable sequence, which would allow us to just store (24,1,340) rather than storing all 365 bits.

Entropy redefined by Shannon

Shannon, in 1948, gave a new formula for the amount of information carried by the random variable $S \in \mathcal{A}$. He said that this amount is in fact the entropy itself, and gave this formula for the entropy H(S):

$$H(S) = -\sum_{s \in \text{supp}(P_S)} p_S(s) \cdot \log_b(p_S(s))$$
(19)

Comments

• $s \in \text{supp}(S)$ is needed because $\log(0)$ is not defined

- if we are using the convention $0 \cdot \log(0) = 0$, then we can simplify the notation like this: $H(S) = -\sum_{s \in \mathcal{A}} p_S(s) \log_b(p_S(s))$
- when b=2 (default) then the unit is the bit. $H(S)=H_2(S)$
- if we rewrite the formula as $H(S) = \sum_{s \in \mathcal{A}} p_S(s) \underbrace{\left(-\log_b(p_S(s))\right)}_{\text{rand, var, } X} = E[X]$, because this is the expression of the

expected value of a random variable X.

EXAMPLE Let the random variable $S \in \mathcal{A}$ be uniformly distributed. Then

$$H(S) = -\sum_{s \in \text{supp}(P_S)} \underbrace{p_S(s)}_{|A|} \log_b \underbrace{\left(p_S(s)\right)}_{|A|}$$

So, Hartley and Shannon agree when the random variable has a uniform distribution. Entropy extends to any number of random variables.

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We saw last time that a source can mathematically be modeled as one or more random variables, each being described by its probability mass function. We saw that the entropy is a number which represents the ultimate amount of bits (not necessarily, but generally, binary) needed to represent a random variable (and therefore a source).

Example 12. $S \in \{0,1\} = A, p_S(0) = P$

$$H(S) = -\sum_{s \in \mathcal{A}} p_S(0) \log_b(p_S(0))$$

$$= \underbrace{-p \log p - (1-p) \log(1-p)}_{h(p) \text{ function of } p}$$

IT inequality

Many results in information theory are the consequence of the following inequality.

Theorem 13 (IT inequality). Let r > 0. Then

$$\log_b(r) \le (r-1)\log_b(e) \tag{20}$$

with the equality iff r = 1.

Theorem 14 (Entropy bounds). Let $s \in A$. Then

$$0 \le H(s) \le \log|\mathcal{A}|\tag{21}$$

with the first inequality holding iff S = const., and the second inequality holding iff $p_S(s) = \frac{1}{|\mathcal{A}|}$.

Example 15. Let S be your 4-digit lock number. Then $S = \{0, 1, \ldots, 9999\}$. Let's say you choose your lock number at random: then $H(s) = \log 10^4$. However, if your grandma <u>always</u> chooses 0000, then s is a constant, and H(S) = 0. A random (least previsible) choice has the most entropy, and a constant (most previsible) choice has the least entropy (zero). This makes sense, and it also means that the random lock number carries the most information, and the constant one carries the least information.

Let's apply this to sources.

Example 16. Let S_1, S_2, \ldots, S_n be a sequence of coin flips. Then $S_i \in \{0, 1\}$, and $P_S(s) = \frac{1}{2}$. Intuitively, we are flipping n coins, and it should take n bits to describe the result (a length-n bitstring).

$$\underbrace{P_{S_1,S_2,\dots,S_n}(s_1,s_2,\dots,s_n)}_{\text{abbreviate as }P(s_1,\dots,s_n)} = \prod_{i=1}^n P(s_i) = \left(\frac{1}{2}\right)^n$$

$$H(S_1,S_2,\dots,S_n) = \log(|\mathcal{A}|^n) = n\log 2 = n$$

PERSONAL NOTE: recall that when we write $P(s_1, s_2, ..., s_n)$, we mean the probability of getting the sequence $(s_1, s_2, ..., s_n) \in \mathcal{A}^n$. Then the cardinality of the alphabet is $|\mathcal{A}^n| = |\mathcal{A}|^n$.

Source coding

The setup we have is the following: let's say we have a source emitting $S_i \in \mathcal{A}$ towards an encoder with an encoding map (a function $\mathcal{A} \to \mathcal{C}$) called Γ . We're going to map each element of the alphabet into a codeword, for example, each letter of the word dinner. For example: $d \to 000$, $i \to 010$, ...

