

The Symmetric Lanczos Algorithm

$$A = A^T$$

$$\left[\begin{array}{l} AV_m = V_m H_m + w_m^T e_m = V_{m+1} \bar{H}_m \quad \text{for any } A \in \mathbb{R}^{n \times n} \\ V_m^T A V_m = H_m \end{array} \right]$$

Theorem

Assume that the Arnoldi method is applied to a real symmetric matrix A

then the coefficients generated by the algorithm are such that

$$\left. \begin{array}{l} a) \quad h_{ij} = 0 \quad 1 \leq i < j-1 \\ b) \quad h_{j,j+1} = h_{j+1,j} \quad j = 1, \dots, m \end{array} \right\} \Leftrightarrow H_m \text{ is symmetric and tri-diagonal}$$

Proof

$$H_m = V_m^T A V_m$$

$$H_m^T = (V_m^T A V_m)^T = V_m^T A^T V_m = V_m^T A V_m = H_m$$

$$H_m \text{ Hessenberg and symmetric} \Rightarrow h_{ij} = 0 \quad 1 \leq i < j-1$$

Hessenberg

$$H_m = \begin{bmatrix} h_{11} & h_{12} & h_{13} & 0 & \dots \\ h_{21} & h_{22} & h_{23} & 0 & \dots \\ 0 & h_{32} & h_{33} & & \\ 0 & 0 & h_{43} & & \\ \vdots & \vdots & \vdots & & \end{bmatrix}$$

$$T_m = \begin{bmatrix} \alpha_1 & \beta_2 & & & \\ \beta_2 & \alpha_2 & \beta_3 & & \\ & \beta_3 & \alpha_3 & \beta_4 & \\ & & \beta_4 & \ddots & \\ 0 & & & \beta_m & \alpha_m \end{bmatrix}$$

Arnoldi algorithm

$$v_1$$

$$w_1 = A v_1$$

$$h_{11} = \alpha_1$$

$$w_1 = A v_1 - (A v_1, v_1) v_1$$

$$h_{21} = \beta_2 = \|A v_1 - (A v_1, v_1) v_1\|$$

$$v_2 = \frac{A v_1 - (A v_1, v_1) v_1}{h_{21}}$$

$$h_{21} v_2 = A v_1 - h_{11} v_1$$

$$\beta_2 v_2 = A v_1 - \alpha_1 v_1$$

$$A v_1 = \alpha_1 v_1 + \beta_2 v_2$$

$$w_2 = Av_2 - \overbrace{(Av_2, v_1)}^{h_{21}=\beta_2} v_1 - \overbrace{(Av_2, v_2)}^{h_{22}=\alpha_2} v_2$$

$$(Av_2, v_1) = v_1^T A v_2 = v_1^T A^T v_2 = (v_2, Av_1) = 0$$

$$= (v_2, \alpha_1 v_1 + \beta_2 v_2) = \alpha_1 (v_2, v_1) + \beta_2 (v_2, v_2)$$

$$w_2 = \beta_3 v_3 = Av_2 - \beta_2 v_1 - \alpha_2 v_2$$

$$Av_2 = \beta_2 v_1 + \alpha_2 v_2 + \beta_3 v_3$$

$$w_3 = Av_3 - \overbrace{(Av_3, v_1)}^{h_{31}=0} v_1 - \overbrace{(Av_3, v_2)}^{h_{32}=\beta_3} v_2 - \overbrace{(Av_3, v_3)}^{\alpha_3} v_3 = \beta_4 v_4$$

