نظریهی یادگیری ماشین

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Solution: Let T denote the training sample and let L(T) be the concept with the smallest radius that is consistent with T.

Suppose our target concept c is the sphere around the origin with radius r. We will choose a slightly smaller radius s by

$$s := \inf\{s' \colon \mathbb{P}(s' \le ||x|| \le r) < \epsilon\}.$$

Let A denote the annulus between radii s and r; that is, $A := \{x : s \le ||x|| \le r\}$. By definition of s, we have $\mathbb{P}(A) \ge \epsilon$. In addition, our generalization

error, $\mathbb{P}(c \Delta L(T))$, must be small if T intersects A. We can state this as

$$\mathbb{P}(c\,\Delta\,L(T)) > \epsilon \implies T \cap A = \emptyset. \tag{2}$$

Thus, we know that any point in T chosen will miss region A with probability at most $1 - \epsilon$. Defining $error := \mathbb{P}(c \Delta L(T))$, we can combine this with (2) to see that

$$\mathbb{P}(error > \epsilon) \le P(T \cap A = \emptyset) \le (1 - \epsilon)^m \le e^{-m\epsilon}.$$

Setting δ to be greater than or equal to the right-hand side leads to $m \geq \frac{1}{\epsilon} \log(\frac{1}{\delta})$.

مو فق باشید