



CEDYA+CMA
XXV CONGRESO DE ECUACIONES DIFERENCIALES Y APLICACIONES
XV CONGRESO DE MATEMÁTICA APLICADA



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Preliminaries

Generalizations of Roth's criteria for solvability of matrix equations

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Semilinear mappings

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A mapping \mathcal{A} from a complex vector space U to a complex vector space V is **semilinear** if

$$\mathcal{A}(u + u') = \mathcal{A}u + \mathcal{A}u', \quad \mathcal{A}(\alpha u) = \bar{\alpha}\mathcal{A}u$$

for all $u, u' \in U$ and $\alpha \in \mathbb{C}$.

We write

- $\mathcal{A} : U \longrightarrow V$ if \mathcal{A} is a **linear mapping**, and
- $\mathcal{A} : U \dashrightarrow V$ if \mathcal{A} is a **semilinear mapping**.

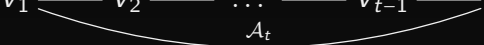
Cycles of linear and semilinear mappings

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We give a canonical form of matrices of a **cycle of linear and semilinear mappings**

$$V_1 \xrightarrow{\mathcal{A}_1} V_2 \xrightarrow{\mathcal{A}_2} \dots \xrightarrow{\mathcal{A}_{t-2}} V_{t-1} \xrightarrow{\mathcal{A}_{t-1}} V_t$$


in which **each line** is

- a full arrow \longrightarrow , \longleftarrow , or
- a dashed arrow \dashrightarrow , \dashleftarrow .

My talk is based on:

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- D. Duarte de Oliveira, V. Futorny, T. Klimchuk, D. Kovalenko, V.V. Sergeichuk, *Cycles of linear and semilinear mappings*), Linear Algebra Appl. 438 (2013) 3442-3453.
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Empty matrices

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Preliminaries

- $\forall n = 0, 1, 2, \dots \exists!$ matrices of sizes $0 \times n$ and $n \times 0$, which correspond to linear mappings $\mathbb{C}^n \rightarrow 0$ and $0 \rightarrow \mathbb{C}^n$.
- They are denoted by 0_{0n} and 0_{n0} and are considered as zero matrices
- For every $p \times q$ matrix M_{pq} :

$$M_{pq} \oplus 0_{n0} = \begin{bmatrix} M_{pq} & 0 \\ 0 & 0_{n0} \end{bmatrix} = \begin{bmatrix} M_{pq} & 0_{p0} \\ 0_{nq} & 0_{n0} \end{bmatrix} = \begin{bmatrix} M_{pq} \\ 0_{nq} \end{bmatrix}$$

$$M_{pq} \oplus 0_{0n} = \begin{bmatrix} M_{pq} & 0 \\ 0 & 0_{0n} \end{bmatrix} = \begin{bmatrix} M_{pq} & 0_{pn} \\ 0_{0q} & 0_{0n} \end{bmatrix} = \begin{bmatrix} M_{pq} & 0_{pn} \end{bmatrix}$$

Sooooooo baad without empty matrices

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$$\forall A \exists \text{ nonsingular } R, S: RAS = \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix}$$

Observation

- Each matrix is equivalent to a direct sum of indecomposable matrices of the form

$$[1], [1\ 0], [1\ 0\ 0], \dots, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \dots$$

- This direct sum is not uniquely determined:

$$\begin{aligned} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} &= \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] = [1\ 0] \oplus [0] \\ &= \left[\begin{array}{c|cc} 1 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] = [1] \oplus [0\ 0] \end{aligned}$$

Goooood with empty matrices

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$$\begin{aligned} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} &= [1 \ 0] \oplus [0] = [1] \oplus 0_{01} \oplus 0_{01} \oplus 0_{10} \\ &= [1] \oplus [0 \ 0] = [1] \oplus 0_{01} \oplus 0_{01} \oplus 0_{10} \end{aligned}$$

A la Jordan Theorem

- *Each matrix is equivalent to a direct sum of indecomposable matrices of the form $[1]$, 0_{01} , 0_{10} .*
- *This direct sum is uniquely determined, up to permutation of summands.*