$$(Av_3, v_1) = (v_3, Av_1) = 0$$

$$(Av_3, v_2) = (v_3, Av_2) = \beta_3$$

$$Av_3 = \beta_3 v_2 + \alpha_3 v_3 + \beta_4 v_4$$

$$Av_1 = "0 v_0" + \alpha_1 v_1 + \beta_2 v_2$$

$$\beta_1 = 0$$

$$Av_j = \beta_j v_{j-1} + \alpha_j v_j + \beta_{j+1} v_{j+1} \quad j \geq 1$$

Lanczos Algorithm

$$\text{Choose } v_1 \quad \|v_1\|=1 \quad \beta_1=0 \quad v_0=0$$

for $j=1, \dots, m$

$$w_j = Av_j - \beta_j v_{j-1}$$

$$\alpha_j = (w_j, v_j)$$

$$w_j = w_j - \alpha_j v_j$$

$$\beta_{j+1} = \|w_j\|$$

$$v_{j+1} = \frac{w_j}{\beta_{j+1}} \quad \leftarrow \text{if } \beta_{j+2} = 0 \text{ break}$$

end

FOM

$$\mathcal{L} = \mathcal{K} = \mathcal{K}_m(A, v_0)$$

$$b - Ax_m = r_m \perp \mathcal{L} = \mathcal{K}_m(A, v_0)$$

$$x_m = x_0 + V_m y_m$$

$$V_m^T (b - Ax_m) = 0$$

$$V_m^T (b - Ax_0 - AV_m y_m) = 0$$

$$V_m^T (r_0 - AV_m y_m) = 0$$

$$\beta e_1 - T_m y_m = 0$$

$$\boxed{T_m y_m = \beta e_1} \leftarrow$$

$$\begin{aligned}
 r_m &= b - Ax_m = r_0 - Av_m y_m = r_0 - V_m \underline{H_m} y_m - w_m e_m^T y_m \\
 &= r_0 - V_m T_m y_m - \beta_{m+1} \underline{v_{m+1}} e_m^T y_m \\
 &= r_0 - V_m \beta e_1 - \beta_{m+1} \underline{v_{m+1}} e_m^T y_m \\
 &= \cancel{r_0} - \cancel{r_0} - \beta_{m+1} \underline{v_{m+1}} \underline{e_m^T y_m} \\
 \|r_m\| &= \beta_{m+1} |y_m(m)|
 \end{aligned}$$

$A_{spd} = A$ is symmetric positive definite

$$T_m = L_m U_m$$

$$\begin{bmatrix} \alpha_1 & \beta_2 & & \\ \beta_2 & \alpha_2 & \beta_3 & \\ & \beta_3 & \alpha_3 & \ddots \\ & & \ddots & \ddots \end{bmatrix}^{T_m} = \begin{bmatrix} 1 & 0 & 0 & \\ \lambda_2 & 1 & 0 & \\ & \lambda_3 & 1 & \\ & & \ddots & \ddots \end{bmatrix}^{L_m} \begin{bmatrix} \eta_1 & \gamma_2 & & \\ 0 & \eta_2 & \gamma_3 & \\ 0 & 0 & \eta_3 & \gamma_4 \\ & & \ddots & \ddots \end{bmatrix}^{U_m}$$

$$\alpha_1 = \eta_1$$

$$\beta_2 = \gamma_2$$

$$\lambda_2 \eta_1 = \beta_2$$

$$\lambda_2 = \frac{\beta_2}{\alpha_1}$$

$$\lambda_2 \gamma_2 + \eta_2 = \alpha_2$$

$$\eta_2 = \alpha_2 - \frac{\beta_2}{\alpha_1} \beta_2$$

$$\gamma_3 = \beta_3$$

$$\lambda_3 \eta_2 = \beta_3$$

$$\lambda_3 = \frac{\beta_3}{\eta_2}$$

$$\beta_1 = 0 \quad \lambda_1 = 0 \quad \gamma_1 = 0 \quad \lambda_3 \gamma_3 + \eta_3 = \alpha_3$$