The encoder is specified by

- an input alphabet A, which is the alphabet of the source
- ullet an output alphabet ${\mathcal C}$
- the encoding map $\Gamma: \mathcal{A} \to \mathcal{C}$

The code is a set of codewords, which are the output of the Γ map. The Γ map is always one-to-one and onto (bijective), but this doesn't mean that we can necessarily go back from the code words to the words, since we usually concatenate the output.

Example 17. Let $\mathcal{A} = \{H, E, L, 0\}$ and $\mathcal{C} = \{01, 10, 0, 11\}$ (Γ maps them in the written order). Then $\Gamma : \mathcal{A} \to \mathcal{C}$ encodes the word HELLO to the bitstring 01100011. The conversion is easy in this direction, but when trying to decode the message, we run into a difficulty: the bitstring could either be interpreted as 01,10,0,0,11, which would give back the correct message HELLO, or as 0,11,0,0,0,11, which would give the incorrect message LOLLLO.

Definition 18. We say that a code is **uniquely decodable** if each concatenation of codewords has a unique parsing into codewords, that is, if we can be sure of getting the correct message when decoding a sequence of codewords. The kinds of encodings that give uniquely decodable codes are the ones that are most interesting in information encoding.

Example 19. Let's have a look at a few different Γ mappings, and check whether they are uniquely decodable or not:

\mathcal{A}	Γ_O	Γ_A	Γ_B	Γ_C
a	00	0	0	0
b	01	01 10	10	01
С	10	10	110	011
d	11	11	1110	0111

FINISH THIS EXAMPLE

Definition 20. A code is said to be **prefix-free** if no codeword is the prefix of a longer codeword. Prefix-free codes are preferred in encoding information. They are also called **instantaneous codes**, since they allow instantaneous decoding.

Remark. Prefixes seem like a good idea, but the problem with codes that are not prefix-free is that when you concatenate words, you need to have all of them to be able to decode it correctly, as shown in the next example.

Example 21. Here's an example of why prefix codes are not the best in terms of decoding. The following code is uniquely decodable, but it uses a prefix:

$$\begin{array}{c|c} \mathcal{A} & \Gamma \\ \hline \mathbf{a} & \mathbf{0} \\ \mathbf{b} & \mathbf{00001} \end{array}$$

If the decoder receives the sequence 00, it cannot instantaneously determine wether this is the start of a b or two concatenated a, and so it has to wait until it has the full string of bits to be able to decode it correctly.

Theorem 22 (Kraft-McMillan 1). If a D-ary code is uniquely decodable, then its codeword lengths l_1, l_2, \ldots, l_M satisfy

$$D^{-l_1} + \dots + D^{-l_M} \le 1 \quad (Kraft's inequality)$$
 (22)

Remark. Kraft's sum is only about lengths!

Example 23. Let's look at the following code:

This is a 2-ary (binary) code with lengths 2 and 4, so Kraft's sum gives

$$2^{-2} + 2^{-4} = \frac{1}{4} + \frac{1}{16} = \frac{5}{16} \le 1,$$

and Kraft's inequality is satisfied, however the code is clearly not uniquely decodable.

Summary. • \mathcal{C} is uniquely decodable \Longrightarrow it satisfies the kraft inequality contrapositive: \mathcal{C} does not satisfy the Kraft inequality $\Longrightarrow \mathcal{C}$ is NOT uniquely decodable.

• the converse is NOT true.

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These following properties are what we aim for with any encoding map $\Gamma: \mathcal{A} \to \mathcal{C}$, in order to optimize transmission and decoding speed:

- \bullet \mathcal{C} be uniquely decodable
- \bullet \mathcal{C} be prefix-free
- \bullet C have its average codeword length be as small as possible

Theorem 24 (Kraft-McMillan 2). If l_1, \ldots, l_m satisfy Kraft's inequality for some positive integer D, then there exists a D-ary prefix-free code that has codeword lengths l_1, \ldots, l_m .

This second part of the Kraft-McMillan theorem implies that any uniquely decodable code can be substituted by a prefix-free code of the same codeword lengths.

Summary (Kraft-McMillan). The theorem is in 2 parts:

- 1. If a *D*-ary code is uniquely decodable, then its codeword lenghts l_1, \ldots, l_M satisfy Kraft's inequality $D^{-l_1} + \cdots + D^{-l_M} < 1$.
- 2. If the positive integers l_1, \ldots, l_M satisfy Kraft's inequality for some integer D, then there exists a D-ary prefix-free code that has those codeword lengths.