$$\eta_3 = \alpha_3 - \frac{\beta_3}{\eta_2} \beta_3$$

$$\eta_1 = \alpha_1$$

$$\gamma_j = \beta_j$$

$$\lambda_j = \frac{\beta_j}{\eta_{j-1}}$$

$$\eta_j = \alpha_j - \frac{\beta_j^2}{\eta_{j-1}}$$

$$L_m U_m y_m = \beta e_1$$

$$L_m z_m = \beta e_1$$

$$\begin{bmatrix} 1 & & & \\ \lambda_2 & 1 & & \\ & \lambda_3 & 1 & \\ & & \lambda_4 & 1 \\ & & & \ddots & \ddots \end{bmatrix}^{L_m} \begin{bmatrix} z_m(1) \\ \\ \\ z_m(m) \end{bmatrix} = \begin{bmatrix} \beta \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$z_m(1) = \beta$$

$$z_m(2) = -\lambda_2 \beta$$

$$\lambda_2 z_m(1) + 1 z_m(2) = 0$$

$$z_m(3) = +\lambda_3 \lambda_2 \beta$$

$$\lambda_3 z_m(2) + 1 z_m(3) = 0$$

$$z_m(j) = (-1)^{j+1} \prod_{i=2}^j \lambda_i \beta \quad j > 1$$

$$U_m y_m = z_m$$

$$y_m(m) = \frac{z_m(m)}{\eta_m}$$

$$\begin{bmatrix} \eta_1 & \beta_2 & & 0 \\ 0 & \eta_2 & \beta_3 & \\ & 0 & \eta_3 & \beta_4 \\ & & & \ddots \\ & & & 0 & \eta_m & \beta_{m+1} \end{bmatrix} \begin{bmatrix} y_m(1) \\ y_m(2) \\ y_m(m) \end{bmatrix} = \begin{bmatrix} z_m(1) \\ z_m(m) \end{bmatrix}$$

$$\rightarrow y_m(m-1) = \frac{-\beta_m y_m(m) + z_m(m-1)}{\eta_{m-1}}$$

$$y_m = U_m^{-1} z_m$$

$$\|r_m\| = \beta_{m+1} |y_m(m)| \leftarrow$$

$$x_m = x_0 + V_m y_m = x_0 + \underbrace{V_m U_m^{-1}}_{P_m} z_m$$

$$P_m = V_m U_m^{-1}$$

$$P_m U_m = V_m$$

$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ \beta_1 & \beta_2 & \beta_3 & \dots & \beta_m \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} \eta_1 \beta_2 \\ 0 \quad \eta_2 \beta_3 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ \vdots & \vdots \\ \vdots & \vdots \\ 1 & 1 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_m \end{bmatrix}$$

$$\eta_1 p_1 = r_1$$

$$p_1 = \frac{1}{\eta_1} r_1$$

$$\beta_2 p_1 + \eta_2 p_2 = r_2$$

$$p_2 = \frac{1}{\eta_2} (r_2 - \beta_2 p_1)$$

$$\beta_3 p_2 + \eta_3 p_3 = r_3$$

$$p_3 = \frac{1}{\eta_3} (r_3 - \beta_3 p_2)$$

$$x_m = x_0 + P_m z_m$$

D-Lanczos (A s.p.d.)

$$\text{Given } x_0 \rightarrow r_0 = b - Ax_0 \quad \beta = \|r_0\| \quad v_1 = \frac{r_0}{\beta} \quad z_m(1) = \beta$$

$$m=1 \quad \eta_1 = \alpha_1 = (Av_1, v_1) \quad \beta_2 = \|Av_1 - \alpha_1 v_1\| \quad v_2 = \frac{Av_1 - \alpha_1 v_1}{\beta_2} \quad p_1 = \frac{v_1}{\eta_1}$$

repeat

$$m = m+1$$

$$w = Av_m - \beta_m v_{m-1}$$

$$\alpha_m = (w, v_m)$$

$$w = w - \alpha_m v_m$$

$$\beta_{m+1} = \|w\| \quad v_{m+1} = \frac{w}{\beta_{m+1}}$$

$$\lambda_m = \frac{\beta_m}{\eta_{m-1}}$$

$$\eta_m = \alpha_m - \frac{\beta_m^2}{\eta_{m-1}} = \alpha_m - \lambda_m \beta_m$$

$$z_m(m) = -\lambda_m z_m(m-1)$$

$$p_m = \frac{1}{\eta_m} (v_m - \beta_m p_{m-1})$$

$$\text{until } \left| \frac{\beta_{m+1} z_m(m)}{\eta_m} \right| < \text{tol}$$

$$x_m = x_{m-1} + z_m(m) p_m$$

Given x_0 $r_0 = b - Ax_0$ $\beta = \|r_0\|$ $v^{\text{old}} = \frac{r_0}{\beta}$ $z_m^{\text{old}} = \beta$ $x_m = x_0$

$\eta^{\text{old}} = \alpha^{\text{old}} = (Ar^{\text{old}}, v^{\text{old}})$ $w = Ar^{\text{old}} - \alpha^{\text{old}} v^{\text{old}}$ $\beta^{\text{new}} = \|w\|$ $v^{\text{new}} = \frac{w}{\beta^{\text{new}}}$

repeat

$w = Av^{\text{new}} - \beta^{\text{new}} v^{\text{old}}$ $\alpha^{\text{new}} = (Av^{\text{new}}, v^{\text{new}})$

$w = w - \alpha^{\text{new}} v^{\text{new}}$ $\beta^{\text{nn}} = \|w\|$ $v^{\text{nn}} = \frac{w}{\beta^{\text{nn}}}$

$\lambda^{\text{new}} = \frac{\beta^{\text{new}}}{\eta^{\text{old}}}$ $\eta^{\text{new}} = \alpha^{\text{new}} - \lambda^{\text{new}} \beta^{\text{new}}$ $z_m^{\text{new}} = -\lambda^{\text{new}} z_m^{\text{old}}$

$p^{\text{new}} = \frac{1}{\eta^{\text{new}}} (v^{\text{new}} - \beta^{\text{new}} p^{\text{old}})$

$x_m = x_m + z_m^{\text{new}} p^{\text{new}}$

$\eta^{\text{old}} = \eta^{\text{new}}$ $\beta^{\text{new}} = \beta^{\text{nn}}$ $v^{\text{new}} = v^{\text{nn}}$ $z_m^{\text{old}} = z_m^{\text{new}}$

until $\left| \beta^{\text{nn}} \frac{z_m^{\text{new}}}{\eta^{\text{new}}} \right| < \text{tol}$

x_m is my solution

Proposition A s.p.d. r_m the residual vectors

- Each residual r_m is orthogonal to all the previous residuals
 $(r_m, r_k) = 0 \quad \forall k < m$
- The auxiliary vectors p_m form an A -conjugate system of vectors
 $(Ap_i, p_j) = 0 \quad i \neq j \quad p_j^T A p_i = 0 \quad i \neq j$

Proof

1) $r_m = -\beta_{m+1} y_m(m) v_{m+1}$ v_j orthonormal $j = 1, \dots, m+1$

2) $q_j^T q_i = 0 \quad q_i \perp q_j$
 $q_j^T I q_i = 0$
 $q_j^T A p_i = 0 \quad q_i \text{ (LA) } q_j$

$P_m^T A P_m$ is diagonal $P_m = V_m U_m^{-1}$

$P_m^T A P_m = (V_m U_m^{-1})^T A V_m U_m^{-1} = U_m^{-T} V_m^T A V_m U_m^{-1} = U_m^{-T} T_m U_m^{-1} = U_m^{-T} L_m \underbrace{U_m U_m^{-1}}_I$

$= U_m^{-T} L_m$

U_m upper bi-diagonal matrix
 U_m^{-1} " " "
 U_m^{-T} lower " "
 L_m " " "
 lower bi-diagonal matrix

$(P_m^T A P_m)^T = P_m^T A^T P_m = (U_m^{-T} L_m)^T$ upper bi-diagonal matrix
 $P_m^T A P_m = U_m^{-T} L_m$ lower bi-diagonal " } diagonal matrix