Definition 25. We define the average length $L(S,\Gamma)$ as

$$L(S,\Gamma) = \sum_{S \in \mathcal{A}} p_S(s) \underbrace{l(\Gamma(s))}_{\text{shorthand } l(s)}.$$
 (23)

Sometimes we write

$$L(S,\Gamma) = \sum_{i} p_i l_i. \tag{24}$$

This is rather intuitively defined, as the expected length should according to common sense indeed depend on the length of each codeword, and on its probability of appearing in the code.

The units of the average length are **code symbols**. When D=2, the units are **bits**.

Question. An interesting question we may now ask ourselves is the following: is there a lower bound to the average length for uniquely decodable codes?

Theorem 26 (lower bound on average length). Let Γ be the encoding map of a D-ary code for the source S. If the D-ary code is uniquely decodable, then

$$H_D(S) \le L(S, \Gamma).$$
 (25)

The entropy is a lower bound to the average length.

Remark. A key observation we may make is that the definition of the average length is somewhat similar to that of the entropy:

$$L(S,\Gamma) = \sum_{s \in \mathcal{A}} p(s)l(\Gamma(s))$$

$$H_D(S) = \sum_{s \in \mathcal{A}} p(s)\log_D\left(\frac{1}{p_S(s)}\right)$$

In fact, the definitions are identical iff $l(\Gamma(s)) = \log_D\left(\frac{1}{p_S(s)}\right)$. Unfortunately this equality is often not possible (the log is often not an integer). But what if we chose $l(\Gamma(s)) = \left\lfloor \log_D\left(\frac{1}{p_S(s)}\right) \right\rfloor$? Is it a valid choice for a prefix-free code (is Kraft's inequality satisfied)?

Definition 27 (Shannon-Fano code). A code \mathcal{C} for which $l_i = \lceil -\log_D(P_S(s)) \rceil$ is called a **Shannon-Fano code**. Visually, it is constructed by going from the top down when creating the code tree.

For all s we $p_S(s)$

Remark. The Shannon-Fano code is not optimal (WHY? COMPLETE THIS).

Definition 28. We say that a probability distribution is **diadic** iff

$$p_i = D^{-l_i} (26)$$

Theorem 29. It is possible to make the codewords lengths l_i equal the entropy iff the code is diadic.

CLEAR UP THE THING ABOUT THE -log(pi) THAT I DONT UNDERSTAND

Remark. Most probability distributions are not diadic. Then, $-\log(p_i)$ is not an integer, and we can't make the length equal that number.

Definition 30 (Huffman code). Visually, the Huffman code on an alphabet is constructed by going from the bottom up when creating the code tree, and grouping together the least probable symbols.

Example 31. The Huffman code on $A = \{a, b, c, d\}$ is:

$$egin{array}{c|c} {\cal A} & \Gamma_H \ \hline a & 000 \ b & 001 \ c & 01 \ d & 1 \ \hline \end{array}$$

We can compute the expected length and the entropy (in bits):

$$L(S, \Gamma_H) = 0.15 + 0.15 + 0.2 + 0.8 = 1.3$$

 $H_2(S) = \dots = 1.022$

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Theorem 32. The average length can also be computed by adding together the probabilities of all nodes on the code tree, except for the last leaves:

$$\sum_{\substack{i \in terminal \\ leaves}} = \sum_{\substack{j \in termediate \\ nodes}} q_j. \tag{27}$$

Theorem 33 (optimality of Huffman codes). Let Γ_G be an encoder of a D-ary Huffman code for S, and let Γ be another D-ary uniquely decodable encoder for S. Then

$$L(S, \Gamma_H) \le L(S, \Gamma).$$
 (28)

Basically, the Huffman code on S is the optimal code on S.

Definition 34 (IID source). A source is said to be **IID** (Independent and I... **Decodable ?????)** iff COMPLETE THIS

Most sources are not IDD.

Example 35. Let $S_1, S_2 \in \{1, 2, ..., 6\}$. They are independent and uniformly distributed. Let (L_1, L_2) be the first and second digit of the sum $S_1 + S_2$. We can compute $P_{L_1|L_2}(1|1) = \frac{P_{L_1|L_2}(1,1)}{P_{L_1}(1)}$. We know that the event $(L_1, L_2) = (1, 1)$ is the same as the event $S_1 + S_2 = 11$, which is the same as saying $(S_1, S_2) \in \{(5, 6), (6, 5)\}$, which has probability 2/36. Then the conditional probability that we wanted to compute is

$$\frac{2/36}{3/36 + 2/36 + 1/36} = \frac{1}{3}$$

Definition 36 (conditional entropy). Let p_X be the probability distribution of a random variable X. We already know how to compute the entropy H(x) from this probability distribution. Then $p_{X|Y=y}$, which is also a probability distribution, allows us to compute the **conditional entropy** H(X|Y=y):

$$H_b(X|Y = y) = -\sum_{x \in X} p_{X|Y}(x|y) \log_b(p_{X|Y}(x|y))$$
(29)

Example 37 (continuation). COMPLETE THIS FROM THE NOTES :DDDDDDDDDDDDDDDD I AM GOING INSANE AND 2 HOURS LEFT :DDDDDDDDDDDDD

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IS THE ENTROPY EQUAL TO THE AVERAGE LENGTH IFF IT IS A HUFFMAN CODE?

Theorem 38. Let X and Y be two random variables. Then

$$H(X|Y) \le H(x),\tag{30}$$

with the equality iff X and Y are independent.

Theorem 39 (chain rule of entropy). Let S_1, \ldots, S_n be random variables. Then

$$H(S_1, \dots, S_n) = \sum_{i=1}^n H(S_1 | S_1, \dots, S_{i-1})$$
(31)

For this to make a bit more sense, recall that $P_{X,Y}(x,y) = P_X(x)P_{Y|X}(y|x)$ (this follows directly from the definition of conditional probability). More generally, $P_{S_1,\ldots,S_n}(s_1,\ldots,s_n) = \prod_{i=1}^n P_{S_i|S_1,\ldots,S_{i-1}}(s_i|s_1,\ldots,s_{i-1})$. The chain rule of entropy is very similar.

Example 40 (continuation). $H(l_1) = 0.65$ bits, $H(l_2) = 3.2188$ bits, $H(l_1, l_2) = 3.744$ bits, $H(l_2|l_1) = H(l_1, l_2) - H(l_1) = 2.624$ bits (as obtained before).

Example 41 (continuation). We saw that (S_1, S_2) determine (l_1, l_2) . Then what is $H(l_1, l_2|S_1, S_2)$? We can know that $H(l_1, l_2|(S_1, S_2) = (s_1, s_2)) = 0$. This is because (S_1, S_2) fully determine (l_1, l_2) (they are NOT independent). As such, when we know that $(S_1, S_2) = (s_1, s_2)$, we know exactly and can *predict* the only possible digits (l_1, l_2) of the sum of s_1 and s_2 , which matrix $(S_1, S_2) = (s_1, s_2)$ for the sum of s_1 and s_2 , which matrix $(S_1, S_2) = (s_1, s_2)$ for $(S_1, S_2) = (s_1, s_2)$.

Suppose we know $H(l_1, l_2)$ and $H(S_1, S_2)$. Then we can compute $H(S_1, S_2 | l_1, l_2)$:

$$\begin{split} H(S_1,S_2,l_1,l_2) & \stackrel{\text{chain}}{=} \begin{cases} H(S_1,S_2) + \underbrace{H(l_1,l_2|S_1,S_2)} \\ H(l_1,l_2) + H(S_1,S_2|l_1,l_2) \end{cases} \\ & \Longrightarrow H(S_1,S_2,|l_1,l_2) = H(S_1,S_2) - H(l_1,l_2), \quad \text{which we both know by supposition.} \end{split}$$

Example 42. Let's say we have a random variable X which takes a value in $\{0, +1, -1, +2, \ldots, +13, -13\}$. Suppose X is uniformly distributed. Any weighing strategy (not yet determined) is an encoding $\Gamma : \mathcal{A} \to \mathcal{C}$ ($|\mathcal{C}| = 3$, so this is a 3-ary code). Γ is a bijective function $x \leftrightarrow s_1 s_2 \ldots s_L$. So $H_3(x) = H_3(S_1, S_2, \ldots S_L)$.

NOTES: a negative number means "light" on the balance, a positive number means it is "heavy". At each step of the guessing process, he makes sure that the new balance is independent of previous knowledge, and that it is evenly distributed (even chances of going on each side). Actually the balls are billiard. One coould be heavier or lighter, ut not the 0 ball. You have a balance for balls. How many times to weigh to determine if one bakk us fakse and if yes, which one and settle if it is heavier or lighter.